

The Complexity Landscape of Fixed-Parameter Directed Steiner Network Problems

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Abstract

Given a directed graph G and a list $(s_1, t_1), \dots, (s_k, t_k)$ of terminal pairs, the DIRECTED STEINER NETWORK problem asks for a minimum-cost subgraph of G that contains a directed $s_i \rightarrow t_i$ path for every $1 \leq i \leq k$. Feldman and Ruhl presented an $n^{O(k)}$ time algorithm for the problem, which shows that it is polynomial-time solvable for every fixed number k of demands. There are special cases of the problem that can be solved much more efficiently: for example, the special case DIRECTED STEINER TREE (when we ask for paths from a root r to terminals t_1, \dots, t_k) is known to be fixed-parameter tractable parameterized by the number of terminals, that is, algorithms with running time of the form $f(k) \cdot n^{O(1)}$ exist for the problem. On the other hand, the special case STRONGLY CONNECTED STEINER SUBGRAPH (when we ask for a path from every t_i to every other t_j) is known to be W[1]-hard parameterized by the number of terminals, hence it is unlikely to be fixed-parameter tractable. In the talk, we survey results on parameterized algorithms for special cases of DIRECTED STEINER NETWORK, including a recent complete classification result (joint work with Andreas Feldmann) that systematically explores the complexity landscape of directed Steiner problems to fully understand which special cases are FPT or W[1]-hard.

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