

On Some Computations on Sparse Polynomials

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Abstract

In arithmetic circuit complexity the standard operations are $\{+, \times\}$. Yet, in some scenarios exponentiation gates are considered as well (see e.g. [6, 1, 28, 30]). In this paper we study the question of efficiently evaluating a polynomial given an oracle access to its power. Among applications, we show that:

- A reconstruction algorithm for a circuit class \mathcal{C} can be extended to handle f^e for $f \in \mathcal{C}$.
- There exists an efficient deterministic algorithm for factoring sparse multiquadratic¹ polynomials.
- There is a deterministic algorithm for testing a factorization of sparse polynomials, with constant individual degrees, into sparse irreducible factors. That is, testing if $f = g_1 \cdots g_m$ when f has constant individual degrees and g_i -s are irreducible.
- There is a deterministic reconstruction algorithm for multilinear² depth-4 circuits with two multiplication gates.
- There exists an efficient deterministic algorithm for testing whether two powers of sparse polynomials are equal. That is, $f^d \equiv g^e$ when f and g are sparse.

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1 Introduction

Let $f(\bar{x}) \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be a polynomial over the field \mathbb{F} . In this paper we study the following question: given $e \in \mathbb{N}$ and an oracle access to $f^e \in \mathbb{F}[x_1, x_2, \dots, x_n]$ can we efficiently implement an oracle access to f ? That is, we wish to evaluate f on a set of points \bar{a}, \bar{b}, \dots (which might be unknown upfront) given an oracle access to f^e . An efficient *randomized* algorithm for this problem was given in [23]. Where, in fact, a randomized polynomial factorization algorithm was given. In addition, in terms of circuit complexity, it was shown in [43, 20] that if f^e has a small circuit then so does f , when the characteristic of \mathbb{F} is zero or coprime with e .

For our applications, we only need to solve the problem in the oracle model, yet *deterministically*. Although, it is conceivable that the techniques of [43, 20] could work in oracle model, they will still be subject to the co-primality condition. In this paper we solve the problem for any e .

It is clear that as the first step, we should be able to extract e -th roots of field elements. For instance, if f is constant. We refer to such an algorithm as an e -th *root oracle* R_e . However, having root oracles is not enough for our task as demonstrated by the following example.

¹ A polynomial is multiquadratic if the degree of each variable is at most 2.

² A polynomial is multilinear if the degree of each variable is at most 1.



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Let $h(x) = 3x - 4$ and $f = h^2$. Suppose that we wish to evaluate $h(x)$ at $x = 1, 2$ given an oracle access to $f(x)$ and using a square-root oracle R_2 . As $f(1) = 1, f(2) = 4$ the oracle might return $h(1) = R_2(1) = 1$ and $h(2) = R_2(4) = 2$ (for example, returning the positive root). Note, however, that these evaluations are inconsistent with either $\pm h$! More generally, there could be e different h_1, \dots, h_e polynomials resulting in the same polynomial when raised the e -th power (i.e. $\forall i \in [e] : h_i^e = f$). Therefore, in order to prevent the aforementioned situation our algorithm should output an oracle access to exactly one of them. We prove the following theorem.

► **Theorem 1 (Technical Contribution).** *There exists a deterministic algorithm that given $e \in \mathbb{N}$, an e -th root oracle R_e and an oracle access to a polynomial $f^e \in \mathbb{F}[x_1, x_2, \dots, x_n]$ of degree at most d uses $\text{poly}(n, d, e, \log |\mathbb{F}|)$ field operations and oracle calls to R_e , and outputs an oracle access to $\omega \cdot f$, where $\omega \in \mathbb{F}$ is such that $\omega^e = 1$.*

We note that similar ideas appeared previously in the literature, although partially and implicitly. The problem can be seen as a version of list-decoding of Reed-Muller codes. Indeed, mirroring the list-decoding algorithm of [42] and the factorization algorithm of [23], the proposed algorithm uses an anchor point and draws a line to that point in order to choose the correct answer from a small list of possible answers. We now discuss related problems and applications.

1.1 Multivariate Polynomial Factorization

One of the fundamental problems in algebraic complexity is the problem of polynomial factorization: given a polynomial $f \in \mathbb{F}[x_1, x_2, \dots, x_n]$ over a field \mathbb{F} , find its irreducible factors. Other than being natural, the problem has many applications such as list decoding [41, 17] and derandomization [19]. A large amount of research has been devoted to finding efficient algorithms for this problem (see e.g. [48]) and numerous *randomized* algorithms were designed [49, 20, 21, 23, 48, 22, 47]. However, the question of whether there exist *deterministic* algorithms for this problem remains an interesting open question (see [48, 27]).

Perhaps the simplest factorization algorithm is a root oracle. We note that the best known *deterministic* root extraction algorithms over the finite fields have polynomial dependence on the field characteristic p (see e.g. [36, 48, 14, 27]). While in the *randomized* setting, this dependence is polynomial in $\log p$. In particular, there is no known efficient deterministic root extraction algorithm when p is large. Over fields with characteristic 0 (e.g. \mathbb{Q}) both the *deterministic* and the *randomized* complexities are polynomial in the bit-complexity of the coefficients (see [31]). Therefore, we can say that root extraction is, perhaps, the simplest hard problem in polynomial factorization. For sake of uniformity we formulate all our results in terms of root oracles and $\log |\mathbb{F}|$ which stands for the bit-complexity of the coefficients in the underlying polynomials.

1.2 Polynomial Reconstruction

Let \mathbb{F} be a field and \mathcal{C} a class of circuits. The *reconstruction* problem for the class \mathcal{C} is defined as follows. Given an oracle access to a polynomial $f \in \mathbb{F}[x_1, x_2, \dots, x_n]$, computable by a circuit from \mathcal{C} , output a circuit $C \in \mathcal{C}$ that computes f . A reconstruction algorithm is *efficient* if the number of queries it makes to f and its running time are polynomial in the size of the representation of f in the class \mathcal{C} . The reconstruction problem can be seen as the algebraic analog of the learning problem.

An immediate application of our main theorem is reconstruction beyond an exponentiation gate. More formally, we can efficiently extend a reconstruction algorithm for a circuit class \mathcal{C} to handle polynomials of the form f^e when f is computable by a circuit $C \in \mathcal{C}$. Note that in general f^e might not be computable by a circuit in \mathcal{C} .

► **Theorem 2.** *Let A be a deterministic (randomized) reconstruction algorithm for a circuit class \mathcal{C} , let $f \in \mathcal{C}$ and let $T(f)$ denote the number of operations A uses to reconstruct f . Then there exists a deterministic (randomized) algorithm that given $e \in \mathbb{N}$, an e -th root oracle R_e and an oracle access to the polynomial $f^e \in \mathbb{F}[x_1, x_2, \dots, x_n]$ of degree at most d , uses $\text{poly}(n, d, \log |\mathbb{F}|, T(f))$ field operations and oracle calls to R_e and A , and outputs a circuit for $\omega \cdot f$, where $\omega \in \mathbb{F}$ is such that $\omega^e = 1$.*

As a corollary we get to extend reconstruction algorithms for specific classes of circuits. An s -sparse polynomial is polynomial with at most s (non-zero) monomials. Sparse polynomials were deeply studied (see e.g. [5, 29, 32]) and, in fact, several efficient deterministic reconstruction algorithms were given. Our next result extends the reconstruction algorithm of [29] to powers of sparse polynomials.

► **Theorem 3.** *Let $n, s, d, e \in \mathbb{N}$ and let $f(\bar{x}) \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be an s -sparse polynomial of degree at most d . Then there exists a deterministic algorithm that given $e \in \mathbb{N}$, an oracle access to the polynomial $f^e \in \mathbb{F}[x_1, x_2, \dots, x_n]$ and an e -th root oracle R_e uses $\text{poly}(n, d, e, s, \log |\mathbb{F}|)$ field operations and oracle calls, and outputs $\omega \cdot f$, where $\omega \in \mathbb{F}$ is such that $\omega^e = 1$.*

Read-once formulas are formulas in which each variable appears at most once. A read-once polynomial is a polynomial computable by a read-once formula. Those are the smallest possible polynomials that depend on all of their variables. Although they form a very restricted model of computation, read-once formulas received a lot of attention [18, 25, 3, 8, 6, 7, 38, 39, 33, 45]. In [38] a $n^{\mathcal{O}(\log n)}$ -time reconstruction algorithm for read-once formulas was given. In [33], the runtime of the algorithm was improved to $\text{poly}(n)$. Our next result extends the reconstruction algorithm further to powers of read-once polynomials. We note that the reconstruction algorithm of [6] actually deals with a richer model of read-once formulas with exponentiation gates. Yet, that algorithm is randomized.

► **Theorem 4.** *Let $n, e \in \mathbb{N}$ and let $f(\bar{x}) \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be a read-once polynomial. Then there exists a deterministic algorithm that given an oracle access to the polynomial $f \in \mathbb{F}[x_1, x_2, \dots, x_n]$ and an e -th root oracle R_e uses $\text{poly}(n) \cdot \text{poly}(e, \log |\mathbb{F}|)$ field operations and oracle calls, and outputs a read-once formula Ψ that computes $\omega \cdot f$, where $\omega \in \mathbb{F}$ is such that $\omega^e = 1$.*

A depth-4 $\Sigma\Pi\Sigma\Pi(k)$ circuit has 4 layers of alternating $(+, \times)$ gates and it computes a polynomial of the form $C(x_1, x_2, \dots, x_n) = \sum_{i=1}^k F_i = \sum_{i=1}^k \prod_{j=1}^{d_i} P_{ij}$ where k is the fan-in of the top Σ gate and d_i are the fan-ins of the Π gates at the second level. These circuits were previously studied in [2, 16, 26, 35]. In particular, in [16] a randomized reconstruction algorithm was given for multilinear depth-4 circuits with $k = 2$ (i.e. $\Sigma\Pi\Sigma\Pi(2)$ circuits). As an application, we derandomize their algorithm using a square root oracle. We note that our result achieves an optimal derandomization since in [46] it was shown that any reconstruction algorithm for this circuit class must compute square roots.

► **Theorem 5.** *Let $n, s \in \mathbb{N}$ and suppose $\text{char}(\mathbb{F}) \neq 2$. Then there exists a deterministic algorithm that given an oracle access to the polynomial $f \in \mathbb{F}[x_1, x_2, \dots, x_n]$ computable by a multilinear $\Sigma\Pi\Sigma\Pi(2)$ circuit of size s and a square root oracle R_2 uses $\text{poly}(n, s, \log |\mathbb{F}|)$ field operations and oracle calls, and outputs a $\Sigma\Pi\Sigma\Pi(2)$ circuit that computes f .*

1.3 Sparse Polynomial Factorization

Coming up with an efficient deterministic factorization algorithm for sparse polynomials (given as a list of monomials) is a classical open question posed by von zur Gathen and Kaltofen in [49]. An inherent difficulty in tackling the problem lies within the fact that a factor of a sparse polynomial need not be sparse. Example 5.1 in [49] demonstrates that a blow-up in the sparsity of a factor can be super-polynomial over any field. Consequently, just writing down the irreducible factors as lists of monomials can take super-polynomial time. In fact, the randomized algorithm of [49] assumes that the upper bound on the sparsity of the factors is known. In light of this difficulty, a simpler problem was posed in that same paper: Given $m + 1$ sparse polynomials f, g_1, g_2, \dots, g_m test if $f = g_1 \cdot g_2 \cdot \dots \cdot g_m$. This problem is referred to as “testing sparse factorization”.

Our main result gives a deterministic factorization algorithm for sparse multiquadratic polynomials.

► **Theorem 6.** *Let $n, s \in \mathbb{N}$ and suppose $\text{char}(\mathbb{F}) \neq 2$. There exists a deterministic algorithm that given an s -sparse multiquadratic polynomial $f(\bar{x}) \in \mathbb{F}[x_1, x_2, \dots, x_n]$ and a square root oracle R_2 uses $\text{poly}(n, s, \log |\mathbb{F}|)$ field operations and oracle calls to R_2 and outputs the irreducible factors of $f(\bar{x})$. That is, a list h_1, \dots, h_k of irreducible polynomials such that $f = h_1 \cdot \dots \cdot h_k$.*

We also show how to test sparse factorization for a special case of polynomials with constant individual degrees.

► **Theorem 7.** *Let $f, g_1, \dots, g_m \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be s -sparse polynomials a let d be a bound on the individual degrees of f . Then given f, g_1, \dots, g_m , there exists a deterministic algorithm that tests if $f = g_1 \cdot g_2 \cdot \dots \cdot g_m$ using $\text{poly}(n, s^d, \log |\mathbb{F}|)$ field operations.*

Using techniques from Differential Field Theory we show that some identity testing algorithms could be extended to work beyond an exponentiation gate. In particular, we prove the following theorem which can be seen as testing symmetric sparse factorization. We note that setting $e = 1$ instantiates to testing sparse factorization in the case when $f_1 = f_2 = \dots = f_m$.

► **Theorem 8.** *Let $n, s, d, e, \delta \in \mathbb{N}$ and let $f(\bar{x}), g(\bar{x}) \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be two s -sparse polynomials of degree at most δ . Furthermore, suppose that $\text{char}(\mathbb{F}) = 0$ or $\text{char}(\mathbb{F}) > \delta \cdot \min(e, d)$. Then there exists a deterministic algorithm that given f, g, d and e uses $\text{poly}(n, s, d, e, \delta, \log |\mathbb{F}|)$ field operations and tests whether $f^d = g^e$.*

We note that similar results to Theorems 7 and 8 follow from the works of [1, 4]. For the result of Theorem 8 we give a more direct and simple algorithm.

1.4 Techniques

Our main technique is to convert an oracle access to a power of a polynomial f^e into an oracle access to the polynomial itself f . As was discussed in the first part of the Introduction, a necessary condition is having an efficient root extraction algorithm for field elements, referred to as a “root oracle”. Yet, as was demonstrated further, applying root oracles naively can result in inconsistency. More specifically, as there could be e roots of a polynomial, differing only by a multiplicative factor of a root of unity of order e , a root oracle can mismatch the answers to different oracle queries. We solve this problem by introducing an anchor and matching all the queries to that anchor. More specifically, we fix a non-zero

assignment \bar{a} of f . For query point \bar{b} we compute the root along the line $\ell_{\bar{a},\bar{b}}(t)$ that passes through \bar{a} and \bar{b} . Thus, we reduce the problem from n variables to 1. Finally, we show how to use a root oracle to compute a root of a univariate polynomial. The latter is carried out via Squarefree decomposition. See Sections 2.5 and 4.1 for more details.

In order to deal with sparse multiquadratic polynomials, we first show that a factor of such a polynomial is also sparse. Next, we apply the quadratic formula to get explicit expressions for the factors. Yet, these expressions involve square roots. Computing a square root of a polynomial h can be seen as computing $\pm f$ given $h = f^2$. To this end, we first apply our main technique to get an oracle access for f and then use a reconstruction algorithm for sparse polynomials to compute the polynomial. See Section 4.3 for more details.

Another tool that we use is Resultants and Subresultants. These objects have seen various applications in algebraic complexity, computer algebra, elimination theory and other areas (see e.g. [15, 48, 10]). In particular, these are used to test coprimality of polynomials. We show how to efficiently employ them with sparse polynomials of constant degree. The main observation is that a resultant of two sparse polynomials of constant degrees is also a somewhat sparse polynomial of a “small” degree. For more details see Sections A and 2.4.

1.5 Previous Results

Over the last three decades the question of derandomizing sparse polynomial factorization has seen only a very partial progress. In [37], Shpilka & Volkovich gave efficient deterministic factorization algorithms for sparse multilinear polynomials. This result was extended in [44] to the model of sparse polynomials that split into multilinear factors. For the testing version of the problem, Saha et al. [34] presented an efficient deterministic algorithm for the special case when the sparse polynomials are sums of univariate polynomials.

1.6 Organization

We begin by some basic definitions and notation in Section 2 when in Section 2.5 we show how to compute a root of a univariate polynomial. In Section 3 we discuss sparse polynomials, their properties and some related efficient algorithms which leverage these properties. In particular, in Section 3.1 we prove that a factor of a sparse multiquadratic polynomial is also sparse. In Section 4 we give all our results showing how to perform certain computations on polynomials given an oracle access to their powers. We begin (Section 4.1) by showing how to convert an oracle access to f^e into an oracle access to f using an e -th root oracle, thus proving Theorem (Theorem 1) which is our main technical contribution. The first application is given in Section 4.2 where we show how to extend a reconstruction algorithm for a circuit class \mathcal{C} to handle powers of polynomials from \mathcal{C} (Theorem 2). As a corollary, we obtain an efficient reconstruction algorithm for powers of sparse (Theorem 3) and read-once (Theorem 4) polynomials. Our main application is given in Section 4.3 where we present the first efficient factorization algorithm for sparse multiquadratic polynomials, thus proving Theorem 6. In Section C, using different techniques but following the general line, we show how certain polynomial identity testing algorithms can be extended to handle powers of polynomials. We conclude the paper with discussion and open questions in Section 5.

2 Preliminaries

Let \mathbb{F} denote a field, finite or otherwise, and let $\bar{\mathbb{F}}$ denote its algebraic closure.

2.1 Polynomials

A polynomial $f \in \mathbb{F}[x_1, x_2, \dots, x_n]$ depends on a variable x_i if there are two inputs $\bar{\alpha}, \bar{\beta} \in \bar{\mathbb{F}}$ differing only in the i^{th} coordinate for which $f(\bar{\alpha}) \neq f(\bar{\beta})$. We denote by $\text{var}(f)$ the set of variables that f depends on. We say that f is *similar* to g and denote by it $f \sim g$ if $f = \alpha g$ for some $\alpha \neq 0 \in \mathbb{F}$. For a polynomial $f(x_1, \dots, x_n)$, a variable x_i and a field element α , we denote with $f|_{x_i=\alpha}$ the polynomial resulting from substituting α to x_i . Similarly given a subset $I \subseteq [n]$ and an assignment $\bar{a} \in \mathbb{F}^n$, we define $f|_{\bar{x}_I=\bar{a}_I}$ to be the polynomial resulting from substituting a_i to x_i for every $i \in I$.

► **Definition 9** (Line). Given $\bar{a}, \bar{b} \in \mathbb{F}^n$ we define a *line* passing through \bar{a} and \bar{b} as $\ell_{\bar{a}, \bar{b}} : \mathbb{F} \rightarrow \mathbb{F}^n$, $\ell_{\bar{a}, \bar{b}}(t) \triangleq (1-t) \cdot \bar{a} + t \cdot \bar{b}$. In particular, $\ell_{\bar{a}, \bar{b}}(0) = \bar{a}$ and $\ell_{\bar{a}, \bar{b}}(1) = \bar{b}$.

► **Definition 10** (Degrees, Leading Monomials, Leading Coefficients). The *leading monomial* of a polynomial f , $\text{lm}(f)$ is defined as the largest non-zero monomial of f (with its coefficient) with respect to the lexicographical order of the monomials. The *total degree* of f is the largest total degree of a monomial in f . Let $x_i \in \text{var}(f)$. We can write: $f = \sum_{j=0}^d f_j \cdot x_i^j$ such that $\forall j, x_i \notin \text{var}(f_j)$ and $f_d \neq 0$. The *leading coefficient* of f w.r.t to x_i is defined as $\text{lc}_{x_i}(f) \triangleq f_d$. The *individual degree* of x_i in f is defined as $\text{deg}_{x_i}(f) \triangleq d$.

It is easy to see that for every $f, g \in \mathbb{F}[x_1, x_2, \dots, x_n]$ and $i \in [n]$ we have that: $\text{lm}(f \cdot g) = \text{lm}(f) \cdot \text{lm}(g)$ and $\text{lc}_{x_i}(f \cdot g) = \text{lc}_{x_i}(f) \cdot \text{lc}_{x_i}(g)$.

2.2 Partial Derivatives

The concept of a *partial derivative* of a multivariate function and its properties are well-known and well-studied for continuous domains (such as, \mathbb{R}, \mathbb{C} etc.). This concept can be extended to polynomials and rational functions over arbitrary fields from a purely algebraic point of view. For more details we refer to reader to [24].

► **Definition 11**. For a monomial $M = \alpha \cdot x_1^{e_1} \dots x_i^{e_i} \dots x_n^{e_n} \in \mathbb{F}[x_1, x_2, \dots, x_n]$ and a variable x_i we define the *partial derivative* of M with respect to x_i , as $\frac{\partial M}{\partial x_i} \triangleq \alpha e_i \cdot x_1^{e_1} \dots x_i^{e_i-1} \dots x_n^{e_n}$. The definition can be extended to $\mathbb{F}[x_1, x_2, \dots, x_n]$ by imposing linearity and to $\mathbb{F}(x_1, x_2, \dots, x_n)$ via the quotient rule.

Observe that the sum, product, quotient and chain rules carry over. In addition, when $\mathbb{F} = \mathbb{R}$ or $\mathbb{F} = \mathbb{C}$ the definition coincides with the analytical one. The following set of rational function plays an important role.

► **Definition 12** (Field of Constants). The *Field of Constants* of $\mathbb{F}(x_1, x_2, \dots, x_n)$ is defined as $C(\mathbb{F}(x_1, x_2, \dots, x_n)) \triangleq \left\{ f \in \mathbb{F}(x_1, x_2, \dots, x_n) \mid \forall i \in [n], \frac{\partial f}{\partial x_i} \equiv 0 \right\}$.

It is easy to see that the field of constants is, indeed, a field and in particular $\mathbb{F} \subseteq C(\mathbb{F}(x_1, x_2, \dots, x_n))$. Furthermore, this containment is proper for fields with positive characteristics and equality holds only for fields with characteristic 0. The following Lemma gives a precise characterization of $C(\mathbb{F}(x_1, x_2, \dots, x_n))$.

► **Lemma 13**. Let \mathbb{F} be a field of characteristic p . Then for every $n \in \mathbb{N}$:

1. $C(\mathbb{F}(x_1, x_2, \dots, x_n)) = \mathbb{F}$ when $p = 0$.
2. $C(\mathbb{F}(x_1, x_2, \dots, x_n)) = \mathbb{F}(x_1^p, x_2^p, \dots, x_n^p)$ when p is positive.

2.3 Factors and Perfect Powers

Let $f, g \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be polynomials. We say that g *divides* f , or equivalently g is a factor of f , and denote it by $g \mid f$ if there exists a polynomial $h \in \mathbb{F}[x_1, x_2, \dots, x_n]$ such that $f = g \cdot h$. We say that f is *irreducible* if f is non-constant and cannot be written as a product of two non-constant polynomials. For $e \in \mathbb{N}$, we say that f is a *perfect e -th power* if there exists a polynomial $h \in \mathbb{F}[x_1, x_2, \dots, x_n]$ such that $f = h^e$. Equivalently, we say that h is f 's e -th root. Given the notion of divisibility we define the gcd of a set of polynomials in the natural way. Given the notion of irreducibility we can state the important property of the uniqueness of factorization,

► **Lemma 14** (Uniqueness of Factorization). *Let $h_1^{e_1} \dots h_k^{e_k} = g_1^{e'_1} \dots g_{k'}^{e'_{k'}}$ be two factorizations of the same non-zero polynomial into irreducible, pairwise coprime factors. Then $k = k'$ and there exists a permutation $\sigma : [k] \rightarrow [k]$ such that $h_i \sim g_{\sigma(i)}$ and $e_i = e'_{\sigma(i)}$ for $i \in [k]$.*

By definition, the ratio α/β of two e -th of roots a field element (i.e. $\alpha^e = \beta^e \neq 0$) is a root of unity of order e . We show that the same holds for perfect roots of polynomials. More precisely, two e -th roots of the same polynomial differ only by a multiplicative factor ω satisfying $\omega^e = 1$.

► **Lemma 15.** *Let $f(\bar{x}), h(\bar{x}), g(\bar{x}) \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be polynomials such that $f(\bar{x}) = h(\bar{x})^e = g(\bar{x})^e$ for some $e \in \mathbb{N}$. In addition, let $\alpha \in \mathbb{F}, \bar{a} \in \mathbb{F}^n$ such that $\alpha^e = f(\bar{a}) \neq 0$. Then*

1. *There exists $\omega \in \mathbb{F}$ such that $\omega^e = 1$ and $h(\bar{x}) = \omega \cdot g(\bar{x})$.*
2. *There exists a unique polynomial $u(\bar{x}) \in \mathbb{F}[x_1, x_2, \dots, x_n]$ s.t. $f(\bar{x}) = u(\bar{x})^e$ and $u(\bar{a}) = \alpha$.*

The proof can be found in Section D.

2.4 GCD and Subresultants

As was mentioned earlier, the notion of divisibility gives rise to the notion of a gcd of a set of polynomials in the natural way. Furthermore, the uniqueness of factorization property of the rings of polynomials $\mathbb{F}[x_1, x_2, \dots, x_n]$ ensures that a gcd is defined up to a multiplication by a field element. We can also consider versions of gcd when we concentrate on a single variable and treat the remaining variables as field elements. That is, given f_1, \dots, f_m consider $\gcd_{x_i}(f_1, \dots, f_m)$. Naturally, such gcd's is defined up to a multiplication by a rational function depending on the remaining variables. Yet, in all such gcd's the variable x_i has the same degree.

► **Example 16.** Let $f = x_1^2 x_2^2 + x_1^2 x_2 + x_1 x_2^2 + x_1 x_2$ and $g = x_1^2 x_2^2$. $\gcd(f, g) = x_1 x_2$ while $\gcd_{x_1}(f, g) = x_1$. Yet, $\deg_{x_i}(\gcd_{x_i}(f, g)) = \deg_{x_i}(\gcd(f, g)) = 1$.

► **Lemma 17.** *Let $f, g \neq 0 \in \mathbb{F}[x_1, x_2, \dots, x_n]$ and let e_i denote the individual degree of x_i in g . Then $g \mid f$ iff $\forall i$ with $e_i > 0 : \deg_{x_i}(\gcd_{x_i}(f, g)) = e_i$.*

Proof. If $g \mid f$ then the statement is clear. Suppose $g \nmid f$. Let $g = \prod g_j^{d_j}$ be a factorization of g into irreducible, pairwise coprime factors. By definition, there exists j such that $g_j^{d_j} \nmid f$. Let $x_i \in \text{var}(g_j)$. As such, $\deg_{x_i}(\gcd_{x_i}(f, g)) \leq e_i - \deg_{x_i}(g_j) < e_i$. ◀

► **Definition 18** (Subresultant - Definition 7.3 from [15]). Let $f, g \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be polynomials. Fix $i \in [n]$ and let d and e denote the degree of the variable x_i in f and g , respectively. We can write: $f = \sum_{j=0}^d f_j \cdot x_i^j$ such that $\forall j, x_i \notin \text{var}(f_j)$ and $g = \sum_{k=0}^e g_k \cdot x_i^k$

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such that $\forall k, x_i \notin \text{var}(g_k)$. For $0 \leq j \leq \min\{e, d\}$ the j -th Subresultant of f and g w.r.t x_i , $S_{x_i}(j, f, g)$ is defined as a determinant of the $(d + e - 2j) \times (d + e - 2j)$ minor of the Sylvester Matrix of f and g . That is, the entities of the matrix are f_j -s and g_k -s.

Below is the crucial property of subresultants:

► **Lemma 19** (Lemma 7.1 and Theorem 7.3 from [15]). *For every variable x_i , the degree of x_i in $\text{gcd}_{x_i}(f, g)$ equals to smallest j such that $S_{x_i}(j, f, g) \neq 0$. In addition, if $u, v \in \mathbb{F}[x_1, x_2, \dots, x_n]$ such that $x_i \notin \text{var}(u) \cup \text{var}(v)$ then $\forall i, j: S_{x_i}(j, uf, vg) = S_{x_i}(j, f, g) \cdot u^{\deg_{x_i}(g)} \cdot v^{\deg_{x_i}(f)}$.*

Combining Lemmas 17 and 19 gives the following:

► **Corollary 20.** *Let $f, g \neq 0 \in \mathbb{F}[x_1, x_2, \dots, x_n]$ and let e_i denote the individual degree of x_i in g . Then $g \mid f$ iff $\forall i$ with $e_i > 0: S_{x_i}(e_i - 1, f, g) \equiv 0$.*

Proof. If $g \mid f$ and $e_i > 0$, then $\deg_{x_i}(\text{gcd}_{x_i}(f, g)) = e_i$ and thus $S_{x_i}(e_i, f, g) \neq 0$ while $S_{x_i}(e_i - 1, f, g) \equiv 0$. On the other hand, if $S_{x_i}(e_i - 1, f, g) \equiv 0$ it must be the case that $S_{x_i}(e_i, f, g) \neq 0$ since $\deg_{x_i}(\text{gcd}_{x_i}(f, g)) \leq e_i$. ◀

2.5 Univariate Polynomials: Squarefree Decomposition and Root Computation

In this section we show how to compute the e -th roots of univariate polynomials using root oracles. We begin by discussing a Squarefree Decomposition of a polynomial. This is one of the steps in the majority of the polynomial factorization algorithms.

► **Definition 21** (Squarefree polynomials). We say that a polynomial $f(y) \in \mathbb{F}[y]$ is *squarefree* if $g(y)^2 \nmid f(y)$ for every $g(y) \in \mathbb{F}[y]$.

► **Definition 22** (Squarefree Decomposition). Let $f(y) \in \mathbb{F}[y]$ be polynomial of degree at most d . The *squarefree decomposition* of $f(y)$ is a sequence of pairwise coprime, squarefree polynomials (g_1, \dots, g_d) such that $f = g_1 \cdot g_2^2 \cdot \dots \cdot g_d^d$.

The next lemma shows that for monic polynomials the squarefree decomposition is unique. Moreover, this decomposition can be computed efficiently.

► **Lemma 23** (Theorem 14.23 of [48] and extensions). *Let $f(y) \in \mathbb{F}[y]$ be a non-constant, monic polynomial of degree at most d . Then there exists a unique squarefree decomposition into a sequence of monic polynomials. Moreover, there exists a deterministic algorithm that given the polynomial $f(y)$ uses $\text{poly}(d, \log |\mathbb{F}|)$ field operations and computes its squarefree decomposition.*

The squarefree decomposition gives rise to a simple e -th root computation algorithm for univariate polynomials. In addition, this algorithm can be used to test whether a univariate polynomial is indeed a perfect power.

► **Lemma 24.** *Let $g(y) \in \mathbb{F}[y]$ be a non-constant, monic polynomial of degree at most d and let (g_1, \dots, g_d) be its squarefree decomposition. Then $g(y) = h(y)^e$ for some $e \in \mathbb{N}$ and $h(y) \in \mathbb{F}[y]$ iff $g_i = 1$ when $e \nmid i$.*

The proof can be found in Section D. The following is immediate given the previous lemmas.

► **Corollary 25.** *There exists a deterministic algorithm that given a non-constant, monic polynomial $f(y) \in \mathbb{F}[y]$ of degree at most d outputs a polynomial $h(y) \in \mathbb{F}[y]$ such that $f(y) = h(y)^e$ if one exists using $\text{poly}(d, \log |\mathbb{F}|)$ field operations.*

We can extend the algorithm to handle arbitrary univariate polynomials by making a call to a root oracle.

► **Lemma 26.** *There exists a deterministic algorithm that given $e \in \mathbb{N}$, an e -th root oracle R_e and a polynomial $f(y) \in \mathbb{F}[y]$ of degree at most d uses $\text{poly}(d, \log |\mathbb{F}|)$ field operations and one oracle call to R_e and computes an e -th root of $f(y)$. That is, the algorithm outputs a polynomial $h(y) \in \mathbb{F}[y]$ such that $f(y) = h(y)^e$ if one exists. Otherwise, the algorithm rejects.*

Proof. If $f(y) = \alpha \in \mathbb{F}$ is a field element (i.e. a constant polynomial), output $R_e(\alpha)$. Otherwise, consider $\hat{f}(y) \triangleq f(y)/\text{lc}(f)$. As $\hat{f}(y)$ is a non-constant, monic polynomial we can apply Corollary 25 to compute $\hat{h}(y) \in \mathbb{F}[y]$ such that $\hat{f}(y) = \hat{h}(y)^e$. In addition, let $\alpha = R_e(\text{lc}(f))$. Output $\alpha \cdot \hat{h}(y)$. Observing that $(\alpha \cdot \hat{h}(y))^e = f(y)$ completes the proof. ◀

3 Sparse Polynomials

In this section we discuss sparse polynomials, their properties and some related efficient algorithms which leverage these properties.

An s -sparse polynomial is polynomial with at most s (non-zero) monomials. We denote by $\|f\|$ the *sparsity* of f . In this section we list several results related to sparse polynomials. We begin with a corollary from [37] that shows that a sparse multilinear polynomial can be factored efficiently. Moreover, all its factors are sparse.

► **Lemma 27** ([37]). *Given a multilinear polynomial $f \in \mathbb{F}[x_1, x_2, \dots, x_n]$, there is a $\text{poly}(n, \|f\|)$ time deterministic algorithm that outputs the irreducible factors, h_1, \dots, h_k of f . Furthermore, $\|h_1\| \cdot \|h_2\| \cdot \dots \cdot \|h_k\| = \|f\|$.*

The following result gives an efficient reconstruction algorithm for sparse polynomials.

► **Lemma 28** ([29]). *Let $n, s, d \in \mathbb{N}$. There exists a deterministic algorithm that given an oracle access to an s -sparse polynomial $f \in \mathbb{F}[x_1, x_2, \dots, x_n]$ of degree d uses $\text{poly}(n, s, d, \log |\mathbb{F}|)$ field operations and outputs f .*

As a corollary we obtain an efficient algorithm for testing identity and, more generally, similarity between sparse polynomials. We leave the proof of the corollary as an easy exercise for the reader.

► **Corollary 29.** *Let $f, g \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be s -sparse polynomials of degree at most d . Then there exists an algorithm that given f, g uses $\text{poly}(n, d, s, \log |\mathbb{F}|)$ field operations and tests if $f \sim g$. If yes, the algorithm also outputs $\alpha \in \mathbb{F}$ such that $f = \alpha g$.*

Additionally, we obtain an efficient algorithm for sparse polynomial division given an upper bound on the sparsity of the quotient polynomial. The main idea is to reconstruct to the quotient polynomial as a sparse polynomial, using the original polynomials as oracle access. Given a candidate sparse polynomial we then can verify whether it is indeed the quotient polynomial.

► **Lemma 30** ([29, 11]). *Let $n, s, d, t \in \mathbb{N}$. Let $f, g \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be s -sparse polynomials of degree at most d . Then there exists an algorithm that given f, g uses $\text{poly}(n, d, s, t, \log |\mathbb{F}|)$ field operations and computes the quotient polynomial of f and g if it is a t -sparse polynomial. That is, if $f = gh$ for some $h \in \mathbb{F}[x_1, x_2, \dots, x_n]$, $\|h\| \leq t$ then the algorithm outputs h . Otherwise, the algorithm rejects.*

Corollary 29 can be also extended to handle products of sparse polynomials.

► **Lemma 31** ([35]). *Let $n, s, d \in \mathbb{N}$. There exists a deterministic algorithm that given an oracle access to a product of s -sparse polynomials $f \in \mathbb{F}[x_1, x_2, \dots, x_n]$ when $f = \prod g_i$ of degree d uses $\text{poly}(n, s, d, \log |\mathbb{F}|)$ field operations and tests if $f \equiv 0$.*

3.1 Sparse Multiquadratic Polynomials

In this section we prepare the ground for our main application - efficient factorization algorithm for sparse multiquadratic polynomials. We begin by showing that a factor of a sparse multiquadratic polynomials is also sparse. Recall that in general a sparse polynomial can have a dense factor.

► **Lemma 32.** *Let $0 \neq f, g \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be polynomials such that g is multiquadratic. Then $f \mid g \implies \|f\| \leq \|g\|$.*

Proof. The proof is by induction on the number of variables. The base case is when $n = 0$. That is, $f, g \in \mathbb{F}$. Clearly, in this case $\|f\| = \|g\| = 1$ and the claim holds. Now suppose that $n \geq 1$. By definition, $f \cdot h = g$ for some $h \in \mathbb{F}[x_1, x_2, \dots, x_n]$. We have two cases to consider: Suppose $\text{var}(f) \cap \text{var}(h) = \emptyset$. In this case $\|f\| \cdot \|h\| = \|g\|$ and hence $\|f\| \leq \|g\|$. Otherwise, pick $x_i \in \text{var}(f) \cap \text{var}(h)$. Since g is multiquadratic we can write $f = f_i x_i + f_0$ and $h = h_i x_i + h_0$ such that f_i, h_i, f_0 and h_0 do not depend on x_i . Therefore: $\|g\| = \|(f_i x_i + f_0) \cdot (h_i x_i + h_0)\| = \|f_i h_i x_i^2 + (f_0 h_i + f_i h_0) x_i + f_0 h_0\| \geq \|f_i h_i\| + \|f_0 h_0\|$. By the induction hypothesis $\|f_i h_i\| \geq \|f_i\|$ and $\|f_0 h_0\| \geq \|f_0\|$. Consequently, $\|g\| \geq \|f_i h_i\| + \|f_0 h_0\| \geq \|f_i\| + \|f_0\| = \|f\|$ implying the claim of the lemma. ◀

It is easy to see that this bound is tight. The following corollary is immediate by combining the bound with Lemma 30.

► **Corollary 33.** *Let $n, s, d \in \mathbb{N}$. There exists an algorithm that given s -sparse multiquadratic polynomials $f, g \in \mathbb{F}[x_1, x_2, \dots, x_n]$ uses $\text{poly}(n, s, d, \log |\mathbb{F}|)$ field operations and computes the quotient polynomial of f and g . That is, if $f = gh$ for some $h \in \mathbb{F}[x_1, x_2, \dots, x_n]$ then the algorithm outputs h . Otherwise, the algorithm rejects.*

We can extend the result to the case when a polynomial is a factor of a product of sparse multiquadratic polynomials. Note that such a product need not be either sparse or multiquadratic.

► **Corollary 34.** *Let $0 \neq f, g_1, \dots, g_k \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be polynomials such that for all $i \in [k]$, g_i is multiquadratic. Then $f \mid g_1 \cdot \dots \cdot g_k \implies \|f\| \leq \|g_1\| \cdot \dots \cdot \|g_k\|$.*

Proof. Since $f \mid g_1 \cdot \dots \cdot g_k$, we can write $f = f_1 \cdot \dots \cdot f_k$ such that $f_i \mid g_i$. By the Lemma: $\|f_i\| \leq \|g_i\|$. Therefore: $\|f\| \leq \|f_1\| \cdot \dots \cdot \|f_k\| \leq \|g_1\| \cdot \dots \cdot \|g_k\|$. ◀

The following lemma shows that if a sparse multiquadratic polynomial over a field with an odd characteristic factors in a certain way, then the corresponding discriminant is a polynomial and, in fact, a sparse polynomial.

► **Lemma 35.** *Suppose $\text{char}(\mathbb{F}) \neq 2$. Let $f = ax_i^2 + bx_i + c \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be a multiquadratic polynomial that can be factored as $f = g \cdot h$ when both g and h depend on x_i . Then there exists a multiquadratic polynomial $\Delta \in \mathbb{F}[x_1, x_2, \dots, x_n]$ such that $\Delta^2 = b^2 - 4ac$. Moreover, $\|\Delta\| \leq \|f\|^2$.*

Proof. Let $g = g_i x_i + g_0$ and $h = h_i x_i + h_0$. By comparing the coefficients of x_i on both sides of the equation we get that $a = g_i h_i$, $b = g_i h_0 + g_0 h_i$ and $c = g_0 h_0$. Therefore, $b^2 - 4ac = (g_i h_0 + g_0 h_i)^2 - 4g_i h_i g_0 h_0 = (g_i h_0 - g_0 h_i)^2$. Consequently, selecting $\Delta \triangleq g_i h_0 - g_0 h_i$ takes care of the first claim. The claim regarding the degree follows from the fact that the degree of every variable in $b^2 - 4ac$ is at most 4. Finally, as $(b + \Delta)(b - \Delta) = 4ac$, by Corollary 34: $\|b + \Delta\| \leq \|a\| \cdot \|c\|$, implying that $\|\Delta\| \leq \|a\| \cdot \|c\| + \|b\| \leq (\|a\| + \|b\| + \|c\|)^2 = \|f\|^2$. ◀

4 Computations beyond an Exponentiation Gate and Application

In this section we give all our results showing how perform certain computations on polynomials given an oracle access to their powers.

4.1 Evaluation beyond an Exponentiation Gate

The most basic task for polynomial manipulation is evaluating a polynomial given via an oracle access. In this section we show how to transform an oracle access to the polynomial f^e into an oracle access to f itself. This can be thought of having an oracle equipped with a clever root extraction algorithm. Our main result is given in the following algorithm.

Input: Oracle access to a polynomial $f = g^e \in \mathbb{F}[x_1, x_2, \dots, x_n]$; $\bar{a} \in \mathbb{F}^n$ s.t. $f(\bar{a}) \neq 0$;
 $e \in \mathbb{N}$, e -th root oracle R_e .
 Evaluation points $\bar{b}_1, \bar{b}_2, \dots \in \mathbb{F}[x_1, x_2, \dots, x_n]$
Output: $h(\bar{b}_1), h(\bar{b}_2), \dots$ when $h(\bar{x}) \in \mathbb{F}[x_1, x_2, \dots, x_n]$ is a polynomial s.t. $h^e = f$.

- 1 $\alpha \leftarrow R_e(f(\bar{a}))$ /* Computed only once. */
- 2 Compute $h_{\bar{b}}(t)$ such that $h_{\bar{b}}(t)^e = f(\ell_{\bar{a}, \bar{b}}(t))$ /* Invoking Lemma 26 */
- 3 $\beta \leftarrow h_{\bar{b}}(0)$;
- 4 **return** $h_{\bar{b}}(1) \cdot \alpha / \beta$

Algorithm 1: Polynomial Oracle Transformation.

► **Lemma 36.** *Let $h(\bar{x}) \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be such that $f(\bar{x}) = h(\bar{x})^e$ and $h(\bar{a}) = \alpha$. Then for every $\bar{b} \in \mathbb{F}[x_1, x_2, \dots, x_n]$ Algorithm 1 outputs $h(\bar{b})$.*

Proof. First, by Lemma 15 such a polynomial $h(\bar{x})$ exists and is unique. In addition, $\beta \neq 0$ since $\beta^e = h_{\bar{b}}(0)^e = f(\ell_{\bar{a}, \bar{b}}(0)) = f(\bar{a}) \neq 0$. Therefore, the output of algorithm is well-defined. Next, we have that $h_{\bar{b}}(t)^e = f(\ell_{\bar{a}, \bar{b}}(t)) = h(\ell_{\bar{a}, \bar{b}}(t))^e$. By Lemma 15, $h_{\bar{b}}(t) = \omega \cdot h(\ell_{\bar{a}, \bar{b}}(t))$ for some $\omega \in \mathbb{F}$. Therefore: $\frac{h_{\bar{b}}(1) \cdot \alpha}{\beta} = \frac{\omega \cdot h(\ell_{\bar{a}, \bar{b}}(1)) \cdot \alpha}{h_{\bar{b}}(0)} = \frac{\omega \cdot h(\bar{b}) \cdot \alpha}{\omega \cdot h(\bar{a})} = h(\bar{b})$. ◀

Note that Algorithm 1 requires a non-zero point of $f(\bar{x})$ as an additional input. Generally speaking, finding such a point is the well-known problem of Polynomial Identity Testing (PIT) which is not known to have an efficient deterministic algorithm. We now argue that for our purposes we do not need a PIT algorithm.

Recall that we are in the setting where the root of $f(\bar{x})$ is evaluated on a sequence of points. Given each new query point $\bar{b} \in \mathbb{F}^n$ we can first evaluate $f(\bar{x})$ on \bar{b} . If $f(\bar{b}) \neq 0$, we can set $\bar{a} = \bar{b}$ and use this \bar{a} as the non-zero input onwards. Observe that Algorithm 1 works for the case $\bar{a} = \bar{b}$ as well. However, one may ask what happens with the previous query points? Or, what if for all the query points \bar{b} are zeros of f ? Observe that if $f(\bar{b}) = 0$ then

$h(\bar{b}) = 0$ for any $h(\bar{x}) \in \mathbb{F}[x_1, x_2, \dots, x_n]$ such that $h(\bar{x})^e = f(\bar{x})$. Therefore, there is no issue of inconsistency here and the oracle just needs to output 0. Consequently, we can patch Algorithm 1 by using the first non-zero query point as \bar{a} (if one exists). Theorem 1 follows as a corollary of Lemma 36 and the above discussion.

4.2 Reconstruction beyond an Exponentiation Gate

An immediate application of the polynomial evaluation algorithm is reconstruction beyond an exponentiation gate. More formally, let A be a reconstruction algorithm for a circuit class \mathcal{C} . By definition, A requires an oracle access to $f \in \mathcal{C}$ to reconstruct it. We can extend the algorithm to reconstruct $f(\bar{x})$ given an oracle access to $f(\bar{x})^e$ and an e -th root oracle R_e , by simulating each query of A . However, in the spirit of Lemma 15 the reconstruction algorithm might end up outputting $\omega \cdot f(\bar{x})$ depending on the root oracle R_e at hand. This reasoning is summarized in Theorem 2. As a corollary we get the following:

Proof of Theorem 3. Apply Theorem 2 with Lemma 28. ◀

Theorem 4 also follows as a corollary given the following result:

► **Lemma 37** ([33]). *Let $n \in \mathbb{N}$. There exists a deterministic algorithm that given an oracle access to a read-once polynomial $f \in \mathbb{F}[x_1, x_2, \dots, x_n]$ uses $\text{poly}(n) \cdot \text{poly}(\log |\mathbb{F}|)$ field operations and outputs a read-once formula Ψ that computes f .*

4.3 Deterministic Factorization of Sparse Multiquadratic Polynomials

For the case of sparse multiquadratic polynomials we can actually push those techniques further to obtain complete factorization thus proving Theorem 6. We now give the overview of the algorithm. Suppose $\text{char}(\mathbb{F}) \neq 2$. Let $f \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be a multiquadratic polynomial and let x_i be a variable such that f factors as $f = g \cdot h$ when both g and h depend on x_i . We can view f as $f = ax_i^2 + bx_i + c$ when $a(\bar{x}), b(\bar{x})$ are $c(\bar{x})$ polynomials that do not depend on x_i . Given this view, we can express g and h in terms of a, b and c using the quadratic formula. That is, we can write $a \cdot f = (ax_i + b/2 + \Delta/2) \cdot (ax_i + b/2 - \Delta/2)$ when Δ is a polynomial satisfying $\Delta^2 = b^2 - 4ac$. By Lemma 32, both factors are $\|f\|$ -sparse so we could continue this process recursively. However, there are some issues with this approach. First, it is not clear that Δ is a polynomial since the expression $b^2 - 4ac$ might not be a perfect square. Next, suppose that Δ were a polynomial. Is it sparse? Answers to these question were given in Lemma 35. Finally, how do we compute Δ ? For that purpose we apply Theorem 3 that allows us reconstruct a sparse polynomial f given an oracle access to its power f^e . Formally, an instantiation of Theorem 3 with $e = 2, d = 4n, s = \|f\|^2$ together with Lemma 35 give rise to the following corollary.

► **Corollary 38.** *Suppose $\text{char}(\mathbb{F}) \neq 2$. Let $f = ax_i^2 + bx_i + c \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be a multiquadratic polynomial that can be factored as $f = g \cdot h$ when both g and h depend on x_i . Then there exists a deterministic algorithm that given $i \in [n]$, the polynomial $f(\bar{x})$ and a square root oracle R_2 uses $\text{poly}(n, \|f\|, \log |\mathbb{F}|)$ field operations and oracle calls, and outputs a multiquadratic polynomial $\Delta \in \mathbb{F}[x_1, x_2, \dots, x_n]$ such that $\Delta^2 = b^2 - 4ac$ and $\|\Delta\| \leq \|f\|^2$.*

However, this still does not solve the problem entirely, as we obtain a factorization of $a \cdot f$ instead of f , while a need not be constant. Another issue is that f could factor differently: $f = (a'x_i^2 + b'x_i + c')h$ and in particular the polynomial $a = a' \cdot h$ could be reducible. We solve both problems by changing the way we apply recursion: we first recursively factorize

$a(x)$ and then iteratively use Corollary 33 to write f as $f = \gcd(f, a) \cdot f'$. To finish the algorithm we need to observe that f' is either irreducible or factors as above. We now move the proof of Theorem 6.

<p>Input: A multiquadratic polynomial $f(\bar{x}) \in \mathbb{F}[x_1, x_2, \dots, x_n]$; A square root oracle R_2</p> <p>Output: A list h_1, \dots, h_k of the irreducible factors of f. That is, $f = h_1 \cdot \dots \cdot h_k$.</p> <pre style="font-family: monospace; font-size: 0.9em;"> 1 $\hat{f} \leftarrow \text{lc}_{x_n}(f)$; 2 if \hat{f} is a constant then $S \leftarrow \emptyset$ else $S \leftarrow \text{Factor}(\hat{f})$; 3 $u \leftarrow f$; $T \leftarrow \emptyset$; 4 foreach $h \in S$ do 5 $v \leftarrow u/h$; /* using the algorithm in Corollary 33. */ 6 if $v \neq \perp$ then $u \leftarrow v$ else $S \leftarrow S \setminus \{h\}$; $T \leftarrow T \cup \{h\}$; 7 end 8 if $\deg_{x_n}(u) = 1$ then 9 return $S \cup \{u\}$ 10 else 11 Write $u = ax_n^2 + bx_n + c$; 12 Compute $\Delta \leftarrow \sqrt{b^2 - 4ac}$; /* using the algorithm in Corollary 38. */ 13 $\eta_+ \leftarrow ax_n + b/2 + \Delta/2$; $\eta_- \leftarrow ax_n + b/2 - \Delta/2$; 14 foreach $h \in T$ do 15 $v \leftarrow \eta_+/h$; /* using the algorithm in Corollary 33. */ 16 if $v \neq \perp$ then $\eta_+ \leftarrow v$; else $\eta_- \leftarrow \eta_-/h$; 17 end 18 $\gamma \leftarrow \text{lm}(u)/\text{lm}(\eta_+ \cdot \eta_-)$; 19 if $u = \gamma\eta_+ \cdot \eta_-$ then return $S \cup \{\gamma\eta_+, \eta_-\}$ else return $S \cup \{u\}$; 20 end </pre>

Algorithm 2: Factoring Sparse Multiquadratic Polynomials when $\text{char}(\mathbb{F}) \neq 2$.

Proof of Theorem 6. The outline of the algorithm is given in Algorithm 2. First of all, as $f(\bar{x})$ is given to us as a list of monomials, we can assume wlog that $\text{var}(f) = [n]$ by renaming the variables. The proof is by induction on $m(f) \triangleq |\text{var}(\text{lc}_{x_n}(f))|$.

Running time: Observe that throughout the execution of the algorithm $\|u\|, \|v\| \leq \|f\|$ and $\|\eta_+\|, \|\eta_-\| \leq \|f\|^2$. Initially, the bound holds by the definition of the polynomials. As each update results from a division, the claim regarding the sparsity follows from Lemma 32. Therefore, by Corollaries 33 and 38 we get that the total number of field operations and oracle calls to R_2 satisfies the following recurrent expression: $t(m, \|f\|) \leq t(m-1, \|f\|) + \text{poly}(m, \|f\|, \log |\mathbb{F}|)$ resulting in $t(m, \|f\|) = \text{poly}(m, \|f\|, \log |\mathbb{F}|)$. As $m \leq n-1$, the claim regarding the running time follows.

Analysis: Suppose that $m(f) \geq 1$. We need to fix some notations. Let $f = h_1 \cdot \dots \cdot h_k$ be a factorization of f into irreducible factors. Let g denote the product of those h_i -s that depend on x_n . Note that there can be at most two such factors. Therefore, we can write: $f = h_1 \cdot \dots \cdot h_{k'} \cdot g$. Finally, let $\hat{g} = \text{lc}_{x_n}(g)$ and let $\hat{g} = \hat{g}_1 \cdot \dots \cdot \hat{g}_\ell$ be a factorization of \hat{g} into irreducible factors. Note that $\gcd(g, \hat{g}) = 1$ since $x_n \notin \text{var}(\hat{g})$ and

g contains only the factors the depend on x_n . Moreover, given the above we get that: $\hat{f} = h_1 \cdot \dots \cdot h_{k'} \cdot \hat{g} = h_1 \cdot \dots \cdot h_{k'} \cdot \hat{g}_1 \cdot \dots \cdot \hat{g}_\ell$ is a factorization of \hat{f} into irreducible factors. As $m(\hat{f}) < m(f)$, by the induction hypothesis the set S will contain the irreducible factors of \hat{f} . By the uniqueness of factorization, S will contain exactly the polynomials $\alpha_1 h_1, \dots, \alpha_{k'} h_{k'}$ and $\beta_1 \hat{g}_1, \dots, \beta_\ell \hat{g}_\ell$ for some $\{\alpha_i\}, \{\beta_j\} \subseteq \mathbb{F} \setminus \{0\}$. Consequently, the ‘for each’ loop separates the h_i -s from \hat{g}_j -s by gradually dividing f by the containment of S . Observe, that at the end of the loop we get that: $S = \{\alpha_1 h_1, \dots, \alpha_{k'} h_{k'}\}$, $T = \{\beta_1 \hat{g}_1, \dots, \beta_\ell \hat{g}_\ell\}$. Moreover, as $u = f = h_1 \cdot \dots \cdot h_{k'} \cdot g$ at the beginning of the loop and $\gcd(g, \hat{g}_j) = 1$ for every j , we get that $u = \frac{f}{\alpha_1 h_1 \cdot \dots \cdot \alpha_{k'} h_{k'}} = \frac{g}{\gamma}$ for some $\gamma \in \mathbb{F}$. Therefore, to complete the algorithm we need to compute the irreducible factors of u and concatenate them with S . Recall that by definition g (and hence u) is a product of at most two irreducible polynomials, both depending on x_n .

If $\deg_{x_n}(u) = \deg_{x_n}(g) = 1$ then u must be a single irreducible factor and thus $f = \alpha_1 h_1 \cdot \dots \cdot \alpha_{k'} h_{k'} \cdot u$ is a factorization of f into irreducible factors. Otherwise, $\deg_{x_n}(u) = \deg_{x_n}(g) = 2$ and there can be two cases. If u is irreducible, then again $f = \alpha_1 h_1 \cdot \dots \cdot \alpha_{k'} h_{k'} \cdot u$ is a factorization of f into irreducible factors and the algorithm will return this factorization since for every η_- and η_+ the identity test $u \stackrel{?}{=} \gamma \eta_+ \cdot \eta_-$ will fail. Otherwise, we can write u as a product of two irreducible polynomials, both depending on x_n . By Corollary 38 the discriminant polynomial Δ in Line 12 is computed successfully. As $\gamma u = g$ we have that $\hat{g} = \gamma a$. Consequently, we can write $u \cdot \hat{g}_1 \cdot \dots \cdot \hat{g}_\ell = u \cdot \hat{g} = u \cdot \gamma a = \gamma \eta_+ \cdot \eta_-$. As each \hat{g}_i is an irreducible polynomial, it must be the case that either $\hat{g}_i \mid \eta_+$ or $\hat{g}_i \mid \eta_-$. Thus, at Line 17 we have that $u = \gamma \eta_+ \cdot \eta_-$. We can easily compute γ by noting that $\text{lm}(u) = \text{lm}(\gamma \eta_+ \cdot \eta_-) = \gamma \text{lm}(\eta_+ \cdot \eta_-)$. In conclusion, $f = \alpha_1 h_1 \cdot \dots \cdot \alpha_{k'} h_{k'} \cdot \gamma \eta_+ \cdot \eta_-$ is a factorization of f into irreducible factors and the algorithm will return this factorization passing the identity test $u \stackrel{?}{=} \gamma \eta_+ \cdot \eta_-$.

The analysis of the base case $m(f) = 0$ is similar. First, note that if $u = f$ is irreducible then the algorithm will return $\{u\}$. Otherwise, we can write u as a product of two irreducible polynomials, both depending on x_n . By definition, $a \cdot u = \eta_+ \cdot \eta_-$. As $a \neq 0 \in \mathbb{F}$, $\gamma = \frac{\text{lm}(u)}{\text{lm}(\eta_+ \cdot \eta_-)} = \frac{\text{lm}(u)}{\text{lm}(a \cdot u)} = \frac{1}{a}$ and hence $u = \frac{1}{a} \eta_+ \cdot \eta_- = \gamma \eta_+ \cdot \eta_-$. In conclusion we get that in the base case, $f = \gamma \eta_+ \cdot \eta_-$ is a factorization of f into irreducible factors and the algorithm will return this factorization passing the identity test $u \stackrel{?}{=} \gamma \eta_+ \cdot \eta_-$. This completes the proof. \blacktriangleleft

5 Discussion & Open Questions

In this paper we study computations beyond a (single) exponentiation gate and present some applications, with the main one being the first efficient deterministic factorization algorithm for sparse multiquadratic polynomials over odd characteristics. Can we devise such algorithms for multicubic polynomials? Or more generally, when the individual degree of each variable is constant? One of the milestones on the route to this goal has to do with estimating the sparsity of the factors of such polynomials. To this end, we propose the following conjecture:

► **Conjecture 39.** *There exists a function $\nu : \mathbb{N} \rightarrow \mathbb{N}$ such that if $f \in \mathbb{F}[x_1, x_2, \dots, x_n]$ is a polynomial with individual degrees at most d then $g \mid f \implies \|g\| \leq \|f\|^{\nu(d)}$.*

Our results show that $\nu(1) = \nu(2) = 1$. As we noted before, the value of $\nu(3)$ is unknown. We also note that the conjecture gives rise to an efficient deterministic algorithm for testing sparse factorization into polynomials with constant individual degrees.

In addition, combined with the randomized factorization algorithm of [49], we can obtain an efficient factorization algorithm for such polynomial. Using Theorem 7 we can this algorithm zero-error, Las Vegas algorithm (i.e. ZPP-type).

Another milestone in sparse polynomial factorization is computing a root of a sparse polynomial. Theorem 8 allows us to test whether the polynomial f is an e -th root of the polynomial g . But can we actually compute f given g ? Once again, an upper bound on the corresponding sparsity could be useful. We can get the desired result by combining this bound with Theorem 3. We propose the following conjecture:

► **Conjecture 40.** *Suppose $\text{char}(\mathbb{F}) = 0$ or “large enough”. There exists a function $\mu : \mathbb{N} \rightarrow \mathbb{N}$ such that for every $f \in \mathbb{F}[x_1, x_2, \dots, x_n]$ and $e \in \mathbb{N}$: $\|f\| \leq \|f^e\|^{\mu(e)}$.*

Note even when $n = 1$, there exist sparse-square polynomials. That is, polynomials f such that $\|f^2\| < \|f\|$, implying that $\mu(2) > 1$. For more details see [13, 9] and references within.

In addition, Example 6.1 in [44] shows that when the field characteristic is close to the degree of the polynomial in question, even a square root of sparse polynomial could be very dense. Therefore, the bound could only hold for “large enough” (in terms of n, d etc..) characteristic. Finally, can we extend Theorem 8 to fields with “small” characteristics? Perhaps, by extending Lemma 48?

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A Sparse Polynomials with Constant Individual Degrees

In this section we present an efficient factorization testing algorithm for sparse polynomials with constant individual degrees. In particular, we prove Theorem 7. We begin by observing that a Subresultant (Definition 18) of two sparse polynomials with constant degrees is a (somewhat) sparse polynomial with a (slightly larger) constant degree.

► **Observation 41.** *Let $f, g \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be s -sparse polynomials with individual degrees at most d . Then for every $i \in [n]$ and $j \leq d$ the polynomial $S_{x_i}(j, f, g)$ is an $s^{\mathcal{O}(d)}$ -sparse polynomial with individual degrees at most $\mathcal{O}(d^2)$.*

► **Lemma 42.** *Let $f, g \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be s -sparse polynomials a let d be a bound on the individual degrees of f . Then there exists an algorithm that given f and g tests if $g \mid f$ using $\text{poly}(n, s^d, \log |\mathbb{F}|)$ field operations.*

Proof. For $i \in [n]$, let d_i and e_i denote the individual degrees of x_i in f and g , respectively. We can assume wlog that $\forall i : e_i \leq d_i \leq d$. Otherwise, the answer is, clearly, “no”. The algorithm will follow the procedure outlined in Corollary 20: Output “yes” iff $\forall i$ with $e_i > 0$: $S_{x_i}(e_i - 1, f, g) \equiv 0$.

The correctness follows immediately from Corollary 20. The running time follows from Observation 41. ◀

The efficient division algorithm gives rise to an efficient procedure for computing GCD given a list of sparse irreducible polynomials. Theorem 7 follows as a corollary of this result.

► **Theorem 43.** *Let $f, g_1, \dots, g_m \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be s -sparse polynomials a let d be a bound on the individual degrees of f . More over, let $g = \prod g_i$ and suppose that g_i -s are irreducible. Then given f, g_1, \dots, g_m , Algorithm 3 computes $\text{gcd}(f, g)$ using $\text{poly}(n, s^d, \log |\mathbb{F}|)$ field operations.*

Input: s -sparse polynomials $f, g_1, \dots, g_m \in \mathbb{F}[x_1, x_2, \dots, x_n]$
Output: e_1, \dots, e_m such that $\text{gcd}(f, g) = \prod g_i^{e_i}$

- 1 Use Corollary 29 to collect similar polynomials /* wlog $g = \prod_{i=1}^{m'} g_i^{e'_i}$ and $e'_i \leq d$,
where g_i are irreducible, pairwise coprime factors */
- 2 For each $i \in [m']$ find the maximal $e_i, 0 \leq e_i \leq e'_i$ such that $g_i^{e_i} \mid f$. /* Using
Lemma 42 */

Algorithm 3: Compute the GCD of sparse polynomials with constant individual degrees.

Proof. The claim regarding the running time follows from Corollary 29 and Lemma 42. Since g_i 's are irreducible polynomials, there exist a subset S such that $g \sim \prod_{g_i \in S} g_i^{e'_i}$. Therefore, $\text{gcd}(f, g)$ will be of the form $\prod_{g_i \in S} g_i^{e_i}$ for some $e_i \leq e'_i$. As d is a bound on the individual degrees of f , we get that $e_i \leq d$. ◀

B

Deterministic Reconstruction Algorithm for Multilinear $\Sigma\Pi\Sigma\Pi(2)$ Circuits

In this section we prove Theorem 5. We build on the following result of Gupta et al. [16]:

► **Lemma 44** (Implicit in [16]). *Let $n, s \in \mathbb{N}$. Let A be an algorithm that given an oracle access to an s -sparse split polynomial $f \in \mathbb{F}[x_1, x_2, \dots, x_n]$ output its irreducible factors using $T(n, s)$ operations. Then there exists a deterministic algorithm that given an oracle access to the polynomial $f \in \mathbb{F}[x_1, x_2, \dots, x_n]$ computable by a multilinear $\Sigma\Pi\Sigma\Pi(2)$ circuit of size s and uses $\text{poly}(n, s, \log |\mathbb{F}|, T(n, s))$ field operations and oracles calls to A , and outputs a $\Sigma\Pi\Sigma\Pi(2)$ circuit that computes f .*

Originally, they invoke the randomized black-box factorization algorithm of Kaltofen & Trager [23] along with Lemma 28 to obtain an efficient randomized reconstruction algorithm. We are able to derandomize the reconstruction algorithm by extending Algorithm 2 to handle

s-sparse split polynomials. These are polynomials that can be written as products of *s*-sparse (not necessarily irreducible) polynomials. Note that an *s*-sparse split polynomial need not be sparse. To this end, we require the following Folklore results. (See e.g. [48], [12], [40] and reference within).

► **Lemma 45 (Folklore).** *Let $f \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be a polynomial of degree d and let $i \in [n]$. We can write: $f = \sum_{j=0}^d f_j \cdot x_i^j$ such that $\forall j, x_i \notin \text{var}(f_j)$. Then there exists a deterministic algorithm that given i, j and an oracle access to f uses $\text{poly}(n, d, \log |\mathbb{F}|)$ field operations and outputs an oracle for f_j .*

To handle a division of *s*-sparse split polynomials we will need a *s*-sparse version of Corollary 33. We give a somewhat stronger statement: a black-box version of Lemma 42.

► **Lemma 46.** *Let $n, s, d \in \mathbb{N}$. Let $f \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be an *s*-sparse split polynomial with individual degrees at most d . There exists an algorithm that given an oracle access to f and an irreducible *s*-sparse polynomial $g \in \mathbb{F}[x_1, x_2, \dots, x_n]$ with individual degrees at most d uses $\text{poly}(n, s^{d^2}, \log |\mathbb{F}|)$ field operations and computes the quotient polynomial of f and g . That is, if $f = gh$ for some $h \in \mathbb{F}[x_1, x_2, \dots, x_n]$ then the algorithm outputs an oracle for h . Otherwise, the algorithm rejects.*

Proof. We can write $f = f' \cdot u$ where f' is the product of all the irreducible factors of f that depend on x_i . In addition, we can write $f' = \sum_{j=0}^d f'_j \cdot x_i^j$ such that $\forall j, x_i \notin \text{var}(f'_j)$. Clearly, f' is s^d sparse and u is *s*-sparse split. Using Lemma 45, we can obtain oracles for $f'_j \cdot u$. For $i \in [n]$, let d_i and e_i denote the individual degrees of x_i in f and g , respectively. We can determine d_i using Lemma 31. Hence, we can assume wlog that $\forall i : e_i \leq d_i \leq d$. Otherwise, the answer is, clearly, “no”. The algorithm will follow the procedure outlined in Corollary 20: Output “yes” iff $\forall i$ with $e_i > 0$: $S_{x_i}(e_i - 1, f, g) \equiv 0$ using Lemma 45 to perform the test. The correctness follows immediately from Corollary 20. For the running time, by Lemma 19, $S_{x_i}(e_i - 1, f, g) = S_{x_i}(e_i - 1, f', g) \cdot u^{e_i}$. $S_{x_i}(e_i - 1, f', g)$ is a determinant of a $(d_i - e_i + 2) \times (d_i - e_i + 2)$ matrix whose entries are s^d -sparse polynomials with individual degrees at most d resulting in an $s^{\mathcal{O}(d^2)}$ -sparse polynomial with individual degrees at most $\mathcal{O}(d^3)$. Therefore, we can compute the expression using Lemmas 31 and 45. ◀

Based on the above we can now prove the *s*-sparse split version of Theorem 6.

► **Theorem 47.** *Let $n, s \in \mathbb{N}$ and suppose $\text{char}(\mathbb{F}) \neq 2$. There exists a deterministic algorithm that given an oracle access to an *s*-sparse split multiquadratic polynomial $f(\bar{x}) \in \mathbb{F}[x_1, x_2, \dots, x_n]$ and a square root oracle R_2 uses $\text{poly}(n, s, \log |\mathbb{F}|)$ field operations and oracle calls to R_2 and outputs the irreducible factors of $f(\bar{x})$. That is, a list h_1, \dots, h_k of irreducible polynomials such that $f = h_1 \cdot \dots \cdot h_k$.*

Proof. By definition, $f = h_1 \cdot \dots \cdot h_k$. By Lemma 32, we can assume wlog that h_i -s are irreducible and are, in fact, the irreducible factors of f . Therefore, we can invoke Algorithm 2 with the following minor changes:

- In Line 1, use Lemma 45 to compute \hat{f} .
- In Line 5, use the algorithm of Lemma 46 with $d = 2$ instead of Corollary 33.
- In Line 11, use Lemma 28 to reconstruct u as an s^2 -sparse polynomial.

The analysis of the algorithms essentially remains the same. Note that these change introduces only a polynomial overhead to sparsities of the intermediate polynomials (and thus to the algorithm). Yet, as was established above, the irreducible factors are *s*-sparse. ◀

Theorem 5 follows by applying Theorem 47 to Lemma 44.

C Polynomial Identity Testing beyond an Exponentiation Gate

Using techniques from Differential Field Theory we show how to transform an identity test of powers of polynomials into an identity test that involves partial derivatives of those same polynomials. This transformation can be applied for classes of polynomials that are closed under partial derivatives such as sparse polynomials.

► **Lemma 48.** *Let $f(\bar{x}), h(\bar{x}) \not\equiv 0 \in \mathbb{F}(x_1, x_2, \dots, x_n)$ and let $e, d \in \mathbb{N}$. There exists $c(\bar{x}) \in \mathbb{F}(x_1, x_2, \dots, x_n)$ such that $f(\bar{x})^d = c(\bar{x}) \cdot h(\bar{x})^e$ and $\frac{\partial c}{\partial x_i} \equiv 0$ iff $d \cdot h \cdot \frac{\partial f}{\partial x_i} = e \cdot f \cdot \frac{\partial h}{\partial x_i}$.*

Proof.

(\Rightarrow) Suppose $f(\bar{x})^d = c(\bar{x}) \cdot h(\bar{x})^e$. Then $d \cdot h \cdot \frac{\partial f}{\partial x_i} = \frac{h}{f^{d-1}} \cdot \frac{\partial(f^d)}{\partial x_i} = \frac{h}{f^{d-1}} \cdot c(\bar{x}) \cdot e \cdot \frac{\partial h}{\partial x_i} \cdot h(\bar{x})^{e-1} = e \cdot c(\bar{x}) \cdot \frac{h(\bar{x})^e}{f^{d-1}} \cdot \frac{\partial h}{\partial x_i} = e f \cdot \frac{\partial h}{\partial x_i}$.

(\Leftarrow) Consider $c \stackrel{\Delta}{=} \frac{f^d}{h^e}$. By definition: $\frac{\partial c}{\partial x_i} = \frac{1}{h^{2e}} \cdot \left(d \cdot \frac{\partial f}{\partial x_i} \cdot f^{d-1} \cdot h^e - e \cdot \frac{\partial h}{\partial x_i} \cdot h^{e-1} \cdot f^d \right) = \frac{f^{d-1}}{h^{e+1}} \cdot \left(d \cdot \frac{\partial f}{\partial x_i} \cdot h - e \cdot \frac{\partial h}{\partial x_i} \cdot f \right) \equiv 0$ and the claim follows. ◀

The following theorem provides an algorithm for an identity testing of powers of polynomials over fields with zero or large enough characteristics.

► **Theorem 49.** *Let $f(\bar{x}), h(\bar{x}) \not\equiv 0 \in \mathbb{F}[x_1, x_2, \dots, x_n]$ be polynomials of degree at most δ and let $e, d \in \mathbb{N}$. Furthermore, suppose that $p \stackrel{\Delta}{=} \text{char}(\mathbb{F}) = 0$ or $p > \delta \cdot \min(e, d)$. Then $f(\bar{x})^d = h(\bar{x})^e$ iff $\text{lm}(f)^d = \text{lm}(h)^e$ and for each $i \in [n]$ we have that $d \cdot h \cdot \frac{\partial f}{\partial x_i} = e \cdot f \cdot \frac{\partial h}{\partial x_i}$.*

Proof.

(\Rightarrow) Follows from Lemma 48 and the definition of lm .

(\Leftarrow) By iterative application of Lemma 48 we get that there exists $c(\bar{x}) \in \mathbb{C}(\mathbb{F}(x_1, x_2, \dots, x_n))$ such that $f(\bar{x})^d = c(\bar{x}) \cdot h(\bar{x})^e$. We claim that $c(\bar{x}) \in \mathbb{F}$. Assume the contrary. Then, by Lemma 13 $p > 0$ and there exist $u(\bar{x}), v(\bar{x}) \in \mathbb{F}[x_1^p, x_2^p, \dots, x_n^p]$ such that $\text{gcd}(u, v) = 1$ and $c(\bar{x}) = \frac{u(\bar{x})}{v(\bar{x})}$. Therefore, we can write: $f(\bar{x})^d \cdot v(\bar{x}) = h(\bar{x})^e \cdot u(\bar{x})$. By definition $\text{lm}(f)^d \cdot \text{lm}(v) = \text{lm}(h)^e \cdot \text{lm}(u)$, which implies that $\text{lm}(v) = \text{lm}(u)$. In particular, $v(\bar{x}), u(\bar{x}) \notin \mathbb{F}$ as $c(\bar{x}) \notin \mathbb{F}$ and thus $\text{deg}(u), \text{deg}(v) \geq p$. Assume wlog that $d \leq e$. Then $p > \delta d$. As $\text{gcd}(u, v) = 1$ we get that $u \mid f^d$ which implies that $p \leq \delta d$ thus leading to a contradiction. Therefore, $c(\bar{x}) = \alpha \in \mathbb{F}$. By definition $\text{lm}(f)^d = \alpha \cdot \text{lm}(h)^e$, which implies that $\alpha = 1$ and we are done. ◀

Theorem 8 follows as an easy corollary by noting that the preconditions of Theorem 49 can be efficiently checked given two sparse polynomials. It is also to be noted that similar characterization could be obtained by considering the 2×2 Wronskian of the polynomials f^d and h^e . However, we believe that our proof is cleaner and more direct.

D Missing Proofs

Proof of Lemma 15.

1. If $h \equiv 0$ then clearly $g \equiv 0$ and the claim follows. Otherwise, let $h = h_1^{e_1} \cdot \dots \cdot h_k^{e_k}$ and $g = g_1^{e'_1} \cdot \dots \cdot g_{k'}^{e'_{k'}}$ be factorizations of h and g into irreducible, pairwise coprime factors, respectively. We have that $h_1^{e_1 \cdot e} \cdot \dots \cdot h_k^{e_k \cdot e} = h^e = g^e = g_1^{e'_1 \cdot e} \cdot \dots \cdot g_{k'}^{e'_{k'} \cdot e}$ are two factorizations of the same non-zero polynomial. By Lemma 14, $k = k'$ and, wlog $h_i \sim g_i$ and $e_i = e'_i$. Consequently, $h = \omega \cdot g$ for some $\omega \in \mathbb{F}$. Finally, $h^e = \omega^e \cdot g^e = \omega^e \cdot h^e$ and the claim follows.

2. First, note that $h(\bar{a})^e = f(\bar{a}) \neq 0$ and thus $h(\bar{a}) \neq 0$. Let us consider $u(\bar{x}) \triangleq \frac{\alpha h(\bar{x})}{h(\bar{a})}$. By definition, $u(\bar{a}) = \frac{\alpha h(\bar{a})}{h(\bar{a})} = \alpha$ and $u(\bar{x})^e = \frac{\alpha^e h(\bar{x})^e}{h(\bar{a})^e} = \frac{f(\bar{a})f(\bar{x})}{f(\bar{a})} = f(\bar{x})$. Now, suppose there exists a polynomial $v(\bar{x}) \in \mathbb{F}[x_1, x_2, \dots, x_n]$ satisfying the same properties. By the first part of the Lemma we have that $u = \omega \cdot v$ for some $\omega \in \mathbb{F}$. Therefore, $\alpha = u(\bar{a}) = \omega \cdot v(\bar{a}) = \omega \cdot \alpha$ implying that $\omega = 1$. Consequently, $u = v$. ◀

Proof of Lemma 24. Let (g_1, \dots, g_d) be as above. Consider the polynomial $h \triangleq \prod_{e|i} g_i^{i/e}$.

We have that: $h^e = \prod_{e|i} g_i^i = \prod_i g_i^i = g$ when the last equality follows from the property of g_i and we are done. For the other direction, let $g = h^e$ and let (h_1, \dots, h_d) be the squarefree decomposition of $h(y)$. Consider the following sequence:

$$\hat{g}_i = \begin{cases} h_{i/e} & e | i \\ 1 & \text{otherwise} \end{cases}$$

We have that

$$\prod_i \hat{g}_i^i = \prod_{e|i} h_{i/e}^i = \prod_j h_j^{j \cdot e} = \left(\prod_j h_j^j \right)^e = h^e = g.$$

In addition, $(\hat{g}_1, \dots, \hat{g}_d)$ is a sequence of pairwise coprime, squarefree polynomials. By uniqueness, the sequence $(\hat{g}_1, \dots, \hat{g}_d)$ is squarefree decomposition of g and the claim follows. ◀