

The Parametric Complexity of Lossy Counter Machines

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Abstract

The reachability problem in lossy counter machines is the best-known ACKERMANN-complete problem and has been used to establish most of the ACKERMANN-hardness statements in the literature. This hides however a complexity gap when the number of counters is fixed. We close this gap and prove F_d -completeness for machines with d counters, which provides the first known uncontrived problems complete for the fast-growing complexity classes at levels $3 < d < \omega$. We develop for this an approach through antichain factorisations of bad sequences and analysing the length of controlled antichains.

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1 Introduction

Mayr and Meyer exhibited in 1981 “the first uncontrived decidable problems which are not primitive-recursive,” namely the finite containment and equality problems in Petri nets [31]. McAloon [33], Clote [8], and Howell and Yen [23] subsequently proved Ackermannian upper bounds for these two problems, essentially matching Mayr and Meyer’s lower bound.

Such an astronomical complexity could have been an isolated phenomenon with only a few examples related to the original problems, but uncontrived problems with a similar complexity actually occur in logic (e.g., relevance logic [47], data logics [11, 15], interval temporal logic [35], linear logic [28], metric temporal logic [27]), verification (e.g., counter machines [43, 22], fragments of the π -calculus [4], broadcast protocols [42], rewriting systems [20], register automata [11, 17]), and games (e.g., partial observation energy games [36], bisimulation games on pushdown automata [24]), and even higher complexities also occur naturally [29, 6, 37, 19, 18, 10]; see [38, Sec. 6] for an overview.

This abundance of results is largely thanks to a framework [41, 42, 39] that comprises:

- The definition of an ordinal-indexed hierarchy $(F_\alpha)_\alpha$ of *fast-growing complexity classes*, along with assorted notions of reductions and completeness suitable to work with such high complexities [38]. The previous decision problems are complete for $\text{ACKERMANN} = F_\omega$ under primitive-recursive reductions; F_ω is the lowest non primitive-recursive class in the hierarchy, where $\text{TOWER} = F_3$ corresponds to problems solvable in time bounded by a tower of exponentials and where each F_k for a finite k is primitive-recursive.



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- The identification of *master* decision problems, which allow to establish completeness more easily than from first principles. For instance, reachability in lossy counter machines [47, 43, 45] plays a similar role for ACKERMANN as, e.g., 3SAT for NP or QBF for PSPACE, and has been used to derive most of the known ACKERMANN-hardness results [4, 11, 15, 35, 27, 22, 20, 17, 24].
- Lower bound techniques for establishing the complexity of such master problems: this typically relies on implementing *weak computers* for *Hardy functions* and their inverses in the formalism at hand, allowing to build a large but bounded working space on which a Turing or a Minsky machine can then be simulated [47, 43, 45, 6, 37, 19, 18].
- Upper bound techniques relying on combinatorial statements, called *length function theorems*, on the length of *controlled bad sequences* over well-quasi-orders, which are used to prove the termination of the decision procedures [33, 8, 49, 7, 14, 40, 3, 37].

From an algorithmic perspective, these results are negative and one could qualify such problems as merely “not undecidable”. What we gain however are insights into the computational power of the models, allowing to compare them and to identify the main sources of complexity – e.g., in lossy counter machines, the key parameter is the number of counters. Furthermore, from a modelling perspective, a formalism with a tremendous computational power that nevertheless falls short of Turing completeness can be quite satisfactory.

Contributions. In this paper, we revisit the proof of the best-known result in this area, namely the ACKERMANN-completeness of reachability in lossy counter machines (LCMs). Those are simply multi-counter Minsky machines with a *lossy semantics* that allows the counters to decrease in an uncontrollable manner during executions; see Section 2.

The gap in the current state of knowledge appears when one fixes the key complexity parameter, i.e., the number d of counters. Indeed, the best known lower bound for LCM reachability is F_d -hardness when $d \geq 3$ [39, Thm. 4.9], but the best known upper bound is F_{d+1} [14, 41, 3]. This complexity gap reveals a serious shortcoming of the framework advertised earlier in this introduction, and also impacts the complexity of many problems shown hard through a reduction from LCM reachability.

Our first main contribution in Proposition 8 is an F_d upper bound, which together with the lower bound from [39, Thm. 4.9] entails the following completeness result.

► **Theorem 1.** *LCM Reachability is F_ω -complete, and F_d -complete if the number $d \geq 3$ of counters is fixed.*

Note that this provides an uncontrived decision problem for every class F_k with $3 \leq k \leq \omega$, whereas no natural F_k -complete problems were previously known for the intermediate primitive-recursive levels strictly between TOWER and ACKERMANN, i.e., for $3 < k < \omega$.

As we recall in Section 3, reachability in lossy counter machines can be solved using the generic *backward coverability algorithm* for *well-structured* systems [1, 16]. As usual, we derive our complexity upper bound by bounding the length of the bad sequences that underlie the termination argument for this algorithm. The main obstacle here is that the length function theorems in [14, 41, 3] – i.e., the bounds on the length of controlled bad sequences over \mathbb{N}^d – are essentially optimal and only yield an F_{d+1} complexity upper bound.

We circumvent this using a new approach in Section 4. We restrict our attention to *strongly controlled* bad sequences rather than the more general *amortised controlled* ones (see Section 4.1), which in turn allows us to work on the *antichain factorisations* of bad sequences (see Section 4.2). This entails that, in order to bound the length of strongly controlled

bad sequences, it suffices to bound the length of strongly controlled antichains. This is tackled in Section 5, where we prove a *width function theorem* on the length of controlled antichains over \mathbb{N}^d ; to the best of our knowledge, this is the first statement of this kind specific to antichains rather than bad sequences. We wrap up with the proof of Proposition 8 in Section 6.

The developments of Sections 4 and 5 form our second main contribution. They are of wide interest beyond lossy counter machines, as they can be applied whenever the termination of an algorithm relies on \mathbb{N}^d having finite (controlled) bad sequences or antichains.

2 Lossy Counter Machines

Syntax. A *lossy counter machine* (LCM) [32] is syntactically identical to a Minsky machine $M = (Q, \mathcal{C}, \delta)$, where the transitions in $\delta \subseteq Q \times \mathcal{C} \times \{=0?, ++, --\} \times Q$ operate on a finite set Q of control locations and a finite set \mathcal{C} of counters through *zero-tests* $c=0?$, *increments* $c++$ and *decrements* $c--$.

Operational Semantics. The semantics of an LCM differ from the usual, ‘reliable’ semantics of a counter machine in that the counter values can decrease in an uncontrolled manner at any point of the execution. Formally, a *configuration* $q(\mathbf{v})$ associates a control location q in Q with a counter valuation \mathbf{v} in $\mathbb{N}^{\mathcal{C}}$, i.e. counter values can never go negative. The set of configurations $Q \times \mathbb{N}^{\mathcal{C}}$ is ordered by the product ordering: $q(\mathbf{v}) \leq q'(\mathbf{v}')$ if $q = q'$ and $\mathbf{v}(c) \leq \mathbf{v}'(c)$ for all $c \in \mathcal{C}$.

A transition of the form $(q, c, \text{op}, q') \in \delta$ defines a set of *reliable computation steps* $q(\mathbf{v}) \rightarrow q'(\mathbf{v}')$, where $\mathbf{v}(c') = \mathbf{v}'(c')$ for all $c \neq c'$ in \mathcal{C} and

- if $\text{op} = =0?$, then $\mathbf{v}(c) = \mathbf{v}'(c) = 0$,
- if $\text{op} = ++$, then $\mathbf{v}(c) + 1 = \mathbf{v}'(c)$, and
- if $\text{op} = --$, then $\mathbf{v}(c) = \mathbf{v}'(c) + 1$.

A *lossy computation step* is then defined by allowing counter values to decrease arbitrarily between reliable steps: $q(\mathbf{v}) \rightarrow_{\ell} q'(\mathbf{v}')$ if there exist $\mathbf{w} \leq \mathbf{v}$ and $\mathbf{w}' \geq \mathbf{v}'$ such that $q(\mathbf{w}) \rightarrow q'(\mathbf{w}')$. We write as usual \rightarrow_{ℓ}^* for the transitive reflexive closure of \rightarrow_{ℓ} .

Reachability. The decision problem we tackle in this paper is the following.

► **Problem** (LCM Reachability).

instance A lossy counter machine (Q, \mathcal{C}, δ) and two configurations $q_0(\mathbf{v}_0)$ and $q_f(\mathbf{v}_f)$.

question Is $q_f(\mathbf{v}_f)$ reachable from $q_0(\mathbf{v}_0)$, i.e., does $q_0(\mathbf{v}_0) \rightarrow_{\ell}^* q_f(\mathbf{v}_f)$?

Note that, due to the lossy semantics, this is equivalent to the *coverability* problem, which asks instead whether there exists $\mathbf{v} \geq \mathbf{v}_f$ such that $q_0(\mathbf{v}_0) \rightarrow_{\ell}^* q_f(\mathbf{v})$. Indeed, such a \mathbf{v} exists if and only if $q_0(\mathbf{v}_0) \geq q_f(\mathbf{v}_f)$ or $q_0(\mathbf{v}_0) \rightarrow_{\ell}^* q_f(\mathbf{v}_f)$.

While many problems are undecidable in LCMs [32, 44], these systems are in fact *well-structured* in the sense of [1, 16], which means that their coverability problem is decidable, as further discussed in Section 3. The ACKERMANN-hardness of reachability was first shown by Schnoebelen [43] in 2002,¹ while an ACKERMANN upper bound follows from the length function theorems for Dickson’s Lemma [33, 8, 14, 41, 3]. Note that LCM reachability is equivalent to reachability in counter machines with *incrementing errors* [11] and to coverability in *reset counter machines* [45, Sec. 6], and this also holds if we fix the number of counters.

¹ Urquhart [47] showed independently in 1999 and using a similar approach the same result for the closely related model of alternating expansive vector addition systems.

3 Well Structured Systems

Well-structured transition systems (WSTS) [1, 16] form a family of computational models where the (usually infinite) set of configurations is equipped with a well-quasi-ordering (see Section 3.1) that is “compatible” with the computation steps (see Section 3.2). The existence of this well-quasi-ordering allows for the decidability of some important behavioural properties like termination (from a given initial configuration) or coverability, see Section 3.3.

3.1 Well-Quasi-Orders

A *quasi-order* (qo) is a pair (X, \leq) where $\leq \subseteq X \times X$ is transitive and reflexive; we write $x < y$ for the associated strict ordering, when $x \leq y$ and $y \not\leq x$, $x \perp y$ for incomparable elements, when $x \not\leq y$ and $y \not\leq x$, and $x \equiv y$ for equivalent elements, when $x \leq y$ and $y \leq x$. The *upward-closure* $\uparrow Y$ of some $Y \subseteq X$ is defined as $\uparrow Y \stackrel{\text{def}}{=} \{x \in X \mid \exists y \in Y. x \geq y\}$; we write $\uparrow x$ instead of $\uparrow\{x\}$ for singletons and say that a set $U \subseteq X$ is *upwards-closed* when $U = \uparrow U$. We call a finite or infinite sequence x_0, x_1, x_2, \dots over X *bad* if for all indices $i < j$, $x_i \not\leq x_j$; if $x_i \perp x_j$ for all $i < j$, then x_0, x_1, x_2, \dots is an *antichain*.

A *well-quasi-order* (wqo) [21, 26] is a qo (X, \leq) where bad sequences are finite. Equivalently, (X, \leq) is a wqo if and only if it is both *well-founded*, i.e., there does not exist any infinite decreasing sequences $x_0 > x_1 > x_2 > \dots$ of elements in X , and has the *finite antichain condition*, i.e., there are no infinite antichains. Still equivalently, (X, \leq) is a wqo if and only if it has the *ascending chain condition*: any increasing sequence $U_0 \subseteq U_1 \subseteq U_2 \subseteq \dots$ of upwards-closed subsets of X eventually stabilises, i.e., $\bigcup_{i \in \mathbb{N}} U_i = U_k = U_{k+1} = U_{k+2} = \dots$ for some k . Still equivalently, (X, \leq) is a wqo if and only if it has the *finite basis property*: any non-empty subset contains at least one, and at most finitely many minimal elements (up to equivalence); thus if $U \subseteq X$ is upwards-closed, then $\min U$ is finite and $U = \uparrow(\min U)$.

For a basic example, consider any finite set Q along with the equality relation, which is a wqo $(Q, =)$ by the pigeonhole principle. Any well-order is a wqo, thus the set of natural numbers and any of its initial segments $[k] \stackrel{\text{def}}{=} \{0, \dots, k-1\}$ along with their natural ordering are also wqos. More examples can be constructed using algebraic operations: for instance, if (X_0, \leq_{X_0}) and (X_1, \leq_{X_1}) are wqos, then so are:

- their disjoint sum $(X_0 \sqcup X_1, \leq)$ where $X_0 \sqcup X_1 \stackrel{\text{def}}{=} \{(x, 0) \mid x \in X_0\} \cup \{(x, 1) \mid x \in X_1\}$ and $(x, i) \leq (y, j)$ if $i = j$ and $x \leq_{X_i} y$;
- their Cartesian product $(X_0 \times X_1, \leq)$ where $(x_0, x_1) \leq (y_0, y_1)$ if $x_i \leq_{X_i} y_i$ for all $0 \leq i \leq 1$; in the case of (\mathbb{N}^d, \leq) , this result is also known as Dickson’s Lemma [12].

Note that the set of configurations $(Q \times \mathbb{N}^c, \leq)$ of an LCM is a wqo for the product ordering.

3.2 Compatibility

An *ordered transition system* $\mathcal{S} = (S, \rightarrow, \leq)$ combines a set S of configurations with a transition relation $\rightarrow \subseteq S \times S$ and a quasi-ordering \leq of its configurations. An ordered transition system $\mathcal{S} = (S, \rightarrow, \leq)$ is *well-structured* if (S, \leq) is a wqo and

$$\forall s_1, s_2, t_1 \in S, (s_1 \rightarrow s_2 \text{ and } s_1 \leq t_1) \text{ implies } \exists t_2 \in S, (t_1 \rightarrow t_2 \text{ and } s_2 \leq t_2). \quad (1)$$

This property is also called *compatibility* (of the ordering with the transitions). Formally, it just means that \leq is a *simulation* relation for (S, \rightarrow) , in precisely the classical sense of [34]. The point of (1) is to ensure that a larger configuration can do at least as much as a smaller configuration. For instance, lossy steps in a LCM are visibly compatible with \leq according to (1), and thus the transition system $(Q \times \mathbb{N}^c, \rightarrow_\ell, \leq)$ defined by the lossy operational semantics of a LCM is a WSTS.

3.3 Coverability

We focus here on the *coverability problem*: given a WSTS (S, \rightarrow, \leq) and two configurations $s, t \in S$, does s cover t , i.e., does there exist $t' \geq t$ such that $s \rightarrow^* t'$? The decidability of this problem uses a set-saturation method first introduced by Arnold and Latteux [5] for reset Petri nets, but the algorithm was independently rediscovered by Abdulla et al. [2] for lossy channel systems and its generic formulation was popularised in the surveys [1, 16].

Backward Coverability. The algorithm computes $\text{Pre}_\exists^*(\uparrow t) \stackrel{\text{def}}{=} \{s' \in S \mid \exists t' \geq t, s' \rightarrow^* t'\}$, i.e., the set of configurations that cover t ; it only remains to check whether $s \in \text{Pre}_\exists^*(\uparrow t)$ in order to answer the coverability instance. More precisely, for a set of configurations $U \subseteq S$, let us define its (existential) *predecessor set* as $\text{Pre}_\exists(U) \stackrel{\text{def}}{=} \{s \in S \mid \exists s' \in U, s \rightarrow s'\}$. The algorithm computes the limit of the sequence $U_0 \subseteq U_1 \subseteq \dots$ defined by

$$U_0 \stackrel{\text{def}}{=} \uparrow t, \quad U_{n+1} \stackrel{\text{def}}{=} U_n \cup \text{Pre}_\exists(U_n). \quad (2)$$

Note that for all n , $U_n = \{s' \in S \mid \exists t' \geq t, s' \rightarrow^{\leq n} t'\}$ is the set of configurations that cover t in at most n steps, and that we can stop this computation as soon as $U_{n+1} \subseteq U_n$.

There is no reason for the chain defined by (2) to stabilise in general ordered transition systems, but it does in the case of a WSTS. Indeed, $\text{Pre}_\exists(U)$ is upwards-closed whenever $U \subseteq S$ is upwards-closed, thus the sequence defined by (2) stabilises to $\bigcup_{i \in \mathbb{N}} U_i = \text{Pre}_\exists^*(\uparrow t)$ after a finite amount of time thanks to the ascending chain condition. Moreover, the finite basis property ensures that all the sets U_i can be finitely represented using their minimal elements, and the union or inclusion of two upwards-closed sets can be computed on this representation. The last ingredients are two effectiveness assumptions:

- (S, \leq) should be effective, meaning that S is recursive and the ordering \leq is decidable,
- there exists an algorithm returning the set of minimal predecessors $\min \text{Pre}_\exists(\uparrow s')$ of any given configuration s' ; this is known as the *effective pred-basis* assumption.

These two assumptions hold in LCMs: $(Q \times \mathbb{N}^c, \leq)$ is certainly effective, and the minimal predecessors of a configuration $q'(\mathbf{v}')$ can be computed by

$$\min \text{Pre}_\exists(\uparrow q'(\mathbf{v}')) = \min\{q(\text{pre}_{c \text{ op}}(\mathbf{v}')) \mid (q, c, \text{op}, q') \in \delta \text{ and } \mathbf{v}'(c) = 0 \text{ if } \text{op} = =0?\} \quad (3)$$

where $\text{pre}_{c \text{ op}}(\mathbf{v}')$ is a vector in \mathbb{N}^c defined by $\text{pre}_{c \text{ op}}(\mathbf{v}')(c') \stackrel{\text{def}}{=} \mathbf{v}'(c')$ for all $c' \neq c$ in \mathbb{C} and

$$\text{pre}_{c=0?}(\mathbf{v}')(c) \stackrel{\text{def}}{=} 0, \quad \text{pre}_{c++}(\mathbf{v}')(c) \stackrel{\text{def}}{=} \max\{0, \mathbf{v}'(c) - 1\}, \quad \text{pre}_{c--}(\mathbf{v}')(c) \stackrel{\text{def}}{=} \mathbf{v}'(c) + 1. \quad (4)$$

Coverability Pseudo-Witnesses. Let us reformulate the termination argument of the backward coverability algorithm in terms of bad sequences. We can extract a sequence of elements t_0, t_1, \dots from the ascending sequence $U_0 \subsetneq U_1 \subsetneq \dots$ defined by (2) before saturation: $t_0 \stackrel{\text{def}}{=} t$ and $t_{i+1} \in U_{i+1} \setminus U_i$ for all i . Note that if $i < j$, then $t_j \in U_j \setminus U_i$ and therefore $t_i \not\leq t_j$: the sequence t_0, t_1, \dots is bad and therefore finite. In fact, we can even pick t_{i+1} at each step among the minimal elements of $\text{Pre}_\exists(\uparrow t_i)$; we call such a bad sequence t_0, t_1, \dots, t_n with

$$t_0 \stackrel{\text{def}}{=} t, \quad t_{i+1} \in \min \text{Pre}_\exists(\uparrow t_i) \setminus U_i. \quad (5)$$

a *pseudo-witness* of the coverability of t . The maximal length of pseudo-witnesses is therefore equal to the number of steps of the backward coverability algorithm, and this is what we will bound in the upcoming Sections 4 and 5.

4 Controlled Bad Sequences and Antichains

As we have just discussed, the running time of the backward coverability algorithm is essentially bounded by the length of the bad sequences constructed by its termination argument. Though bad sequences over a wqo are finite, we cannot bound their lengths in general; e.g., $(0, n+1), (0, n), \dots, (0, 0)$ and $(1, 0), (0, n), (0, n-1), \dots, (0, 1), (0, 0)$ are bad sequences over \mathbb{N}^2 of length $n+2$ for all n . Nevertheless, a bad sequence produced by an algorithm like the backward coverability algorithm of Section 3.3 is not arbitrary, because its elements are determined by the algorithm's input and the complexity of its operations. We capture this intuition formally through *controlled sequences*.

4.1 Controlling Sequences

Norms. Given a wqo (X, \leq_X) , we posit a *norm* function $|\cdot|_X: X \rightarrow \mathbb{N}$; if $x \leq_X x'$ implies $|x|_X \leq |x'|_X$, we call this norm *monotone*. In order to be able to derive combinatorial statements, we require $X_{\leq n} \stackrel{\text{def}}{=} \{x \in X \mid |x|_X \leq n\}$ to be finite for every n ; we call the resulting structure $(X, \leq_X, |\cdot|_X)$ a *normed wqo* (nwqo).

We will use the following monotone norms on the wqos we defined in Section 3.1: over a finite Q , all the elements have the same norm 0; over \mathbb{N} or $[d]$, n has norm $|n|_{\mathbb{N}} = |n|_{[d]} = n$; over disjoint sums $X_0 \sqcup X_1$, (x, i) uses the norm $|x|_{X_i}$ of its underlying set; finally, over Cartesian products $X \times Y$, (x, y) uses the infinite norm $\max(|x|_X, |y|_Y)$.

Controls. Let $n_0 \in \mathbb{N}$ and let $g: \mathbb{N} \rightarrow \mathbb{N}$ be a monotone and inflationary function, i.e., for all $x \leq x'$, $g(x) \leq g(x')$ and $x \leq g(x)$. We say that a sequence x_0, x_1, x_2, \dots of elements in X is *amortised (g, n_0) -controlled* if

$$\forall i. |x_i|_X \leq g^i(n_0), \quad (6)$$

where g^i denotes the i th iterate of g . We say that it is *strongly (g, n_0) -controlled* if

$$|x_0|_X \leq n_0 \quad \text{and} \quad \forall i. |x_{i+1}|_X \leq g(|x_i|_X). \quad (7)$$

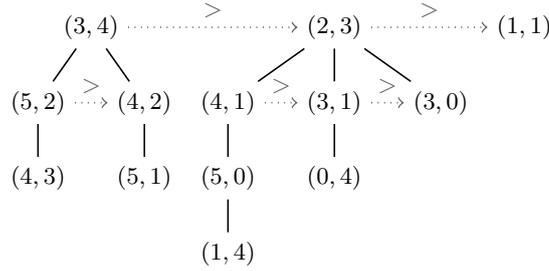
By definition, a strongly controlled sequence is also amortised controlled: $|x_0|_X \leq g^0(n_0) = n_0$, which prompts the name of *initial norm* for n_0 , and amortised steps cannot grow faster than g the *control function*.

Previous works like [14, 41, 3] focused on the more general amortised controlled sequences, but strong controlled ones are actually more relevant in practice. For instance, in the case of LCM coverability, the computation of minimal predecessors in (3–4) shows that the pseudo-witnesses from (5) of the coverability of a target configuration $q_f(\mathbf{v}_f)$ are strongly $(H, |\mathbf{v}_f|)$ -controlled by the initial norm $|\mathbf{v}_f| = \max_{c \in C} \mathbf{v}_f(c)$ and the control function $H(x) \stackrel{\text{def}}{=} x + 1$.

Length, Norm, and Width Functions. The point of controlled sequences is that their length can be bounded. Consider for this the tree obtained by sharing the common prefixes of all the strongly (g, n_0) -controlled bad sequences over a normed wqo $(X, \leq_X, |\cdot|_X)$.

- This tree is finitely branching by (7) – its branching degree is bounded by the cardinal of $X_{\leq g^i(n_0)}$ for a node at depth i –, and
- it has no infinite branches since bad sequences over (X, \leq_X) are finite.

By König's Lemma, this tree of bad sequences is therefore finite, of some height $L_{g,X}^s(n_0)$ representing the length of the maximal strongly (g, n_0) -controlled bad sequence(s) over X , and we also let $N_{g,X}^s(n_0)$ bound the norms encountered along such sequences; note that



■ **Figure 1** The antichain factorisation of the strongly $(H, 4)$ -controlled bad sequence $(3, 4) (5, 2) (4, 3) (4, 2) (5, 1) (2, 3) (4, 1) (5, 0) (1, 4) (3, 1) (0, 4) (3, 0) (1, 1)$ over \mathbb{N}^2 for $H(x) \stackrel{\text{def}}{=} x + 1$.

$N_{g,X}^s(n_0) \leq g^{L_{g,X}^s(n_0)}(n_0)$ since g is monotone inflationary. Similarly, there exists a maximal length, denoted by $W_{g,X}^a(n_0)$ (resp. $W_{g,X}^s(n_0)$), for amortised (resp. strongly) (g, n_0) -controlled antichains over X . We call $L_{g,X}^s$, $N_{g,X}^s$, and $W_{g,X}^s$ the *strong length*, *strong norm*, and *strong width* functions respectively, and $W_{g,X}^a$ the *width* function. By definition, a strongly controlled antichain is amortised controlled, i.e.,

$$W_{g,X}^s(n_0) \leq W_{g,X}^a(n_0), \quad (8)$$

and the length of a bad sequence where all the elements are of norm at most $N = N_{g,X}^s(n_0)$ is bounded by the cardinal of $X_{\leq N}$, i.e.,

$$L_{g,X}^s(n_0) \leq |X_{\leq N_{g,X}^s(n_0)}|. \quad (9)$$

Observe that $L_{g,X}^s(|t|_X)$ bounds the number of steps required by the backward coverability algorithm for a WSTS over $(X, \leq_X, |\cdot|_X)$ with target configuration t where $s' \in \min \text{Pre}(\uparrow t')$ implies $|s'|_X \leq g(|t'|_X)$. In the case of LCMs, we are therefore interested in $L_{H,Q \times N^c}^s(|\mathbf{v}_f|)$.

4.2 Antichain Factorisations

Let $(X, \leq_X, |\cdot|_X)$ be a nwqo where $|\cdot|_X$ is monotone – i.e., $x \leq x'$ implies $|x|_X \leq |x'|_X$ –, and let $x_0, x_1, \dots, x_{\ell-1} \in X^*$ be a strongly (g, n_0) -controlled bad sequence over $(X, \leq_X, |\cdot|_X)$. Informally, the *antichain factorisation* of $x_0, x_1, \dots, x_{\ell-1}$ is an ordered forest A where all the branches are strongly (g, n_0) -controlled antichains, siblings are ordered left-to-right by the strict ordering $>_X$, and such that the pre-order traversal of A yields back the bad sequence. Consider for instance the example of Figure 1: this bad sequence has length 13, thus the norm of its elements is at most $H^{12}(4) = 16$, but because the height of its antichain factorisation is 4, we can actually bound the norm by $H^3(4) = 7$.

We can compute this factorisation from any strongly (g, n_0) -controlled bad sequence. Formally, $A \subseteq X^*$ is a prefix-closed finite set of antichains with the prefix ordering as vertical ordering. Two antichains u and v in A are *siblings* if $u = w \cdot x$ and $v = w \cdot y$ for some $w \in X^*$ and $x, y \in X$, and we order such siblings by letting $u >_X v$ if $x >_X y$. Given $x_0, \dots, x_{\ell-1}$, we let $A \stackrel{\text{def}}{=} \text{Fact}(x_0, 1)$ where

$$\text{Fact}(y_0 \cdots y_m, i) \stackrel{\text{def}}{=} \{y_0 \cdots y_m\} \cup \begin{cases} \emptyset & \text{if } i = \ell, \\ \text{Fact}(y_0 \cdots y_m x_i, i + 1) & \text{if } \forall j. y_j \not>_X x_i, \\ \text{Fact}(y_0 \cdots y_{k-1} x_i, i + 1) & \text{if } k = \min\{j \mid y_j >_X x_i\}. \end{cases} \quad (10)$$

This corresponds to scanning the elements x_i of the bad sequence from left to right while building the current “rightmost branch” $y_0 \cdots y_m \in A$, which is (by induction on i) a strongly (g, n_0) -controlled antichain and a scattered subword of $x_0 \cdots x_{i-1}$ (thus $y_j \not\leq x_i$ for all $0 \leq j \leq m$) such that $y_m = x_{i-1}$. If $y_j \not\leq_X x_i$ for all $0 \leq j \leq m$, then $y_0 \cdots y_m x_i$ is a (g, n_0) -controlled antichain and a scattered subword of $x_0 \cdots x_i$. If otherwise $y_j >_X x_i$ for some y_j , we let k be the minimal such j and we start a new rightmost branch with x_i out of y_{k-1} (x_i is possibly a new root if $k = 0$); crucially, because $|\cdot|_X$ is monotone and $x_i <_X y_k$, we have $|x_i|_X \leq |y_k|_X \leq g(|y_{k-1}|_X)$ (or $|x_i|_X \leq |y_k|_X \leq n_0$ at the root), thus $y_0 \cdots y_{k-1} x_i$ is again a strongly (g, n_0) -controlled antichain and a scattered subword of $x_0 \cdots x_i$.

We deduce a bound on the strong norm function in terms of the strong width function.

► **Lemma 2 (Antichain Factorisation).** *Let $(X, \leq_X, |\cdot|_X)$ be a normed wqo with $|\cdot|_X$ monotone, n_0 in \mathbb{N} , and $g: \mathbb{N} \rightarrow \mathbb{N}$ monotone inflationary. Then $N_{g,X}^s(n_0) \leq g^{W_{g,X}^s(n_0)}(n_0)$.*

Lemma 2 combined with (8) shows that the strong norm function $N_{g,X}^s$ can be bounded in terms of the width function $W_{g,X}^a$. By (9), this will also yield a bound on the strong length function $L_{g,X}^s$. We focus therefore on the width function in the upcoming Section 5.

5 Width Function Theorem

As seen in Section 4, by suitably controlling how large the elements can grow in antichains, we can derive upper bounds on the time and space required by the backward coverability algorithm of Section 3. We prove in this section a *width function theorem*, a combinatorial statement on the length of amortised controlled antichains over tuples of natural numbers, which will allow to derive a complexity upper bound for reachability in lossy counter machines.

The high complexities at play here require the use of ordinal-indexed *subrecursive functions* in order to denote non-elementary growths. We first recall the definitions of two families of such functions in Section 5.1; we refer the reader to [46, 41] for further details. We then prove in Section 5.2 a bound on the width function W_{g,\mathbb{N}^d}^a using the framework of [40, 41].

5.1 Subrecursive Hierarchies

Fundamental Sequences and Predecessors. A *fundamental sequence* for a limit ordinal λ is a strictly increasing sequence $(\lambda(x))_{x < \omega}$ of ordinal terms with supremum λ . We use the standard assignment of fundamental sequences to limit ordinals below ε_0 in Cantor normal form, defined inductively by

$$(\gamma + \omega^{\beta+1})(x) \stackrel{\text{def}}{=} \gamma + \omega^\beta \cdot (x+1), \quad (\gamma + \omega^\lambda)(x) \stackrel{\text{def}}{=} \gamma + \omega^{\lambda(x)}. \quad (11)$$

This particular assignment satisfies e.g. $0 < \lambda(x) < \lambda(y)$ for all $x < y$. For instance, $\omega(x) = x+1$, $(\omega^{\omega^4} + \omega^{\omega^3 + \omega^2})(x) = \omega^{\omega^4} + \omega^{\omega^3 + \omega \cdot (x+1)}$.

The *predecessor* $P_x(\alpha)$ of an ordinal term $0 < \alpha < \varepsilon_0$ at $x \in \mathbb{N}$ is defined inductively by

$$P_x(\alpha + 1) \stackrel{\text{def}}{=} \alpha, \quad P_x(\lambda) \stackrel{\text{def}}{=} P_x(\lambda(x)). \quad (12)$$

In essence, the predecessor of an ordinal is obtained by repeatedly taking the x th element in the fundamental sequence of limit ordinals, until we finally reach a successor ordinal and may remove 1. For instance, $P_x(\omega^2) = P_x(\omega \cdot (x+1)) = P_x(\omega \cdot x + x + 1) = \omega \cdot x + x$.

Hardy and Cichoń Hierarchies. Let $h: \mathbb{N} \rightarrow \mathbb{N}$ be a function. The *Hardy hierarchy* $(h^\alpha)_{\alpha \in \varepsilon_0}$ and the *Cichoń hierarchy* $(h_\alpha)_{\alpha \in \varepsilon_0}$ relative to h are defined for all $0 < \alpha < \varepsilon_0$ by

$$h^0(x) \stackrel{\text{def}}{=} x, \quad h^\alpha(x) \stackrel{\text{def}}{=} h^{P_x(\alpha)}(h(x)), \quad h_0(x) \stackrel{\text{def}}{=} 0, \quad h_\alpha(x) \stackrel{\text{def}}{=} 1 + h_{P_x(\alpha)}(h(x)). \quad (13)$$

Observe that $h^k(x) = h^{P_x(k)}(h(x)) = h^{k-1}(h(x))$ for some finite k is the k th iterate of h . This intuition carries over: h^α is a “transfinite” iteration of the function h , using diagonalisation in the fundamental sequences to handle limit ordinals. A standard choice for the function h is the successor function, noted $H(x) \stackrel{\text{def}}{=} x + 1$; in that case, we see that a first diagonalisation yields $H^\omega(x) = H^x(x + 1) = 2x + 1$. The next diagonalisation occurs at $H^{\omega \cdot 2}(x) = H^{\omega+x}(x + 1) = H^\omega(2x + 1) = 4x + 3$. Fast-forwarding a bit, we get for instance a function of exponential growth $H^{\omega^2}(x) = 2^{x+1}(x + 1) - 1$, and later a non-elementary function $H^{\omega^3}(x)$ akin to a tower of exponentials of height x , and an “Ackermannian” non primitive-recursive function H^{ω^ω} .

Both h^α and h_α are monotone and inflationary whenever h is monotone inflationary. Hardy functions are well-suited for expressing large iterates of a control function, and therefore for bounding the norms of elements in a controlled sequence. Cichoń functions are well-suited for expressing the length of controlled sequences: we can compute how many times we should iterate h in order to compute $h^\alpha(x)$ using the corresponding Cichoń function [7]:

$$h^\alpha(x) = h^{h_\alpha(x)}(x). \quad (14)$$

5.2 Width Function for Dickson’s Lemma

The starting point for our analysis is a *descent equation* for amortised controlled antichains through *residuals*, similar to the equations proven in [14, 40] for bad sequences (see Lemma 3). The key idea introduced in [14] is then to over-approximate the residuals of \mathbb{N}^d by working over *polynomial nwqos*, where disjoint sums are also allowed. Then, the notion of “over-approximation” of residuals of polynomial nwqos is captured formally by showing the existence of a *normed reflection* into another polynomial nwqo. The final step lifts this to ordinals, allowing to relate $W_{g,X}^a$ for a polynomial nwqo X to functions in the Cichoń hierarchy.

Strict Polynomial Normed wqos. Let us write $X \cdot p$ for $\overbrace{X \sqcup \dots \sqcup X}^{p \text{ times}}$, X^d for $\overbrace{X \times \dots \times X}^{d \text{ times}}$, and $\mathbf{0}$ for the empty nwqo. We call a nwqo of the form $\mathbb{N}^{d_1} \sqcup \dots \sqcup \mathbb{N}^{d_m}$ for some $m \geq 0$ and $d_1, \dots, d_m \geq 1$ a *strict polynomial nwqo*. The set of configurations $Q \times \mathbb{N}^c$ of an LCM with $|Q| = q$ locations and $|C| = d \geq 1$ counters, along with its ordering and infinite norm, is isomorphic to the strict polynomial nwqo $\mathbb{N}^d \cdot q$.

Residuals and a Descent Equation. Let $(X, \leq_X, |\cdot|_X)$ be a normed wqo and x be an element of X . We write $X_{\perp x} \stackrel{\text{def}}{=} \{y \in X \mid x \perp y\}$ for the *residual* of X in x . By the finite antichain condition, there cannot be infinite sequences of residuations $(\dots((X_{\perp x_0})_{\perp x_1})_{\perp x_2} \dots)_{\perp x_i}$ because $x_i \perp x_j$ for all $i < j$ and it would create an infinite antichain.

Consider now an amortised (g, n_0) -controlled antichain x_0, x_1, x_2, \dots over X . Assuming the sequence is not empty, then for all $i > 0$, $x_0 \perp x_i$, i.e. the suffix x_1, x_2, \dots is actually an antichain over $X_{\perp x_0}$. This suffix is now amortised $(g, g(n_0))$ -controlled, and thus of length bounded by $W_{g, X_{\perp x_0}}^a(g(n_0))$. This yields the following *descent equation* when considering all the possible amortised (g, n_0) -controlled antichains; see the full version for a proof.

► **Lemma 3.** *Let $(X, \leq_X, |\cdot|_X)$ be a nwqo, $n_0 \in \mathbb{N}$ and $g: \mathbb{N} \rightarrow \mathbb{N}$. Then $W_{g,X}^a(n_0) = \max_{x \in X_{\leq n_0}} 1 + W_{g, X_{\perp x}}^a(g(n_0))$.*

Reflecting Normed wqos. The descent equation, though it offers a way of computing the width function, quickly leads to complex residual expressions. We are going to over-approximate these $X_{\perp x}$'s using *nwqo reflections*, so that the computation can be carried out without leaving the realm of strict polynomial nwqos, leading to an *inductive* over-approximation of $X_{\perp x}$ over the structure of the strict polynomial nwqo X .

A *nwqo reflection* [40] is a mapping $r: X \rightarrow Y$ between two nwqos $(X, \leq_X, |\cdot|_X)$ and $(Y, \leq_Y, |\cdot|_Y)$ that satisfies the two following properties:

$$\forall x, x' \in X. \quad r(x) \leq_Y r(x') \quad \text{implies} \quad x \leq_X x', \quad (15)$$

$$\forall x \in X. \quad |r(x)|_Y \leq |x|_X. \quad (16)$$

In other words, a nwqo reflection is an order reflection that is not norm-increasing. This induces a quasi-ordering between nwqos, written $X \hookrightarrow Y$. Remark that reflections are compatible with disjoint sums and products [40, Prop. 3.5]:

$$X_0 \hookrightarrow Y_0 \text{ and } X_1 \hookrightarrow Y_1 \quad \text{imply} \quad X_0 \sqcup X_1 \hookrightarrow Y_0 \sqcup Y_1 \text{ and } X_0 \times X_1 \hookrightarrow Y_0 \times Y_1. \quad (17)$$

Crucially, nwqo reflections preserve amortised controlled antichains. Indeed, let $r: X \hookrightarrow Y$, and consider a sequence x_0, x_1, \dots over X . Then by (15), $r(x_0), r(x_1), \dots$ is an antichain when x_0, x_1, \dots is, and by (16), it is (g, n) -controlled when x_0, x_1, \dots is. Hence

$$X \hookrightarrow Y \quad \text{implies} \quad W_{g,X}^a(n) \leq W_{g,Y}^a(n) \text{ for all } g, n. \quad (18)$$

Inductive Reflection of Residuals. We provide a strict polynomial wqo reflecting $X_{\perp x}$ by induction over the structure of the strict polynomial nwqo X . The key difference compared to the analysis of bad sequences in [14, 41] occurs for $X = \mathbb{N}$: if $k \in \mathbb{N}$,

$$\mathbb{N}_{\perp k} = \mathbf{0}. \quad (19)$$

Regarding disjoint sums $X_0 \sqcup X_1$, it is plain that

$$(X_0 \sqcup X_1)_{\perp(x,i)} = (X_i)_{\perp x} \sqcup X_{1-i}. \quad (20)$$

Consider now $(\mathbb{N}^d)_{\perp \mathbf{v}}$ where $d > 1$ and $\mathbf{v} \in \mathbb{N}^d$. Observe that if $\mathbf{u} \in \mathbb{N}^d$ is such that $\mathbf{u} \perp \mathbf{v}$, then there exists $1 \leq i \leq d$ such that $\mathbf{u}(i) < \mathbf{v}(i)$, as otherwise we would have $\mathbf{u} \geq \mathbf{v}$. Thus

$$(\mathbb{N}^d)_{\perp \mathbf{v}} \hookrightarrow \bigsqcup_{1 \leq i \leq d} \mathbb{N}^{d-1} \times [\mathbf{v}(i)] \hookrightarrow \mathbb{N}^{d-1} \cdot \sum_{1 \leq i \leq d} \mathbf{v}(i). \quad (21)$$

Ordinal Notations. As it is more convenient to reason with ordinals than with polynomial nwqos, we use the following bijection between strict polynomial nwqos and ω^ω :

$$w(\mathbf{0}) \stackrel{\text{def}}{=} 0, \quad w(\mathbb{N}^d) \stackrel{\text{def}}{=} \omega^{d-1}, \quad w(X_0 \sqcup X_1) = w(X_0) \oplus w(X_1). \quad (22)$$

where “ \oplus ” denotes the *natural sum* (aka *Hessenberg sum*) on ordinals: the natural sum $\alpha \oplus \beta$ of two ordinals with Cantor normal forms $\alpha = \sum_{i=1}^p \omega^{\alpha_i}$ and $\beta = \sum_{j=1}^m \omega^{\beta_j}$ is $\omega^{\gamma_1} + \dots + \omega^{\gamma_{p+m}}$ where the exponents $\gamma_1 \geq \dots \geq \gamma_{p+m}$ are a reordering of $\alpha_1, \dots, \alpha_p, \beta_1, \dots, \beta_m$. Given a strict polynomial nwqo $X = \bigsqcup_{i=1}^m \mathbb{N}^{d_i}$, its associated ordinal is $w(X) = \bigoplus_{i=1}^m \omega^{d_i-1}$. In the case of an LCM with $d \stackrel{\text{def}}{=} |\mathbb{C}|$ counters and $q \stackrel{\text{def}}{=} |Q|$ locations, $w(Q \times \mathbb{N}^{\mathbb{C}}) = \omega^{d-1} \cdot q$.

For each $n \in \mathbb{N}$, we define a relation ∂_n over ordinals in ω^ω that mirrors the inductive residuation and reflection operations on strict polynomial nwqos X over the ordinals $w(X)$:

$$\partial_n \alpha \stackrel{\text{def}}{=} \{ \gamma \oplus \partial_n \omega^d \mid \alpha = \gamma \oplus \omega^d \}, \quad \partial_n \omega^d \stackrel{\text{def}}{=} \begin{cases} 0 & \text{if } d = 0, \\ \omega^{d-1} \cdot n(d+1) & \text{otherwise.} \end{cases} \quad (23)$$

The intuition here is that $w(Y) \in \partial_n w(X)$ implies $X_{\perp x} \hookrightarrow Y$ for some $x \in X_{\leq n}$. Observe that $\alpha' \in \partial_n \alpha$ implies $\alpha' < \alpha$, thus $\bigcup_n \partial_n$ is a well-founded relation. This leads to the definition of an over-approximation of the width function $W_{g,X}^a$ (see the full version):

$$M_{g,\alpha}(n) \stackrel{\text{def}}{=} \max_{\alpha' \in \partial_n \alpha} \{1 + M_{g,\alpha'}(g(n))\}. \quad (24)$$

► **Proposition 4.** *Let $(X, \leq_X, | \cdot |_X)$ be a strict polynomial nwqo, $n_0 \in \mathbb{N}$, and $g: \mathbb{N} \rightarrow \mathbb{N}$. Then $W_{g,X}^a(n_0) \leq M_{g,w(X)}(n_0)$.*

It remains to compare $M_{g,\alpha}$ with standard subrecursive functions like the Cichoń functions, which was already done in [41, Sec. 2.4.3] for a very similar function; see the full version.

► **Proposition 5.** *Let n be in \mathbb{N} , $g: \mathbb{N} \rightarrow \mathbb{N}$ a monotone inflationary function, and $0 < \alpha < \omega^d$. Then $M_{g,\alpha}(n) \leq 1 + M_{g,P_{nd}(\alpha)}(n)$.*

This extra twist of using a predecessor function different from the standard one from (12) can be avoided by instead over-approximating the control function g .

► **Theorem 6** (Width Function for Strict Polynomial nwqos). *Let $d > 0$, $(X, \leq_X, | \cdot |_X)$ be a strict polynomial nwqo with $w(X) < \omega^d$, $n_0 \in \mathbb{N}$, $g: \mathbb{N} \rightarrow \mathbb{N}$ monotone inflationary, and let $h: \mathbb{N} \rightarrow \mathbb{N}$ be a monotone function such that $h(x \cdot d) \geq g(x) \cdot d$ for all x . Then $W_{g,X}^a(n_0) \leq h_{w(X)}(n_0 d)$.*

Proof. By Proposition 4, it suffices to show that $M_{g,w(X)}(n) \leq h_{w(X)}(nd)$, which we do by induction over $\alpha \stackrel{\text{def}}{=} w(X)$. If $\alpha = 0$, then $\partial_n \alpha = \emptyset$ thus $M_{g,\alpha}(n) = 0 \leq h_\alpha(nd)$. Otherwise, by Proposition 5, $M_{g,\alpha}(n) \leq 1 + M_{g,P_{nd}(\alpha)}(g(n))$. Because $P_{nd}(\alpha) < \alpha$, we can apply the induction hypothesis, yielding $M_{g,\alpha}(n) \leq 1 + h_{P_{nd}(\alpha)}(g(n)d) \leq 1 + h_{P_{nd}(\alpha)}(h(nd)) = h_\alpha(nd)$, where the last inequality follows from $h(nd) \geq g(n)d$ and the monotonicity of $h_{P_{nd}(\alpha)}$. ◀

Setting $h(x) \stackrel{\text{def}}{=} g(x)d$ always satisfies the conditions of the theorem. There are cases where setting $h \stackrel{\text{def}}{=} g$ suffices: e.g., $g(x) \stackrel{\text{def}}{=} 2x$, $g(x) \stackrel{\text{def}}{=} x^2$, $g(x) \stackrel{\text{def}}{=} 2^x$, and more generally whenever g is *super-homogeneous*, i.e. satisfies $g(dx) \geq g(x)d$ for all $d, x \geq 1$. In the case of LCMs, where $w(Q \times \mathbb{N}^c) < \omega^d$ if $d \stackrel{\text{def}}{=} |C| > 0$, a control function $g(x) \stackrel{\text{def}}{=} x + 1 = H(x)$ fits, thus setting $h(x) \stackrel{\text{def}}{=} x + d = H^d(x)$ satisfies $h(dx) = dx + d = (x + 1)d = g(x)d$.

By (8), Lemma 2, and (14), Theorem 6 also yields a bound on the strong norm function.

► **Corollary 7** (Strong Norm Function for Strict Polynomial nwqos). *Let d, X, n_0, g , and h be as in Theorem 6. Then $N_{g,X}^s(n_0) \leq h^{w(X)}(n_0 d)$.*

6 Wrapping up

We have now all the ingredients needed to prove an F_d upper bound on LCM Reachability. Let us first recall the definition of the fast-growing complexity classes from [38].

Fast-Growing Complexity Classes. The *fast-growing* complexity classes [38] form a strict ordinal-indexed hierarchy of complexity classes $(F_\alpha)_{\alpha < \varepsilon_0}$ using the Hardy functions $(H^\alpha)_{\alpha < \varepsilon_0}$ relative to $H(x) \stackrel{\text{def}}{=} x + 1$ as a standard against which to measure high complexities. Let

$$\mathcal{F}_{<\alpha} \stackrel{\text{def}}{=} \bigcup_{\beta < \omega^\alpha} \text{FDTIME}(H^\beta(n)), \quad F_\alpha \stackrel{\text{def}}{=} \bigcup_{p \in \mathcal{F}_{<\alpha}} \text{DTIME}(H^{\omega^\alpha}(p(n))). \quad (25)$$

Then $\mathcal{F}_{<\alpha}$ is the class of functions computed by deterministic Turing machines in time $O(H^\beta(n))$ for some $\beta < \omega^\alpha$; this captures for instance the class of Kalmar elementary functions as $\mathcal{F}_{<3}$ and the class of primitive-recursive functions as $\mathcal{F}_{<\omega}$ [30, 48]. The class F_α is

the class of decision problems solved by deterministic Turing machines in time $O(H^{\omega^\alpha}(p(n)))$ for some function $p \in \mathcal{F}_{<\alpha}$. The intuition behind this quantification of p is that, just like e.g. $\text{EXP} = \bigcup_{p \in \text{poly}} \text{DTIME}(2^{p(n)})$ quantifies over polynomial functions to provide enough “wobble room” to account for polynomial reductions, \mathcal{F}_α is closed under $\mathcal{F}_{<\alpha}$ reductions [38, Thms. 4.7 and 4.8]. For instance, $\text{TOWER} \stackrel{\text{def}}{=} \mathcal{F}_3$ defines the class of problems that can be solved in time bounded by a tower of exponentials of elementary height in the size of the input, $\bigcup_{k \in \mathbb{N}} \mathcal{F}_k$ is the class of primitive-recursive decision problems, and $\text{ACKERMANN} \stackrel{\text{def}}{=} \mathcal{F}_\omega$ is the class of problems that can be solved in time bounded by the Ackermann function applied to some primitive-recursive function of the input size.

Upper Bound. Recall from Section 3.3 that a pseudo-witness for coverability of a configuration $q_f(\mathbf{v}_f)$ in a LCM with $d \stackrel{\text{def}}{=} |\mathcal{C}| > 0$ counters and $q \stackrel{\text{def}}{=} |Q|$ locations is a strongly $(H, |\mathbf{v}_f|)$ -controlled bad sequence over $Q \times \mathbb{N}^c$, which as discussed in Section 5.2 is a strict polynomial wqo with $w(Q \times \mathbb{N}^c) = \omega^{d-1} \cdot q < \omega^d$, and that $h \stackrel{\text{def}}{=} H^d$ fits the conditions of Theorem 6 and Corollary 7. As stated in Theorem 1, together with the lower bounds from [39], the following entails the \mathcal{F}_d -completeness of LCM Reachability with a fixed number $d \geq 3$ of counters.

► **Proposition 8** (Upper Bound for LCM Reachability). *LCM Reachability is in \mathcal{F}_ω , and in \mathcal{F}_d if the number $d \geq 3$ of counters is fixed.*

Proof. Let $n_0 \stackrel{\text{def}}{=} |\mathbf{v}_f|$ be the infinite norm of the target configuration, $d \stackrel{\text{def}}{=} |\mathcal{C}| \geq 3$ be the number of counters, and $q \stackrel{\text{def}}{=} |Q| \geq 1$ the number of locations. By Corollary 7, the elements in a pseudo-witness of the coverability of $q_f(\mathbf{v}_f)$ are of norm at most $N \stackrel{\text{def}}{=} N_{H, Q \times \mathbb{N}^c}^s(n_0) = h^{\omega^{d-1} \cdot q}(n_0)$ for $h(x) \stackrel{\text{def}}{=} H^d(x)$. Let $n \stackrel{\text{def}}{=} \max\{qd - 1, n_0\}$. As shown in the full version, this means that

$$N \leq H^{\omega^{d-1} \cdot qd}(n_0) \leq H^{\omega^{d-1} \cdot qd}(n) \leq H^{\omega^d}(n) \quad (26)$$

by monotonicity of the Hardy functions.

Note that there are at most $q(N+1)^d$ different configurations in $Q \times \mathbb{N}^c$ of norm bounded by N , i.e., $|(Q \times \mathbb{N}^c)_{\leq N}| \leq q(N+1)^d$. By (9), this is also a bound on the strong length function $L_{H, Q \times \mathbb{N}^c}^s(n_0)$. Thus the number of steps in the backward coverability algorithm is bounded by $q(N+1)^d$, and each step can be carried in time $O(N)$, hence the algorithm works in deterministic time $O(q(N+1)^{d+1}) = O(f(N)) = O(f(H^{\omega^d}(n)))$ for some elementary function $f \in \mathcal{F}_{<3}$. By [38, Cor. A.9], there exists an elementary inflationary function $p \in \mathcal{F}_{<3}$ such that $f(H^{\omega^d}(n)) \leq H^{\omega^d}(p(n))$: the backward coverability algorithm therefore works in deterministic time $O(H^{\omega^d}(p(n)))$ for some $p \in \mathcal{F}_{<3}$, which is an expression of the form (25).

Therefore, LCM Reachability is in \mathcal{F}_d when d is fixed, and in \mathcal{F}_ω otherwise because $p(n) \geq n \geq d - 1$ and thus $H^{\omega^d}(p(n)) \leq H^{\omega^\omega}(p(n))$. ◀

7 Concluding Remarks

We have shown the \mathcal{F}_d -completeness of reachability in lossy counter machines with a fixed number $d \geq 3$ of counters. The key novelty is that we analyse the length of controlled antichains over \mathbb{N}^d rather than that of controlled bad sequences. A possible explanation why this leads to improved upper bounds is that the *ordinal width* of \mathbb{N}^d , i.e., the ordinal rank of its antichains, is conjectured to be ω^{d-1} [13], while its *maximal order type*, i.e., the ordinal rank of its bad sequences, is well-known to be ω^d [9].

Our approach might be employed to tackle related parameterised complexity gaps, like the one between $F_{\omega^{m-2}}$ -hardness [25] and $F_{\omega^{m-1}+1}$ membership [40] of reachability in *lossy channel systems* with $m \geq 4$ channel symbols and a single channel. Those results rely however on the set of finite words over an alphabet of size m being a wqo for Higman’s scattered subword ordering [21], for which the ordinal width and maximal order type coincide at $\omega^{\omega^{m-1}}$ [13, 9].

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