Pseudorandom Generators, Resolution and Heavy Width

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Abstract
Following the paper of Alekhnovich, Ben-Sasson, Razborov, Wigderson [2] we call a pseudorandom generator $F : \{0,1\}^n \rightarrow \{0,1\}^m$ hard for a propositional proof system $P$ if $P$ cannot efficiently prove the (properly encoded) statement $b \notin \text{Im}(F)$ for any string $b \in \{0,1\}^m$.

In [2] the authors suggested the “functional encoding” of the considered statement for Nisan–Wigderson generator that allows the introduction of “local” extension variables. These extension variables may potentially significantly increase the power of the proof system. In [2] authors gave a lower bound of $\exp\left[\Omega\left(\frac{n^2}{m^{2\Delta}}\right)\right]$ on the length of Resolution proofs where $\Delta$ is the degree of the dependency graph of the generator. This lower bound meets the barrier for the restriction technique.

In this paper, we introduce a “heavy width” measure for Resolution that allows us to show a lower bound of $\exp\left[\frac{n^2}{m^{2\Delta n}}\right]$ on the length of Resolution proofs of the considered statement for the Nisan–Wigderson generator. This gives an exponential lower bound up to $\Delta := \log^{2-\epsilon} n$ (the bigger degree the more extension variables we can use). In [2] authors left an open problem to get rid of scaling factor $2^{2\Delta}$, it is a solution to this open problem.

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1 Introduction

Pseudorandom generators [25] are one the most important notions in modern computer science. A pseudorandom generator can be considered as a function $F : \{0,1\}^n \rightarrow \{0,1\}^m$ such that for all small circuits $C \in \mathcal{C}$:

$$\left| \Pr_{x \in \{0,1\}^n}[C(F(x))] - \Pr_{y \in \{0,1\}^m}[C(y)] \right| \rightarrow 0, \quad n \rightarrow \infty,$$

where $\mathcal{C}$ is some circuit class, and $x,y$ are taken from the uniform distribution.

The condition on a pseudorandom generator can be rephrased in the following more informal way: “For a class of circuits $\mathcal{C}$ it is hard to distinguish points inside and outside of the image of $F$”. This fact was used by Alekhnovich, Ben-Sasson, Razborov, and Wigderson [2] who suggested a natural way of viewing pseudorandom generators from the proof complexity perspective. Following [2] we call a pseudorandom generator $F : \{0,1\}^n \rightarrow \{0,1\}^m$ hard for...
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a propositional proof system \( P \) if \( P \) cannot efficiently prove the (properly encoded as a CNF formula) statement \( b \notin \text{Im}(F) \) for any string \( b \in \{0,1\}^m \). Similar constructions were also proposed by Krajíček [13].

The problem of proving lower and upper bounds on the considered formulas is natural and at the same time there are lots of motivations from different areas of computer science. We discuss some of them and also refer the reader to [2, 5, 22] for the detailed survey.

Candidate Hard Examples for Strong Proof Systems. Despite the success of proving lower bounds on weak proof systems like Resolution, Polynomial Calculus, etc. we are still far away from lower bounds on strong proof systems like Frege or Extended Frege. Moreover, at this moment, we have few candidates for hard examples for these systems. In [22] Razborov introduced explicit conjectures that formulas obtained from Nisan–Wigderson pseudorandom generators are hard for Frege and Extended Frege.

These conjectures of Razborov are based on the deep connection between pseudorandom generators and so-called Circuit formulas. This provides another important motivation in circuit complexity.

Circuit Lower Bound. In [18] Razborov introduced the principle \( \text{Circuit}_t(f_n) \) expressing that the circuit size of the Boolean function \( f_n \) in \( n \) variables, given as its truth-table, is lower bounded by \( t = t(n) \). Razborov stated that to show that a proof system \( P \) does not have efficient proofs of the formula \( \text{Circuit}_t(f_n) \), it suffices to design a sufficiently constructive pseudorandom generator hard for \( P \) and such that the number of output bits, as a function of the number of input bits, is as large as possible. In other words, the pseudorandom generators in proof complexity capture the arguments that are required to prove the circuit lower bounds (see also [2, 19]).

In this paper, we focus on the Nisan–Wigderson generators that were mention above. This partial case already illustrates all considered applications and shows the limits of the current techniques for proving lower bounds in proof complexity that we discuss next section.

1.1 Nisan–Wigderson Generators

The Nisan–Wigderson pseudorandom generator [16] may be described by a family of functions \( f := \{f_1, \ldots, f_n\} \) and a bipartite dependency graph \( G := (L, R, E) \) where \( |L| = m, |R| = n \) and each vertex in \( L \) has degree \( \Delta \). We identify the right part of this graph with a set of boolean variables \( x_1, \ldots, x_n \) and the left part with the output bits. We define a function \( F_{G,f} : \{0,1\}^n \to \{0,1\}^m \) such that the \( j \)-th bit of the output is defined by \( f_j(x_{i_1}, x_{i_2}, \ldots, x_{i_k}) \) where \( x_{i_k} \) are neighbours of the vertex \( v_j \in L \) that are ordered in arbitrary but fixed way.

Pick some \( b \in \{0,1\}^n \setminus \text{Im}(F_{G,f}) \). We produce the unsatisfiable CNF formula \( \text{PRG}_{G,f,b} \) that states \( b \notin \text{Im}(F) \) in the most natural way i.e. we encode the constraints \( f_j(x) = b_j \) independently. If the function \( f_j \) is simple enough (or \( \Delta \) is small enough) then we can encode it in CNF directly in terms of \( x_{i_1}, x_{i_2}, \ldots, x_{i_k} \). But if \( \Delta \gg \log n \) this encoding will be superpolynomial even in the case of parity function. To solve this problem, in [2] the authors suggested to use “local” extension variables (so-called “functional encoding”). In other words we can introduce any variable \( y_g \) whose value corresponds to some function \( g \) that depends on some set of variables \( X_g \) and \( X_g \subseteq N(v) \) where \( v \in L \) and \( N(v) \) is a set of neighbours of \( v \).

Another important motivation for the considered functional encoding is that it naturally characterizes the spectrum of proof systems between Resolution and Extended Frege. To see this we remind a classical Theorem that Resolution with all extension variables is equivalent to Extended Frege [8, 12]. So if we omit the locality constraint \( X_g \subseteq N(v) \) and allow all
possible extension variables then any lower bound on the size of Resolution proofs can be transformed into lower bounds on the Extended Frege. Note that the bigger $\Delta$ the more extension variables we allow to use, and the behaviour of Resolution is closer to the behaviour of Extended Frege. So the question about proving the lower bounds for a bigger degree of the dependency graph is a necessary step for proving lower bound on stronger proof systems.

1.1.1 Technical Aspects of Proving Lower Bounds

The most popular technique for proving lower bounds in proof complexity is a restriction. The main idea of this technique that we can hit the small proof by some restriction and obtain a well-structured proof. For example, this trick was used to reduce the question about the size of the resolution proof to a question about the width of proof. It can be used explicitly [2] or implicitly [7, 11, 6].

The “quality” of the restriction trick depends on the number of variables in our formula. Hence the lower bounds on the functional encoding of Nisan–Wigderson generator are an important barrier. The lower bound presented in [2] shows the limits of the classical restriction approach.

1.1.2 Prior Results

Despite the importance of the problem, only a few lower bounds are known. Alekhnovich, Ben-Sasson, Razborov, and Wigderson [2] showed a lower bound $\exp \Omega \left( \frac{n^2}{m^{2\Delta}} \right)$ on the length of Resolution proofs on the functional encoding of the Nisan–Wigderson generator. Since this proof used the “pure restriction technique” it also works for the Polynomial Calculus, which was also done in the same paper. This is the only lower bound that deals with the full functional encoding. They formulated a list of open problems that included:

- to prove a lower bound that works for $m \gg n^2$;
- to get rid of the $2^{2\Delta}$ scaling factor in the lower bound.

The state of the art techniques say that if we want to prove a lower bound then we need an expansion property of the dependency graph of the NW generator. And without a solution to the second problem we cannot deal with large $\Delta$ and hence for large enough $m$ we cannot deal with expanders. So it seems that a solution to the second problem is a necessary step for any solution to the first problem.

In [15] Krajíček showed a simplified proof of the lower bound from [2], but it works only for a certain choice of the small number of local extension variables. This lower bound is given via reduction from the Pigeonhole Principle and hence it works for the bigger class of proof systems. For another choice of local extension variables Razborov [22] showed a superpolynomial lower bound up to $m = O(n^{\log n})$. This lower bound works for the Resolution and $k$-DNF Resolution, and it is obtained via the so-called “Small Restriction Switching Lemma” [23, 22].

If we switch back from the Nisan–Wigderson generator to the general case then we must point out that in [22] Razborov showed a lower bound for subexponential parameter $m$. This lower bound is based on two ideas: a lower bound on the Nisan–Wigderson generator, and the composition Theorem [14, 22]. The generator used in this lower bound is a composition of several Nisan–Wigderson generators.
1.2 Our Results

We develop a new measure of resolution proofs that we call “heavy width”. This measure

gives us a way to deal with extension variables in a structured way. We modify the restriction
technique and show that for “proper” formulas small resolution proof may be transformed
into a proof of small heavy width. Also, we show a way for proving lower bounds on heavy
width (even in cases when we cannot bound classical resolution width).

By using the considered measure and techniques we show the following result, that is a
solution to an open problem [2]: to get rid of scaling factor $2^{2\Delta}$ in lower bounds on resolution
proofs of PRG formulas.

\begin{itemize}
  \item \textbf{Theorem 1 (Informal).} Let $G := (L, R, E)$ be an $(r, \Delta, (1 - \varepsilon)\Delta)$-expander, where $|L| = m, |R| = n$. If $f_i$ is a family of good functions then for any $b \notin \Im(F_{G,f})$ any resolution
proof of $\text{PRG}_{G,f,b}$ requires size $\exp\left[2^{-O(\varepsilon\Delta)} \cdot \frac{r^2}{m}\right]$.

  For good enough expander graphs $r = \Omega\left(\frac{m}{\text{poly}(\Delta)}\right)$. We give a definition of a “good”
function and expander graph later (see Definition 3 and section 2.1). Informally speaking
function is good iff it remains balanced even if we fix some of its input variables (Parity is a
good function). We may think about expander graphs as about bipartite random graphs
with left degree $\Delta$.

  The parameter $\varepsilon$ may depends on $n$ and $\Delta$ which allows us to show lower bounds of
the form $\exp\left[2^{-o(\Delta)} \cdot \frac{r^2}{m}\right]$ for the proper expander graphs. In particular, we may consider
natural distribution over random graphs $G(m, n, \Delta)$ (see section 2.2) for which, our Theorem
implies the following result.

  \item \textbf{Theorem 2 (Informal).} Let $n$ be large enough integer number, $\delta > 0$, $m := n^{2-\delta}$, $\Delta :=
\log^{2-\delta} n$ and $G \sim G(m, n, \Delta)$. If $f_i$ is a family of good functions then whp for any $b \notin \Im(F_{G,f})$ any
resolution proof of $\text{PRG}_{G,f,b}$ requires size $\exp\left[n^{O(\delta)}\right]$.

  We believe that heavy width measure could be of independent interest.
\end{itemize}

1.3 Our Technique

Let $F_{G,f} : \{0, 1\}^n \rightarrow \{0, 1\}^m$. Let us remind that we pick some $b \in \{0, 1\}^n \setminus \Im(F_{G,f})$ and
produce the unsatisfiable CNF formula $\text{PRG}_{G,f,b}$ that states $b \in \Im(F)$ by encoding the
constraints $f_i(x) = b_i$ independently. To do this, for every function $g$ that depends on some
set of variables $X_a$ and $X_b \subseteq N (v)$ where $v \in L$, we introduce an extension variable $y_g$ whose
value corresponds to $g$. For formal construction see Section 3. Note, that since for all $v \in L$
the size of $N (v)$ is $\Delta$ our CNF formula consists of $m \cdot 2^{2\Delta}$ variables.

We start with the approach that gives a lower bound $\exp\left[\Omega\left(\frac{n^2}{m \cdot 2^{2\Delta}}\right)\right]$ on the size of
resolution proofs of $\text{PRG}_{G,f}$. This strategy has the same flavor as a strategy from [2] but has
some differences in details.

Let $\pi := (D_1, \ldots, D_k)$ be a Resolution proof of $\text{PRG}_{G,f}$ and $H$ is a set of clauses of width
at least $w_0$. For the sake of contradiction assume that $\pi$ has small size and apply the following
algorithm.

1. If $\pi$ is small then $H$ is small.
2. Pick the most frequent literal $y$ in $H$. Note that it is contained in at least $\frac{w_0}{m \cdot 2^{2\Delta}}$ fraction
   of clauses (by a naive averaging argument).
3. Set $y$ to 0 in $\pi$. This operation kills all clauses that contain $y$.
4. After this assignment $\pi \upharpoonright (y = 0)$ is still a proof of a restricted formula.
5. We apply a “closure” trick [3, 2] to make sure that the remaining formula does not contain a “local contradiction” (see also an iterative version of this trick in [24]).

6. Repeat while we have clauses of large width.

If $H$ is small we kill all clauses of large width in a few iterations. To achieve a contradiction it remains to show that if there is no “local contradiction” then any resolution proof requires width at least $w_0$ for the right choice of $w_0$.

This strategy is semantic, i.e. we do not care about the exact form of clauses in the proof; we need only two properties:

- clauses of large width can be killed with large probability by a “random assignment”;
- clauses of small width are not so easy to satisfy (we need this property for the width lower bound).

The bottleneck of the considered strategy is the fraction of clauses that contain some specific literal. So if we want to improve the lower bound, we need to expand this bottleneck. First of all, we will count the number of output bits that are “touched” (in other words, $i$-th output bit is touched iff there is a variable (or extension variable) in a clause from $N(i)$ (that value depends only on $N(i)$)) by a clause rather than the number of input variables. To do so we define a “functional form” of a clause that helps to split all variables into $m$ baskets. Unfortunately, our functional form of a clause is a syntactic representation, i.e., it heavily depends on the exact representation of a clause and not only the function defined by it. Moreover this representation is not unique and that affects our complexity measures.

On the one hand, the syntactic measure has already provided problems in the analysis. On the other hand, it is still not enough for our lower bound. To expand the bottleneck even more we introduce the new measure “heavy width”. Informally speaking if we have clause $D$ then we want to count only those output bits of the generator the value of which are heavily correlated to a value of the clause $D$.

Let us define the full strategy. Let $\pi := (D_1, \ldots, D_\ell)$ be a Resolution proof of $\text{PRG}_{G,f}$ and $H$ be a set of clauses of heavy width at least $w_0$ (in other words there are at least $w_0$ output bits of the generator whose values are correlated with a value of a clause). For the sake of contradiction assume that $\pi$ has small size and apply the following algorithm.

1. If $\pi$ is small then $H$ is small.
2. Pick an output bit $v$ of the generator uniformly at random.
3. Set all neighbors of $v$ in order to satisfy constraints to this output bit. In our case this operation kills $\frac{2^{-\Delta} \ell}{m}$ fraction of clauses in $H$ (this argument will follow from the definition of heavy width).
4. After this assignment the restricted proof is still a proof of a restricted formula.
5. We apply a “closure” trick to make sure that the remaining formula does not contain “local contradiction”.
6. Make sure that heavy width of alive clauses does not grow too much. This is the new and one of the most problematic step.
7. Repeat while we have clauses of large width.

If $H$ is small we kill all clauses of large width in a few iterations. To achieve a contradiction it remains to show that if there is no “local contradiction” then any resolution proof requires a clause of large “heavy width”.

To show the lower bound on the heavy width we equip a game approach (that is similar to [17, 4]) with a new invariant. This is the place where the problem with the syntactic definition of a functional form arises. To avoid this problem we again will use the expansion properties of our dependency graph.
2 Preliminaries

Let \( x \) be a propositional variable, i.e., a variable that ranges over the set \( \{0, 1\} \). A literal of \( x \) is either \( x \) (denoted sometimes as \( x^1 \)) or \( \neg x \) (denoted sometimes as \( x^0 \)). A clause \( C := x_1^{c_1} \lor x_2^{c_2} \lor \cdots \lor x_n^{c_n} \) is a disjunction of literals where \( c_1, c_2, \ldots, c_n \in \{0, 1\} \). A CNF formula \( \varphi := C_1 \land \cdots \land C_m \) is a conjunction of clauses. We think of clauses and CNF formulas as sets: order is irrelevant and there are no repetitions.

A Resolution proof \( \pi \) of an unsatisfiable CNF formula \( \varphi \) is an ordered sequence of clauses \( \pi := C_1, \ldots, C_s \) such that \( C_s \notin \emptyset \) is an empty clause and for each \( i \in [s] \) either \( C_i \) is a clause in \( \varphi \) or there exist \( j, k < i \) such that \( C_i \) is derived from \( C_j \) and \( C_k \) by the resolution rule

\[
\frac{C \lor x}{C \lor D} \quad \frac{C \lor \neg x}{D \lor x} \quad \frac{C \lor x}{C \lor D} \quad \frac{C \lor \neg x}{D \lor x}
\]

or by the weakening rule

\[
\frac{C}{D} \quad [C \subseteq D].
\]

A partial assignment or a restriction on a function \( f \) (or a formula \( \varphi \)) is a mapping \( \rho : \text{Vars}(f) \to \{0, 1, \ast\} \). We let \( \text{supp}(\rho) := \rho^{-1}(\{0, 1\}) \) denote the set of assigned variables. The restriction of a function \( f \) (or a formula \( \varphi \)) by \( \rho \), denoted \( f|_\rho \) (\( \varphi|_\rho \)), is the Boolean function (propositional formula) obtained from \( f \) (from \( \varphi \), respectively) by setting the value of each \( x_i \in \text{supp}(\rho) \) to \( \rho(x_i) \) and leaving each \( x_i \notin \text{supp}(\rho) \) unassigned.

The size of a partial assignment \( \rho \) is the size of the \( \text{supp}(\rho) \). We denote it by \( |\rho| \).

**Definition 3.** Let \( f : \{0, 1\}^n \to \{0, 1\} \). We say that \( f \) is \((\delta, k)\)-balanced for some \( 0 < \delta \leq \frac{1}{2} \) and \( k \geq 0 \) iff for any \( b \in \{0, 1\} \) and any partial assignment \( \rho \) of size at most \( k \) the size of \( (f|_\rho)^{-1}(b) \) is at least \( \delta \cdot 2^{n-|\rho|} \).

Some examples.
- \( \text{Parity}(x_1, \ldots, x_n) \) is \((\frac{1}{2}, n-1)\)-balanced;
- \( \text{IP} := \sum_{i=1}^{\lfloor n/2 \rfloor} x_i y_i \mod 2 \) is \((\frac{1}{2}, \frac{n}{2}-1)\)-balanced;
- a random function is \((\frac{1}{4}, n - \sqrt{n})\)-balanced (see Lemma 30 for the calculations).

2.1 Expanders and Closure

We use the following notation: \( N_G(S) \) is the set of neighbours of the set of vertices \( S \) in the graph \( G \), \( \partial_G(S) \) is the set of vertices \( u \) that are connected with \( S \) by exactly one edge. We omit the index \( G \) if the graph is evident from the context.

**Definition 4.** A bipartite graph \( G := (L, R, E) \) is an \((r, \Delta, c)\)-expander if all vertices \( u \in L \) have degree at most \( \Delta \) and for all sets \( S \subseteq L, |S| \leq r \), it holds that \( |N(G,S)| \geq c \cdot |S| \).

Similarly, \( G := (L, R, E) \) is an \((r, \Delta, c)\)-boundary expander if all vertices \( u \in L \) have degree at most \( \Delta \) and for all sets \( S \subseteq L, |S| \leq r \), it holds that \( |\partial(G,S)| \geq c \cdot |S| \).

In this context, a simple but useful observation is that

\[
\frac{|N(S)| - |\partial(S)|}{2} + \frac{\Delta|S| - |\partial(S)|}{2} = \frac{\Delta|S| + |\partial(S)|}{2},
\]
since all non-unique neighbours have at least two incident edges. This implies that for any \( \varepsilon \leq \frac{1}{2} \) if a graph \( G \) is an \((r, \Delta, (1-\varepsilon)\Delta)\)-expander then it is also an \((r, \Delta, (1-2\varepsilon)\Delta)\)-boundary expander.

The next proposition is well known in the literature. In this form it was used in [10].

**Proposition 5.** If \( G = (L, R, E) \) is an \((r, \Delta, c)\)-boundary expander then for any set \( S \subseteq L \) of size \( k \leq r \) there is an enumeration \( v_1, v_2, \ldots, v_k \in S \) and a sequence \( R_1, \ldots, R_k \subseteq N(S) \) such that:

\[
\begin{align*}
R_i &= N(v_i) \setminus \left( \bigcup_{j=1}^{i-1} N(v_j) \right); \\
|R_i| &\geq c.
\end{align*}
\]

In particular, there is a matching on the set \( S \).

**Proof.** We create this sequence in reversed order. Since \(|S| \leq r\) it holds that \(|\partial(S)| \geq c|S|\) and there is a vertex \( v_k \in S \) such that \(|\partial(S) \cap N(v_k)| \geq c\). Let \( R_k := |\partial(S) \cap N(v_k)| \), and repeat the process on \( S \setminus \{v_k\} \). ▶

Let \( G = (L, R, E) \) denote a bipartite graph. Consider a closure operation that seems to have originated in [3, 2].

**Definition 6.** For a vertex set \( U \subseteq R \) we say that a set \( S \subseteq L \) is \((U, r, \nu)\)-contained if \(|S| \leq r \) and \(|\partial(S) \setminus U| < \nu|S|\). For any set \( J \subseteq R \) let \( Cl^{r,\nu}(J) \) denote an arbitrary but fixed set of maximal size such that \( Cl^{r,\nu}(J) \) is \((J, r, \nu)\)-contained. We say that \( Cl^{r,\nu}(J) \) is a closure of \( J \).

Note that for any \( J \subseteq R \) and any positive \( r, \nu \) the empty set is \((J, r, \nu)\)-contained and closure is well-defined.

**Lemma 7.** Suppose that \( G \) is an \((r, \Delta, c)\)-boundary expander and that \( J \subseteq R \) has size \(|J| \leq \Delta r\). Then \(|Cl^{r,\nu}(J)| < \frac{|J|}{c-r}\).

**Proof.** By definition we have that \(|\partial(Cl^{r,\nu}(J)) \setminus J| < \nu|Cl^{r,\nu}(J)|\). Since \(|Cl^{r,\nu}(J)| \leq r\) by definition, the expansion property of the graph guarantees that \( c|Cl^{r,\nu}(J)| - |J| \leq |\partial(Cl^{r,\nu}(J)) \setminus J|\). The conclusion follows. ▶

Suppose \( J \subseteq R \) is not too large. Then Lemma 7 shows that the closure of \( J \) is not much larger. Thus, after removing the closure and its neighbourhood from the graph, we are still left with a decent expander. The following lemma makes this intuition precise.

**Lemma 8.** Let \( J \subseteq R \) be such that \(|J| \leq \Delta r\) and \(|Cl^{r,\nu}(J)| \leq \frac{\nu}{2}\) and let \( G' := G \setminus (Cl^{r,\nu}(J) \cup J \cup N(Cl^{r,\nu}(J))) \). Then any set \( S \) of vertices from the left side of \( G' \), with size \(|S| \leq \frac{\nu}{2}\), satisfies that \(|\partial_{G'}(S)| \geq \nu|S|\).

**Proof.** Suppose the set \( S \subseteq L(G') \) violates the boundary expansion guarantee. Observe that \( Cl^{r,\nu}(J) \) and \( S \) are both sets of size at most \( \frac{\nu}{2} \). Furthermore, the set \((Cl^{r,\nu}(J) \cup S)\) is \((J, r, \nu)\)-contained in the graph \( G \). As \( Cl^{r,\nu}(J) \) is a \((J, r, \nu)\)-contained set of maximal cardinality, this leads to a contradiction. ▶

**2.2 Existence**

For \( n, m, \Delta \in \mathbb{N} \), we denote by \( \mathcal{G}(m, n, \Delta) \) the distribution over bipartite graphs with disjoint vertex sets \( L := \{v_1, \ldots, v_m\} \) and \( R := \{u_1, \ldots, u_n\} \) where the neighbourhood of a vertex \( v \in L \) is chosen by sampling a subset of size \( \Delta \) uniformly at random from \( R \).

The next claim follows from the standard calculation.
Lemma 9 (de Rezende et al. [9]). Let \( n, m \) and \( \Delta \) be large enough integers such that \( m > n \geq \Delta \). Let \( \xi, \chi \in \mathbb{R}^{+} \) be such that \( \xi < 1/2, \xi \ln \chi \geq 2 \) and \( \Delta \ln \chi \geq 4 \ln m \). Then for \( r = n/(\Delta \cdot \chi) \) and \( c = (1 - 2\xi)\Delta \) it holds asymptotically almost surely for a randomly sampled graph \( G \sim G(m, n, \Delta) \) that \( G \) is an \((r, \Delta, c)\)-boundary expander.

3 Nisan–Wigderson PRG and Its Encoding

Let \( G := (L, R, E) \) be a bipartite graph such that \( L := \{v_1, v_2, \ldots, v_m\} \), \( R := \{u_1, u_2, \ldots, u_n\} \) and each vertex in \( L \) has degree \( \Delta \). Also for each vertex \( v \in L \) we fix some arbitrary enumeration of its neighbours. We identify the right part of this graph with a set of boolean variables \( \{x_1, x_2, \ldots, x_n\} \) and the left part with a set of output bits. Based on this identity we introduce a pseudorandom generator \( F_{G,f} : \{0,1\}^n \rightarrow \{0,1\}^m \) that is defined by the graph \( G \) and a family of the base functions \( f_1, f_2, \ldots, f_m : \{0,1\}^\Delta \rightarrow \{0,1\} \) in the natural way: the \( j \)-th bit of output is defined by \( f_j(u_{i_1}, u_{i_2}, \ldots, u_{i_\Delta}) \) (here we use enumeration of neighbours of the vertex \( v_j \)) where \( u_{i_k} \in N(v_j) \) is a set of neighbours of the vertex \( v_j \in L \). We also use a notation \( Vars_j := N(v_j) \).

We want to encode the question about inversion of the function \( F_G \) as a propositional formula. Following the [2] and [1] we allow to use “local” extension variables.

3.1 Functional Encoding

Let \( F_{G,f} : \{0,1\}^n \rightarrow \{0,1\}^m \) be a pseudorandom generator based on the graph \( G \) and base functions \( f_1, f_2, \ldots, f_m : \{0,1\}^\Delta \rightarrow \{0,1\} \). Let \( b \in \{0,1\}^m \) be an arbitrary point. We say that a boolean function \( g \) is local iff there is some \( i \in [m] \) such that \( g \) depends only on \( Vars_i \).

Let \( \mathcal{G} \) be a collection of local functions.

For each local function \( g \in \mathcal{G} \) we introduce a variable \( y_g \). And we write a CNF formula \( PRG_{G,f,b} \) on variables \( y_g \) which consists of the following disjunctions:

\[
(y_{g_1}^1 \lor y_{g_2}^2 \lor \cdots \lor y_{g_\ell}^\ell), \text{ for all tuples } g_1, g_2, \ldots, g_\ell \text{ where } \ell \leq 2^\Delta \text{ and all } c_1, c_2, \ldots, c_\ell \in \{0,1\} \text{ such that there is } i \in [m]:
\]

- \( g_j \) depends only on \( Vars_i \) for all \( j \in [\ell] \);
- any assignment \( a \in \{0,1\}^\Delta \) that satisfy the equality \( f_i(a) = b_i \) also satisfy the equality \( g_k = c_k \) for at least one \( k \in [\ell] \). In other words the equality \( g_k = c_k \) semantically follows from the equality \( f_i(a) = b_i \).

Note that, in particular, \( PRG_{G,f,b} \) contains the following constraints:

\[
(y_{g_i}^i), \text{ for all } i \in [m];
\]

\[
(\neg y_s \lor y_g), (\neg y_s \lor y_h) \text{ and } (y_s \lor \neg y_g \lor \neg y_h) \text{ for all local functions } s, g, h \text{ such that:}
\]

- \( s = g \land h \);
- there is \( i \in [m] \) such that \( s, g, h \) depends only on \( Vars_i \).

We omit indices of \( PRG_{G,f,b} \) if it is clear from the context. Following [2] we say that it is the functional encoding. The following observation is a straightforward corollary from the definition.

Remark 10 (Aleckhovich et al. [2]). Formula \( PRG_{G,f,b} \) is unsatisfiable iff \( b \notin \text{Im}(F_G) \).

3.1.1 Assignments, Restrictions and Intuition

If we have some total assignment \( \rho \) to \( x \) variables of \( F \) (we call it \( x \)-assignment) it can define an assignment on \( y \) variables in the natural way:
We may think about a clause. We can use these equalities and group variables of the clause.
We denote this assignment by $\rho$. We consider only normal assignments.

Proof. Follows from definition of the functional form. Let $B_1, B_2, \ldots, B_m$ be a sequence of subsets (or bags) of literals $\{g_{y_1}, g_{y_2}, \ldots, g_{y_m}\}$ such that:

- for all $i \in [m], j \in [\ell]$ if $y_{ij} \in B_i$ then $\text{Vars}(g_j) \subseteq \text{Vars}_i$;
- for all $j \in [\ell]$ there is at least one $i \in [m]$ such that $y_{ij} \in B_i$.

Consider a clause $D := (g_{y_1} \lor g_{y_2} \lor \cdots \lor g_{y_m})$ in $y$ variables where $c_i \in \{0, 1\}$. Note, that under normal assignments:

- $y_0^0 \equiv y_{1-g}$;
- $y_0 \lor y_0' \equiv y_g \lor y_g'$.

We can use these equalities and group variables of the clause $D$. Denote by $D := (y_{h_1} \lor y_{h_2} \lor \cdots \lor y_{h_m})$ where

$h_i(x) := \bigvee_{y_i \in B_i} (1 \oplus c \oplus g(x)).$

We may think about a clause $D$ as about the following disjunction:

$F := \bigvee_{i \in [m]} (h_i(x) = 1),$

and we say that $F$ is a functional form of the clause $D$. Denote by

$F|_\rho := \bigvee_{i \in [m]} (h_i(x)|_\rho = 1),$

where $\rho$ is an $x$-assignment.

\textbf{Remark 11.} Functional form is not unique.

To illustrate Remark 11 consider the following situation for some function $g$ such that $y_g \in D$: $\text{Vars}(g) \subseteq (\text{Vars}_i \cap \text{Vars}_j)$. In this case we can put the literal $y_g$ into a bag $B_i$, into a bag $B_j$, or into both of these bags (also into none of them if we have an opportunity to put it into some third bag).

On the other hand Remark 11 provides additional problems if we want to work with functional forms of the clauses since we should care about all possible functional forms. On the other hand non-uniqueness allows to deal with assignments.

\textbf{Lemma 12.} Let $F := \bigvee_{i \in [m]} (h_i(x) = 1)$ be a functional form of a clause $D$. If $\rho$ is a partial $x$-assignment then $F|_\rho$ is a functional form of a clause $D|_{\rho'}$.

\textbf{Proof.} Follows from definition of the functional form. Let $D := (g_{y_1} \lor g_{y_2} \lor \cdots \lor g_{y_m})$, and $B_1, B_2, \ldots, B_m$ be a collection of bags that generates the functional form $(y_{h_1} \lor y_{h_2} \lor \cdots \lor y_{h_m})$. 

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To define a functional form of a clause since we should always pay an attention to the exact form of the clauses.

The observation 13 is a source of problems for the proof of the main theorem, that concludes the proof.

Remark 13. The definition of functional form is “syntactic”, or in other words it heavily depends on variables that appear in the clause $D$ and not only on the boolean function that is defined by it.

To illustrate the remark above let us consider an example. At first we have to define dependency graph (otherwise the notion of local function is meaningless). The graph is defined on fig. 1. Let us choose some collection of local functions:

$$
\ell(x) := x_1 \oplus x_2 \oplus x_3, \quad \ell'(x) := x_1 \oplus x_2, \quad \ell''(x) := x_3
$$

and consider two clauses:

$$
D := y_\ell \vee y_\ell', \quad D' := y_\ell \vee y_\ell'.
$$

To define a functional form of a clause $D$ we have to define two bags $B_1, B_2$. We have to put literal $y_\ell$ into the bag $B_1$ (we have to put it somewhere, and we cannot put it into bag $B_2$ since $\text{Vars}(\ell) \not\subseteq \text{Vars}_2$). The same situation with the literal $y_\ell'$, so there is only way to define bags: $B_1 := \{y_\ell, y_\ell'\}, B_2 := \emptyset$, and in this case the functional form of $D$ is unique and is defined by the following functions:

$$
h_1(x) := (x_1 \oplus x_2 \oplus x_3) \vee (x_1 \oplus x_2), \quad h_2(x) := 0.
$$

To define a functional form of a clause $D'$ we have to define two bags $B'_1, B'_2$. But the situation is different for this clause. Again we have to put literal $y_\ell$ into the bag $B'_1$, but the literal $y_\ell'$ we can put into $B'_1$ or $B'_2$ or into both of them, so there are three ways:

- $B'_1 := \{y_\ell, y_\ell'\}$, $B'_2 := \emptyset$ that give a functional form that is defined by the functions:
  $$
h_1(x) := (x_1 \oplus x_2 \oplus x_3) \vee x_3, \quad h_2(x) := 0;
$$

- $B'_1 := \{y_\ell\}$, $B'_2 := \{y_\ell'\}$ that give a functional form that is defined by the functions:
  $$
h_1(x) := (x_1 \oplus x_2 \oplus x_3), \quad h_2(x) := x_3;
$$

- $B'_1 := \{y_\ell, y_\ell'\}$, $B'_2 := \{y_\ell'\}$ that give a functional form that is defined by the functions:
  $$
h_1(x) := (x_1 \oplus x_2 \oplus x_3) \vee x_3, \quad h_2(x) := x_3.
$$

So functional forms of $D$ and $D'$ are different, but under normal assignments these clauses are equivalent. The observation 13 is a source of problems for the proof of the main theorem, since we should always pay an attention to the exact form of the clauses.
4 Lower Bound

In this section we prove the main Theorem.

Theorem 14 (Formalization of Theorem 1). Let $G := (L, R, E)$ be an $(r, \Delta, (1 - \varepsilon)\Delta)$-expander, where $|L| = m, |R| = n$. If $f_i$ is a family of $(\frac{1}{4}, 3\varepsilon\Delta)$-balanced functions then for any $b \not\in \text{Im}(F_{G,f})$ any resolution proof of $PR_{G,f,b}$ has size $\exp\left[\Omega\left(\frac{\varepsilon^2 r^2}{m}\right)\right]$.

We defer the proof of this Theorem to section 4.4 and start with a plan of our proof.

- We introduce an analog of the width measure on clauses with two important differences:
  - we want to count number of output bits that are touched by a clause rather than number of variables;
  - we want to count only those outputs that we cannot erase from a clause “for free”.
- Let call this measure “heavy width”.
- We hit our proof by a random restriction. We will do it step by step and at each step we create an $x$-assignment $\sigma$ by choosing some output bit $v_i \in [m]$ and assign its neighbours in order to satisfy it. This assignment is equivalent to erasing some vertices from the right part of the graph. So after each step some output bit will not satisfy the expansion property of the graph. We say that these output bits are in danger and choose some $x$-assignment $\nu$ on its neighbours to satisfy them. We hit our proof by $(\sigma \cup \nu)^y$.
- We repeat this process while we do not kill all clauses of big heavy width. At this step it is important that we deal with heavy width rather than usual width.
- We prove a lower bound on the heavy width. For the sake of contradiction we assume that there is a proof of small heavy width. We trace a path in this resolution proof from the final clause to some axiom and maintain a partial assignment that:
  - does not satisfy the current clause (note that this clause may have a large classical width, hence our assignments will not set this clause to a constant);
  - does not violate any axiom.
In the leaf these properties will give a contradiction.

We apply this Theorem for good enough graphs.

Theorem 15 (Formalization of Theorem 2). Let $n$ be large enough integer number, $\delta > 0$, $m := n^{2 - \delta}, \Delta := \log^{2 - \delta} n$ and $G \sim G(m, n, \Delta)$. If $f_i$ is a family of $(\frac{1}{4}, 3\varepsilon\Delta)$-balanced functions then whp for any $b \not\in \text{Im}(F_{G,f})$ any resolution proof of $PR_{G,f,b}$ has size $\exp\left[n^{\Omega(\delta)}\right]$.

Proof. Fix $\chi := n^{6/10}$ and $\xi := \frac{100}{\delta \log n}$.

We use Lemma 9 and show that our graph $G$ whp is an $(\frac{n^{1 - \delta}}{\text{polylog}(n)}, \log^{2 - \delta} n, (1 - \frac{200}{\pi \log n})\Delta)$-expander. Indeed:

- $\xi < \frac{1}{2}$;
- $\xi \ln \chi = \frac{100}{\delta \log n} \ln n > 2$;
- $\xi \ln \chi \Delta \geq 4 \ln n$.

Hence by Theorem 14 size of any resolution proof of $PR_{G,f,b}$ has size at least $\exp\left[\Omega\left(\frac{n^{2 - \delta/5}}{\text{polylog}(n)}\right)^{2\ln(n) / \ln m}\right] \geq \exp\left[\Omega\left(\frac{n^{2 - \delta/5}}{n^{2 - \delta/10}}\right)\right] = \exp[n^{\Omega(\delta)}]$. ∎

Remark 16. Note that if $f_i$ is a balanced function then $f_i(x) \oplus b_i$ is also a balanced function. Hence to simplify the notation we assume that $b = 0^n$ and we omit an index $b$ in the rest of the section. All the results holds for any $b \not\in \text{Im}(F_{G,f})$.  

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4.1 The “Heavy Width”

In the classical restriction technique the notion of the width of a clause $C$ is used to estimate the probability that a random restriction will satisfy a clause. We give the next definition in order to save this property even if we deal with extension variables.

Definition 17. Fix a formula $\text{PRG}_{G,f}$. Let $C$ be a clause with functional form: $F := \bigvee_{i=1}^m (h_i(x) = 1)$. We say that $i$-th output bit is $\eta$-heavy in $F$ wrt $\text{PRG}_{G,f}$ iff $\Pr_{z \leftarrow f^{-1}(0)} [h_i(z) = 1] \geq \eta$. And the $\eta$-heavy width or $\text{hw}_{\text{PRG}_{G,f}}^\eta$ of $F$ is the number of $\eta$-heavy output bits in $F$.

This definition of width depends on the formula. To justify this notion we may think about the “information” about $i$-th output bit in the clause $C$ (despite the fact that it is defined for functional form). We pick a point $z \in \{0, 1\}^\Delta$ that satisfy the constraint $f_i(z) = 0$ uniformly at random. If the probability that we satisfy $C$ by this assignment is small then $C$ “almost avoids” $y$ variables that belongs to $i$-th output bit. In this case we pretend that the clause $C$ is independent of $i$-th output bit, otherwise the value of $C$ is heavily correlated with the value of $f_i$.

Remark 18. The standard width measure can be considered as an $\eta$-heavy width measure. But in the different part of the proofs of classical resolution lower bounds we assume different parameters $\eta$.

- for the reduction from size to width: $\eta$ is an absolute positive constant (usually $\frac{1}{2}$);
- for the width lower bound: $0 < \eta < \frac{1}{2^r}$.

And it works since without extension variables for local functions we can state that: if an output bit is $\eta$-heavy for some $\eta > 0$ then it also $\eta'$-heavy for some $\eta' \approx \frac{1}{2}$.

We define heavy width on functional form of the clause, that may give us potential problems due to the Remark 13.

Definition 19. Let $\pi := D_1, D_2, \ldots, D_s$ be a resolution proof of $\text{PRG}_{G,f}$. And the $\eta$-heavy width $\text{hw}_{\text{PRG}_{G,f}}^\eta$ of the proof $\pi$ is the minimal natural number $w$ such that there is a sequence $F_1, F_2, \ldots, F_s$ where for all $i \in [s]$:

- $F_i$ is a functional form of $D_i$;
- $\text{hw}_{\text{PRG}_{G,f}}^\eta$ of $F_i$ is at most $w$.

4.2 Size to Heavy Width Reduction

In this section we present a random restriction argument that helps to reduce the question about size of proof to a question about $\eta$-heavy width of the proof for carefully chosen parameter $\eta$. Fix some $\text{PRG}_{G,f}$.

Let define the key object that we use in our main Theorem.

Definition 20. Let $G := (L, R, E)$ be an $(r, \Delta, (1 - \varepsilon)\Delta)$-expander. We say that an $x$-assignment $\rho$ of $\text{PRG}_{G,f}$ is self-reduction iff there is a set $L_\rho \subseteq L$ such that:

- $|L_\rho| \leq \varepsilon^2 \frac{r}{\Delta}$;
- $\rho$ assigns all and only variables from $N(L_\rho)$, moreover $\rho$ satisfy constraints from the set $L_\rho$;
- $G \setminus (L_\rho \cup N(L_\rho))$ is an $(r, \Delta, (1 - 2\varepsilon)\Delta)$-expander.

The size of self-reduction is the size of the set $L_\rho$.

The next observation is trivial, but at the same it gives an opportunity to deal with heavy width measure since it is defined only for the $\text{PRG}$ formulas.
Algorithm 1 generates a self-reduction of \( \text{PRG}_G^f \) where \( \text{PRG}_G^f |_{\rho^i} \) is equivalent to \( \text{PRG}_{G', f'} \) under normal assignments where:

- \( G' := G \setminus (L_\rho \cup N(L_\rho)) \);
- \( f' := \{f'_1, \ldots, f'_m\} \) and \( f'_i := f_i |_{\rho^i} \).

We use the following algorithm to generate self-reductions.

**Algorithm 1** \( r, \varepsilon \) are parameters.

1. \( O_1 := \emptyset \) \quad \triangleright \text{Set of active output bits}
2. \( G_1 := G \) \quad \triangleright \text{ } G_i = (L_i, R_i, E_i)
3. \( i := 1 \)
4. \( \rho_1 := \emptyset \)
5. For all \( j \in [m] \): \( p^i_j := f_j \)
6. While \( i \leq \varepsilon^3 \frac{r}{2} \) do
7. Pick a vertex \( v^i \in L_i \) uniformly at random
8. Pick an \( x \)-assignment \( \sigma_i \leftarrow (p^i_0)^{-1}(0) \) uniformly at random
9. \( O_{i+1} := O_i \cup \{v^i\} \)
10. \( G_{i+1}' := G_i \setminus (\{v^i\} \cup N_{G_i}(v^i)) \)
11. \( B_i := \text{argmax}\{|B| \mid B \subseteq L_{i+1}, |B| \leq r_i \partial_{G_{i+1}'}(B) \leq (1 - 2\varepsilon)|B|\} \)
12. Pick an \( x \)-assignment \( \nu_i \) on \( N_{G_{i+1}'}(B_i) \) that satisfy all constraints from the set \( B_i \)
13. \( G_{i+1} := G_{i+1}' \setminus (B_i \cup N_{G_{i+1}}(B_i)) \)
14. \( \rho_{i+1} := \rho_i \cup \sigma_i \cup \nu_i \)
15. For all \( j \in [m] \): \( p^{i+1}_j := f_j |_{\rho_{i+1}} \)
16. \( i := i + 1 \)

**Remark 21.** If \( \rho \) is a self-reduction of \( \text{PRG}_G^f \) then \( \text{PRG}_G^f |_{\rho^i} \) is equivalent to \( \text{PRG}_{G', f'} \).

Following the Remark 21 note that \( (\text{PRG}_G^f) |_{\rho^i} \) is equivalent to \( \text{PRG}_{G_i, f'} \).

**Lemma 22.** Let \( G := (L, R, E) \) be an \( (r, \Delta, (1 - \varepsilon)\Delta) \)-expander graph such that \( |L| = m \), \( |R| = n \) and \( \frac{m}{n} \leq r \). If \( f := \{f_1, \ldots, f_m\} \) is a collection of \( \frac{1}{2}, 3\varepsilon \Delta \)-balanced functions then Algorithm 1 generates a self-reduction of \( \varphi := \text{PRG}_G^f \).

Before the proof we present an intuition about parameters. We are given a family of expander graphs that fixes some \( \varepsilon \) (that we want to be as small as possible) and \( \Delta \). We choose a family of balanced functions with proper parameters. Parameter \( \varepsilon \) determines \( \gamma := 2^{-\varepsilon \Delta} \), on the one hand it is just abbreviation, on the other hand it corresponds to the scaling factor \( 2^\varepsilon \) from the definition of balanced function. In the classical Resolution lower bounds \( \gamma \) is some constant (that is implicit and hidden inside the proof).

**Proof.** Let \( \ell := \varepsilon^3 \frac{r}{2} \) be the number of iterations of our algorithm.

By induction we show the following properties:

- \( G_i \) is an \( (r, \Delta, (1 - 2\varepsilon)\Delta) \)-expander;
- \( |G_i| \leq \varepsilon^2 \frac{r}{2^\Delta}, \)

where \( C_i := \bigcup_{j=1}^{i} B_j \). For proof see Proposition 29 in appendix A.

We have to show that on each iteration we can find some \( x \)-assignment \( \nu_i \) that satisfy the requirements. Since \( |C_i| \leq \varepsilon^2 \frac{r}{2^\Delta} \) that imply, in particular, that \( |B_j| \leq \varepsilon^2 \frac{r}{2^\Delta} \).
Fix some iteration \( i \). Since \( G_i \) is an \((r, \Delta, (1-2\varepsilon)\Delta)\)-expander then by Lemma 28 graph \( G_{i+1} \) is an \((r, \Delta, (1-3\varepsilon)\Delta)\)-expander. Hence by Proposition 5 there is an enumeration \( v^1, v^2, \ldots, v^{|B_i|} \in B_i \) and a sequence \( R_1, \ldots, R_k \subseteq N_{G_{i+1}}(S) \) such that for all \( e \in [|B_i|] \):

\[
\begin{align*}
R_e &= N_{G_{i+1}}(v^e) \setminus \left( \bigcup_{j=1}^{e-1} N_{G_{i+1}}(v^j) \right) \\
|R_e| &\geq (1-3\varepsilon)\Delta.
\end{align*}
\]

We define the \( x \)-assignment \( \nu_i \) step by step starting from \( v^1 \). Consider an auxiliary \( x \)-assignment \( \kappa := \rho_i \cup \sigma_i \). Since \( f_{v^1} \) is a \((\frac{1}{4}, 3\varepsilon\Delta)\)-balanced function and \( \kappa \) assigns at most \(|N_G(v^1)| - |N_{G_{i+1}}(v^1)| \) \(< 3\varepsilon\Delta \) its variables then \( f_{v^1} \mid \kappa \) is not a constant and we define an \( x \)-assignment \( \nu_i^{v^1} \) to \( R_1 \) variables to satisfy the constraint \( f_{v^1}(x) = 0 \). We continue this process for vertices \( v^j \) and \( \kappa := \rho_i \cup \sigma_i \cup \bigcup_{b=1}^{j-1} \nu_b^{v^b} \). The \( x \)-assignment \( \nu_i := \bigcup_{b=1}^{i} \nu_i^{v^b} \) satisfy all constraints from the set \( B_i \) as desired.

At this moment we proved that we can realise all steps of our algorithm. The \( x \)-assignment \( \rho_i \) assigns only variables from \( N(O_T \cup C_T) \), hence \( L_\rho := O_T \cup C_T \). The first property of self-reduction is satisfied: \(|L_\rho| \leq \ell + \varepsilon^2 \frac{1}{16} \leq \varepsilon^2 \frac{1}{10}\). The second follow from the construction. The third property was proved above. Moreover all intermediate \( x \)-assignments \( \rho_i \) are also satisfy these properties.

\begin{align*}
\textbf{Theorem 23.} \text{Let } G := (L, R, E) \text{ be an } (r, \Delta, (1-\varepsilon)\Delta) \text{-expander graph such that } |L| = m, |R| = n \text{ and } \frac{10}{r} \leq \varepsilon. \text{ Fix } \gamma := 2^{-en}. \text{ Let } f := \{f_1, \ldots, f_m\} \text{ be a collection of } (\frac{1}{4}, 3\varepsilon\Delta) \text{-balanced functions, and } \pi := D_1, \ldots, D_s \text{ be a resolution proof of } \varphi := \text{PRG}_{G,f}.

\text{If } s < \exp\left( \frac{\varepsilon^3 \cdot 1}{32} \cdot \frac{\gamma \cdot 0}{\varepsilon} \right) \text{ for some } w \in \mathbb{N} \text{ then there is a self-reduction } \rho \text{ such that } \text{hw}_{\varphi|_{\rho_\pi}}^{\gamma^3} \text{ of } \pi|_{\rho_\pi} \text{ is at most } w.
\end{align*}

\textbf{Proof.} Let \( \theta := F_1, F_2, \ldots, F_s \) where \( F_i \) is a functional form of \( D_i \).

We show that under the current assumptions Algorithm 1 whp give such an \( x \)-assignment. Let \( \ell := \varepsilon^3 \frac{r}{32} \) be the number of iterations of our algorithm. By Lemma 22 it generates self-reduction \( \rho \). We have to check that whp \( \pi|_{\rho_\pi} \) is a proof of small heavy width. We do it for each line in the proof separately and moreover for all \( i \in [s] \) we show that \( (F_i)|_{\rho_\pi} \) has small heavy width.

One of the important difference of heavy width and a classical width that after application of a partial assignment it may increase since we also apply an assignment to the functions \( f_i \) and change our formula. To avoid this problem we analyse \( \text{hw}_{\varphi|_{\rho_\pi}}^{\gamma} \) rather than \( \text{hw}_{\varphi|_{\rho_\pi}}^{\gamma^3} \) of the clauses and show that for any \( F \in \theta \):

\[
\begin{align*}
\text{(i) } &\text{hw}_{\varphi|_{\rho_\pi}}^{\gamma^6} (F|_{\rho_i}) \text{ is small for any } i \leq \ell \text{ than it cannot “grow” to much in the end (in terms of } \text{hw}_{\varphi|_{\rho_\pi}}^{\gamma^3}) \text{;} \\
\text{(ii) } &\text{if } \text{hw}_{\varphi|_{\rho_\pi}}^{\gamma^6} (F|_{\rho_i}) \text{ is big enough for some } i \leq \ell \text{ it will be killed with good enough probability on } i + 1\text{-th iteration.}
\end{align*}
\]

We start with the first part of the proof. Let \( F \in \theta \) be a functional form of a clause from \( \pi \) and \( F \) is defined by the functions \( h_1, h_2, \ldots, h_m \). Fix some \( i \leq \ell \) and pick some alive output bit \( v \in L \setminus L_\rho \). We remind a notation \( p_v := f_v|_{\rho_\pi} \). Output bit \( v \) is alive and graph \( G_t \) is an \((r, \Delta, (1-3\varepsilon)\Delta)\)-expander, hence \( x \)-assignments \( \rho_i \) and \( \rho_t \) can assign at most \( 3\varepsilon\Delta \) variables from \( N(v) \). Thus for all \( i \leq \ell \):

\begin{align*}
\text{(i)} &\text{hw}_{\varphi|_{\rho_\pi}}^{\gamma^6} (F|_{\rho_i}) \text{ is small for any } i \leq \ell \text{ than it cannot “grow” to much in the end (in terms of } \text{hw}_{\varphi|_{\rho_\pi}}^{\gamma^3}) \text{;} \\
\text{(ii)} &\text{if } \text{hw}_{\varphi|_{\rho_\pi}}^{\gamma^6} (F|_{\rho_i}) \text{ is big enough for some } i \leq \ell \text{ it will be killed with good enough probability on } i + 1\text{-th iteration.}
\end{align*}
Hence for all $F \in \theta$ and all $v \in L$ if $v$ is $\gamma^3$-heavy in $F|_{\rho t}$ wrt $\varphi|_{\rho t}$ then $v$ is $\frac{\gamma^6}{3}$-heavy in $F|_{\rho^t}$, wrt $\varphi|_{\rho^t}$ for all $i \leq \ell$. And $\text{hw}^3 \varphi|_{\rho^t} (F|_{\rho t}) \geq w$ imply that $\text{hw}^6 \varphi|_{\rho^t} (F|_{\rho t}) \geq w$ for all $i \leq \ell$.

Consider a clause $D$ in $\pi|_{\rho^t_{i-1}}$ and its functional form $F \in \theta$. Denote by $H$ the event that $v^i$ is $\frac{\gamma^6}{3}$-heavy output bit in $F$ wrt $\text{PRG}_{G,f}|_{\rho^t_{i-1}}$. Clause $D$ is killed by $\rho^t_y$ with probability at least:

$$
\Pr_{v^i,\sigma_i}[D|_{\sigma_i} = 1] \geq \Pr_{v^i,\sigma_i}[h_{v^i}(x)|_{\sigma_i} = 1] \\
\geq \Pr_{v^i,\sigma_i}[H] \cdot \Pr_{v^i,\sigma_i}[(h_{v^i}|_{\sigma_i} = 1) | H] \\
\geq \frac{|\{v^i \in [m] | H\}|}{m} \cdot \frac{\gamma^6}{3}.
$$

Hence for the clause $D \in \pi$ there are two ways.

- At some moment $i \leq \ell$ the $\text{hw}^6 \varphi|_{\rho^t} (F|_{\rho^t}) \leq w$. In this case $D$ is not interesting for us anymore, as we proved above $\text{hw}^3 \varphi|_{\rho^t} (F|_{\rho^t}) \leq w$.

- If $\text{hw}^6 \varphi|_{\rho^t} (F|_{\rho^t}) \geq w$ then the probability that the clause $D|_{\rho^t}$ is survived on $i + 1$-th iteration is at most:

$$
\Pr[D|_{\rho^t} \text{ is survived on } i + 1 \text{-th iteration}] \leq 1 - \frac{w \gamma^6}{m}.
$$

And hence:

$$
\Pr[D \text{ is survived after } \ell \text{ iterations}] \leq \\
\prod_{i} \Pr[D|_{\rho^t_i} \text{ is survived on } i + 1 \text{-th iteration}] \leq \\
\left(1 - \frac{w \gamma^6}{m}\right)^\ell, \quad \text{since } \text{hw}^6 \varphi|_{\rho^t} (F|_{\rho^t}) \geq w
$$

To conclude the proof note that

$$
\Pr[\text{hw}^3 \varphi|_{\rho^t} (F|_{\rho^t}) > w] \leq \left(1 - \frac{w \gamma^6}{m}\right)^\ell = \left(1 - \frac{w \gamma^6}{m}\right)^{\frac{\gamma^6}{3} \frac{1}{m}} \leq \left(1 - \frac{w \gamma^6}{m}\right)^{\frac{\gamma^6}{3}} \frac{\gamma^6}{3} \log s < \frac{1}{s}.
$$
By the union bound over all $F \in \theta$ we conclude that:
\[
\Pr[\exists F \in \theta, \text{hw}_{\varphi|_{\rho_1}}^\gamma (F|_{\rho_1}) > w] < 1.
\]
Or in other words there is an $x$-assignment $\rho$ that satisfy all required properties. ▷

## 4.3 Heavy Width Lower Bound

For the sake of contradiction assume that we have a proof $\pi := (D_1, \ldots, D_n)$ of small heavy width. Starting from $D_1$ we trace the path $p$ in the dag of $\pi$ to the initial clause. During this process we maintain a partial $x$-assignment $\sigma$ such that in the clause $D \in p$ for any small set $S$ of initial clauses the $x$-assignment $\sigma$ can be extended for an $x$-assignment $\kappa \supseteq \sigma$ such that $S$ is satisfied by $\kappa$, but $D$ does not. That give us a contradiction in a leaf where $D$ should be one of the initial clauses.

This assignment $\sigma$ will assign neighbours of heavy output bits of the generator and some extension (closure) to make sure that the remaining graph (after removing assigned variables) is an expander. Since the remainder is an expander (in particular we assign not so many neighbours of any alive output bit) then the existence of the assignment $\kappa$ will follow from the fact other output bit are not heavy that means that there are a lot of points that satisfy the constraint but not satisfy the clause.

In this section we assume that $G := (L, R, E)$ be an $(r, \Delta, (1 - \varepsilon)\Delta)$-expander and $\text{PRG}_{G, f}$ is based on this graph an some functions $f_i$ (again we assume that zero point not in $\text{Im}(F|_{G, f})$ and state our result for this point, but it holds for all $b \notin \text{Im}(F|_{G, f})$). All clauses deal with variables of $\text{PRG}_{G, f}$. We also fix an abbreviation $\gamma := 2^{-\varepsilon}\Delta$.

Let start with auxiliary objects and lemmas.

► **Definition 24.** Let $\rho$ be a self-reduction of $\text{PRG}_{G, f}$. Let $C$ be a clause and $F$ its functional form, $I_\eta$ be a set of $\eta$-heavy output bits wrt $\text{PRG}_{G, f}|_{\rho^\gamma}$. We say that an output bit $v$ is $(\eta, \nu)$-dangerous for $F$ iff $v \in \text{Cl}^{\nu, \tau}(N_G (I_\eta \cup L_\rho))$. Denote this set by $D^\eta_{\nu, \rho}$.

Note that this definition make sense only if graph $G$ is an expander. Also note that $I_\eta \cup L_\rho \subseteq \text{Cl}^{\nu, \tau}(N_G (I_\eta \cup L_\rho))$. For fixed parameters $\eta$ and $\nu$ and a clause $C$ with functional form $F$ we also say that an $x$-assignment $\sigma \supseteq \rho$ is $(\eta, \nu)$-locally consistent iff:

- $\sigma^{-1}(\{0, 1\}) = N (D^\eta_{\nu, \rho})$;
- $C|_{\sigma v} \neq 1$;
- $\sigma$ satisfy all constraints that correspond to $D^\eta_{\nu, \rho}$.

The following Lemma is the heart of the proof. It says that locally consistent assignments cannot violate any constraint from our formula.

► **Lemma 25.** Let $f := \{f_1, \ldots, f_m\}$ be a collection of $\{\frac{1}{4}, 3\varepsilon\Delta\}$-balanced functions, $\gamma < \frac{1}{8}$ and $\rho$ be a self-reduction of $\text{PRG}_{G, f}$. If $C$ is a clause with functional form $F$ such that $\text{hw}^\gamma_{\text{PRG}_{G, f}|_{\rho^\gamma}}(F) \leq \varepsilon_8$ and $\sigma$ is a $(\gamma^3, (1 - 2\varepsilon)\Delta)$-locally consistent assignment then for any $J \subseteq L$ such that $|J| \leq \varepsilon_3 \frac{1}{3}$, there is an extension $\kappa \supseteq \sigma$ such that:

- $\kappa^{-1}(\{0, 1\}) \supseteq N (D^\gamma_{\rho, f}|_{\kappa}) \cup N (J)$;
- $C|_{\kappa v} \neq 1$;
- $\forall v \in J, f_\nu(x)|_{\kappa} = 0$.

**Proof.** Let $D := D^\gamma_{\rho, f}|_{\kappa}$ and $F := \bigvee(h_i(x) = 1)$. Let $I := \text{Cl}^{\tau, (1 - 2\varepsilon)\Delta}(N_G (J) \cup N_G (D)) \setminus D$. By Lemma 7 $|I| \leq \frac{3}{8^{\gamma}}$. By the definition of closure $I \supseteq J \setminus D$. 

By Lemma 8 graph $G' := G \setminus (D \cup N_G (D))$ is an $(\frac{1}{2}, \Delta, (1 - 2\varepsilon)\Delta)$-expander. By Proposition 5 there is an enumeration $v^1, v^2, \ldots, v^{|I|} \in I$ and a sequence $R_1, \ldots, R_{|I|} \subseteq N_G (S)$ such that:

$R_i = N_G (v^i) \setminus \bigcup_{j=1}^{i-1} N_G (v^j)$;

$|R_i| \geq (1 - 2\varepsilon)\Delta$.

We define a family of $x$-assignments $\nu_i$ and $\kappa_i := \bigcup_{j=1}^i \nu_i \cup \sigma$ step by step, starting from $\nu_1$ in the following way:

- $\nu_1^{-1} (\{0, 1\}) = R_i$;
- $f_{\nu_i} (x) |_{\kappa_i} = 0$;
- $C_{|\kappa_i^*} \neq 1$.

We have to show the existence of such $\nu_i$. Note that $|R_i| \geq (1 - 2\varepsilon)\Delta$ hence $\kappa_{i-1}$ can assign at most $2\varepsilon\Delta$ variables in $N_G (v^i)$. Since $f_{\nu_i}$ is a balanced function:

$|f_{\nu_i} |_{\kappa_{i-1}} (0) | \leq \frac{1}{4} \gamma^2 \Delta \geq \frac{1}{4} \gamma^2 |f_{\nu_i}^{-1} (0)|$.

Output bit $v^i$ is not $\gamma^3$-heavy hence there are at most $\gamma^3 |f_{\nu_i}^{-1} (0)|$ different $x$-assignments to $R_i$ that maps $h_{\nu_i}$ to 1, assuming that $\gamma < \frac{1}{2}$ we can find an assignment that maps $h_{\nu_i}$ to 0 and satisfy the constraint $f_{\nu_i} (x) = 0$. We define $\kappa := \kappa_{|I|}$.

It remains to check that $\kappa y$ does not satisfy $C$, that does not immediately follow from the construction due to Remark 13. To show this fact we use an expansion of underlying graph. For the sake of contradiction assume that $\kappa y$ maps some literal $y_x \in C$ to 1 and this literal belongs to bag $B_v$. Consider three cases.

1. $\kappa$ assigns all variables from $N (v)$. In this case $h_v (x) |_{\kappa}$ is mapped to 1 since $h_v$ is a disjunction of $(1 \oplus c \oplus y)$ with some function. that contradicts with the choice of $\kappa$.

2. $\kappa$ assigns at most $2\varepsilon\Delta$ variables from $N (v)$. Note that

$$\Pr_{z \leftarrow f_{\nu_i}^{-1} (0)} [h_v (z) = 1] \geq \Pr_{z \leftarrow f_{\nu_i}^{-1} (0)} [z \text{ cons. with } \kappa] \geq \Pr_{z \leftarrow \{0, 1\}^\Delta} [z \text{ cons. with } \kappa \wedge f_v (z) = 0] \geq \gamma^2 \Pr_{z \leftarrow \{0, 1\}^\Delta} [f_v (z) = 0 \mid z \text{ cons. with } \kappa] \geq \gamma^2 \Pr_{z \leftarrow \{0, 1\}^\Delta} [f_v (z) |_{\kappa} = 0] \geq \frac{\gamma^2}{4} \geq \gamma^3.$$

But in this case $v \in D$ by definition of $D$. Hence $\kappa$ should assign all variable in $N (v)$.

3. $\kappa$ assigns at least $2\varepsilon\Delta + 1$ variables from $N (v)$ but not all of them. That contradicts with the fact that $\kappa$ assigns variables from $N (I \cap D) = N \left( C^{r-1, (1-2\varepsilon)\Delta} (N_G (J) \cup N_G (D)) \right)$ and Lemma 8.

Theorem 26. Let $\varepsilon < \frac{1}{4}$, $G := (L, R, E)$ be an $(r, \Delta, (1 - \varepsilon)\Delta)$-expander graph such that $|L| = m$, $|R| = n$. Fix $\gamma := 2^{-r \Delta} < \frac{1}{2}$. If $f := \{ f_1, \ldots, f_m \}$ is a collection of $(\frac{1}{4}, 3\varepsilon\Delta)$-balanced functions then $hw_{\rho y}^2 (PRG_{G,f} |_{\rho y})$ of any resolution proof of $PRG_{G,f} |_{\rho y}$ is at least $\varepsilon^2 \frac{8}{49} m$, where $\rho$ is self-reduction.

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Proof. For the sake of contradiction assume that \( \pi = (D_1, \ldots, D_s) \) is a resolution proof of \( \text{PRG}_{G,f} |_{\rho^x} \) at most \( \epsilon^2 \frac{r^2}{m} \). Let \( \theta = (F_1, F_2, \ldots, F_s) \) be a sequence of functional forms that is witnessing heavy width of \( \pi \). For a disjunction \( F_i \in \theta \) we denote \( D_i := \text{hw}_{\text{PRG}_{G,f}}^{F_i} |_{\rho^y} \).

For the clause \( D_s \) with functional form \( F_s \) an \( x \)-assignment \( \rho \) is locally consistent, since graph \( (G \setminus (L_\rho \cup N(L_\rho))) \) is an \((r, \Delta, (1-2\epsilon)\Delta)\)-expander. We want to show that the existence of a locally consistent assignment \( \kappa^D \) for some clause \( D \in \pi \) with functional form \( F \in \theta \) imply the existence of a locally consistent assignment for at least one of its predecessors. In this case the one can trace the path from \( D_s \) to some initial clause \( D_k \in \pi \cap \text{PRG}_{G,f} |_{\rho^y} \) with functional form \( F_k \) and show the existence of a locally consistent assignment \( \kappa^{D_k} \) for this clause.

Suppose that \( D_k := (y_{g_1} \lor y_{g_2} \lor y_{g_3} \lor y_{g_4}) \). By construction of \( \text{PRG}_{G,f} \) we can find an \( i \in [m] \) such that for all \( j \in [k] \):

\[
\begin{align*}
&= g_j \text{ depends only on } \text{Vars}_i; \\
&= \text{the equality } g_j(x) = c_j \text{ semantically follows from the equality } f_i(x) = 0.
\end{align*}
\]

But in this case \( i \) is \( 1 \)-heavy for \( D_k \) and for any \( x \)-assignment \( \sigma \) the condition \( f_i(x) |_{\sigma} = 0 \) imply that \( D_k |_{\rho^y} \equiv 1 \). This fact contradicts with the definition of locally consistent assignment.

Suppose a locally consistent assignment \( \kappa \) exists for a clause \( D_i \in \pi \) with functional form \( F_i \in \theta \) and \( D_a, D_b \) are predecessors of \( D_i \) in \( \pi \) with functional forms \( F_a, F_b \) respectively. Note, that \( \text{hw}_{\kappa}^{F_a} \) of these functional forms are at most \( \epsilon^2 \frac{16}{10} \), hence Lemma 7 together with the upper bound \( |L_\rho| \leq \frac{4r}{10} \) imply that the sizes of \( D_i, D_a, D_b \) are at most \( \epsilon \frac{4r}{10} + \frac{4r}{10} = \epsilon \frac{8r}{10} \). By Lemma 25 we have an extension \( \sigma \geq \kappa \) on \( N_G(D_a \cup D_b) \) that satisfy constraints of \( \text{PRG}_{G,f} \) that correspond to \( D_a \cup D_b \) but do not satisfy \( D_i \). And since \( \sigma \) do not satisfy \( D_i \) it also do not satisfy at least one of its predecessor, wlog it is \( D_a \). And the \( x \)-assignment \( \sigma \cap N_G(D_a) \) is a locally consistent for \( D_a \) and \( F_a \) as desired.

4.4 Proof of Theorem 14

For the sake of contradiction assume that \( \pi := D_1, D_2, \ldots, D_a \) is a resolution proof of \( \text{PRG}_{G,f} \) and \( s \leq \exp \frac{\delta \cdot 2^r \gamma^2}{\epsilon \cdot m^2} \) for some \( \delta \leq 10^{-4} \).

Fix \( w := \frac{2^r \gamma^2}{20} \) and \( \gamma := 2^{-\epsilon \Delta} \). Note that:

\[
\exp \left( \frac{\epsilon^5 \cdot r^2}{32} \cdot \frac{1}{3^6} \cdot \frac{w}{m} \right) = \exp \left( \frac{\epsilon^3 \cdot 3^6}{32} \cdot \frac{1}{3^6} \cdot \frac{r^2}{20 \cdot m} \right) \geq \exp \left( \frac{\epsilon^5}{2000} \cdot \frac{r^2}{m} \right) \geq \exp \left( \delta \cdot \frac{2^r \gamma^2}{20} \right) \geq s,
\]

hence we can apply Theorem 23 that gives a self-reduction \( \rho \). We hit the proof \( \pi \) by \( \rho^y \) and the proof \( \pi |_{\rho^y} \) is a proof of \( \text{PRG}_{G,f} |_{\rho^y} \). Moreover the \( \text{hw}_{\text{PRG}_{G,f} |_{\rho^y}}^{\pi} \) is at most \( w \).

Since \( \rho \) is a self-reduction then by Theorem 26 any proof of \( \text{PRG}_{G,f} |_{\rho^y} \) requires \( \text{hw}_{\text{PRG}_{G,f} |_{\rho^y}}^{\pi} \) at least \( \epsilon^2 \frac{r}{10} > w \). Contradiction.

5 Comments and Further Directions

The most important is the lower bounds on the Nisan–Wigderson generator with \( m \gg n^2 \). The technical barrier for doing it is the scaling factor \( \frac{1}{m} \) that comes from the step 7 of the algorithm 1. And it is a fundamental problem of the general restriction technique that we use in proof complexity. The most promising approach for avoiding this problem is the “pseudowidth” that was created by Razborov in [20, 21] and equipped with a closure trick in [9].
The pseudowidth technique may be viewed as a replacement of the “self-reductions” and algorithm from Section 4.2. Instead of hitting the proof by a restriction we look at the small enough proof and try to add a carefully chosen set of axioms to our formula that allows to transform this formula into a proof of small “pseudowidth”. The pseudowidth measure itself may be considered as an α-heavy width where parameter α can be different for different output bits. Unfortunately, to apply this strategy we have to deal with large enough parameters α, but all results from Section 4.3 used the fact that α is small enough. That leads to another technical, but the important open problem: can one prove that any resolution proof of \( PRG_{G,f} \) has \( \frac{1}{100} \)-heavy width at least \( \Omega(n^\delta) \)?

We may also ask to generalize the lower bounds to stronger proof systems. It seems adaptation of this technique for Polynomial Calculus (or Sherali–Adams) may be a challenging problem if we want to go beyond the logarithmic threshold, i.e. \( \Delta \gg \log n \).

The current result also does not seem tight. We believe that if the dependency graph of NW generator is an \( (r, \Delta, 0.99 \cdot \Delta, 0) \)-boundary expander then the right bound should depend only on parameters \( m \) and \( r \) (usually \( r \approx \frac{n^{poly(\Delta)}}{m} \)). As an explicit open problem we ask to show the following lower bound: \( \exp \left[ r^2 \frac{n^{poly(\Delta)}}{m} \right] \).

References

At first we show a simple auxiliary statement.

Lemma 27. Suppose that $G := (L, R, E)$ is an $(r, \Delta, c)$-boundary expander and that $J \subseteq R$ has size $|J| \leq \Delta r$. Then if $X \subseteq L$ has size $|X| \leq r$ and $|\partial(X) \setminus J| \leq \nu|X|$ then $X \leq \frac{|J|}{c-\nu}$.

Proof. The expansion property of the graph guarantees that $c|X| - |J| \leq |\partial(X) \setminus J|$. The conclusion follows.
Lemma 28. Let $G := (L, R, E)$ be an $(r, \Delta, (1 - \varepsilon)\Delta)$-boundary expander. Then $G \setminus \{v\}$ is an $(r - 1, \Delta, (1 - \frac{3}{2}\varepsilon)\Delta)$-expander where $v \in L$ is an arbitrary vertex.

Proof. Fix some $v \in L$ and denote $G' \setminus \{v\} := G \setminus \{v\}$.

Consider some set of $S \subseteq (L \setminus \{v\})$ of size at most $r - 1$ and denote $H := N(S) \cap N(v)$. Since $G$ is an expander:

$$|\partial_G (S \cup v)| = |\partial_G (S)| + \Delta - |H| \geq (1 - \varepsilon)\Delta(|S| + 1)$$

$$|\partial_{G'} (S)| \geq (1 - \varepsilon)\Delta|S| - \varepsilon\Delta + |H|.$$ But from the other point of view:

$$|\partial_{G'} (S)| \geq |\partial_G (S)| - |H| \geq (1 - \varepsilon)\Delta|S| - |H|.$$ Altogether:

$$|\partial_{G'} (S)| \geq (1 - \varepsilon)\Delta|S| - \min(|H|, \varepsilon\Delta - |H|) \geq (1 - \varepsilon)\Delta|S| - \frac{\varepsilon}{2}\Delta \geq \left(1 - \frac{3}{2}\varepsilon\right)\Delta|S|.$$ ◀

Proposition 29 (Analog of [24]). For all $i \leq \ell$:

- $G_i$ is an $(r, \Delta, (1 - 2\varepsilon)\Delta)$-expander;
- $|C_i| \leq \varepsilon^2 \frac{r}{2\Delta}$.

Proof. At first we prove the second claim $|C_i| \leq \varepsilon^2 \frac{r}{2\Delta}$ by induction. $C_0$ is an empty set. Suppose that $|C_{i-1}| \leq \varepsilon^2 \frac{r}{2\Delta}$. There are two steps in the proof:

- we show that $|B_i| \leq \frac{r}{4}$ that give us an opportunity to use expansion property for the set $C_i$;
- we give a lower bound on size $\partial_G (C_i)$ by using expansion property and the upper bound by the choice of $B_i$ that together give us an upper bound on size of $C_i$.

Let start with the first step. $|\partial_G (B_i) \setminus N_G (C_{i-1} \cup O_{i+1})| \leq |\partial_{G_{i+1}} (B_i)| \leq (1 - 2\varepsilon)|B_i|$. By definition $|B_i| \leq r$ and hence by Lemma 27 $|B_i| \leq \frac{|N_G (C_{i-1} \cup O_{i+1})|}{\varepsilon\Delta} \leq \frac{r}{4} + \frac{\varepsilon}{2}r \leq \frac{r}{4}$. That concludes the first step.

$$(1 - \varepsilon)\Delta|C_i| \leq |\partial_G (C_i)| \leq \left| \bigcup_{j=1}^{i} (\partial_G (B_j) \setminus N_G (C_{j-1})) \right| \leq \left| \bigcup_{j=1}^{i} (\partial_G (B_j) \setminus (N_G (C_{j-1}) \cup N (O_{j+1})) \cup N (O_{j+1})) \right| \leq \left| \bigcup_{j=1}^{i} \partial_{G_{j+1}} (B_j) \cup N (O_{i+1}) \right| \leq (1 - 2\varepsilon)\Delta \sum_{j=1}^{i} |B_j| + |N (O_{i+1})| \leq (1 - 2\varepsilon)\Delta|C_i| + |N (O_{i+1})|.$$

And hence $|C_i| \leq \frac{|N (O_{i+1})|}{\varepsilon\Delta} \leq \varepsilon^2 \frac{r}{2\Delta}$ as desired.
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The first claim we prove by contradiction. Pick the minimal \( i \) such that \( G := G_i \) is not an \((r, \Delta, (1 - 2\varepsilon))\)-boundary expander and \( S \subseteq L \) be a witness of it, i.e. \( |S| \leq r \) and \( |\partial G (S)\| \leq (1 - 2\varepsilon)|S|\). As in previous case \( |\partial G (S) \setminus (N_G (C_{i-1} \cup O_{i}) | \leq |\partial G (S)\| \leq (1 - 2\varepsilon)|S|\) hence by Lemma 27 \( |S| \leq \frac{|N_G (C_{i-1} \cup O_{i})|}{2} \leq \frac{r}{2} \).

Consider a set \( S \cup B_{i-1} \) and note that size of it at most \( r \).

\[ |\partial G' (S \cup B_{i-1}) | \subseteq |\partial G_i (S) \cup \partial G_i (B_{i-1}) | \] by definition of \( G_i \). This implies \( |\partial G_i (S \cup B_{i-1}) | \leq (1 - 2\varepsilon)\Delta |S| + (1 - 2\varepsilon)\Delta |B_{i-1}| = (1 - 2\varepsilon)\Delta |S \cup B_{i-1}| \). That contradicts with the choice of \( B_{i-1} \).

\[ \Leftrightarrow \quad \text{Lemma 30. There is a constant } n_0 \in \mathbb{N} \text{ such that for any } n > n_0 \text{ if a function } f : \{0, 1\}^n \to \{0, 1\} \text{ is chosen uniformly at random then whp it is } (\frac{1}{4}, n - \sqrt{n})-balanced. \]

\[ \text{Proof. There are at most } \sum_{i=0}^{n} \left( \frac{n}{i} \right) \cdot 2^i = 3^n \]

different partial assignments.

A fixed partial assignment \( \rho \) of size \( k \) corresponds to a boolean subcube \( S \subseteq \{0, 1\} \) of size \( 2^{n-k} \) for which we want to estimate number of ones and zeroes. Note that:

\[ \Pr_f \left[ (|f|_{\rho})^{-1}(1) \leq \frac{1}{4} 2^{n-k} \right] \leq \sum_{i=0}^{2^{n-k}/4} \left( \begin{array}{c} 2^{n-k} \end{array} \right) \cdot 2^{-2^{n-k}} \leq 2^{-\left(1 - H(1/4)\right)2^{n-k}} \leq 2^{-0.1 \cdot 2^{n-k}}. \]

Altogether:

\[ \sum_{\rho, |\rho| \leq n - \sqrt{n}} \left( \Pr_f \left[ (|f|_{\rho})^{-1}(1) \leq \frac{1}{4} 2^{n-|\rho|} \right] + \Pr_f \left[ (|f|_{\rho})^{-1}(0) \leq \frac{1}{4} 2^{n-|\rho|} \right] \right) \leq 2 \cdot 3^n \cdot 2^{-0.1 \cdot 2^{\sqrt{n}}} \leq 2^{-2^{0.1 \sqrt{n}}}. \]