The Longest Run Subsequence Problem

Sven Schrinner

Algorithmic Bioinformatics, Heinrich Heine University Düsseldorf, Germany sven.schrinner@hhu.de

Manish Goel ©



Max Planck Institute for Plant Breeding Research, Cologne, Germany

Michael Wulfert

Algorithmic Bioinformatics, Heinrich Heine University Düsseldorf, Germany



Algorithmic Bioinformatics, Heinrich Heine University Düsseldorf, Germany

Korbinian Schneeberger



Max Planck Institute for Plant Breeding Research, Cologne, Germany Cluster of Excellence on Plant Sciences (CEPLAS), Heinrich Heine University Düsseldorf, Germany Faculty of Biology, LMU Munich, Planegg-Martinsried, Germany

Gunnar W. Klau¹



Algorithmic Bioinformatics, Heinrich Heine University Düsseldorf, Germany Cluster of Excellence on Plant Sciences (CEPLAS), Heinrich Heine University Düsseldorf, Germany gunnar.klau@hhu.de

Abstract

Genome assembly is one of the most important problems in computational genomics. Here, we suggest addressing the scaffolding phase, in which contigs need to be linked and ordered to obtain larger pseudo-chromosomes, by means of a second incomplete assembly of a related species. The idea is to use alignments of binned regions in one contig to find the most homologous contig in the other assembly. We show that ordering the contigs of the other assembly can be expressed by a new string problem, the longest run subsequence problem (LRS). We show that LRS is NP-hard and present reduction rules and two algorithmic approaches that, together, are able to solve large instances of LRS to provable optimality. In particular, they can solve realistic instances resulting from partial Arabidopsis thaliana assemblies in short computation time. Our source code and all data used in the experiments are freely available.

2012 ACM Subject Classification Theory of computation → Dynamic programming; Mathematics of computing \rightarrow Combinatorial optimization; Applied computing \rightarrow Computational genomics

Keywords and phrases alignments, assembly, string algorithm, longest subsequence

Digital Object Identifier 10.4230/LIPIcs.WABI.2020.6

Supplementary Material Source code and all data used in the experiments available at https: //github.com/AlBi-HHU/longest-run-subsequence.

Funding Funded by the Deutsche Forschungsgemeinschaft (DFG, German Research Foundation) – projectID 395192176 – as well as under Germany's Excellence Strategy – EXC 2048/1 – projectID 390686111.

1 Introduction

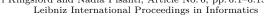
Genome assembly from sequencing reads enables the analysis of an organism at its genome level and is one of the most important problems in computational genomics. The first step is usually to assemble the reads based on overlap or k-mer based approaches to create contigs,

Corresponding author



© Sven Schrinner, Manish Goel, Michael Wulfert, Philipp Spohr, Korbinian Schneeberger, and Gunnar W. Klau;

licensed under Creative Commons License CC-BY 20th International Workshop on Algorithms in Bioinformatics (WABI 2020). Editors: Carl Kingsford and Nadia Pisanti; Article No. 6; pp. 6:1–6:13



6:2 The Longest Run Subsequence Problem

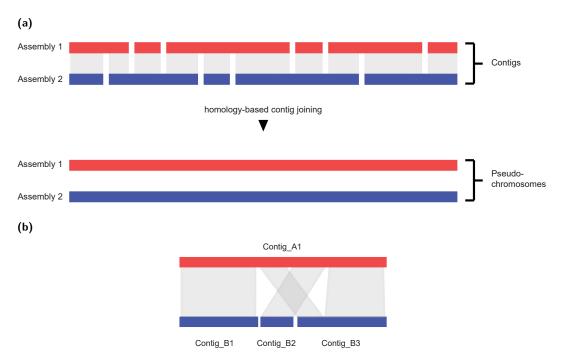


Figure 1 Homology-based scaffolding. (a) Independent initial assemblies (contigs), which are joined into pseudo-chromosomes by using homologies between contigs for scaffolding. (b) Alignments between contigs from different samples. A1 determines the order of B1, B2 and B3.

which then need to be put into correct order and orientation in a scaffolding phase to generate the final assembly of pseudo-chromosomes. Presence of a high-quality chromosome-level reference genome of the same species can significantly simplify assembly generation as it can be used as a template to order these contigs [1, 3]. However, for many species, such a reference genome is not available.

There are two commonly used approaches for scaffolding. First, different types of maps provide anchors for the contigs in the genome. These could be, for example, genetic maps, physical maps or cytological maps providing markers with known positions in the genome and known distances between each other [9]. The other approach is to use long-range genomic information to link multiple contigs and put them into correct order and orientation. Prominent examples are linked barcoded reads like 10X sequencing [10], Hi-C data based on chromatin conformation capture [2] and optical mapping [7].

Yet another way for contig scaffolding is to use two or more incomplete assemblies from closely related samples [4]. Regions of unconnected contigs for one sample might be connected with the help of another, related sample, e.g., a genome assembly of an individual of the same species, providing an overall gain in information for both samples. Local similarities between contigs from different samples can be used to align and order them. Ideally, this leads to long chromosome like sequences called pseudo-chromosomes, where the contigs of different samples are aligned like shingles next to each other, as illustrated in Figure 1(a).

Note that structural rearrangements (such as translocations or inversions) and repeat regions between genomes can result in non-sequential and non-unique mappings within contigs and can thus lead to misleading connections between contigs. These events need to be considered when finding homologous contigs as shown in Figure 1(b).

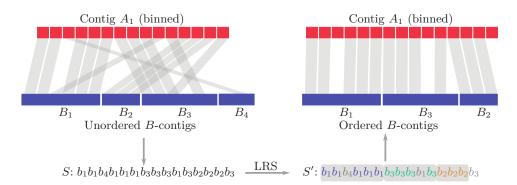


Figure 2 Processing of a single contig A_1 . The bins are matched against all contigs of another sample B. Solving Longest Run Subsequence (LRS) on the corresponding string S, yields a maximal subsequence with at most one run for every contig. This induces the optimal order for a subset of B-contigs.

In the simplest setting of two incomplete assemblies we are given two sets of contigs $A = \{A_1, \ldots, A_l\}$ and $B = \{B_1, \ldots, B_m\}$ computed from two different samples. As already stated, the contigs are not ordered with respect to genome positions, and it is this order we rather want to compute. More precisely, we aim at inferring the most likely order from between-sample overlaps among the contigs.

Assuming we want to order the contigs in B, we divide every contig A_i of A into smaller, equally sized chunks, called bins, map them against the contigs in B and determine the best matching contig for every bin. If A_i actually overlaps with multiple contigs in B, we should be able to partition A_i into smaller parts based on mapping the bins to different contigs in B. However, sequencing or mapping errors as well as mutations between the samples can cause some bins to map onto a "wrong" contig, i.e., a contig belonging to a different area than the bin. Therefore a method to find the best partition of A_i needs to distinguish between actual transitions from one B-contig to another and noise introduced by errors or mutations.

Figure 2 illustrates the different steps in solving this problem. Starting from a binned contig from A, here A_1 for illustration, and its mapping preferences to the unordered contigs in B, we reformulate this ordering problem as a string problem. In essence, we want to find the longest subsequence of the input string of mapping preferences that consists only of consecutive runs of contigs from B where each such run may occur at most once. This subsequence corresponds to an ordering of the contigs in B, which can be transferred to the original problem.

In this paper we formalize this process and introduce the *Longest Run Subsequence* problem (LRS). We show that LRS is NP-hard. Nevertheless, we want to solve large instances of LRS to provable optimality in reasonable running time and therefore present a number of reduction rules and two algorithms based on integer linear programming and dynamic programming, respectively. We evaluate both approaches on synthetic instances and find that they show complementary strengths regarding the number of runs and the alphabet size. We also test our approaches on realistic instances, which occurred during assembly of *Arabidopsis thaliana* samples and could not be solved by a brute-force method. We show that all those instances can be solved within short computation time. Our code and all data used in the experiments are freely available at https://github.com/AlBi-HHU/longest-run-subsequence.

2 Problem Formulation

A string $S = s_1, \ldots, s_m$ is a sequence over characters from a finite alphabet Σ . A subsequence of S is a sequence s_{i_1}, \ldots, s_{i_k} , such that $1 \leq i_1 < i_2 < \ldots < i_k \leq m$. We denote the substring s_i, \ldots, s_j of S as S[i,j] and k consecutive occurrences of a character σ inside a string S as σ^k and call it a run. Let $\sigma(r)$ be the character of the run r and L(r) its length. By summarizing the characters of S into maximally long runs, S can be represented as a unique sequence of runs $r_1, \ldots, r_n = \sigma(r_1)^{L(r_1)} \ldots \sigma(r_n)^{L(r_n)}$. For every $\sigma \in \Sigma$ we define $P_{\sigma}(i)$ as the index of the last run before r_i containing σ in S (0 if it does not occur). As an example, the string from Figure 2 can be compressed to $b_1^2 b_4^3 b_1^3 b_3^3 b_1^1 b_3^1 b_2^3 b_3^1$ with $P_{b_1}(4) = 3$, $P_{b_1}(3) = 1$ and $P_{b_4}(1) = 0$.

We propose to model the optimal partition of a single contig as a string optimization problem. Formally, we use the contigs from set B as the alphabet, that is $\Sigma = \{b_1, \ldots, b_l\}$ and write the contig A_i as a string $S = b_{i_1} \ldots b_{i_m}$ over Σ by replacing the bins of A_i with the corresponding character of the best match from B. On the one hand, we want every single bin to be assigned to its preferred contig in B, but we also want a simple partition, which is not skewed by wrong mappings of single bins. We therefore restrict valid partitions of A_i to contain at most one continuous part for every contig in B. This prevents large parts to be interrupted by single mismatching bins, at the cost of not being able to capture short-ranged translocations as seen in Figure 1(b). A partition can be represented as a subsequence S' of the string S, which only contains at most one run for every $\sigma \in \Sigma$. The runs in S' are the parts corresponding to one B-contig each, while the dropped characters from S are bins in conflict with S'. Finding the best partition can thus be stated as the following optimization problem:

▶ Problem 1 (Longest Run Subsequence, LRS). Given an alphabet $\Sigma = \{\sigma_1, \ldots, \sigma_{|\Sigma|}\}$ and a string $s = s_1, \ldots, s_m$ with $s_i \in \Sigma$, find a longest subsequence $S' = s'_1, \ldots, s'_k$ of S, such that S' contains at most one run for every $\sigma \in \Sigma$. That is, for every pair of positions i and j with i < j, it holds that

$$s'_i = s'_i \Rightarrow s'_l = s'_i$$
 for all $i < l < j$.

We denote the length of an optimal LRS solution for S with LRS (S). Since we want to maximize the length of the run subsequence, it is always beneficial to either completely add or completely remove a run of S. Once a character $s_i \in \Sigma$ from a run s_i^k is added to s', there can never be any other occurrence of s_i outside this run. Thus, the entire run must be added to s' to achieve maximum length. We will therefore mainly refer to runs instead of single characters.

3 Complexity

In this section we prove hardness of the Longest Run Subsequence problem. More precisely, we show that dLRS, the decision version of the problem is NP-complete. An instance of dLRS is given by a tuple (S, k) and consists in answering the question whether S has a longest run subsequence of length at least k.

▶ Theorem 1. dLRS is NP-complete.

Proof. It is easy to see that dLRS is in NP, because it can be checked in polynomial time whether a string s' is a solution, that is, s' is a run subsequence and $|s'| \ge k$.

To prove NP-hardness, we reduce from the Linear Ordering Problem (LOP), which has been shown to be NP-hard [5]. LOP takes a complete directed graph with edge weights and no self-loops as input and looks for an ordering among the vertices, such that the total weights of edges following this order (i.e., edges leading from lower ordered vertices to higher ordered vertices) is maximized.

We show that dLOP, the decision problem of LOP, that is, the question whether a vertex ordering exists whose weight is at least a given threshold, can be polynomially reduced to dLRS. Let G = (V, E) be a complete digraph with |V| = n. We denote the weight of $(v_i, v_j) \in E$ with w_{ij} and the sum of all weights of G as w_{sum} . Without loss of generality we can assume that all edge weights are positive: The number of edges following a linear order is fixed, so adding a sufficiently large offset to all weights only adds a fixed value to any solution without changing the core problem. This allows us to characterize LOP as finding an acyclic subgraph G' with maximum weight, because the non-negativity of the weights always forces either (v_i, v_j) or (v_j, v_i) to be in G' for every pair of vertices $v_i, v_j \in V$.

The proof consists of two parts. First, we show how to transform G into a string S. Second, we show that G has a LOP solution of weight k if and only if S has a LRS of size

$$f_G(k) := (n-1) \cdot M + \frac{n(n-1)(n-2)}{3} \cdot M' + n(n-1) \cdot w_{\text{sum}} + 2k \tag{1}$$

with $M' := 4n^2 \cdot w_{\text{sum}}$ and $M := M' \cdot n^3$.

For the transformation, we define Σ using three different types of characters:

- 1. Separators $\$_i$ for every vertex $v_i \in V$.
- **2.** Edge signs $E_{\{i,j\}}$ for every pair $v_i, v_j \in V$. Note that $E_{\{i,j\}} = E_{\{j,i\}}$.
- 3. Triangle signs $\Delta_{(i,j,k)}$ for every triangle in G. Note that triangles between three vertices have an orientation and can be rotated. Therefore $\Delta_{(i,j,k)} = \Delta_{(j,k,i)} = \Delta_{(k,i,j)} \neq \Delta_{(i,k,j)} = \Delta_{(k,j,i)} = \Delta_{(j,i,k)}$.

On the highest level the string S is constructed as shown in Equation 2. It consists of one large block per vertex, each of them separated by a run of the associated separation sign of length M.

$$S = \underbrace{(EB)_{1,2}^{\text{edge block}} (EB)_{1,3} \dots (EB)_{1,n}}_{\text{vertex block for } v_1} \$_1^M (EB)_{2,1} \dots (EB)_{2,n} \$_2^M \dots \$_{n-1}^M (EB)_{n,1} \dots (EB)_{n,n-1}$$
(2)

Each vertex block consists of a series of edge blocks (EB), which we define as follows:

$$[EB]_{i,j} = E_{\{i,j\}}^{w_{ij} + w_{\text{sum}}} \quad \Delta_{(i,j,1)}^{M'} \dots \Delta_{(i,j,n)}^{M'} \quad E_{\{i,j\}}^{w_{ij} + w_{\text{sum}}}$$
(3)

In the same way as the *i*-th vertex block is associated with vertex v_i , the edge substrings in it are associated with the outgoing edges of v_i . Note that there is one EB missing in every vertex block, as self-loops are not allowed. Finally, $[EB]_{i,j}$ contains all triangle signs for triangles, in which (v_i, v_j) occurs, i.e., $\{\Delta_{(i,j,k)} \mid 1 \leq k \leq n, k \neq i, k \neq j\}$, which, for the sake of notation, is written as $\Delta_{(i,j,1)}^{M'} \dots \Delta_{(i,j,n)}^{M'}$ in Equation 3. The triangle signs are padded by edge signs for (v_i, v_j) . Every edge sign $E_{\{i,j\}}$ occurs only in the two edge blocks $[EB]_{i,j}$ and $[EB]_{j,i}$. The length of the edge sign runs depends on the weight of the corresponding edge (in either direction), rewarding the higher weighted edge. We also add w_{sum} to the length every edge sign run $E_{\{i,j\}}$.

As for the numbers M and M', the latter is chosen to be larger than the combined length of all edge sign runs. This makes a single triangle sign run more profitable than any selection of edge sign runs. In the same manner, M is chosen to be larger than all triangle sign runs combined.

Using this construction, a valid solution G' = (V, E') for a dLOP instance (G, k), i.e., an acyclic subgraph of G with total weight at least k, can be transformed into a valid solution for a dLRS instance $(S, f_G(k))$. First, all separation runs are selected, yielding a total length of $(n-1) \cdot M$. Second, for every edge in E', all edge signs in the corresponding edge blocks are selected. Since $|E'| = \frac{n(n-1)}{2}$, this adds at least $2 \cdot \left(\frac{n(n-1)}{2} \cdot w_{\text{sum}} + k\right)$ characters to the solution. Finally, G' is acyclic, so for every triangle in G, there is at least one edge missing in G'. Thus, by construction of S, one run can be selected for every triangle sign without interfering with the edge sign runs, adding the missing $\frac{n(n-1)(n-2)}{3} \cdot M'$ characters.

Given a solution S' for the dLRS instance $(S, f_G(k))$, we show how to obtain a subgraph G' of total weight at least k for the original dLOP instance. The subsequence S' must contain all separation runs and a run for every triangle sign, because without all separation and triangle signs selected at some place, it is (by choice of M and M') impossible to reach length $f_G(k)$ for any k. Every selected edge sign run is therefore restricted to a single edge block. The idea is that the choice of selecting $E_{\{i,j\}}$ either in $[EB]_{i,j}$ or $[EB]_{j,i}$ corresponds to the choice of having either (i, j) or (j, i) in the DAG G' for the original LOP. Since we added w_{sum} to the length of every edge sign run and there are only $\frac{n(n-1)}{2}$ edge signs in total, S'must contain both runs inside an edge block, in order to reach length $n(n-1) \cdot w_{\text{sum}}$ (the third summand in $f_G(k)$). Thus, either edge signs or triangle signs may be selected inside an edge block, but not both. G' is finally obtained by selecting an edge e if and only if the edge sign runs in the corresponding edge block are selected. This yields $\frac{n(n-1)}{2}$ edges with a total weight of at least k. For every vertex pair v_i, v_j , exactly one of the edges (v_i, v_j) and (v_j, v_i) is selected, because their corresponding edge blocks share the same edge sign.

It remains to be shown that the obtained subgraph G' is acyclic. We can directly conclude that G' contains no triangles, since every triangle sign $\Delta_{(i,j,k)}$ has to be taken, prohibiting either (i,j),(j,k) or (k,i) (or two of them) to be part of G'. Assume that G' contains a cycle $v_{i_1}, v_{i_2}, v_{i_3}, \dots, v_{i_l}, v_{i_1}$ of length $l \geq 4$. Then, either (v_{i_1}, v_{i_3}) or (v_{i_3}, v_{i_1}) must be in G'. The latter would lead to a triangle, which we could already exclude from G'. But $(v_{i_1}, v_{i_2}) \in G'$ implies that a circle of length l-1 also exists in G'. Repeated use of this argument implies that G' also has a cycle with length 3, which is a contradiction to triangles being excluded. Thus, G' cannot contain a cycle of length 4 or greater and must be acyclic.

In summary, the decision problem whether there is a solution for a dLOP instance (G, k)can be reduced to the decision problem whether a solution for the dLRS instance $(S, f_G(k))$ obtained from G exists.

Solution Strategies

To solve instances of LRS in practice we propose three reduction rules and two algorithmic approaches. As of Theorem 1 we cannot guarantee a polynomial running time.

4.1 Reduction Rules

In Section 2 we already pointed out that an optimal solution for LRS always selects complete runs of characters and we reduced the notation of the input to runs of characters with a certain length each. This can also be seen as a reduction rule to the original problem formulation as the remaining size of the solution space now depends on the number of runs n instead of the actual string length m. We refer to this as the $run\ rule$. Two more reduction rules rely on the following lemma:

▶ Lemma 2. Let S,T be two strings over the disjoint alphabets Σ_S and Σ_T . Then the optimal LRS solutions for S and T can be concatenated to form an optimal solution for the concatenated string ST.

Proof. Since the two alphabets are disjoint, an LRS solution for S does not contain any characters from Σ_T . Therefore the choice of the subsequence for S does not influence the valid subsequences for T and vice versa. This means that optimal solutions for S and T can be computed independently and concatenated fo form a valid solution for ST. Obviously, an optimal solution for ST cannot be longer than the combined length of optimal solutions for the S and T, otherwise the latter would not be optimal.

According to Lemma 2 we can divide an LRS instance S into smaller independent instances, if we find a prefix r_1, \ldots, r_l of S, which uses an exclusive sub-alphabet Σ_p , i.e., $r_1, \ldots, r_l \in \Sigma_p^*$ and $r_{l+1}, \ldots, r_n \in (\Sigma \setminus \Sigma_p)^*$. This prefix rule can be applied in linear time by starting with the prefix r_1 and extending it until we either reach the end of S, in which case no independent suffix exists, or until the prefix is closed regarding the used characters. Let l be the index of the last occurrence of $\sigma(r_1)$. Since $\sigma(r_1)$ is used in the prefix, all runs r_2, \ldots, r_l must belong to the prefix. Now start with k=2 and update l to the index of the last occurrence of $\sigma(r_k)$ (if this index is higher than l), increase k by 1 and repeat until k > l. If l < n, an independent prefix is found, otherwise such a prefix does not exist.

This idea can be extended to the *infix rule*, which finds independent infixes via the following lemma.

▶ **Lemma 3.** Let S,T be two strings over the disjoint alphabets Σ_S and Σ_T and let l be an arbitrary position in S. Then it holds that

$$LRS(s_1 \dots s_l T s_{l+1} \dots s_m) = LRS(s_1 \dots s_l \$^{LRS(T)} s_{l+1} \dots s)$$

with $\$ \notin \Sigma_S \cup \Sigma_T$.

Proof. For the same reason as in Lemma 2 LRS for T can be solved independently from S. For the combined string $s_1 \ldots s_l T s_{l+1} \ldots s_m$ the infix T is either entirely dropped in the optimal subsequence or the optimal solution of T itself is entirely taken as a part of the combined solution. Thus, T contributes either 0 or LRS (T) characters to the optimal combined solution. Therefore, if the solution for T is already known, $s_1 \ldots s_l T s_{l+1} \ldots s_m$ can be solved by replacing T with a run of length LRS (T) of a new character \$.

Following Lemma 3 we can search for an independent infix in S to obtain two smaller instances. Instead of starting with r_1 , we start with an arbitrary character $\sigma \in \Sigma$ as anchor and use the infix r_k, \ldots, r_l as a start with r_k and r_l being the first and last occurrence of σ , respectively. Similarly to the prefix search, we iterate over all runs in the infix and move the markers k, l to the left and right, whenever we encounter a new character with occurrences outside r_k, \ldots, r_l , until the infix is closed (with respect to used characters) or the entire string is contained. This is repeated with every character in Σ as anchor, possibly yielding multiple infixes. Adjacent independent infixes are merged into larger ones, since we want as many runs as possible to be replaced with a single run, as shown in Lemma 3. Infixes, which consist of only one run, are discarded, because they do not pose an actual reduction. Finding and merging all infixes can be done in time $\mathcal{O}(n \cdot |\Sigma|)$.

For a maximum reduction, the rules are applied as follows: First, the prefix rule is iteratively applied on S until no further independent prefix can be found. Second, the infix rule is applied on every sub-instance found so far. For every infix found the procedure is repeated by starting with the prefix rule again.

4.2 Solving with Integer Linear Programming

We present two algorithms to solve LRS to optimality, which have complementary strengths and weaknesses. The first is based on an Integer Linear Program (ILP). This approach scales well with large alphabets, but struggles with a large number of runs. We also propose a dynamic programming (DP) approach, which remains fast for long strings, but suffers from large alphabets. Both algorithms work exclusively on the runs of an input string S.

ILPs are a commonly used technique to model and solve combinatorial optimization problems. We model the LRS formulation from before as an ILP in the following way: Let n be the number of runs in S and let x_1, \ldots, x_n be binary variables with $x_i = 1$ if r_i is in the optimal subsequence and $x_i = 0$ otherwise. Any possible subsequence of runs can therefore be represented by a variable assignment. Since we want to maximize the length of the subsequence, we define our objective function as the weighted sum over all taken runs, using their lengths as weights:

$$\max \sum_{i=1}^{n} x_i L(r_i) \tag{4}$$

Let r_i, r_j be two runs with i < j and $\sigma(r_i) = \sigma(r_j)$. If both runs are selected, no other intermediate run with a different character can be selected according to the LRS conditions. This is ensured by adding the following constraints for any pair of run r_i, r_j , with the same

subject to
$$(j-i)x_i + \left(\sum_{\substack{i < l < j \\ \sigma(r_l) \neq \sigma(r_i)}} x_l\right) + (j-i)x_j \le 2(j-i)$$
 for all $1 \le i < j$ (5)

If either r_i or r_j are not taken, the constraint does not prevent any other combination of runs between them. The total number of constraints is bounded by $\lceil \frac{n}{2} \rceil^2$ and the number of non-zero entries in the constraint matrix is bounded by $n \cdot \lceil \frac{n}{2} \rceil^2$. The ILP has been implemented using the Python interface of PuLP, which solves the ILP with the free solver $CoinOR^2$.

4.3 Solving with Dynamic Programming

As an alternative to the ILP formulation the problem can also be solved bottom-up by a DP. Let D[i, F] be the length of an optimal LRS solution for $r_1 \dots r_i$, which includes r_i itself and one run for every $\sigma \in F \subseteq \Sigma$ only. The DP can be initialized with $D[0,\emptyset] = 0$ and $D[0,F]=-\infty$ for $F\neq\emptyset$. Known solutions can be extended by adding the runs of S iteratively, always selecting an optimal predecessor for each run and keeping track of already used characters with the second parameter F.

https://github.com/coin-or/pulp

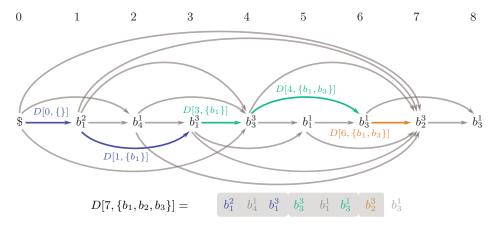


Figure 3 Graph visualizing the recursion for the running example. Arcs represent the possible predecessors for every run. Colors mark the optimal path and the DP entries taken by the recursion.

The full DP is as follows:

$$D[0, F] = 0 \quad \forall F \subseteq \Sigma$$

$$D[0, F] = -\infty \quad \forall F \neq \emptyset$$

$$D[i, F] = \begin{cases} \max_{\sigma \in \Sigma \cup \{\$\}} \left\{ \begin{array}{l} D[P_{\sigma}(i), F] + L(r_{i}) & \text{if } \sigma = \sigma(r_{i}) \\ D[P_{\sigma}(i), F \setminus \{\sigma(r_{i})\}] + L(r_{i}), & \text{if } \sigma \neq \sigma(r_{i}) \end{array} \right\} & \text{if } \sigma(r_{i}) \in F \\ -\infty & \text{otherwise} \end{cases}$$

$$(6)$$

The recursion can be visualized by a directed acyclic graph as shown in Figure 3. It contains a start vertex corresponding to the empty prefix of S and one vertex for every run in S. Each vertex has an incoming edge from the start vertex and from position $P_{\sigma}(i)$ for every $\sigma \in \Sigma$. Every path in the graph corresponds to a (possibly invalid for LRS) subsequence of S. It is optimal to only consider the last occurrences of any character before r_i as predecessors for r_i itself, because if we take a LRS subsequence s', where r_i is proceeded by the second to last occurrence of some other character σ before r_i , we can make s' longer by adding the last occurrence of σ as well.

To compute D[i,F] we first check whether the character of the i-th run is in F. If not, then there is no subsequence using only characters from F, but containing r_i , so the optimal value for this case is $-\infty$. Otherwise, D[i,F] is computed by taking the maximum over all previous occurrences for every $\sigma \in \Sigma \cup \{\$\}$: For σ we take the longest solution from position $P_{\sigma}(i)$ and the set $F \setminus \{\sigma(r_i)\}$ as used characters, because such a solution can be extended to a solution for D[i,F] by appending r_i . Note that \$ is a character not in Σ and that $P_{\$}(i)=0$. The only exception is made for $\sigma=\sigma(r_i)$, where we know that $D[P_{\sigma}(i),F]$ corresponds to a subsequence ending with $\sigma(r_i)$, such that we can append r_i without any new characters being used.

The optimal solution for LRS can be found by taking the entry of D with the highest score and using the backtracking information from the DP to obtain the corresponding subsequence. The DP table has a total of n+1 columns and $2^{|\Sigma|}$ rows with each entry taking $\mathcal{O}(|\Sigma|)$ time to compute. This leads to a worst-case runtime of $\mathcal{O}\left(|\Sigma| \cdot n \cdot 2^{|\Sigma|}\right)$ for the DP, making this a fixed parameter tractable (FPT) approach for LRS with the alphabet size as parameter.

5 Experiments

We performed computational experiments on two different types of instances. First, we generated random instances to see how the two algorithms scale on string length and alphabet size. Second, we ran both algorithms on instances, which we came across a different project [4]. Originally these instances were solved by a brute-force approach, but this failed for longer strings, which motivated us to further investigate this problem.

All tests were run on an AMD Ryzen 7 2700X with 32GB of memory on Ubuntu 20.04. The algorithms are implemented in Python and executed via Snakemake [8] using Python 3.7.6 and PuLP version 1.6.8.

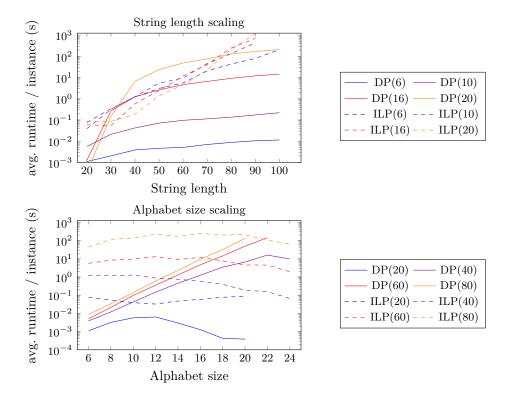


Figure 4 Run time plotted against string length (top) and alphabet size (bottom). Each curve represents an algorithm and an additional parameter (number in parentheses), which is alphabet size in the top blot and the string length in the bottom plot.

5.1 Synthetic Data

The synthetic data was created by randomly generating strings with different lengths and alphabet sizes. For any combination a total of 20 strings was generated, such that every string is guaranteed to use the entire alphabet assigned to it. These instances pose worst-case instances for our algorithms, as the proposed reduction rules can hardly be applied. The runs are quite short in general and since there is no structurally induced locality among the characters, instances could be split very rarely. All runs instances were solved with all reductions rules applied.

Figure 4 shows how the runtime scales with both increasing string lengths and increasing alphabet size. For a fixed alphabet size the runtime scales about exponentially with the string length for the ILP as shown in the top plot. In fact, the alphabet size only has very

Table 1 Comparison of runtime (in seconds) between DP and ILP on instances from real data. The times are for all 15 instances.

Algorithm	All rules	Runs and prefix	Only runs
DP	0.01	0.01	out of memory
ILP	2.15	2.03	0.09

minor effect on the ILP compared to the string length, which becomes visible in the bottom plot, with a slight favor of larger alphabets. The DP behaves complementary to the ILP, scaling exponentially in the alphabet size and sub-exponentially with string length. Longer strings take longer to process according to the top plot as opposed to the ILP being almost oblivious to the alphabet size. However, if the alphabet becomes very large in relation to the string length, the running time suddenly decreases for the DP.

The scaling can be explained by the properties of the algorithms. The ILP has a binary decision variable for every run, increasing the number of possible (but not necessarily feasible) variable assignments exponentially with the number of runs. Since ILP solvers usually fall back to branching in case cutting planes do not suffice, the bad scaling with running times appears logical. Larger alphabets might lead to a lower number of constraints (and thus a lower runtime), as the ILP contains one constraint for every pair of runs with the same character. As already pointed out in Section 4.3 the DP table grows linearly with the number of runs and exponentially with alphabet size, explaining the high running time on large alphabets. But also the memory consumption grew drastically. While the DP only needed 227MB of RAM for a string of length of 60 and $|\Sigma| = 16$, the consumption went up to 2,8GB for $|\Sigma| = 20$ and to 9,2GB for $|\Sigma| = 22$. With $|\Sigma| = 24$ the machine ran out of memory, making the memory consumption a larger bottleneck than the computation time. With the ILP no such issues could be observed. The decreasing running time for very large alphabets is caused by the reduction rules, as it leads to a higher number of characters occurring only in a single run and thus to a higher chance of the string being splittable into independent parts.

5.2 Real-World Data

We consider a dataset which was generated to test the performance of an approach to find structural rearrangements [4]. It consists of fragmented assemblies that have been generated by introducing random breaks in chromosome-level assemblies of the Col-0 and Ler accessions of Arabidopsis thaliana [6, 4]. We tested 15 instances, which remained unsolved by brute-force methods, containing string lengths between 34 and 50 and alphabets of size 31 to 38.

Using all three reduction rules, both algorithms were able to solve all instances in very short time with the DP outperforming the ILP quite significantly, see Table 1. However, not using the prefix and infix rules caused the DP to run out of memory because of the large alphabets, while the ILP got faster. Since the reduction rules themselves only have minimal impact on the runtime, this must be due to overhead in the ILP solver when solving many small instances instead of one large one.

6 Discussion

The experiments showed that optimal LRS solutions can be found in short time for instance sizes that occur on assemblies of real samples. We presented two different algorithms whose running times depend on two important instance properties, namely string length and

6:12 The Longest Run Subsequence Problem

alphabet size. Random strings, however, do not seem to be a good indicator for actual assembly instances, which are already pre-sorted except for some noise or rearrangements. The reduction rules have little to no impact on random strings, while they reduce the assembly instances to almost trivial sub-instances. This implies that reduction rules might be more important in practice than the algorithm to process the remaining preprocessed instance.

One potential problem of the model itself was mentioned in Section 2. LRS only allows for one run per character, which automatically induces an ordering on the underlying contigs. This can be problematic if the binned contig contains a translocation that splits a long run into two, e.g., $b_1b_1b_2b_2b_2b_1b_1b_1$. The LRS model will drop one of the b_1 runs, even though it would be better to leave the order of B_1 and B_2 open due to lack of evidence.

Another limitation arises while mapping the bins. Since only the best match for every bin is taken, any mapping ambiguity is ignored, which might drop valuable information. There is also no support for inversions inside the model. While inverted alignments can be taken into account for the mapping step of a single bin, the model stays unaware of inversions and the fact that an interval of bins is actually in the reverse order compared to the second assembly. However, this might not be as problematic as it sounds, because the bins are not mapped to other bins but to entire contigs. As long as inversions are contained in a single contig, they should have no impact on the ordering that the model produces.

7 Conclusion

Ordering contigs by means of an incomplete assembly of a related species occurs as a variant of homology-assisted assembly, which does not require chromosome-level assemblies already. We introduced the Longest Run Subsequence (LRS) problem, formalizing the contig ordering problem as a string problem. We proved that LRS is NP-complete and presented reduction rules and two algorithms, which work well for long instances and large alphabets, respectively, which we showed on a synthetic data set. Regarding real data, we managed to solve all instances that could not be solved by a brute force approach in short computation time.

From the theoretical side, we find it interesting to further investigate approximability and fixed-parameter tractability of LRS. From a practical perspective, we plan to further test the approach on real assembly data, also taking more than two related assemblies into account.

References

- Michael Alonge, Sebastian Soyk, Srividya Ramakrishnan, Xingang Wang, Sara Goodwin, Fritz J. Sedlazeck, Zachary B. Lippman, and Michael C. Schatz. RaGOO: fast and accurate reference-guided scaffolding of draft genomes. *Genome Biology*, 20(1):224, October 2019. doi:10.1186/s13059-019-1829-6.
- Joshua N. Burton, Andrew Adey, Rupali P. Patwardhan, Ruolan Qiu, Jacob O. Kitzman, and Jay Shendure. Chromosome-scale scaffolding of de novo genome assemblies based on chromatin interactions. Nature Biotechnology, 31(12):1119-1125, December 2013. doi:10.1038/nbt.2727.
- 3 Lauren Coombe, Vladimir Nikolić, Justin Chu, Inanc Birol, and René L Warren. ntJoin: Fast and lightweight assembly-guided scaffolding using minimizer graphs. *Bioinformatics*, April 2020. btaa253. doi:10.1093/bioinformatics/btaa253.
- 4 Manish Goel, Hequan Sun, Wen-Biao Jiao, and Korbinian Schneeberger. SyRI: finding genomic rearrangements and local sequence differences from whole-genome assemblies. *Genome Biology*, 20(1):277, December 2019. doi:10.1186/s13059-019-1911-0.
- 5 Martin Grötschel, Michael Jünger, and Gerhard Reinelt. A cutting plane algorithm for the linear ordering problem. Operations Research, 32:1195–1220, December 1984. doi: 10.1287/opre.32.6.1195.

- 6 The Arabidopsis Genome Initiative. Analysis of the genome sequence of the flowering plant Arabidopsis thaliana. *Nature*, 408(6814):796–815, 2000.
- Wen-Biao Jiao, Gonzalo Garcia Accinelli, Benjamin Hartwig, Christiane Kiefer, David Baker, Edouard Severing, Eva-Maria Willing, Mathieu Piednoel, Stefan Woetzel, Eva Madrid-Herrero, Bruno Huettel, Ulrike Hümann, Richard Reinhard, Marcus A. Koch, Daniel Swan, Bernardo Clavijo, George Coupland, and Korbinian Schneeberger. Improving and correcting the contiguity of long-read genome assemblies of three plant species using optical mapping and chromosome conformation capture data. *Genome Research*, 27(5):778–786, May 2017. doi:10.1101/gr.213652.116.
- 3 Johannes Köster and Sven Rahmann. Snakemake—a scalable bioinformatics workflow engine. Bioinformatics, 28(19):2520–2522, August 2012. doi:10.1093/bioinformatics/bts480.
- 9 Haibao Tang, Xingtan Zhang, Chenyong Miao, Jisen Zhang, Ray Ming, James C. Schnable, Patrick S. Schnable, Eric Lyons, and Jianguo Lu. ALLMAPS: robust scaffold ordering based on multiple maps. *Genome Biology*, 16(1):3, January 2015. doi:10.1186/s13059-014-0573-1.
- Neil I. Weisenfeld, Vijay Kumar, Preyas Shah, Deanna M. Church, and David B. Jaffe. Direct determination of diploid genome sequences. Genome Research, 27(5):757-767, 2017. doi:10.1101/gr.214874.116.