

Reconstruction of Weakly Simple Polygons from their Edges*

Hugo A. Akitaya¹ and Csaba D. Tóth²

1 Tufts University, Medford, MA, USA

hugo.alves_akitaya@tufts.edu

2 Tufts University, Medford, MA, USA, and

California State University Northridge, Los Angeles, CA, USA

cdtoth@acm.org

Abstract

Given n line segments in the plane, do they form the edge set of a *weakly simple polygon*; that is, can the segment endpoints be perturbed by at most ε , for any $\varepsilon > 0$, to obtain a simple polygon? While the analogous question for *simple polygons* can easily be answered in $O(n \log n)$ time, we show that it is NP-complete for weakly simple polygons. We give $O(n)$ -time algorithms in two special cases: when all segments are collinear, or the segment endpoints are in general position. These results extend to the variant in which the segments are *directed*, and the counterclockwise traversal of a polygon should follow the orientation.

We study related problems for the case that the union of the n input segments is connected.

(i) If each segment can be subdivided into several segments, find the minimum number of subdivision points to form a weakly simple polygon. (ii) If new line segments can be added, find the minimum total length of new segments that creates a weakly simple polygon. We give worst-case upper and lower bounds for both problems.

1998 ACM Subject Classification F.2.2 Nonnumerical Algorithms and Problems, Geometrical problems and computations

Keywords and phrases simple polygon, line segment, geometric graph

Digital Object Identifier 10.4230/LIPIcs.ISAAC.2016.10

1 Introduction

In the design and analysis of geometric algorithms, the input is often assumed to be in general position. This is justified from the theoretical point of view: degenerate cases can typically be handled without increasing the computational complexity, or symbolic perturbation schemes can reduce any input to one in general position [4]. In this paper, we present a geometric problem about simple polygons in the plane, which has a straightforward solution if the input is in general position, but is NP-complete otherwise.

Suppose we are given n line segments in the plane. It is easy to decide in $O(n \log n)$ time whether they form a simple polygon by detecting intersections in a line sweep: if the segments are disjoint apart from common endpoints, then they form a plane graph, and a simple traversal can determine whether the graph is a cycle. If the input segments overlap, more than two segments have a common endpoint, or some segment endpoints lie in the interior of another segment, then they definitely do not form a simple polygon, but they

* Research on this paper was partially supported by NSF awards CCF-1422311 and CCF-1423615. The first author was supported by the Science Without Borders program.



might still be perturbed into a simple polygon (i.e., they form a weakly simple polygon). We study the decision problem for weakly simple polygons in this paper.

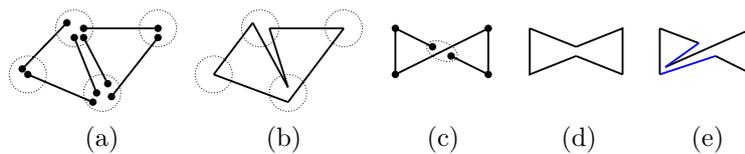
Organization and Results. We start with necessary definitions, and formulate the problem of reconstructing a weakly simple polygons from a set of edges (Section 2). We present polynomial-time algorithms when the given segments form a geometric graph or are collinear (Sections 3). The problem in general, however, is strongly NP-hard by a reduction from PLANAR-MONOTONE-3SAT (Section 4). Nevertheless, every set of noncrossing line segments in the plane can be turned into the edge set of a weakly simple polygon by (i) subdividing the edges into several edges, or (ii) inserting new edges. In Sections 5 we show that if $G = (V, E)$ is Eulerian, the edges can be subdivided $O(n)$ times to obtain a weakly simple Euler tour. We also show that inserting new edges of total length at most $3\|E\|$ is always sufficient and sometimes necessary to create a weakly simple Euler tour. We conclude with future directions (Section 6). Omitted proofs are available in the full paper [2].

Related Work. Reconstruction of simple polygons from partial information (such as vertices, visibility graphs, visibility angles, cross sections) has been studied for decades [3, 6, 11, 12, 16]. For example, an orthogonal simple polygon can be uniquely reconstruction from its vertices [16], but if the edges have 3 or more directions, the problem becomes NP-hard [12]. For a simple polygon, the set of all edges (studied in this paper) gives complete information: the cyclic order of the edges is easy to recover. In contrast, a set of edges may correspond to exponentially many weakly simple polygons, and the reconstruction problem becomes nontrivial. The problems considered in Section 5 are closely related to geometric graph augmentation and subgraph problems: (i) Can a given plane straight-line graph be augmented with new edges into a simple polygon, a Hamiltonian plane graph, or a 2-connected plane graph [14, 17, 18, 19]? (ii) Does a given a geometric graph contain certain noncrossing subgraphs (e.g., spanning trees or perfect matchings) [15]?

2 Preliminaries

A *polygon* $P = (p_0, \dots, p_{n-1})$ is a cyclic sequence of points in the plane (*vertices*), where every two consecutive vertices are connected by a line segment (*edge*). The cycle of edges can be parameterized by a piecewise linear curve $\gamma : \mathbb{S}^1 \rightarrow \mathbb{R}^2$. Polygon P is *simple* if γ is a *Jordan curve* (i.e., γ is injective); equivalently, if (p_0, \dots, p_{n-1}) is the plane embedding of a Hamiltonian cycle. Polygon P is *weakly simple* if, for every $\varepsilon > 0$, the vertices p_i can be perturbed to points p'_i , $\|p_i p'_i\| < \varepsilon$, such that $P' = (p'_0, \dots, p'_{n-1})$ is a simple polygon. The function $\|\cdot\|$ denotes the Euclidean length of a line segment. Equivalently, a polygon given by γ is weakly simple if it can be perturbed to a Jordan curve $\gamma' : \mathbb{S}^1 \rightarrow \mathbb{R}^2$ such that the Fréchet distance of the two curves is bounded by ε (i.e., $\text{dist}_F(\gamma, \gamma') < \varepsilon$) [7]. We can test whether a polygon $P = (p_0, \dots, p_{n-1})$, is simple or weakly simple, respectively, in $O(n)$ time [8] and $O(n \log n)$ time [1].

We define the WEAKLYSIMPLEPOLYGONRECONSTRUCTION (WSPR) problem as the following decision problem: Given a multiset E of line segments in \mathbb{R}^2 , does there exist a weakly simple polygon P whose edge multiset is E ? For a multiset E of *directed* segments, we also define DIRECTED-WSPR that asks whether there exists a weakly simple polygon $P = (p_0, \dots, p_{n-1})$ such that $\{p_i p_{i+1 \bmod n} : 0 \leq i \leq n-1\} = E$. In both undirected and directed variants, we represent the input segments as a straight-line multigraph $G = (V, E)$,



■ **Figure 1** (a) A multi-set of line segments. Circles indicate common segment endpoints. (b) A weakly simple Euler tour. (c) An Eulerian graph that has no weakly simple Euler tour. An edge subdivision (d) or the insertion of two edges (e), yields a weakly simple Euler tour.

where V is the set of all segment endpoints. Note that G may have overlapping edges, and an edge may pass through vertices, so it need not be a *geometric graph*.

Two Necessary Conditions. Two line segments *cross* if they share exactly one interior point. If the multiset of segments E forms a weakly simple polygon, then no two segment cross. This condition can be easily tested in $O(|E| \log |E|)$ time by a line sweep.

If there is a weakly simple polygon $P = (p_0, \dots, p_{n-1})$ with edge set E , then P is an Euler tour of the graph $G = (V, E)$. (However, an Euler tour need not be weakly simple; see Fig. 1(b)). A graph is Eulerian if and only if it is connected and every vertex has even degree. A *simple* (undirected) plane graph G is Eulerian if and only if its dual graph is bipartite. This result extends to plane *multigraphs* when an edge of multiplicity k is embedded as k interior-disjoint Jordan arcs, that enclose $k - 1$ faces. A directed graph is Eulerian if and only if all vertices are part of the same strongly connected component and if, for each vertex, the in-degree equals the out-degree.

3 Special Cases

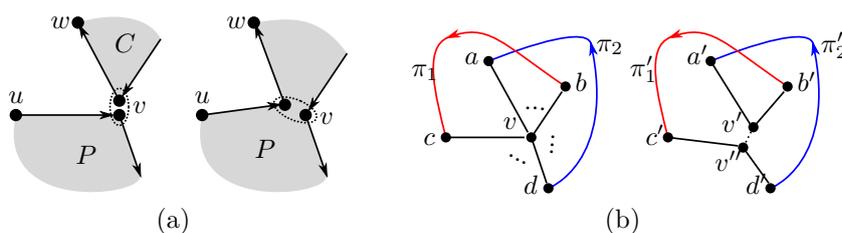
We show that both WSPR and Directed-WSPR admit polynomial-time algorithms in the special cases that (i) $G = (V, E)$ is a *simple geometric graph*, that is, no two edges overlap, and no vertex lies in the interior of an edge, and (ii) all edges in $G = (V, E)$ are collinear. We assume that G satisfies both necessary conditions.

3.1 Geometric Graphs

Note that in an Eulerian geometric graph the boundary of each face is a weakly simple circuit, where repeated vertices are possible, but there are no repeated edges. The following is a modified version of Hierholzer's algorithm [13]. It computes a weakly simple Euler tour P in the Eulerian graph G , or reports that no such tour exists.

Algorithm A (G)

1. 2-color the faces of G white and gray so that the outer face is white; and create a list L of circuits on the boundaries of the gray faces.
2. If G is directed and the edges around a gray face do not form a directed circuit or if there exist both clockwise (cw) and counterclockwise (ccw) circuits in L , report that G has no weakly simple Euler tour.
3. Choose an arbitrary circuit in L , remove it from L and call it P .
4. While there is a circuit in L , do:
 - 4.1 Find two consecutive edges, (u, v) and (v, w) , along a white face such that $(u, v) \in P$ and $(v, w) \in C$ for some $C \in L$.



■ **Figure 2** (a) Merging two cycles. The vertices circled by the dotted ellipse correspond to the same vertex v . (b) If v has two consecutive incoming edges (a, v) and (c, v) , G does not admit a weakly simple Euler tour.

4.2 Remove C from the list L , and merge C and P by traversing C starting with the edge (v, w) followed by the traversal of P that ends with the edge (u, v) ; see Figure 2(a).

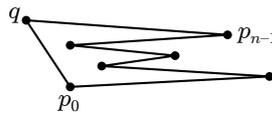
5. Return P .

► **Theorem 1.** *A simple geometric graph $G = (V, E)$ admits a weakly simple Euler tour if and only if G is Eulerian and, if G is directed, the circular order of edges around each vertex alternates between incoming and outgoing. A weakly simple Euler tour, if exists, can be computed in $O(|E|)$ time.*

Proof. If $G = (V, E)$ is undirected, the algorithm construct an Euler tour P [13]; and the tour is weakly simple by construction. In the remainder of the proof, we consider a directed Eulerian geometric graph G . First, we show that if G satisfies the conditions of Theorem 1, then Algorithm A returns a weakly simple Euler tour. If the circular order of edges around each vertex alternates between incoming and outgoing, then all edges on the boundary of a face of G have the same orientation (ccw or cw), and adjacent faces have opposite orientations. Without loss of generality, the edges on the boundaries of white (resp., gray) faces are oriented ccw (resp., cw). Hence, the condition in step 2 of the algorithm is satisfied.

We show that the Euler tour P constructed by Algorithm A is weakly simple, that is, it can be perturbed into a simple polygon. Initially, each circuit $C = (p_0, \dots, p_{k-1})$ in L is the boundary of a gray face, and hence it is a simple polygon. Let $C' = (p'_0, \dots, p'_{k-1})$ be perturbation obtained by moving each point p_i to the interior of the face along an angle bisector of $\angle p_{i-1}p_i p_{i+1}$. Initially P is a weakly simple polygon (one of the circuits). It is enough to show that Step 4.2 maintains a weakly simple polygon, that is, when we merge P and a circuit C , their Jordan curve perturbations P' and C' can also be combined. Edges (u, v) and (v, w) are adjacent to a common white face f_0 ; they correspond to an edge (p_u, p_v) in P' and (q_v, q_w) in C' , where both p_v and q_v lie in the ε -neighborhood of v in two different gray faces adjacent to f_0 . We can modify P' and C' in the ε -neighborhood of v , by removing a short Jordan arc from each and reconnecting them across the white face f_0 into a single Jordan curve. By induction, we can obtain a Jordan curve within ε Fréchet distance from the output polygon P . Hence, the algorithm returns a weakly simple Euler tour P .

Now, we show that if G has a vertex v with two consecutive incoming (resp., outgoing) edges (a, v) and (c, v) , then G does not admit a weakly simple Euler tour. Suppose, for contradiction, that there exists a weakly simple Euler tour P . Since both (a, v) and (c, v) are directed into v , the tour P contains edge-disjoint paths (a, v, b) and (c, v, d) . Since P is weakly simple, the circular order of these four edges incident to v must be as shown in Figure 2(b). The polygon must contain edge-disjoint paths $\pi_1 = (v, b, \dots, c, v)$ and $\pi_2 = (d, \dots, a)$. The perturbation of π_1 is $\pi'_1 = (v', b', \dots, c', v'')$ where $v' \neq v''$. Note that a and d are on opposite



■ **Figure 3** Every collinear Eulerian tour can be transformed in a y -monotonic simple polygon.

sides of the cycle $\pi' \cup v'v''$. The perturbation of π_2 , path π'_2 , can intersect neither π'_1 nor $v'v''$, because (a, v) and (c, v) are adjacent to the same face. Hence P is not weakly simple.

Finally, Algorithm A runs in $O(|E|)$ time. Step 1 and 2 can be done by traversing the dual graph of G . Step 4 executes $O(|E|)$ merges, each of which takes constant time. ◀

► **Corollary 2.** *A geometric multigraph $G = (V, E)$ admits a weakly simple Euler tour if and only if G is Eulerian. A weakly simple Euler tour, if exists, can be computed in $O(|E|)$ time.*

Proof. Replace every edge e of multiplicity k by k edge-disjoint paths of length two whose interior points are close to the midpoint of e . We obtain a simple Eulerian geometric graph with $|V| + 2|E|$ vertices. Theorem 1 completes the proof. ◀

► **Remark.** In the case that $G = (V, E)$ is a directed multigraph, replace every directed edge (u, v) of multiplicity k by edge-disjoint paths (u, w_i, v) , with new (subdivision) vertices w_i , $i = 1, \dots, k$, and denote by G' the resulting simple directed graph. The alternating direction condition of Theorem 1 requires that the multiplicity of (u, v) and (v, u) differ by at most one. If their multiplicities differ by exactly one, then there is a unique way to interleave the replacement paths between u and v . In fact, if any edge of G has odd multiplicity, the alternating direction condition determines the cyclic order of all paths (u, w_i, v) , and we can apply Theorem 1 for G' . If, however, all edges of G have even multiplicity, then there are two possibilities for the cyclic orders, both of which yield weakly simple Euler tours by Theorem 1.

3.2 Collinear Line Segments

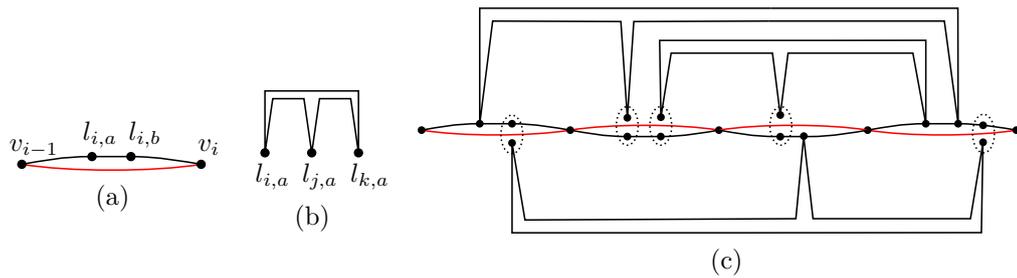
► **Theorem 3.** *If all edges of a graph $G = (V, E)$ are collinear, then every Euler tour of G is a weakly simple polygon.*

Proof. Without loss of generality, assume that all vertices are on the x -axis. Let $\varepsilon > 0$ be given. Let $P = (p_0, \dots, p_{n-1})$ be an Euler tour of G , and let p_0 be a leftmost vertex. For each vertex p_i , $i \in \{0, \dots, n-1\}$, create a point p'_i with $x(p'_i) = x(p_i)$ and $y(p'_i) = i\varepsilon/(2n)$. The polygonal path (p'_0, \dots, p'_{n-1}) is strictly y -monotonic and therefore does not cross itself. The edge (p'_{n-1}, p'_0) can be realized as a one-bend polyline (p'_{n-1}, q, p'_0) with $q = (-\varepsilon/2, \varepsilon/2)$, which is outside of the axis-aligned bounding box of all other edges. Therefore $P' = (p'_0, \dots, p'_{n-1})$, illustrated in Figure 3, is a simple polygon where $\text{dist}_F(P, P') < \varepsilon$. ◀

4 NP-Completeness

In this section we analyze the general case of WSPR. First we discuss the undirected case and then the directed version.

► **Lemma 4.** *Both WSPR and Directed-WSCR are in NP.*



■ **Figure 4** (a) Variable gadget, (b) clause gadget and (c) the reduction from PLANAR-MONOTONE-3SAT to undirected WSPR.

Proof. Given a polygon $P = (p_0, \dots, p_{n-1})$ and a (directed) straight-line multigraph $G = (V, E)$, we can check whether P is a (directed) Euler tour in G in $O(|E|)$ time, and whether P is weakly simple in $O(n \log n)$ time [1]. ◀

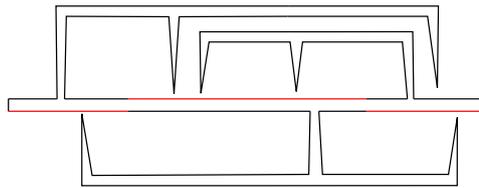
We prove that both directed and undirected WSPC are strongly NP-hard in the general case by a reduction from PLANAR-MONOTONE-3SAT, which is strongly NP-hard [5]. An instance of PLANAR-MONOTONE-3SAT consists of a plane bipartite graph G_B whose partite sets are variables nodes and clauses nodes. The variable nodes are on the x -axis, the clause nodes are above or below the x -axis; each clause is adjacent to three variables. A clause is *positive* if it lies above the x -axis, and *negative* otherwise. PLANAR-MONOTONE-3SAT asks if there is a binary assignment from $\{\text{true}, \text{false}\}$ to the set of variables such that every positive clause is adjacent to at least one **true** variable and every negative clause is adjacent to at least one **false** variable.

► **Lemma 5.** *Undirected WSPR is NP-hard.*

Proof. Given an instance of PLANAR-MONOTONE-3SAT, we build an instance of undirected WSPR as shown in Figure 4(c). We split the construction into two basic gadgets. A variable and a clause gadget are shown in Figure 4(a) and (b), respectively. The figure shows collinear edges distorted and colored for clarity. All vertices shown as small black disks are on the x -axis and vertices circled with a dotted ellipse represent the same graph vertex.

First, place vertices v_0, \dots, v_n equally spaced on the variable line from left to right. The variable gadget corresponding to the i th variable consists of two collinear paths between v_{i-1} and v_i , which are called *red* and *black* paths; see Figure 4. The red path is a single edge $v_{i-1}v_i$; and the black path is made of $p + 1$ edges where p is the degree of the i -th variable in the bipartite graph G_B . We assign a vertex in the interior of this path to each edge connected to the variable, naming the vertex $l_{i,a}$ for the edge connecting the i -th variable to the a -th clause. We call such vertices *literal* vertices. The clause gadget is composed of 9 edges arranged in a cycle as shown in Figure 4(b). The three labeled vertices correspond to the literal vertices in the clause gadgets. The planar embedding of the PLANAR-MONOTONE-3SAT instance guarantees that we can embed the graph of the directed WSPR instance.

Assume that the PLANAR-MONOTONE-3SAT instance have a satisfying assignment. We build a weakly simple Euler tour P as follows. Each individual gadget defines a cycle. As in Algorithm A, we will merge the cycles into the polygon P . Every cycle will be traversed clockwise, however, cycles defined by variable gadgets are collinear and there is no clear definition of winding direction for them. We perturb the red edges based on the truth values of the variables. For each variable assigned **true** (resp., **false**), we perturb the red edge to pass below (resp., above) the x -axis. All variable cycles can be safely merged into a single



■ **Figure 5** Simple polygon that certifies that an Euler tour of P is weakly simple.

circuit. We merge each clause to the variable cycle through a literal vertex of a **true** variable if the clause is positive or through a literal vertex of a **false** variable otherwise.

To show that P is weakly simple, we build a simple polygon P' within ε Fréchet distance from P as follows (see Figure 5). For each v_i create two vertices v_i^+ and v_i^- located $\varepsilon/2$ above and below v_i respectively. If the solution assigns the i -th variable **true**, move vertices $l_{i,a}$ up by $\varepsilon/2$, replace vertices v_{i-1} and v_i by v_{i-1}^+ and v_i^+ in the black edges (of the corresponding gadget) and by v_{i-1}^- and v_i^- in the red edges. Connect vertices v_0^+ and v_0^- with an edge. Do the same for v_n^+ and v_n^- . If the variable is assigned **false**, do analogous replacements symmetrically about the x -axis. For each clause gadget, choose a literal $l_{i,a}$ with a **true** value, split $l_{i,a}$ into two vertices, $l'_{i,a}$ and $l''_{i,a}$, with the same y -coordinate and ε distance apart, such that they each are incident to one edge of the variable gadget and one edge of the clause gadget. For the other two literals, split $l_{i,a}$ into two vertices, $l^+_{i,a}$ and $l^-_{i,a}$, with the same x -coordinate and $\frac{\varepsilon}{2}$ distance apart, such that the one closer to the x -axis is incident to two edges of the variable gadget, and the other to two edges of the clause gadget. The result is a simple polygon and therefore undirected WSPR have a positive solution.

Now assume that the graph produced by the reduction admits a weakly simple Euler tour P . Then, there exist a simple polygon P' within an arbitrarily small Fréchet distance from P . Such a polygon determines a vertical order between the paths of each variable gadget. Since every literal vertex has degree 4, there are only two possible ways to match its incident edges in a noncrossing manner: matching two horizontal edges and two clause edges, or a horizontal with a clause edge. In both cases, the two horizontal black edges incident to a literal vertex are placed above or below the red path. Therefore, all edges of the black path of a variable gadget are on the same side of its red path. For each variable, assign **true** if the black path of its gadget is above the red path and **false** otherwise. Since each clause gadget needs to be connected to some edge in a variable gadget, if the clause is positive/negative, one of its corresponding variables were assigned **true/false**. Hence, the assignment satisfies all clauses and the PLANAR-MONOTONE-3SAT instance have a positive solution. ◀

► **Lemma 6.** *Directed-WSPR is NP-hard.*

As a consequence of Lemmas 4, 5, and 6, we have the following result.

► **Theorem 7.** *Both WSPR and Directed-WSPR are NP-complete.*

► **Remark.** Our reduction can be modified by perturbing the points in our variable gadgets so that: (i) points belonging to the same gadget are collinear; (ii) no three points, each belonging to a different gadget are collinear; and (iii) no edge crossing is introduced. By reducing from PLANAR-MONOTONE-(2,3)-SAT-3 [10], in which clauses may have two or three literals and each variable can appear only in up to three clauses, we can show that WSPR remain NP-hard even if the number of mutually collinear points is constant.

5 Related problems

Since WSPR is NP-complete in the general case, we study related problems in which a weakly simple polygon is always achievable by allowing edge subdivision and insertion of new edges.

5.1 Edge subdivision

Given a noncrossing graph $G = (V, E)$ where every vertex has even degree and the point set $\bigcup E$ is connected, we define the problem WSPR* as finding a sequence of edge subdivision operations that produces a graph $G^* = (V, E^*)$ that admits a weakly simple Euler tour. The *subdivision* of an edge uv at a vertex $w \in \text{relint}(uv)$ replaces uv by two edges uw and wv .

It is easy to see that WSPR* is always feasible with $O(n^2)$ subdivisions where $n = |V|$. Indeed, subdivide every edge uv recursively at each vertex that lies in the interior of uv . We obtain a connected geometric multigraph with even degrees, which admits a weakly simple Euler tour by Corollary 2. The main result of this section is the following.

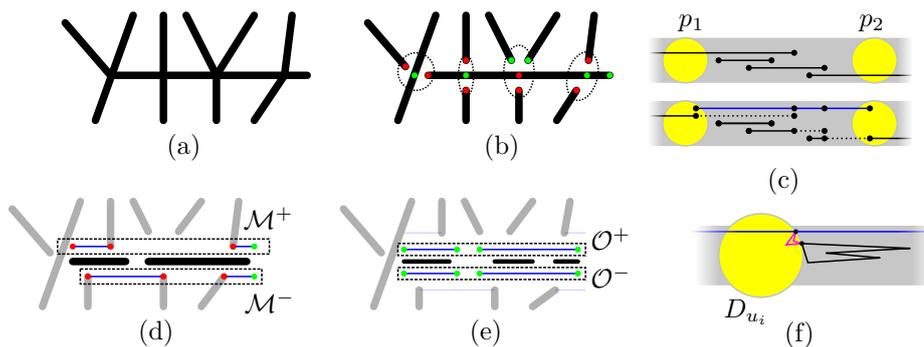
► **Theorem 8.** *Every noncrossing graph $G = (V, E)$ such that every $v \in V$ has even degree and $\bigcup E$ is connected, can be transformed into a graph $G^* = (V, E^*)$ using $O(|E|)$ edge subdivisions, and this bound cannot be improved.*

Before the proof, we introduce some notation (from [1, 7, 9]). Let $G = (V, E)$ be a noncrossing graph. The transitive closure of the *overlap* relation is an equivalence relation on E . The union of all edges in an equivalence class is called a *bar*, it is a line segment. A vertex $v \in b$ is called *b-odd* if v is incident to an odd number of edges contained in b , or *b-even* otherwise. A vertex can be *b-odd* and *b'-even* for different bars b and b' (see Figure 6(b)).

Our algorithm will compute simple paths formed by subdivided edges. Let b be a horizontal bar with vertices $p_1, p_2 \in b$, $x(p_1) \leq x(p_2)$. Let $q_1q_2 \in E$ be an edge that contains p_1 and its right endpoint has minimum x -coordinate. A *subdivided paths*, denoted by $\widehat{p_1p_2}$, is a path between p_1 and p_2 , defined recursively (see Fig. 6(d)): (i) if $x(p_1) = x(p_2)$, $\widehat{p_1p_2} = \emptyset$; (ii) if $p_2 \in q_1q_2$, then subdivide q_1q_2 into three edges $e_1 = q_1p_1$, $e_2 = p_1p_2$, and $e_3 = p_2q_2$ and put $\widehat{p_1p_2} = (e_2)$; (iii) if $p_2 \notin q_1q_2$, then subdivide q_1q_2 into two edges $e_1 = q_1p_1$ and $e_2 = p_1q_2$, and put $\widehat{p_1p_2} = (e_2) \oplus \widehat{q_2p_2}$, where \oplus denotes concatenation. Consequently, if the segment p_1p_2 contains k vertices, a path $\widehat{p_1p_2}$ can be constructed using at most k edge subdivisions. An example is shown in Figure 6(c).

Proof of Theorem 8. The proof of the upper bound is constructive. The algorithm subdivides edges within each bar independently. Let b be a bar containing m vertices. We apply $O(m)$ edge subdivisions and partition the edges in b into subsets: Subsets \mathcal{M}^+ and \mathcal{M}^- will consist of subdivision paths between the intersection points of b with other bars lying above and below b , respectively; all remaining edges will be partitioned into tours (each of which is a weakly simple polygon by Theorem 3). The algorithm is divided into three phases: Phase 1 creates \mathcal{M}^+ and \mathcal{M}^- ; phase 2 forms circuits; and phase 3 establishes common vertices between the subdivision paths and circuits. Refer to Figure 6.

Phase 1. Compute a list B^+ (resp., B^-) of points p in the interior of b such that p is b' -odd for some bar b' that is above or collinear to b (resp., below b). A point can appear more than once in each list if it is odd in multiple bars b' . Sort the lists by $x(p)$, ties are broken by clockwise (resp., counterclockwise) order of the corresponding bars b' . If the left (resp., right) endpoint of b is b -odd, add it to the beginning (resp., end) of the list B^+ . If any of the lists have odd cardinality, append the right endpoint of b at the end of the list. Create a



■ **Figure 6** (a) A bar b and its adjacent bars. (b) Each bar b' is shown with its b' -odd and b' -even vertices shown in red and green respectively. (c) The subdivided path $\widehat{p_1 p_2}$ is shown in blue. Examples of (d) \mathcal{M}^+ and \mathcal{M}^- ; (e) \mathcal{O}^+ and \mathcal{O}^- . (f) Connecting a component of \mathcal{B}' to a path in \mathcal{O}^+ with two polygonal paths shown in magenta.

perfect matching of consecutive endpoints in each list. Construct edge disjoint subdivided paths between each pair of matched points, and let \mathcal{M}^+ and \mathcal{M}^- denote the set of edges in such paths for B^+ and B^- , respectively (see Figure 6(d)).

Phase 2. Let \mathcal{B} be the set of (subdivided) edges that lie on b and are not in $\mathcal{M}^+ \cup \mathcal{M}^-$. The union of edges in \mathcal{B} may be a disconnected point set (e.g., as shown in Figure 6(d)). Let the line segment $r_1 r_2$ be one of the connected components of $\bigcup \mathcal{B}$. Construct two edge disjoint subdivided paths $\widehat{r_1 r_2}^+$ and $\widehat{r_1 r_2}^-$ from the edges in \mathcal{B} . For every path $\widehat{p_1 p_2}$ in \mathcal{M}^+ (resp., \mathcal{M}^-) that overlaps with $r_1 r_2$, identify an edge of $\widehat{r_1 r_2}^+$ (resp., $\widehat{r_1 r_2}^-$) that contains a vertex of $\widehat{p_1 p_2}$ and subdivide it at such vertex (see Figure 6(e)). Let \mathcal{O}^+ (resp., \mathcal{O}^-) be the set of edges in $\widehat{r_1 r_2}^+$ (resp., $\widehat{r_1 r_2}^-$) for all components $r_1 r_2$ of the union of edges in \mathcal{B} .

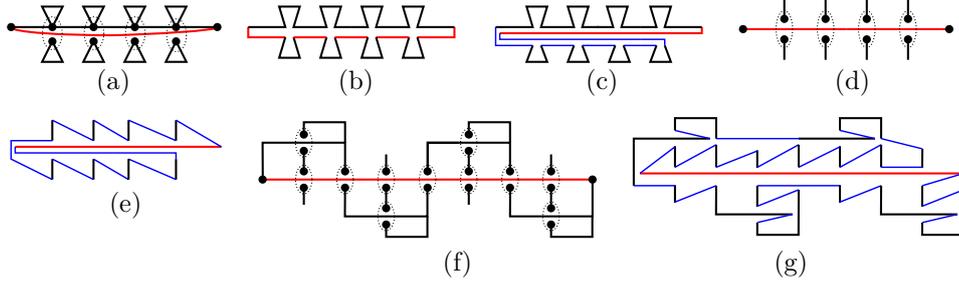
Phase 3. Let \mathcal{B}' be the set of edges in $\mathcal{B} \setminus (\mathcal{O}^+ \cup \mathcal{O}^-)$. For every component C of the subgraph induced by \mathcal{B}' , let p_0 be the leftmost vertex of C , identify the edge in \mathcal{O}^+ that contains p_0 and subdivide it at p_0 . This concludes the construction of G^* .

Correctness. Now we prove that G^* admits a weakly simple Euler tour. Notice that G^* is connected since the subdivisions in phase 2 connects every component of \mathcal{M}^+ or \mathcal{M}^- to every overlapping component of \mathcal{O}^+ or \mathcal{O}^- , and phase 3 connects every component of \mathcal{B}' to some component in \mathcal{O}^+ . Since edge subdivisions do not change the parity of degrees, every vertex in G^* has even degree, hence G^* is Eulerian. We construct an Eulerian geometric graph G' such that every Euler tour in G' is within $\varepsilon/2$ Fréchet distance from an Euler tour in G^* . Theorem 1 will then imply that there exists a simple polygon within ε Fréchet distance from an Euler tour in G^* .

We recall some notation introduced in [7]. For every vertex $v \in V$, let D_v be a disk centered at v of radius $\frac{\varepsilon}{4}$. For a bar b between u_0 and u_k , let D_b be the ε^2 neighborhood of b setminus $D_{u_0} \cup D_{u_k}$. Assume that $\varepsilon \in (0, \frac{1}{4})$ is so small that the disks D_v are pairwise disjoint; a disk D_v intersects D_b only if $v \in b$, and the neighborhoods D_b are pairwise disjoint.

For each bar b with vertices u_0, \dots, u_k , we perturb the edges of E^* contained in b into noncrossing simple polygons and polygonal chains. Embed each subdivided path in \mathcal{M}^+ (resp., \mathcal{M}^-) $\widehat{u_i u_j}$ in the upper (resp., lower) boundary of the region D_b such that u_i is on the boundary of D_{u_i} and u_j is on the boundary of D_{u_j} . Subdivide D_b with $\ell + 1$ horizontal

10:10 Reconstruction of Weakly Simple Polygons from their Edges



■ **Figure 7** Lower bound constructions.

lines where ℓ is the number of components of the subgraph induced by \mathcal{B}' . Embed all edges in \mathcal{O}^+ (resp., \mathcal{O}^-) in the first (resp., $\ell + 1$ -th) such line.

Recall that every vertex of G has even degree. If b contains a b -odd vertex p , there must exist a bar b' such that p is b' -odd. Because \mathcal{M}^+ and \mathcal{M}^- matches such points, the subgraph induced by \mathcal{B} contain only even degree vertices. By construction the edges in $\mathcal{O}^+ \cup \mathcal{O}^-$ form nonoverlapping disjoint circuits. Hence, the subgraph induced by \mathcal{B}' contains only even degree vertices. Consequently, each of its components is Eulerian and forms a weakly simple polygons that we denote by $\gamma_1(b), \dots, \gamma_\ell(b)$, sorted by the x -coordinates of their left endpoints. Perturb $\gamma_1(b), \dots, \gamma_\ell(b)$ into simple polygons that lie in the interior of D_b , separated by one of the $\ell + 1$ lines, in this linear order (ties are broken arbitrarily). For $i = 0, \dots, k$, consider all polygons $\gamma_j(b)$ whose leftmost vertex is u_i . Connect the left endpoints of each such $\gamma_j(b)$ to the copy of u_i in \mathcal{O}^+ by two polygonal paths within D_{u_i} (these paths connect different copies of vertex $u_i \in V^*$, see Figure 6(f)). Similarly, for each subdivision performed in phase 2 at u_i of an edge in \mathcal{O}^+ (resp., \mathcal{O}^-) in a path $\widehat{r_1 r_2}$, connect the copy of u_i in this path to a copy in \mathcal{M}^+ (resp., \mathcal{O}^-) by two polygonal paths within the disk D_{u_i} . Connect the endpoints of the overlapping paths in \mathcal{O}^+ and \mathcal{O}^- (forming a cycle of each), and if the right endpoint of b is not b -odd and was added to B^+, B^- , connect the copies of u_k in \mathcal{M}^+ and \mathcal{M}^- . For each matching in B^+ and B^- involving a point u_i that is a b' -odd endpoint of a bar b' , connect the paths in \mathcal{M}^+ or \mathcal{M}^- that correspond to a match in b to the path in \mathcal{M}^+ of b' that contains p . Finally, for each point u_i that is the endpoint of a bar b' and is b' -even, connect the corresponding copies of u_i , making the graph induced by all edges containing a point on b connected. This concludes the construction of G' .

Theorem 1 completes the proof: An Euler tour \widehat{P} of G' can be perturbed into a simple polygon P such that $\text{dist}_F(P, \widehat{P}) < \frac{\varepsilon}{2}$. The tour \widehat{P} maps to an Euler tour P^* of G^* by identifying the vertices that lie in the same disk D_v , $v \in V^*$; and $\text{dist}_F(\widehat{P}, P^*) < \frac{\varepsilon}{2}$.

Our lower bound construction is shown in Figure 7(a). It consists of a graph $G = (V, E)$ containing a long edge e_R (shown in red) and a path of $(|E| + 5)/7$ non-overlapping collinear edges that connects the endpoints of e_R . Each vertex in the interior of e_R is also incident to two small cycles above and below e_R respectively. Although the graph is Eulerian, it does not admit a weakly simple Euler tour. Each vertex p in the interior of the red edge e_R is incident to two small triangles. Suppose that e_R is *not* subdivided at p . Then p has degree 6. In any perturbation of a weakly simple Euler tour, vertex p is split into 3 copies, each of degree 2, and each lying above or below e_R . Suppose only one copy of p lies below e_R . Then it is incident to two edges of a small triangle below e_R , which is then disconnected from the rest of the graph, a contradiction. Consequently, e_R must be subdivided at all interior vertices. Figure 7(b) shows that $O(|E|)$ subdivisions of e_R suffice in this case. ◀

5.2 Edge insertion

We define the problem WSPR^+ as finding a set of edges E^+ such that $G^+ = (V, E \cup E^+)$ admits a weakly simple Euler tour. Denote by $\|E\|$ and $\|E^+\|$, respectively, the sum of the lengths of all edges in E and E^+ . If the point set $\bigcup E$ is disconnected, then there is no upper bound on $\|E^+\|$. Otherwise, we can establish worst-case upper and lower bounds for $\|E^+\|$ in terms of $\|E\|$.

► **Theorem 9.** *Let $G = (V, E)$ be a noncrossing multigraph such that $\bigcup E$ is a connected point set. Then there exists a set of line segments E^+ such that $\|E^+\| \leq 3\|E\|$ and $G^+ = (V, E \cup E^+)$ admits a weakly simple Euler tour.*

Proof. We construct E^+ as follows. Partition E into *bars* (equivalence classes of the transitive closure of the overlap relation on E). Denote by b the union of edges in a bar. W.l.o.g., we may assume that b is horizontal. Denote by $u_0, \dots, u_k \in V$ the vertices of V along b sorted by x -coordinates (where $b = u_0u_k$). For $i = 1, \dots, k$, add an edge $u_{i-1}u_i$ to E^+ if the edges of E in the bar cover the line segment $u_{i-1}u_i$ an odd number of times. The old and new edges in the bar b jointly form a graph of even degree that we denote by $G(b)$. By Theorem 3, every component of $G(b)$ admits a weakly simple Euler tour. Finally, add two more copies of edge $u_{i-1}u_i$ to E^+ for all $i = 1, \dots, k$. After repeating the above steps for every bar, we have $\|E^+\| \leq 3\|E\|$ and $G^+ = (V, E \cup E^+)$ is Eulerian.

We omit the proof of correctness (which is provided in the full paper [2]), that shows that G^+ admits a weakly simple Euler tour, since it is similar to the proof of Theorem 8. ◀

Lower bound constructions. All our lower bound constructions are graphs $G = (V, E)$ in which an edge connects two points on the boundary of the convex hull of V , denoted $\text{ch}(V)$.

► **Theorem 10.** *Let \mathcal{G} be a family of noncrossing multigraphs. For $G = (V, E) \in \mathcal{G}$, let E^+ be an edge set of minimum length $\|E^+\|$ such that $G^+ = (V, E \cup E^+)$ admits a weakly simple Euler tour; and let $\lambda(\mathcal{G}) = \sup_{G \in \mathcal{G}} \|E^+\|/\|E\|$. Then:*

1. $\lambda(\mathcal{G}_1) \geq 1$, where $\mathcal{G}_1 = \{\text{Eulerian noncrossing multigraphs}\}$.
2. $\lambda(\mathcal{G}_2) \geq \frac{6}{5}$, where $\mathcal{G}_2 = \{\text{connected noncrossing multigraphs}\}$.
3. $\lambda(\mathcal{G}_3) \geq 3$, where $\mathcal{G}_3 = \{\text{noncrossing multigraphs } G = (V, E) \text{ such that } \bigcup E \text{ is connected}\}$.

Proof.

(1) Refer to Figs. 7(a)–(c). Let $n \in \mathbb{N}$ and $\delta \in (0, \frac{1}{3})$. Place vertices $v_i = (i, 0)$, for $i = 0, \dots, n$, on the x -axis. A red edge of length n connects v_0 and v_n . A black edge of length $1/n$ connects v_{i-1} and v_i for $1 \leq i \leq n$. A small cycle of length $\delta < \frac{1}{3}$ is placed on each v_i , $1 \leq i \leq n-1$, on each side of the x -axis. The total length of the construction is $\|E\| = 2n + 2(n-1)\delta$.

Let $G^+ = (V, E \cup E^+)$ be a multigraph in which P is a weakly simple Euler tour; and let P' be an ε -perturbation into a simple polygon, for some $0 < \varepsilon < \delta$. We define a pair of vertical lines $\ell_i^- : x = i + \delta$ and $\ell_i^+ : x = (i+1) - \delta$, for $0 \leq i \leq n-1$. The portion of P' between any two of these lines consists of disjoint paths whose endpoints are on the lines. By Morse theory, P' contains an even number of paths between any two of these lines; and the length of such a path is at least the distance between the parallel lines. The input edges already contain two line segments between any two of these lines: a red and a black segment.

We claim that G^+ contains at least 4 paths between ℓ_i^- and ℓ_i^+ for all but at most one index $0 \leq i \leq n-1$. Indeed, suppose that there are two such paths between ℓ_i^- and ℓ_i^+ and between ℓ_j^- and ℓ_j^+ ($0 \leq i < j \leq n-1$). We may assume w.l.o.g. that the black edge is above the red edge between ℓ_i^- and ℓ_i^+ . Then the black edge must be above the red edge

between ℓ_j^- and ℓ_j^+ , as well. Consequently, P' cannot reach the small cycles at v_{i+1}, \dots, v_j . This confirms the claim. It follows that $\|E \cup E^+\| \geq (4n - 2)(1 - 2\delta)$. This lower bound tends to $2\|E\|$ as $n \rightarrow \infty$ and $\delta n \rightarrow 0$.

Due to space restrictions, we omit the proofs for cases 2 and 3. ◀

6 Conclusions

We have shown that WSPR is NP-complete. It follows that the decision version of the problems in Section 5 are also NP-complete: It is NP-complete to find up to k subdivision points to form a weakly simple polygon, or to find an edge set with length up to k that produce a weakly simple polygon. We have shown that $\Theta(|E|)$ subdivision points are always sufficient and sometimes necessary when the input is Eulerian; and new edges of length $\Theta(\|E\|)$ are always sufficient and sometimes necessary when $\bigcup E$ is connected. However, the best constant coefficients are not known in most cases. We conjecture that every noncrossing Eulerian graph $G = (V, E)$ can be augmented into a graph $G^+ = (V, E \cup E^+)$ that admits a weakly simple Euler tour such that $\|E^+\| \leq \|E\|$.

If the segments in E do not form a weakly simple polygon, we can subdivide segments or insert new segments to create a weakly simple polygon. On the other end of the spectrum, a set of n line segment may form an exponential number of weakly simple polygons, even if all segments are collinear. It is an open problem to count exactly how many weakly simple polygons can be obtained from the same set of line segments. Finally, we mention an open problem about reconstructing *simple polygons* from a subset of its edges. It is NP-complete to decide whether a geometric graph $G = (V, E)$ can be augmented into a *simple* polygon $P = (V, E \cup E^+)$ [17]. However, it is not known whether the problem remains NP-hard when G is a perfect matching.

Acknowledgements. We thank Adrian Dumitrescu for bringing this problem to our attention.

References

- 1 Hugo A. Akitaya, Greg Aloupis, Jeff Erickson, and Csaba Tóth. Recognizing weakly simple polygons. In *Proc. 32nd Int. Sympos. Comput. Geom.*, volume 51 of *LIPICs*, Dagstuhl, 2016.
- 2 Hugo A. Akitaya and Csaba D. Tóth. Reconstruction of weakly simple polygons from their edges. Preprint, [arXiv](https://arxiv.org/abs/1608.07811), 2016.
- 3 Gill Barequet, Craig Gotsman, and Avishay Sidlesky. Polygon reconstruction from line cross-sections. In *Proc. 18th Canadian Conf. Comput. Geom.*, Kingston, ON, 2006.
- 4 Mark de Berg, Otfried Cheong, Marc van Kreveld, and Mark Overmars. *Computational Geometry: Algorithms and Applications*. Springer-Verlag, Berlin, 3rd edition, 2008.
- 5 Mark de Berg and Amirali Khosravi. Optimal binary space partitions in the plane. *Internat. J. Comput. Geom. Appl.*, 22(3):187–205, 2012.
- 6 Therese Biedl, Stephane Durocher, and Jack Snoeyink. Reconstructing polygons from scanner data. *Theoret. Comput. Sci.*, 412(32):4161–4172, 2011.
- 7 Hsien-Chih Chang, Jeff Erickson, and Chao Xu. Detecting weakly simple polygons. In *Proc. 26th ACM-SIAM Symposium on Discrete Algorithms*, pages 1655–1670. SIAM, 2015.
- 8 Bernard Chazelle. Triangulating a simple polygon in linear time. *Discrete Comput. Geom.*, 6(3):485–524, 1991.
- 9 Pier Francesco Cortese, Giuseppe Di Battista, Maurizio Patrignani, and Maurizio Pizzonia. On embedding a cycle in a plane graph. *Discrete Math.*, 309(7):1856–1869, 2009.

- 10 Andreas Darmann, Janosch Döcker, and Britta Dorn. On planar variants of the monotone satisfiability problem with bounded variable appearances. Preprint, [arXiv:1604.05588](https://arxiv.org/abs/1604.05588), 2016.
- 11 Yann Disser, Matúš Mihalák, and Peter Widmayer. A polygon is determined by its angles. *Comput. Geom. Theory Appl.*, 44(8):418–426, 2011.
- 12 Michael Formann and Gerhard J. Woeginger. On the reconstruction of simple polygons. *Bulletin EATCS*, 40:225–230, 1990.
- 13 Carl Hierholzer and Chr Wiener. Über die Möglichkeit, einen Linienzug ohne Wiederholung und ohne Unterbrechung zu umfahren. *Mathematische Annalen*, 6(1):30–32, 1873.
- 14 Michael Hoffmann and Csaba D Tóth. Segment endpoint visibility graphs are Hamiltonian. *Comput. Geom. Theory Appl.*, 26(1):47–68, 2003.
- 15 Klaus Jansen and Gerhard J Woeginger. The complexity of detecting crossingfree configurations in the plane. *BIT Numerical Mathematics*, 33(4):580–595, 1993.
- 16 Joseph O’Rourke. Uniqueness of orthogonal connect-the-dots. In Godfried T. Toussaint, editor, *Computational Morphology*, pages 97–104. North-Holland, 1988.
- 17 David Rappaport. Computing simple circuits from a set of line segments is NP-complete. *SIAM J. Comput.*, 18(6):1128–1139, 1989.
- 18 Csaba D Tóth. Connectivity augmentation in planar straight line graphs. *European J. Combin.*, 33(3):408–425, 2012.
- 19 Masatsugu Urabe and Mamoru Watanabe. On a counterexample to a conjecture of Mirzaian. *Comput. Geom. Theory Appl.*, 2(1):51–53, 1992.