

Decision Problems for Linear Logic with Least and Greatest Fixed Points

Anupam Das ✉

University of Birmingham, UK

Abhishek De ✉

IRIF, CNRS, Université Paris Cité & INRIA, France

Alexis Saurin ✉

IRIF, CNRS, Université Paris Cité & INRIA, France

Abstract

Linear logic is an important logic for modelling resources and decomposing computational interpretations of proofs. Decision problems for fragments of linear logic exhibiting “infinitary” behaviour (such as exponentials) are notoriously complicated. In this work, we address the decision problems for variations of linear logic with fixed points (μ MALL), in particular, recent systems based on “circular” and “non-wellfounded” reasoning. In this paper, we show that μ MALL is undecidable.

More explicitly, we show that the general non-wellfounded system is Π_1^0 -hard via a reduction to the non-halting of Minsky machines, and thus is strictly stronger than its circular counterpart (which is in Σ_1^0). Moreover, we show that the restriction of these systems to theorems with only the least fixed points is already Σ_1^0 -complete via a reduction to the reachability problem of alternating vector addition systems with states. This implies that both the circular system and the finitary system (with explicit (co)induction) are Σ_1^0 -complete.

2012 ACM Subject Classification Theory of computation \rightarrow Linear logic; Theory of computation \rightarrow Proof theory; Theory of computation \rightarrow Complexity theory and logic

Keywords and phrases Linear logic, fixed points, decidability, vector addition systems

Digital Object Identifier 10.4230/LIPIcs.FSCD.2022.20

Related Version *Full Version:* <https://hal.archives-ouvertes.fr/hal-03655651>

Funding *Anupam Das:* This author is supported by a UKRI Future Leaders Fellowship, *Structure vs. Invariants in Proofs*, project reference MR/S035540/1.

Abhishek De: This author has received funding from the European Union’s Horizon 2020 research and innovation programme under the Marie Skłodowska-Curie grant agreement No 754362.

Alexis Saurin: This author has been partially supported by ANR project *RECIPROG*, project reference ANR-21-CE48-019-01.

Acknowledgements We would like to thank anonymous reviewers for their valuable comments that enhanced the clarity and presentation of this paper. We also thank Sylvain Schmitz for his insights on alternating vector addition systems.

1 Introduction

Fixed point theory occurs in just about every field of computer science, including program analysis [30], game theory [10, 46], automata theory [33, 47], and programming language theory [53]. In the setting of fixed point logics, the (multi)modal μ -calculus (the extension of basic modal logic K with least and greatest fixed point operators) is probably the most well-studied. The most important result in this direction is the obtention of completeness of Hilbert-style axiomatisations for the logic [33, 59, 58]. Another relevant case study is that of



© Anupam Das, Abhishek De, and Alexis Saurin;
licensed under Creative Commons License CC-BY 4.0

7th International Conference on Formal Structures for Computation and Deduction (FSCD 2022).

Editor: Amy P. Felty; Article No. 20; pp. 20:1–20:20

Leibniz International Proceedings in Informatics



LIPICs Schloss Dagstuhl – Leibniz-Zentrum für Informatik, Dagstuhl Publishing, Germany

Kleene Algebra (and extensions) where basic algebraic structures are extended by a “Kleene star” modelling iteration. Such theories have similarly received axiomatisations that have been proved complete (over relational and language models) [32, 35, 9, 22].

These formalisations employ inference rules that express an *explicit* (co)induction scheme *i.e.* the induction invariant must be provided explicitly. However, more recently both these settings have received proof-theoretic developments allowing for an implicit treatment of (co)induction, by way of “non-wellfounded” and “circular” reasoning [48, 1, 16]. Such systems admit greater proof-theoretic expressivity while, at the same time, reinforcing connections between these logics and automata theory. Evidence of their utility has been duly provided in recent works that recover the aforementioned completeness results using entirely proof-theoretic (as opposed to automata theoretic) methods, in particular [1], building on [48], in the case of the μ -calculus, and [15], building on [16], in the case of Kleene algebra.

In a parallel direction, the extension of fragments of *linear logic* by fixed points has become increasingly developed in the last 15 years. Baelde and Miller [5, 2] developed a finitary deductive system for first-order linear logic with least and greatest fixed points. Santocanale was the first to propose a circular system in this area, in particular for an extension of “lattice logic” by fixed points in [51], and later with Fortier proved a form of cut-elimination [25]. Baelde, Doumane and Saurin in [4] extended both the system and the cut-elimination result to the full propositional fragment of Baelde and Miller’s logic, now yielding three systems: $\mu\text{MALL}^{\text{ind}}$ (based on explicit (co)induction), μMALL^{∞} (based on non-wellfounded reasoning) and μMALL^{ω} (based on circular reasoning).

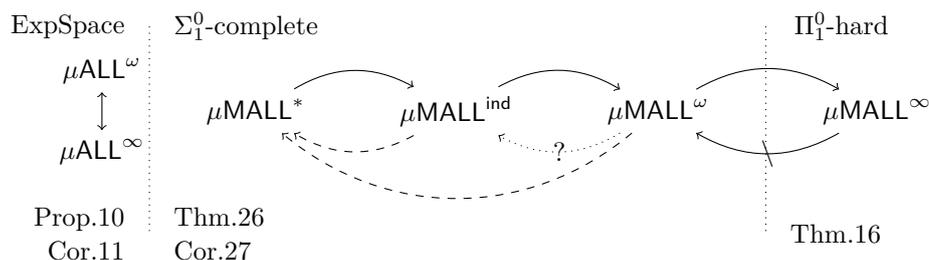
In terms of expressivity, μMALL can be seen as an amalgamation of the properties of μ -calculus and Kleene Algebras. Like Kleene Algebras, μMALL is also “resource-conscious” (indeed, Kleene Algebra and extensions are just fragments of a non-commutative μMALL); and like the μ -calculus, μMALL also allows for unrestricted interleaving of fixed points.

In this work, we study systems for μMALL in terms of proof-theoretic strength, in particular asking whether a system is *conservative* over another. A pertinent observation at this juncture is that the aforementioned techniques for the μ -calculus and Kleene algebra for comparing such systems seem to break down in the more general setting of substructural logics. Indeed, in this work, we shall show that they do *not* hold *per se*, by addressing the complexity of deciding theorems of μMALL^{∞} and μMALL^{ω} . In particular, we show that provability in μMALL^{∞} is Π_1^0 -hard, *i.e.* at least co-recursively enumerable. Our proof method is based on an encoding of Minsky machines that is inspired by a previous work of Kuznetsov [37]. Since μMALL^{ω} is a calculus of finite (recursively checkable) proofs, and so is in Σ_1^0 , this in particular implies that it proves strictly fewer theorems than μMALL^{∞} .

Our second main result is that μMALL^* , the fragment of μMALL restricted to only least fixed points (on which all three aforementioned systems coincide), is Σ_1^0 -complete and consequently, undecidable. We use Lincoln’s idea of encoding alternating vector addition systems which he originally employed to prove the undecidability of full linear logic [41]. However, in the absence of exponentials, we have had to reinvent the encoding.

The resulting relationships between the systems we consider in this work are summarised in Figure 1.

Organization of the paper. This paper is organised as follows. In Section 2 we motivate our work from the point of view of “regularisation”, *i.e.* the transformation of a non-wellfounded proof into a circular one. We describe the syntax and relevant properties of μMALL in Section 3 and show regularisation in the additive fragment. In Section 4.1, we prove our first main result that μMALL^{∞} is Π_1^0 -hard (and thus, in general, non-regularisable). In Section 5,



■ **Figure 1** Relationships between systems in this work. Solid arrows \rightarrow denote inclusion, dashed arrows denote conservative extensions, negated arrows $\not\rightarrow$ denote non-inclusion.

we give our second main result, that μMALL^* is Σ_1^0 -complete. Finally, in Section 6, we conclude and discuss some directions of future work. Additional material, discussions and proof details can be found in an extended version of this paper [14].

2 Motivation: regularisation techniques are not logic-independent

Non-wellfounded systems for logics such as the μ -calculus [1, 17, 21, 48], and in our case μMALL [4], handle least (“ μ ”) and greatest (“ ν ”) fixed points by identical rules:

$$\text{Fixed point rules: } \frac{\Gamma, \phi(\mu X.\phi(X))}{\Gamma, \mu X.\phi(X)} \mu \qquad \frac{\Gamma, \phi(\nu X.\phi(X))}{\Gamma, \nu X.\phi(X)} \nu \qquad (1)$$

Here Γ (a “sequent”) is a list, set or multiset of formulas and the comma is to be read as a form of disjunction, all depending on the logic at hand. To distinguish the two fixed points, non-wellfounded proofs impose a certain global correctness condition; informally speaking, each infinite branch must have a “critical” ν -formula that is unfolded infinitely often (a formal definition is given in the next section). This corresponds to a sort of “infinite descent” argument that mimics inductive reasoning on the fixed point. At least one motivation for our work is to understand when, in general, we can transform a non-wellfounded proof tree into one that is *regular*, i.e. one that has finitely many distinct subtrees, and so may be written as a finite directed (cyclic) graph.

Regularising μ -calculus is easy. In the case of the modal μ -calculus, a simple proof system is readily obtained by extending (multi)modal logic K (cf., e.g., [6]) by the rules in Equation (1). The induced (cut-free) calculus enjoys a certain generalisation of the subformula property (the “Fischer-Ladner closure”) meaning that only finitely many distinct sequents may occur in a proof. As a result, once a particular sequent to be proved is fixed, the aforementioned global correctness criterion becomes an ω -regular property on infinite branches. This allows us to reduce *regular* completeness of the system to *non-wellfounded* completeness of the system, thanks to Rabin’s basis theorem [50]. This idea is implicit in Niwinski and Walukiewicz’s seminal work [48].

This reduction is, a priori, non-constructive: it asserts the existence of a regular proof but does not tell us how to construct one from a given non-wellfounded one. However it is possible to define a constructive such procedure that “cuts” branches of an infinite proof tree to transform it into a regular one, using automata-theoretic techniques.

20:4 Decision Problems for Linear Logic with Least and Greatest Fixed Points

Structural rules:	$\frac{}{\phi, \phi^\perp} \text{id}$	$\frac{\Gamma_1, \phi \quad \Gamma_2, \phi^\perp}{\Gamma_1, \Gamma_2} \text{cut}$	$\frac{\Gamma, \phi_2, \phi_1, \Delta}{\Gamma, \phi_1, \phi_2, \Delta} \text{ex}$	
Logical rules:	$\frac{\Gamma, \phi_1, \phi_2}{\Gamma, \phi_1 \wp \phi_2} \wp$	$\frac{\Gamma_1, \phi_1 \quad \Gamma_2, \phi_2}{\Gamma_1, \Gamma_2, \phi_1 \otimes \phi_2} \otimes$	$\frac{\Gamma, \phi_i}{\Gamma, \phi_1 \oplus \phi_2} \oplus_i$	$\frac{\Gamma, \phi_1 \quad \Gamma, \phi_2}{\Gamma, \phi \& \phi_2} \&$
Logical rules (units):	$\frac{}{\mathbf{1}} \mathbf{1}$	$\frac{\Gamma}{\Gamma, \perp} \perp$	$\frac{}{\Gamma, \top} \top$	No rule for $\mathbf{0}$

■ **Figure 2** Inference rules for MALL, where $i \in \{1, 2\}$.

Regularisation not possible (in general) in predicate settings. The situation is considerably different in predicate logics with (co)induction or fixed points, e.g. [7, 8, 54]. There neither is cut eliminable in general, nor are proofs regularisable in general, due to infinitely many choices available when instantiating existentials by terms. Indeed both of these observations have recently been demonstrated formally for cyclic systems corresponding to fragments of Peano Arithmetic [13].

The trouble with structural rules. Returning to the propositional setting, at first glance the regularisation argument for the μ -calculus is rather general, relying only on the finitude of sequents occurring in a proof to obtain ω -regularity of the global correctness criterion. However, such finitude of sequents is a rather peculiar property in structural proof theory at large. For the μ -calculus this is a consequence of the underlying classical framework: the admissibility of contraction (duplicating formulas) and weakening (deleting formulas) allows us to limit the number of formula repetitions in a sequent.

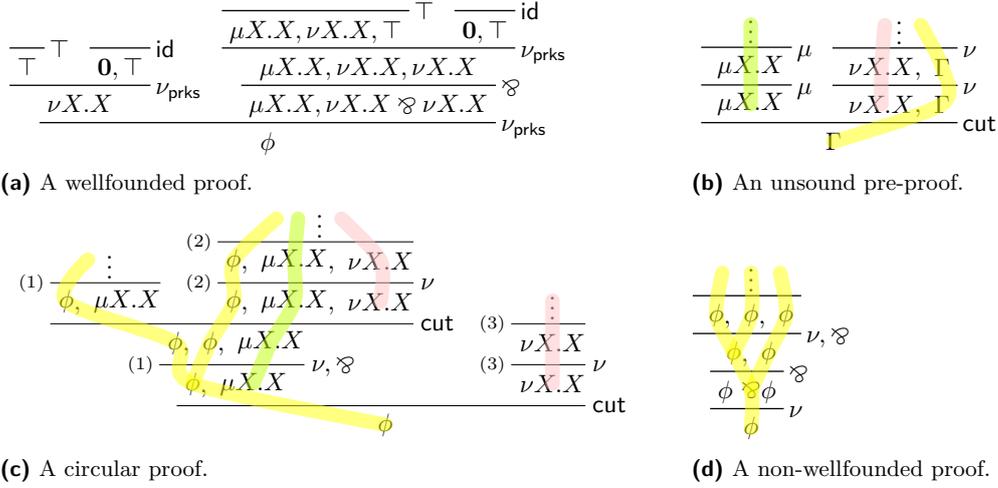
Substructural logics are logics lacking at least one of the usual structural rules. Decidability of substructural logics is often very difficult [34, 57, 38]. In *linear logic* [28], one of the most well-studied substructural logics, sequents are effectively multisets and the use of contraction and weakening is carefully controlled. Conjunction and disjunction each have two versions in linear logic: *multiplicative* and *additive*.

	conjunction	disjunction	true	false
multiplicative	\otimes	\wp	$\mathbf{1}$	\perp
additive	$\&$	\oplus	\top	$\mathbf{0}$

The logical system thus obtained is called multiplicative-additive linear logic (MALL) and its inference rules are depicted in Figure 2 (sequents being construed as finite lists). Note that, despite the absence of structural rules weakening and contraction, *cut-admissibility* implies that all sequents in a proof have size bounded by that of the conclusion and that the proof search space has only polynomial depth; thus provability is in PSpace (in fact, MALL is PSpace-complete [43]).

Full linear logic extends MALL by incorporating certain “exponential” modalities, written $?\phi$ and, dually, $!\phi$. Structural rules are recovered in the case of $?\phi$, and the resulting logic is undecidable [43]. This is because allowing structural rules only on certain formulas can lead to sequents of unbounded size during proof search. Notably, decidability of multiplicative exponential linear logic (MELL) is still an open question¹ [42, 55].

¹ In [43], non-commutative MELL *i.e.* the fragment without the exchange rule has been proved to be undecidable.



■ **Figure 3** Various shapes of proof trees for μMALL . Here $\phi = \nu X.X \wp X$. Rules marked (i) , for $i \in \{1, 2, 3\}$, are roots of identical subtrees.

Adding the fixed point rules from Equation (1) to MALL leads to a similar issue, and there is no general way to arrive at such a bound on the set of sequents during proof search. This not only makes decidability of provability non-trivial, but also regularisation of non-wellfounded proofs.

3 Preliminaries

3.1 μMALL : multiplicative additive linear logic with fixed points

In this subsection we recall the system μMALL^∞ introduced in [4].

► **Definition 1.** Fix a countable set of propositional constants $\mathcal{A} = \{A, B, \dots\}$ and variables $\mathcal{V} = \{X, Y, \dots\}$ such that $\mathcal{A} \cap \mathcal{V} = \emptyset$. μMALL pre-formulas are given by the grammar:

$$\phi, \psi ::= \mathbf{0} \mid \top \mid \perp \mid \mathbf{1} \mid A \mid A^\perp \mid X \mid \phi \wp \psi \mid \phi \otimes \psi \mid \phi \oplus \psi \mid \phi \& \psi \mid \mu X.\phi \mid \nu X.\phi$$

where $A \in \mathcal{A}$, $X \in \mathcal{V}$, and μ, ν bind the variable X in ϕ . Free and bound variables, and capture-avoiding substitution are defined as usual. The subformula ordering is denoted \leq . When a pre-formula is closed (i.e. no free variables), we simply call it a **formula**.

Negation, $(\bullet)^\perp$, defined as a meta-operation on pre-formulas, will be used only on formulas. As it is not part of the syntax, we do not need any positivity condition on the fixed-point expressions. As expected, least and greatest fixed-points are the dual of each other.

► **Definition 2.** Negation of a pre-formula is defined inductively as follows.

$$\begin{aligned} (\mathbf{0})^\perp &= \top; & (\top)^\perp &= \mathbf{0}; & (\perp)^\perp &= \mathbf{1}; & (\mathbf{1})^\perp &= \perp; & (A)^\perp &= A^\perp; & (A^\perp)^\perp &= A; \\ (X)^\perp &= X; & (\phi \wp \psi)^\perp &= \phi^\perp \otimes \psi^\perp; & (\phi \otimes \psi)^\perp &= \phi^\perp \wp \psi^\perp; & (\phi \oplus \psi)^\perp &= \phi^\perp \& \psi^\perp; \\ (\phi \& \psi)^\perp &= \phi^\perp \oplus \psi^\perp; & (\mu X.\phi)^\perp &= \nu X.\phi^\perp; & (\nu X.\phi)^\perp &= \mu X.\phi^\perp. \end{aligned}$$

The system is classical, hence, it is enough to consider a one-sided proof system. However, as discussed in Section 2 it is imperative to allow multiple copies of the same formula in a sequent. A one-sided μMALL sequent is thus a finite list of formulas.

► **Definition 3.** A **pre-proof** of μMALL^∞ is a possibly infinite tree generated from the inference rules of MALL (see Figure 2) and the fixed point rules from Equation (1).

Let us recall some standard terminology relating to inference rules [11]. The sequent(s) in a rule displayed above the line are **premise(s)** and the unique sequent below the line is the **conclusion**. In a logical or fixed point rule, the **principal formula** is the distinguished formula occurrence in its conclusion in Equation (1) or Figure 2. **Auxiliary formulas** are the formula occurrences distinguished in the premise(s). Other formula occurrences in logical or fixed point rules are **side formulas**.

► **Definition 4.** Given a pre-proof π , for all rules r occurring in π , we define the **immediate ancestor** relation $\text{IA}(r)$ on formula occurrences of r by: $(\phi, \psi) \in \text{IA}(r)$ if ϕ is principal and ψ is auxiliary; or ϕ is a side formula occurrence in the conclusion and ψ is the corresponding side formula occurrence in a premise; or r is structural and ϕ is a formula occurrence in the conclusion and ψ is the corresponding formula occurrence in a premise.

Several examples of pre-proofs can be found in Figure 3. Immediate ancestors are indicated by the same colour (note that immediate ancestors always “go upwards”).

One of the key caveats of non-wellfounded pre-proofs is that, unconstrained, they admit inconsistencies: it is possible to derive any sequent, as shown in Figure 3b. For this reason we impose a global criterion on pre-proofs.

► **Definition 5** ([4]). Let $\beta = (\Gamma_i)_{i < \omega}$ be an infinite branch of a μMALL^∞ pre-proof π and let r_i be the rule with conclusion Γ_i . A **thread** of β is given by $k \in \mathbb{N}$ and a sequence of formula occurrences $\{\phi_i\}_{k < i < \omega}$ such that, for $k < i < \omega$, we have $(\phi_i, \phi_{i+1}) \in \text{IA}(r_i)$.

A thread τ is **progressing** if: it is infinitely often principal; and, the smallest formula occurring infinitely often in τ is a ν -formula.²

π is called a **proof** if every infinite branch has a progressing thread.

For example, in Figure 3b, while the right infinite branch has a progressing thread along $\nu X.X$ (indicated red), the left branch has no progressing thread, so the pre-proof is not a proof. Figure 3d is indeed a proof, assuming, say, each ν step has the left-most ϕ occurrence principal. In this work we shall crucially make use of the *admissibility* of cut in μMALL^∞ :

► **Theorem 6** ([4, 3, 19]). Every provable μMALL^∞ sequent has a cut-free proof.

Finally, we consider a fragment of pre-proofs that have a finite presentation.

► **Definition 7.** A μMALL^∞ pre-proof is said to be **circular** (aka **regular**) if it has finitely many distinct sub-trees. The class of circular proofs is denoted by μMALL^ω .

Figure 3c is a regular pre-proof. In fact, it is a proof; any infinite branch must either loop on one of (1), (2) or (3), whence there is an infinite progressing thread on ϕ (indicated yellow), $\nu X.X$ (indicated red) or $\nu X.X$ (indicated red) respectively, or it alternates between (1) and (2) infinitely often, whence there is an infinite progressing thread (indicated yellow) on ϕ .

Importantly, given a regular pre-proof π , we can decide whether it is a proof by reduction to the universality of non-deterministic parity ω -word automata, cf. [48, 18, 21]. Observe that ν -unfoldings are the source of infiniteness in proofs: with only μ -unfoldings, no infinite branch may have a progressing thread. So ν -free proofs, *i.e.* proofs without any ν s, are necessarily finite. Let us call this class of proofs μMALL^* ; clearly, $\mu\text{MALL}^* \subseteq \mu\text{MALL}^\omega \subseteq \mu\text{MALL}^\infty$.

² A “smallest” formula must exist along a thread, since immediate ancestry is compatible with the Fischer-Ladner pre-order, cf. [24] (see also [56, 21]). By construction this formula is unique and, furthermore, is a subformula of all other infinitely occurring formulas in τ .

$$\frac{\Gamma, \psi \quad \bullet \frac{\psi^\perp, \phi(\psi) \quad \phi^\perp(\psi^\perp), \nu X.\phi(X)}{\psi^\perp, \nu X.\phi(X)} \text{cut}}{\nu X.\phi(X), \Gamma} \text{cut}$$

$$\frac{\bullet \frac{\psi^\perp, \nu X.\phi(X)}{\phi^\perp(\psi^\perp), \phi(\nu X.\phi(X))} \text{cut}}{\phi^\perp(\psi^\perp), \phi(\nu X.\phi(X))} \phi$$

$$\frac{\psi^\perp, \nu X.\phi(X)}{\nu X.\phi(X), \Gamma} \text{cut}$$

■ **Figure 4** A (logic-independent) simulation of the Park’s rule in circular proofs. The steps marked ϕ are given by “functoriality” or “deep inference” with respect to the positive formula $\phi(X)$.

Although the focus of the paper are these systems, we briefly discuss $\mu\text{MALL}^{\text{ind}}$, the wellfounded system with explicit coinduction. The system has the same set of inference rules as Definition 3 except the rule for the greatest fixed-point which is replaced by the so-called *Park’s rule*, implementing a form of (co)induction:

$$\frac{\Gamma, \psi \quad \psi^\perp, \phi(\psi)}{\Gamma, \nu X.\phi(X)} \nu_{\text{prks}}$$

We exhibit a $\mu\text{MALL}^{\text{ind}}$ proof in Figure 3a. We still have that $\mu\text{MALL}^* \subseteq \mu\text{MALL}^{\text{ind}}$, and it is not hard to see that $\mu\text{MALL}^{\text{ind}} \subseteq \mu\text{MALL}^\omega$ as shown in Figure 4.

The opposite direction *i.e.* the question of equiprovability of $\mu\text{MALL}^{\text{ind}}$ and μMALL^ω is a manifestation of the so-called *Brotherston-Simpson conjecture* in the setting of μMALL [8] and is a difficult open question.

3.2 Focusing

In structural proof theory, focused proofs are a family of proofs that have more structure than usual sequent calculus proofs. The additional structure brought by focusing will be crucial in the next sections in order to extract traces of execution in the computational models that we consider. We describe focused proofs as a complete, proper class of μMALL^∞ proofs. The starting point of focusing is the classification of the inference rules (*resp.* connectives) of linear logic into two categories: **positive** and **negative**.

The **negative** connectives have *invertible* inferences: if the conclusion of the inference is provable, so are its premisses. For example, if a sequent $\Gamma, \phi \wp \psi$ is provable, so is Γ, ϕ, ψ . The negative (*resp.* positive) connectives of μMALL^∞ are $\&, \wp, \perp, \top, \nu$ (*resp.* $\otimes, \oplus, 1, 0, \mu$).³

By assigning arbitrary polarities to atomic variables one can extend the notion to formulas in such a way that each formula is either positive or negative. A sequent is **positive** if it contains only positive or atomic formulas, it is **negative** otherwise.

► **Definition 8.** A μMALL^∞ proof is said to be in **negative normal form** if every negative sequent occurring in it is the conclusion of a negative inference. A μMALL^∞ proof π is said to be **focused** if it is in negative normal form and if, for every rule r with a positive sequent s as conclusion, the auxiliary formulas of r are principal in its premisses (the “focus”), unless they are negative atomic formulas.⁴

³ Observe that both the μ and ν rules are invertible. See [4, 21] for an explanation of the choice.

⁴ As is usual, we neglect the structural rule of exchange in this definition, by working with the exchange built in the other rules.

Note that the focusing constraint enforces that when a positive formula is principal (the “focus”), so are its auxiliary formulas and so on until a negative formula is reached.

► **Theorem 9** ([4, 21]). *If a sequent is provable in μMALL^∞ , it has a focused cut-free proof.*⁵

3.3 Regularising fragments of μMALL^∞ : the complexity of μALL

While cuts are admissible in μMALL^∞ , cf. Theorem 6, regularity of proofs is not, in general, preserved by cut-elimination. In other words, the process of cut-elimination on a circular proof produces a non-wellfounded proof which, in general, may not have finitely many distinct sub-proofs. In fact, we can show that the cut-free μMALL^∞ and the cut-free μMALL^ω are not equiprovable since $\nu X.X \wp X$ has a unique cut-free μMALL^∞ proof (up to choices of principal formulas), given in Figure 3d, that is non-regular. However, there is indeed a circular proof with cuts (see Figure 3c) of the aforementioned theorem. It is natural to ask: *Is every theorem of μMALL^∞ also provable in μMALL^ω (possibly with cuts)?* In this paper we formally show that such a regularisation result does not hold.

It is worth pointing out that the argument we mentioned for regularisation in the μ -calculus in Section 2 can in fact be adapted to certain fragments of μMALL , in particular the additive fragment. Writing μALL^∞ and μALL^ω for the restriction of μMALL^∞ and μMALL^ω , respectively, to only additive connectives, we have:

► **Proposition 10.** *If Γ is provable in μALL^∞ , then it is also (cut-free) provable in μALL^ω .*

Proof. By the cut-elimination theorem of [25], we may assume that Γ has a cut-free μALL^∞ proof π . Note that each (non-cut) rule of μALL preserves, bottom-up, the number of formulas in a sequent. Since there are only finitely many formulas that can occur (just those in the Fischer-Ladner closure of Γ , cf. [4]), π may contain only finitely many distinct sequents.

As a result, the set of non-wellfounded proofs of Γ constitutes an ω -regular tree language (since the progressing thread criterion is ω -regular). Since we assumed that this language was non-empty, there must be a regular such proof by Rabin’s basis theorem [50]. ◀

Note that this also implies the *decidability* of μALL^∞ since, after guessing a (exponential-size) pre-proof of Γ , checking that it is a proof is decidable (in space polynomial in the size of the proof).

► **Corollary 11.** *μALL^∞ (equivalently μALL^ω) is decidable in exponential space.*

We stop short of attempting to optimise this result since, in particular, it seems sensitive to the precise presentation of μALL . Often $(\mu)\text{ALL}$ is presented with *exactly* two formulas in a sequent, e.g. [51, 25], and this invariant is maintained by the rules of $(\mu)\text{ALL}$. In such a presentation, there are only quadratically many distinct sequents in a μALL^∞ proof.

However note that the calculi μALL^ω and μALL^∞ make sense with an arbitrary number of formulas in a sequent, since branches need not terminate at an initial step. For instance, it is easy to see that μALL^∞ proves $\Gamma, \nu X.X$, for any Γ , by simply continuously unfolding $\nu X.X$. In this more general setting the number of possible sequents becomes exponential.

⁵ The focusing result in [4] is for a logic without atoms but the proof technique can be straightforwardly extended to account for atoms.

4 μMALL^∞ is Π_1^0 -hard via (non-halting of) Minsky machines

We prove that the following problem is undecidable by a reduction to the non-halting of Minsky machines.

Given a sequent Γ does there exist a μMALL^∞ proof of Γ ?

Our reduction is inspired by [37] for commutative action logic with Kleene star. At first glance, it seems straightforward to be able to embed this logic in μMALL^∞ via the standard encoding of the Kleene star as $F^* = \mu X.(1 \oplus (F \otimes X))$. However, there are a couple of issues with this.

First, action logic is intuitionistic, requiring an extension of the conservativity of linear logic over intuitionistic linear logic [52] to μMALL^∞ . Strictly speaking, this is not possible since $\mathbf{0}$ is itself encodable as a fixed point *viz.* $\mu X.X$, and it is not obvious what language such a conservativity result might hold over.

Moreover, the inference rule for the Kleene star in [37] is omega-branching. Therefore, one would also need to establish translations from the omega-branching μMALL to μMALL^∞ (and vice versa) which seem to be quite nontrivial and require yet further intermediary systems. Therefore, we provide a direct reduction.

4.1 The hardness result

We begin by formally defining a Minsky machine and its corresponding (non)-halting problem.

► **Definition 12.** A **Minsky machine** \mathcal{M} is a tuple (Q, r_1, r_2, I) where Q is a finite set of states, r_1, r_2 are two registers, and I is a set of instructions of the form $\text{INC}(\bullet, \bullet, \bullet)$ and $\text{JZDEC}(\bullet, \bullet, \bullet, \bullet)$ that manipulate the current state and the contents of the registers. The operational semantics of \mathcal{M} is given by its configuration graph, the vertices of which are configurations of form $\langle q, a, b \rangle \in Q \times \mathbb{N} \times \mathbb{N}$ and edges are one of the following forms:

$$\begin{array}{ll} \langle p, a, b \rangle \xrightarrow{\text{INC}(p, r_1, q)} \langle q, a + 1, b \rangle & \langle p, a, b \rangle \xrightarrow{\text{INC}(p, r_2, q)} \langle q, a, b + 1 \rangle \\ \langle p, 0, b \rangle \xrightarrow{\text{JZDEC}(p, r_1, q_0, q_1)} \langle q_0, 0, b \rangle & \langle p, a, 0 \rangle \xrightarrow{\text{JZDEC}(p, r_2, q_0, q_1)} \langle q_0, a, 0 \rangle \\ \langle p, a + 1, b \rangle \xrightarrow{\text{JZDEC}(p, r_1, q_0, q_1)} \langle q_1, a, b \rangle & \langle p, a, b + 1 \rangle \xrightarrow{\text{JZDEC}(p, r_2, q_0, q_1)} \langle q_1, a, b \rangle \end{array}$$

Given a state q_s , a **run** of \mathcal{M} is a sequence of configurations $\{s_i\}_{i \in \mathfrak{o}}$ ($\mathfrak{o} \in \omega + 1$) such that $s_0 = \langle q_s, 0, 0 \rangle$ and for all $i \in \mathfrak{o}$ with $i + 1 \in \mathfrak{o}$, (s_i, s_{i+1}) is an edge in the configuration graph.

► **Theorem 13** ([45]). Given a Minsky machine \mathcal{M} and an initial state q_s , checking that it has an infinite run from q_s is Π_1^0 -hard.

Fixing a Minsky machine as in the definition above, we construe $\{a, b, z_a, z_b\} \cup Q$ as a set of propositional variables (assuming $\{a, b, z_a, z_b\} \cap Q = \emptyset$). We use a and z_a (*resp.* b and z_b) to represent the contents of the register r_1 (*resp.* r_2). We encode instructions (with any extra 0-ary instruction **zero-check**) as follows:

$$\begin{array}{l} [\text{INC}(p, r_1, q)] \triangleq p \wp (q^\perp \otimes a^\perp) \\ [\text{JZDEC}(p, r_1, q_0, q_1)] \triangleq (p \wp (q_0^\perp \oplus z_a^\perp)) \& ((p \wp a) \wp q_1^\perp) \\ [\text{zero-check}] \triangleq (z_a \otimes z_a^\perp) \oplus (z_b \otimes z_b^\perp) \end{array}$$

20:10 Decision Problems for Linear Logic with Least and Greatest Fixed Points

For any formula F , define $F^* = \mu X.(\mathbf{1} \oplus (F \otimes X))$ and $F^\omega = \nu X.(\perp \& (F \wp X))$. Observe that $(F^*)^\perp = (F^\perp)^\omega$. For typographic ease, we use a^n to denote $\overbrace{a, \dots, a}^{n \text{ times}}$ in a sequent.

► **Proposition 14.** *For any formula F and any $n \in \mathbb{N}$, $F^n, (F^\perp)^*$ is provable.*

Proof. We proceed by induction on n . We call π_F^n the proof of $F^n, (F^\perp)^*$.

Base Case: $n = 0$. We have

$$\frac{\frac{\overline{\mathbf{1}}}{\mathbf{1}}}{\mathbf{1} \oplus (F^\perp \otimes (F^\perp)^*)} \oplus_1 \mu \frac{}{(F^\perp)^*}$$

Induction Case: $n = m + 1$. We have

$$\frac{\frac{}{F, F^\perp} \text{id} \quad \frac{\text{IH} = \pi_F^m}{F^m, (F^\perp)^*}}{\frac{F^{m+1}, F^\perp \otimes (F^\perp)^*}{F^{m+1}, (F^\perp)^*}} \otimes \mu, \oplus_2 \quad \blacktriangleleft$$

In the following, let S be a finite set and $[\bullet] : S \rightarrow \mu\text{MALL}^\infty$. We write CH_S for $\bigoplus_{s \in S} [s]^\perp$, the formula that offers a choice of picking the dual of one of the (encoding of) elements of S .

When S is a set of instructions we rely on the above encoding, when S is a set of states, we use the identity encoding benefiting from the fact that states are indeed propositional variables. The reader might be surprised by our use of the logical duality here: it is simply because we are working in the one-sided calculus. Finally, we encode the invariant to be maintained by

$$\boxed{\text{Inv} \triangleq ((a^\perp)^* \otimes (b^\perp)^* \otimes \text{CH}_Q) \oplus ((b^\perp)^* \otimes z_a) \oplus ((a^\perp)^* \otimes z_b)}.$$

It checks one of the three following conditions: (i) the control is at a valid configuration (ii) r_1 is zero (iii) r_2 is zero. Note that $[q] = q$ where the left-hand side is the state q and the right-hand side is the propositional variable q .

► **Theorem 15.** *A Minsky machine \mathcal{M} has an infinite run from the state q_s iff $\text{CH}_I^\omega, q_s, \text{Inv}$ is derivable in μMALL^∞ .*

As a direct consequence of Theorem 15 and Theorem 13 we have the following:

► **Theorem 16.** *The set of μMALL^∞ -provable sequents is Π_1^0 -hard.*

The main technical ingredient of Theorem 15 is the following lemma.

► **Lemma 17.** *\mathcal{M} performs n steps starting from $\langle q_s, 0, 0 \rangle$ iff $\text{CH}_I^n, q_s, \text{Inv}$ is derivable.*

Before showing how this lemma is proved, let us first see how it allows us to obtain our main result:

Proof of Theorem 15. For the only if part we assume that \mathcal{M} loops. So, \mathcal{M} runs for n steps for all $n \in \mathbb{N}$. Therefore, by Lemma 17, we have that $\Gamma_n = \text{CH}_I^n, q_s, \text{Inv}$ is derivable for all $n \in \mathbb{N}$. Let us call π_n a proof of Γ_n , for $n \in \mathbb{N}$. We have

$$\frac{\frac{\pi_0}{q_s, \text{Inv}} \perp \quad \frac{\frac{\pi_1}{\text{CH}_I, q_s, \text{Inv}} \perp \quad \vdots}{\text{CH}_I, \perp, q_s, \text{Inv}} \perp \quad \frac{}{\text{CH}_I, \text{CH}_I^\omega, q_s, \text{Inv}}}{\frac{}{\text{CH}_I \wp \text{CH}_I^\omega, q_s, \text{Inv}} \wp, \nu, \&} \nu, \& \frac{}{\text{CH}_I^\omega, q_s, \text{Inv}} \nu, \&$$

$$\begin{array}{c}
\frac{\frac{\pi_b^n}{b^n, (b^\perp)^*} \quad \frac{\text{id}}{z_a, z_a^\perp}}{z_a, b^n, (b^\perp)^* \otimes z_a^\perp} \otimes \\
\frac{}{z_a, b^n, \text{Inv}} \oplus_2 \\
\vdots \\
\frac{\frac{\text{id}}{z_a, z_a^\perp} \quad \frac{\text{id}}{z_a, \text{CH}_I^{\ell-1}, b^n, \text{Inv}}}{z_a, z_a \otimes z_a^\perp, \text{CH}_I^{\ell-1}, b^n, \text{Inv}} \otimes \\
\frac{\text{IH} = \pi_F^m}{q_0, \text{CH}_I^\ell, b^n, \text{Inv}} \quad \frac{}{z_a, \text{zero-check}, \text{CH}_I^{\ell-1}, b^n, \text{Inv}} \oplus_1 \\
\frac{}{p^\perp, p} \text{id} \quad \frac{}{q_0 \& z_a, \text{CH}_I^\ell, b^n, \text{Inv}} \& \\
\frac{}{p^\perp \otimes (q_0 \& z_a), \text{CH}_I^\ell, p, b^n, \text{Inv}} \otimes \\
\frac{}{[\text{JZDEC}(p, r_1, q_0, q_1)]^\perp, \text{CH}_I^\ell, p, b^n, \text{Inv}} \oplus_1 \\
\frac{}{\text{CH}_I^{\ell+1}, p, b^n, \text{Inv}} \oplus
\end{array}$$

■ **Figure 5** A proof that does a zero-check.

Observe that this pre-proof is indeed a proof as the right-most non-wellfounded branch is validated by a thread on CH_I^ω . For the other direction assume that we have a proof π of $\text{CH}_I^\omega, q_s, \text{Inv}$. Observe that for all $n \in \mathbb{N}$ we have a proof of $\text{CH}_I^n, q_s, \text{Inv}$:

$$\frac{\frac{\pi_{\text{CH}_I}^n}{\text{CH}_I^n, (\text{CH}_I^\perp)^*} \quad \frac{\pi}{\text{CH}_I^\omega, q_s, \text{Inv}}}{\text{CH}_I^n, q_s, \text{Inv}} \text{cut}$$

By Lemma 17, \mathcal{M} runs at least n steps for all $n \in \mathbb{N}$. We collect all these runs and get a finitely branching infinite tree rooted at $\langle q_s, 0, 0 \rangle$. König's lemma ensures that there is an infinite run of \mathcal{M} from q_s . ◀

Proof sketch of Lemma 17. We will prove a stronger statement (stated this way it is easier to apply induction, however, as demonstrated above, we only need the weaker statement to prove the theorem): \mathcal{M} performs k steps from $\langle p, m, n \rangle$ iff $\text{CH}_I^k, p, a^m, b^n, \text{Inv}$ is derivable.

The **only-if** part is proved by induction on k . The base case ensures that the initial configuration is indeed a valid configuration. For the induction case, one examines the first step of the execution and applies the corresponding encoding of the instruction. We will exhibit the case of the decrementation of a zero-valued register.

Suppose the first instruction is $\text{JZDEC}(p, r_1, q_0, q_1)$ and $m = 0$. We have the derivation shown in Figure 5 where we select the appropriate instruction by applying the corresponding \oplus inference. The vertical ellipsis symbolises the repeating pattern decreasing the number of CH_I formulas in the sequent.

For the **if** part we first observe that the proof is necessarily finite and hence we can induct on it. The base case is vacuous. For the induction case, we will first assume (*wlog* by Theorem 6 and Theorem 9) that we have a focused and cut-free proof of $\text{CH}_I^k, p, a^m, b^n, \text{Inv}$. We assign atomic polarities as follows: a, b and q are negative for any state $q \in Q$, z_a, z_b are positive. By careful case-analysis, we get that one of the CH_I s is necessarily the focus. The instruction it chooses, we will execute that on \mathcal{M} . Finally, we check that **zero-check** cannot be chosen and after choosing a decrementation one cannot be led astray into the wrong state.

Basically a focused proof is forced to go exactly as exhibited in the only-if part and we will end up in a subproof of the shape $\text{CH}_I^{k-1}, q, a^{m'}, b^{n'}, \text{Inv}$ for some state q and some natural number m', n' . We can then apply the induction hypothesis and get the desired result. ◀

4.2 Separation of regular and non-wellfounded proofs

An immediate consequence of our results is that μMALL^ω and μMALL^∞ are distinct logics.

► **Theorem 18.** *There are theorems of μMALL^∞ that are not provable in μMALL^ω .*

Proof. Any μMALL^ω pre-proof has only finitely many distinct sequents, and so can be checked for correctness recursively by reduction to universality of non-deterministic parity automata over infinite words. Thus $\mu\text{MALL}^\omega \in \Sigma_1^0$. On the other hand, we showed in Theorem 16 that μMALL^∞ is Π_1^0 -hard, and we conclude since $\Pi_1^0 \setminus \Sigma_1^0 \neq \emptyset$. ◀

Observe that this proof is apparently non-constructive in the sense that we do not explicitly exhibit a sequent in $\mu\text{MALL}^\infty \setminus \mu\text{MALL}^\omega$. While it is clear that not all sequents of the form $\text{CH}_I^\omega, q_s, \text{Inv}$ from Section 4 can be derivable in μMALL^ω , it is not clear which particular Minsky machine \mathcal{M} to choose to witness this underivability. In fact the argument can indeed be constructivised using established recursion-theoretic techniques, namely the notion of *productive function*. The application of such techniques to the present situation is explained elegantly by Kuznetsov in [[36], pp. 497], so we shall not recast it here.

5 μMALL^* is Σ_1^0 -complete via (reachability in) AVASS

5.1 Towards an upper bound

The works of Palka [49] and Kuznetsov [37] proceed by showing Π_1^0 membership of their various logics (say L) in two stages:

1. The cut-free fragment L^μ with only least fixed points (*i.e.* the Kleene star is only on the right side of the sequent) is decidable.
2. The provability problem for any sequent is in $\Pi_1^0(L^\mu)$, whence it is in Π_1^0 by (1) above.

Usually, the difficult part is (2), requiring some combination of proof-theoretic and logical techniques, typically requiring infinitary wellfounded proof search to obtain the Π_1^0 bound. However, in our case, we are already stuck at (1): μ -only cut-free μMALL , *i.e.* μMALL^* , is undecidable. In the absence of greatest fixed-points, all systems (non-wellfounded, circular, inductive) coincide; so the logic μMALL^* is indeed an interesting and robustly defined core of the theory of linear logic with fixed points.

Propositional linear logic was shown to be undecidable [41, 43] by a reduction from the reachability problem in an *and-branching* two counter machine without zero-test. Such machines are essentially equivalent to a particular extension of vector addition systems, called *alternating vector addition systems with states* (or AVASS) [39, 31] (in particular, the fork rule is exactly the same). More recently, other substructural logics have been related with extensions of vector addition systems [20, 39, 40]. Our work is in the spirit of this line of research and we show the undecidability of μMALL^* by a reduction from the reachability problem of AVASS.

One could try using the undecidability of propositional linear logic to prove the undecidability of μMALL^* using a standard encoding of the exponential modalities by fixed point formulas of the following form:

$$[?F] = \mu X. \perp \oplus [F] \oplus (X \wp X) \quad ; \quad [!F] = \nu X. \mathbf{1} \& [F] \& (X \otimes X)$$

However, this encoding is not known to be faithful. Note that the reduction in [41, 43] uses only $?$ so the encoding is indeed in μMALL^* . We provide a direct proof via the reachability problem of AVASS.

Before defining the reduction in the next subsection (Section 5.2), we conclude this subsection by formally introducing AVASS and the corresponding reachability problem.

► **Definition 19.** An AVASS is a tuple $\mathcal{B} = (Q, Q_\ell, k, \mathbf{A}, T_u, T_f)$ such that:

- Q is a finite set of states with $Q_\ell \subseteq Q$;
- $k \in \mathbb{N}$ is called the **dimension**;
- \mathbf{A} is a finite subset of \mathbb{N}^k called the set of **axioms**;
- $T_u \subseteq Q \times \mathbb{Z}^k \times Q$ and $T_f \subseteq Q^3$ are finite and called the **unary** and **fork** rules respectively. A configuration of an AVASS \mathcal{B} is a pair $(q, \vec{v}) \in Q \times \mathbb{N}^k$ where Q is the set of states of \mathcal{B} and k is its dimension.

► **Definition 20.** Given an AVASS $\mathcal{B} = (Q, Q_\ell, k, \mathbf{A}, T_u, T_f)$, a configuration $(q, \vec{v}) \in Q \times \mathbb{N}^k$ is said to be **reachable** if there is a binary tree labelled by configurations such that:

- The root node is labelled by (q, \vec{v}) .
- If a node (q, \vec{v}) has a unique child (q', \vec{v}') then $(q, \vec{v} - \vec{v}', q') \in T_u$.
- If a node (q, \vec{v}) has children (q', \vec{v}') and (q'', \vec{v}'') then $\vec{v} = \vec{v}' = \vec{v}''$ and $(q, q', q'') \in T_f$.
- The leaves are labelled by elements of $Q_\ell \times \mathbf{A}$.

Such that a binary tree is called the **run tree** of the configuration.

► **Theorem 21** ([43]). The AVASS reachability problem is Σ_1^0 -complete.

5.2 Encoding an AVASS in μMALL^*

We fix $k + 1$ propositional variables, a_1, \dots, a_k, z , and define below an encoding of integer vectors of dimension up to k (the unique vector of dimension 0 is written ϵ). For the purpose of the encoding vectors will be read from left to right *i.e.* a vector \vec{v} of dimension $l + 1$ will be of the form (n, \vec{u}) for an integer n and a vector \vec{u} of dimension l .

► **Definition 22.** The **encoding of an integer vector** \vec{v} of dimension d , relative to propositional variables b_i, \dots, b_{d+i-1}, z , written $[\vec{v}]_{b_i, \dots, b_{d+i-1}, z}$, is defined inductively as follows:

$$[\vec{v}]_{b_i, \dots, b_{d+i-1}} \triangleq \begin{cases} z & \text{if } \vec{v} = \epsilon; \\ b_i \wp [\vec{v}']_{b_i, \dots, b_{d+i-1}, z} & \text{if } \vec{v} = (n, \vec{u}), n \geq 1, \text{ and } \vec{v}' = (n-1, \vec{u}); \\ b_i^\perp \otimes [\vec{v}']_{b_i, \dots, b_{d+i-1}, z} & \text{if } \vec{v} = (n, \vec{u}), n \leq -1, \text{ and } \vec{v}' = (n+1, \vec{u}); \\ [\vec{u}]_{b_{i+1}, \dots, b_{d+i-1}, z} & \text{if } \vec{v} = (0, \vec{u}). \end{cases}$$

We will simply write $[\vec{v}]$ for the encoding of a vector of dimension k relative to a_1, \dots, a_k, z . (We also use this lighter notation for vectors of lower dimension when the dimension and the $\{a_i, \dots, a_k, z\}$ to be used are clear from the context.)

The encoding is slightly involved, so let us first consider an example:

20:14 Decision Problems for Linear Logic with Least and Greatest Fixed Points

► **Example 23.** Consider the encoding of $(-1, 0, 1)$ relative to b_1, b_2, b_3, z .

$$\begin{aligned} [(-1, 0, 1)]_{b_1, b_2, b_3} &= b_1^\perp \otimes [(0, 0, 1)]_{b_1, b_2, b_3} \\ &= b_1^\perp \otimes [(1)]_{b_3} = b_1^\perp \otimes (b_3 \wp [(0)]_{b_3}) \\ &= b_1^\perp \otimes (b_3 \wp [\epsilon]_{b_3}) = b_1^\perp \otimes (b_3 \wp z) \end{aligned}$$

Observe that the i^{th} coordinate is represented by the propositional variables b_i . The following lemma shows that the encoding is meaningful with respect to vector equality.

► **Lemma 24.** *Let \vec{u} and \vec{v} be vectors of the same dimension. Then $[\vec{u}]^\perp, [\vec{v}]$ is derivable if and only if $\vec{u} = \vec{v}$.*

Proof sketch. The “if” direction is trivial. Let us consider the “only if” direction. Assume that $\vec{u} = (n_{k-d+1}, \dots, n_k)$, $\vec{v} = (m_{k-d+1}, \dots, m_k)$ and $[\vec{u}]^\perp, [\vec{v}]$ is derivable. Let π be a cut-free proof of this sequent. Since π is a MALL proof we can apply the soundness of the sequent calculus wrt. phase semantics [28]. Consider for instance the phase space⁶ $((\mathbb{Z}, +, 0), \{0\})$ and for each propositional variable a_i , $1 \leq i \leq k$, consider the valuation ϕ_i such that $\phi_i(a_i) = \{1\}$ and $\phi_i(b) = \{0\}$ for $b \neq a_i$. Soundness ensures that $[\vec{u}]^\perp, [\vec{v}]$ is valid in every phase model, that is $\llbracket [\vec{u}]^\perp, [\vec{v}] \rrbracket^{\phi_i} = m_i - n_i = 0$ for $k-d+1 \leq i \leq k$, that is $\vec{u} = \vec{v}$. ◀

The following technical lemma will allow us to reason by induction on the dimension via the encoding at the provability level, which is crucial to prove our forthcoming theorem.

► **Lemma 25.** *Let $1 \leq i \leq k$, $m \geq 0$ and s an integer such that $s + m \geq 0$. Let \vec{q} be an integer vector of dimension $k - i$. If $[\vec{q}], \Gamma, a_i^{s+m}, a_{i+1}^{m_{i+1}}, \dots, a_k^{m_k}$ is provable, then so is $[\vec{r}], \Gamma, a_i^m, a_{i+1}^{m_{i+1}}, \dots, a_k^{m_k}$ where $\vec{r} = (s, \vec{q})$ and $\vec{v} = (m, \vec{u})$.*

Proof. Let π be a proof of $[\vec{q}]^\perp, \Gamma, [\vec{u}], a_i^m$. We have three cases depending on s : when s is positive, negative, or zero.

Case 1: If s is positive.

Case 2: If s is negative.

$$\frac{\frac{\text{id}}{\{a_i^\perp, a_i\}_s} \quad \frac{\pi}{[\vec{q}]^\perp, \Gamma, a_i^m, [\vec{u}]}}{[\vec{r}]^\perp, \Gamma, a_i^{s+m}, [\vec{u}]} \otimes^s \quad \frac{\pi}{[\vec{q}]^\perp, \Gamma, [\vec{u}], a_i^m} \wp^{s+m} \quad \frac{a_i^{|s|}, [\vec{q}]^\perp, \Gamma, [\vec{v}]}{[\vec{r}]^\perp, \Gamma, [\vec{v}]} \wp^{|s|s_i}$$

Case 3: If s is zero, then by the encoding it is simply ignored, hence this case is trivial. ◀

We can now define the encoding of an AVASS. Fix an AVASS \mathcal{B} with $|Q_\ell \times \mathbf{A}| = \alpha$, $|T_u| = \beta$, and $|T_f| = \gamma$.

- For a unary rule $t \in T_u$ of the form (p, \vec{r}, q) we have $[t] \triangleq p \wp (q^\perp \otimes [\vec{r}])$.
- For a fork rule $t \in T_f$ of the form (p, q_1, q_2) we have that $[t] \triangleq (p \wp (q_1^\perp \otimes z)) \oplus (p \wp (q_2^\perp \otimes z))$.
- For a “final” configuration $(q, \vec{v}) \in Q_\ell \times \mathbf{A}$, we have that $[(q, \vec{v})] \triangleq q \wp [\vec{v}]$.

$$\mathcal{B} \text{ is encoded as } B \triangleq \mu X. (\text{CH}_{Q_\ell \times \mathbf{A}} \oplus (\text{CH}_{T_u} \wp (z \otimes X)) \oplus (\text{CH}_{T_f} \wp (z \otimes X))).$$

⁶ The facts of this phase space are the singletons, \mathbb{Z} and \emptyset . One has $\llbracket A^\perp \otimes B^\perp \rrbracket^\phi = \llbracket A \rrbracket^\phi + \llbracket B \rrbracket^\phi$, $\llbracket A \wp B \rrbracket^\phi = \llbracket A \otimes B \rrbracket^{\phi^\perp}$ when $+$ is lifted to sets of integers. In particular, the interpretations of \otimes and \wp coincide on formulas interpreted with singleton facts.

of a id rule, which leaves us with a subproof on which we can apply the induction hypothesis and we get a run-tree rooted at (q_1, \vec{v}) . Similarly we get a run-tree rooted at (q_2, \vec{v}) . Now we have a run tree rooted at (q, \vec{v}) where the first rule is the fork rule (q, q_1, q_2) . ◀

From Theorem 21 and Theorem 26, we have the following corollaries.

► **Corollary 27.** μMALL^* is Σ_1^0 -complete.

► **Corollary 28.** $\mu\text{MALL}^{\text{ind}}$ and μMALL^ω are Σ_1^0 -complete.

Proof sketch. Σ_1^0 -membership is immediate, since both $\mu\text{MALL}^{\text{ind}}$ and μMALL^ω are systems of finitely presentable proofs that are recursively checkable.

For hardness, note that $\mu\text{MALL}^\infty \supseteq \mu\text{MALL}^\omega \supseteq \mu\text{MALL}^{\text{ind}} \supseteq \mu\text{MALL}^*$ satisfies cut-elimination [4]. Since any μMALL^∞ proof of a μ -only sequent is necessarily a finite tree, all these systems are actually conservative over μMALL^* , and thus Σ_1^0 -hardness is inherited. ◀

It is folklore that if $\phi(X)$ is an LK formula with a free variable X then $\phi(X)$ and $\phi(\phi(X))$ are equivalent. This immediately gives us a conservative embedding of μLK (note that this is different from μ -calculus since there are no modalities) in LK with a polynomial blowup. In the same vein, [27, 26] shows that there is a conservative embedding of μLJ in LJ with an exponential blowup. MALL is known to be PSpace-complete [43]. Therefore we have the following corollary.

► **Corollary 29.** *There is no effectively computable reduction from μMALL^* (or $\mu\text{MALL}^{\text{ind}}$, μMALL^ω) to MALL.*

6 Conclusions and future work

In this work we classify the complexity of several systems for fixed point logics (cf. Figure 1). In particular, we proved that the non-wellfounded calculus μMALL^∞ is undecidable (via a reduction to the non-halting of Minsky machines) and prove strictly more theorems than μMALL^ω , its regular counterpart. We further proved that the finite provability for μMALL (in any of our systems) is already undecidable. Namely the problem is Σ_1^0 -complete, via a reduction to reachability in alternating vector addition systems. One novelty of our reductions is that they are based on focusing and establishes an isomorphism between proof-trees and run-trees of Minsky machines and AVASSs.

Since its inception, linear logic was advertised as the logic for concurrency [29] and its relation with VASs (or, rather, Petri nets) has been significantly explored from both syntactic [23] and semantic [44] points of view. Our results are also cognate with this line of research. The main open questions that remain from this work is:

Complexity of μMALL^∞ . There is a trivial upper bound for μMALL^∞ viz. Σ_3^1 in the analytical hierarchy. That leaves a huge gap between our Π_1^0 lower bound proved in Theorem 15. Discerning the exact complexity of μMALL^∞ therefore, amounts to closing this gap. Note that the undecidability of μMALL^* shows that established strategies [12, 49, 36, 37] of proving a Π_1^0 upper bound cannot be adapted to μMALL^∞ .

Induction vs cycles. Is $\mu\text{MALL}^{\text{ind}}$ equivalent to μMALL^ω ? This is a manifestation of the so-called *Brotherston-Simpson conjecture* in the setting of μMALL [8]. Roughly speaking, is induction as powerful as circular reasoning? Note that if the answer is indeed negative, then such a result cannot be obtained using techniques similar to Section 4.2 since in Section 5 we show that they have the same complexities.

We conclude by mentioning another pertinent direction for future work. In Section 3.3 we exhibited a purely multiplicative sequent $\nu X.X \wp X$ which has a circular proof only if we allow cuts (Figure 3c). It would be interesting to further develop regularisation procedures that blend ideas from both automata theory and proof theory, generalising the construction in Figure 3c. Naturally, by Theorem 18, no such procedure can be well-defined for all of μMALL^∞ , but it is reasonable to ask if there is a middle ground.

References

- 1 Bahareh Afshari, Gerhard Jäger, and Graham E. Leigh. An infinitary treatment of full μ -calculus. In Rosalie Iemhoff, Michael Moortgat, and Ruy de Queiroz, editors, *Logic, Language, Information, and Computation*, pages 17–34, Berlin, Heidelberg, 2019. Springer Berlin Heidelberg.
- 2 David Baelde. On the proof theory of regular fixed points. In Martin Giese and Arild Waaler, editors, *Automated Reasoning with Analytic Tableaux and Related Methods, 18th International Conference, TABLEAUX 2009, Oslo, Norway, July 6-10, 2009. Proceedings*, volume 5607 of *Lecture Notes in Computer Science*, pages 93–107. Springer, 2009. doi:10.1007/978-3-642-02716-1_8.
- 3 David Baelde, Amina Doumane, Denis Kuperberg, and Alexis Saurin. Bouncing threads for infinitary and circular proofs. In *LICS*, New York, NY, USA, 2022. Association for Computing Machinery. (to appear).
- 4 David Baelde, Amina Doumane, and Alexis Saurin. Infinitary proof theory: the multiplicative additive case. In *25th EACSL Annual Conference on Computer Science Logic, CSL 2016, August 29 - September 1, 2016, Marseille, France*, volume 62 of *LIPICs*, pages 42:1–42:17. Schloss Dagstuhl - Leibniz-Zentrum fuer Informatik, 2016. URL: <http://www.dagstuhl.de/dagpub/978-3-95977-022-4>.
- 5 David Baelde and Dale Miller. Least and greatest fixed points in linear logic. In Nachum Dershowitz and Andrei Voronkov, editors, *Logic for Programming, Artificial Intelligence, and Reasoning, 14th International Conference, LPAR 2007, Yerevan, Armenia, October 15-19, 2007, Proceedings*, volume 4790 of *Lecture Notes in Computer Science*, pages 92–106. Springer, 2007. doi:10.1007/978-3-540-75560-9_9.
- 6 Patrick Blackburn, J. F. A. K. van Benthem, and Frank Wolter, editors. *Handbook of Modal Logic*, volume 3 of *Studies in logic and practical reasoning*. North-Holland, 2007. URL: <https://www.sciencedirect.com/bookseries/studies-in-logic-and-practical-reasoning/vol/3/suppl/C>.
- 7 James Brotherston. Cyclic proofs for first-order logic with inductive definitions. In Bernhard Beckert, editor, *Automated Reasoning with Analytic Tableaux and Related Methods*, pages 78–92, Berlin, Heidelberg, 2005. Springer Berlin Heidelberg.
- 8 James Brotherston and Alex Simpson. Sequent calculi for induction and infinite descent. *Journal of Logic and Computation*, 21(6):1177–1216, October 2010. doi:10.1093/logcom/exq052.
- 9 Paul Brunet. A complete axiomatisation of a fragment of language algebra. In Maribel Fernández and Anca Muscholl, editors, *28th EACSL Annual Conference on Computer Science Logic, CSL 2020, January 13-16, 2020, Barcelona, Spain*, volume 152 of *LIPICs*, pages 11:1–11:15. Schloss Dagstuhl - Leibniz-Zentrum für Informatik, 2020. doi:10.4230/LIPICs.CSL.2020.11.
- 10 J. Richard Buchi and Lawrence H. Landweber. Solving sequential conditions by finite-state strategies. *Transactions of the American Mathematical Society*, 138:295–311, 1969. URL: <http://www.jstor.org/stable/1994916>.
- 11 S. Buss. Chapter 1: An introduction to proof theory. In Samuel R. Buss, editor, *Handbook of Proof Theory*. Elsevier, 1998.

- 12 Wojciech Buszkowski. On action logic: Equational theories of action algebras. *Journal of Logic and Computation*, 17(1):199–217, October 2006. doi:10.1093/logcom/ex1036.
- 13 Anupam Das. On the logical complexity of cyclic arithmetic. *Log. Methods Comput. Sci.*, 16(1), 2020. doi:10.23638/LMCS-16(1:1)2020.
- 14 Anupam Das, Abhishek De, and Alexis Saurin. Decision problems for linear logic with least and greatest fixed points (Extended version). working paper or preprint, April 2022. URL: <https://hal.archives-ouvertes.fr/hal-03655651>.
- 15 Anupam Das, Amina Doumane, and Damien Pous. Left-handed completeness for Kleene algebra, via cyclic proofs. In *LPAR*, volume 57 of *EPiC Series in Computing*, pages 271–289. EasyChair, 2018.
- 16 Anupam Das and Damien Pous. A cut-free cyclic proof system for Kleene algebra. In Renate A. Schmidt and Cláudia Nalon, editors, *Automated Reasoning with Analytic Tableaux and Related Methods*, pages 261–277, Cham, 2017. Springer International Publishing.
- 17 Christian Dax, Martin Hofmann, and Martin Lange. A proof system for the linear time μ -calculus. In *FSTTCS*, volume 4337 of *Lecture Notes in Computer Science*, pages 273–284. Springer, 2006.
- 18 Christian Dax, Martin Hofmann, and Martin Lange. A proof system for the linear time μ -calculus. In S. Arun-Kumar and Naveen Garg, editors, *FSTTCS 2006: Foundations of Software Technology and Theoretical Computer Science, 26th International Conference, Kolkata, India, December 13-15, 2006, Proceedings*, volume 4337 of *Lecture Notes in Computer Science*, pages 273–284. Springer, 2006. doi:10.1007/11944836_26.
- 19 Abhishek De, Luc Pellissier, and Alexis Saurin. Canonical proof-objects for coinductive programming: Infinites with infinitely many cuts. In *23rd International Symposium on Principles and Practice of Declarative Programming*, PPDP 2021, New York, NY, USA, 2021. Association for Computing Machinery. doi:10.1145/3479394.3479402.
- 20 P. de Groote, B. Guillaume, and S. Salvati. Vector addition tree automata. In *Proceedings of the 19th Annual IEEE Symposium on Logic in Computer Science, 2004.*, pages 64–73, 2004. doi:10.1109/LICS.2004.1319601.
- 21 Amina Doumane. *On the infinitary proof theory of logics with fixed points. (Théorie de la démonstration infinitaire pour les logiques à points fixes)*. PhD thesis, Paris Diderot University, France, 2017. URL: <https://tel.archives-ouvertes.fr/tel-01676953>.
- 22 Amina Doumane and Damien Pous. Completeness for identity-free kleene lattices. In Sven Schewe and Lijun Zhang, editors, *29th International Conference on Concurrency Theory, CONCUR 2018, September 4-7, 2018, Beijing, China*, volume 118 of *LIPICs*, pages 18:1–18:17. Schloss Dagstuhl - Leibniz-Zentrum für Informatik, 2018. doi:10.4230/LIPICs.CONCUR.2018.18.
- 23 Uffe Engberg and Glynn Winskel. Petri nets as models of linear logic. In A. Arnold, editor, *CAAP '90*, pages 147–161, Berlin, Heidelberg, 1990. Springer Berlin Heidelberg.
- 24 Michael J. Fischer and Richard E. Ladner. Propositional dynamic logic of regular programs. *Journal of Computer and System Sciences*, 18(2):194–211, 1979. doi:10.1016/0022-0000(79)90046-1.
- 25 Jérôme Fortier and Luigi Santocanale. Cuts for circular proofs: semantics and cut-elimination. In *CSL*, 2013.
- 26 Silvio Ghilardi, Maria João Gouveia, and Luigi Santocanale. Fixed-point elimination in the intuitionistic propositional calculus. *ACM Trans. Comput. Logic*, 21(1), September 2019. doi:10.1145/3359669.
- 27 Silvio Ghilardi, Maria João Gouveia, and Luigi Santocanale. Fixed-point elimination in the intuitionistic propositional calculus. In Bart Jacobs and Christof Löding, editors, *Foundations of Software Science and Computation Structures*, pages 126–141, Berlin, Heidelberg, 2016. Springer Berlin Heidelberg.
- 28 Jean-Yves Girard. Linear logic. *Theor. Comput. Sci.*, 50:1–102, 1987. doi:10.1016/0304-3975(87)90045-4.

- 29 Jean-Yves Girard. Linear logic: Its syntax and semantics. In Jean-Yves Girard, Yves Lafont, and Laurent Regnier, editors, *Advances in Linear Logic*, pages 222–1. Cambridge University Press, 1995.
- 30 Gary A. Kildall. A unified approach to global program optimization. In *Proceedings of the 1st Annual ACM SIGACT-SIGPLAN Symposium on Principles of Programming Languages*, POPL '73, pages 194–206, New York, NY, USA, 1973. Association for Computing Machinery. doi:10.1145/512927.512945.
- 31 Alexei Kopylov. Decidability of linear affine logic. *Inf. Comput.*, 164:173–198, January 2001. doi:10.1006/inco.1999.2834.
- 32 D. Kozen. A completeness theorem for kleene algebras and the algebra of regular events. In *[1991] Proceedings Sixth Annual IEEE Symposium on Logic in Computer Science*, pages 214–225, 1991. doi:10.1109/LICS.1991.151646.
- 33 Dexter Kozen. Results on the propositional μ -calculus. *Theoretical Computer Science*, 27(3):333–354, 1983. Special Issue Ninth International Colloquium on Automata, Languages and Programming (ICALP) Aarhus, Summer 1982. doi:10.1016/0304-3975(82)90125-6.
- 34 Saul Aaron Kripke. The problem of entailment” (abstract). *The Journal of Symbolic Logic*, 24(4):312–326, 1959. URL: <http://www.jstor.org/stable/2963903>.
- 35 Daniel Krob. Complete systems of b-rational identities. *Theoretical Computer Science*, 89(2):207–343, 1991. doi:10.1016/0304-3975(91)90395-I.
- 36 Stepan Kuznetsov. *-continuity vs. induction: Divide and conquer. In Guram Bezhanishvili, Giovanna D’Agostino, George Metcalfe, and Thomas Studer, editors, *Advances in Modal Logic 12, proceedings of the 12th conference on “Advances in Modal Logic,” held in Bern, Switzerland, August 27-31, 2018*, pages 493–510. College Publications, 2018. URL: <http://www.aiml.net/volumes/volume12/Kuznetsov.pdf>.
- 37 Stepan Kuznetsov. Complexity of commutative infinitary action logic. In Manuel A. Martins and Igor Sedlár, editors, *Dynamic Logic. New Trends and Applications*, pages 155–169, Cham, 2020. Springer International Publishing.
- 38 Yves Lafont. The finite model property for various fragments of linear logic. *Journal of Symbolic Logic*, 62(4):1202–1208, 1997. doi:10.2307/2275637.
- 39 Ranko Lazić and Sylvain Schmitz. Non-elementary complexities for branching vass, mell, and extensions. In *Proceedings of the Joint Meeting of the Twenty-Third EACSL Annual Conference on Computer Science Logic (CSL) and the Twenty-Ninth Annual ACM/IEEE Symposium on Logic in Computer Science (LICS)*, CSL-LICS '14, New York, NY, USA, 2014. Association for Computing Machinery. doi:10.1145/2603088.2603129.
- 40 Ranko Lazić and Sylvain Schmitz. Nonelementary complexities for branching vass, mell, and extensions. *ACM Trans. Comput. Logic*, 16(3), June 2015. doi:10.1145/2733375.
- 41 Patrick Lincoln. *Computational Aspects of Linear Logic*. PhD thesis, Stanford University, 1992.
- 42 Patrick Lincoln. Deciding provability of linear logic formulas. In *Proceedings of the Workshop on Advances in Linear Logic*, pages 109–122, USA, 1995. Cambridge University Press.
- 43 Patrick Lincoln, John Mitchell, Scedrov Andre, and Natarajan Shankar. Decision problems for propositional linear logic. *Annals of Pure and Applied Logic*, 56(1):239–311, 1992. doi:10.1016/0168-0072(92)90075-B.
- 44 José Meseguer and Ugo Montanari. Petri nets are monoids. *Information and Computation*, 88(2):105–155, 1990. doi:10.1016/0890-5401(90)90013-8.
- 45 Marvin L. Minsky. *Computation: Finite and Infinite Machines*. Prentice-Hall, Inc., USA, 1967.
- 46 J. F. Nash. Equilibrium points in N -person games. *Proceedings of the National Academy of Sciences of the United States of America*, 36(48-49), 1950.
- 47 Damian Niwiński. Fixed point characterization of infinite behavior of finite-state systems. *Theor. Comput. Sci.*, 189(1–2):1–69, December 1997. doi:10.1016/S0304-3975(97)00039-X.

- 48 Damian Niwinski and Igor Walukiewicz. Games for the μ -calculus. *Theor. Comput. Sci.*, 163(1&2):99–116, 1996. doi:10.1016/0304-3975(95)00136-0.
- 49 Ewa Palka. An infinitary sequent system for the equational theory of $*$ -continuous action lattices. *Fundam. Inf.*, 78(2):295–309, April 2007.
- 50 Michael Oser Rabin. *Automata on Infinite Objects and Church's Problem*. American Mathematical Society, USA, 1972.
- 51 Luigi Santocanale. A calculus of circular proofs and its categorical semantics. In Mogens Nielsen and Uffe Engberg, editors, *Foundations of Software Science and Computation Structures*, pages 357–371, Berlin, Heidelberg, 2002. Springer Berlin Heidelberg.
- 52 HAROLD SCHELLINX. Some Syntactical Observations on Linear Logic. *Journal of Logic and Computation*, 1(4):537–559, September 1991. doi:10.1093/logcom/1.4.537.
- 53 Dana Scott. Outline of a mathematical theory of computation. Technical Report PRG02, OUCL, November 1970.
- 54 Alex Simpson. Cyclic arithmetic is equivalent to peano arithmetic. In Javier Esparza and Andrzej S. Murawski, editors, *Foundations of Software Science and Computation Structures - 20th International Conference, FOSSACS 2017, Held as Part of the European Joint Conferences on Theory and Practice of Software, ETAPS 2017, Uppsala, Sweden, April 22-29, 2017, Proceedings*, volume 10203 of *Lecture Notes in Computer Science*, pages 283–300, 2017. doi:10.1007/978-3-662-54458-7_17.
- 55 Lutz Straßburger. On the decision problem for MELL. *Theoretical Computer Science*, 768:91–98, 2019. doi:10.1016/j.tcs.2019.02.022.
- 56 Thomas Studer. On the proof theory of the modal μ -calculus. *Studia Logica: An International Journal for Symbolic Logic*, 89(3):343–363, 2008. URL: <http://www.jstor.org/stable/40268983>.
- 57 Alasdair Urquhart. The complexity of decision procedures in relevance logic ii. *The Journal of Symbolic Logic*, 64(4):1774–1802, 1999. URL: <http://www.jstor.org/stable/2586811>.
- 58 Igor Walukiewicz. *A complete deductive system for the μ -calculus*. PhD thesis, Warsaw University, 1994.
- 59 Igor Walukiewicz. Completeness of Kozen's axiomatisation of the propositional μ -calculus. In *LICS 95, San Diego, California, USA, June 26-29, 1995*, pages 14–24, 1995.