# The GaussianSketch for Almost Relative Error Kernel Distance 

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#### Abstract

We introduce two versions of a new sketch for approximately embedding the Gaussian kernel into Euclidean inner product space. These work by truncating infinite expansions of the Gaussian kernel, and carefully invoking the RecursiveTensorSketch [Ahle et al. SODA 2020]. After providing concentration and approximation properties of these sketches, we use them to approximate the kernel distance between points sets. These sketches yield almost $(1+\varepsilon)$-relative error, but with a small additive $\alpha$ term. In the first variants the dependence on $1 / \alpha$ is poly-logarithmic, but has higher degree of polynomial dependence on the original dimension $d$. In the second variant, the dependence on $1 / \alpha$ is still poly-logarithmic, but the dependence on $d$ is linear.


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## 1 Introduction

Kernel methods are a pillar of machine learning and general data analysis. These approaches consider classic problems such as PCA, linear regression, linear classification, $k$-means clustering which at their heart fit a linear subspace to a complex data set. Each of the methods can be solved by only inspecting the data via a dot product $\langle x, p\rangle$. Kernel methods, and specifically the "kernel trick," simply replaces these Euclidean dot products with a nonlinear inner product operation. The two most common inner products are the polynomial kernel $K_{z}(x, p)=(\langle x, p\rangle+1)^{z}$ and the Gaussian kernel $K(x, p)=\exp \left(-\|x-p\|^{2}\right)$.

The "magic" of the kernel method works mainly because of the existence of a reproducing kernel Hilbert space (RKHS) $\mathcal{H}_{K}$ associated with any positive definite (p.d.) kernel [43] $K$. It is a function space, so for any data point $x \in \mathbb{R}^{d}$, there is a mapping $\phi: \mathbb{R}^{d} \rightarrow \mathcal{H}_{K}$ so $\phi(x)=K(x, \cdot)$. Since $\phi(x)$ is a function with domain $\mathbb{R}^{d}$, and each "coordinate" of $\phi(x)$ is associated with another point $p \in \mathbb{R}^{d}$, there are an infinite number of "coordinates," and $\mathcal{H}_{K}$ can be infinite dimensional. However, since $\langle\phi(x), \phi(p)\rangle_{\mathcal{H}_{K}}=K(x, p)$, this embedding does not ever need to be computed, we can simply evaluate $K(x, p)$. And life was good.

However, at the dawn of the age of big data, it became necessary to try to explicitly, but approximately, compute this map $\phi$. Kernel methods typically start by computing and then analyzing the $n \times n$ gram matrix $K_{X}$ where $\left(K_{X}\right)_{i, j}=K\left(x_{i}, x_{j}\right)$ for a data sets $X$

of size $n$. As $n$ became huge, this became untenable. In a hallmark paper, Rahimi and Recht [37] devised random Fourier features (RFFs) for p.d. kernels (with max value 1, e.g., Gaussians) that compute a random $\operatorname{map} \tilde{\phi}: \mathbb{R}^{d} \rightarrow \mathbb{R}^{\tilde{D}}$ so $\langle\tilde{\phi}(x), \tilde{\phi}(p)\rangle$ is an unbiased estimate of $K(x, p)$, and with probability at least $1-\delta$ has error $|K(x, p)-\langle\tilde{\phi}(x), \tilde{\phi}(p)\rangle| \leq \varepsilon$. For just one pair of points they require $\tilde{D}=O\left(\left(1 / \varepsilon^{2}\right) \log (1 / \delta)\right)$, or for all comparisons among $n$ points $\tilde{D}_{n}=\left(\left(1 / \varepsilon^{2}\right) \log (n / \delta)\right)$, or for any points in a region $\Lambda$ of $\operatorname{volume} \operatorname{vol}(\Lambda) \leq V$, then $\tilde{D}_{V}=\left(\left(1 / \varepsilon^{2}\right) \log (V / \delta)\right)$.

However, relative-error-preserving RKHS embeddings for p.d. kernels are impossible without some restriction on the size $n$ or domain $\Lambda$ of the data. Consider $n$ data points each far from each other so any pair $x, p \in \mathbb{R}^{d}$ satisfies $K(x, p)<1 / n$. In any relative-errorapproximate embedding $\hat{\phi}: \mathbb{R}^{d} \rightarrow \mathbb{R}^{\hat{D}}$, each point must be virtually orthogonal to all other points, and hence $\Omega(n)$ dimensions are required [28].

Instead, to obtain (almost) relative-error results in big data sets, researchers have relied on other approaches such as sampling [45], exploiting structure of p.d. Gram matrices [34], devising modified RFFs for regularized kernel regression [9], or building data structures for kernel density estimate queries [12].

The kernel distance and data set embeddings. To address these difficulties, we first turn our attention from the inner product $\langle\phi(x), \phi(p)\rangle_{\mathcal{H}_{K}}=K(x, p)$ in the RKHS to the natural distance it implies. Before stating this distance, we generalize the inner product to point sets $P \subset \mathbb{R}^{d}$ (which extends naturally to probability distributions $\mu_{P}$ with domain $\mathbb{R}^{d}$ ). We treat $P$ as a discrete probability distribution with uniform $1 /|P|$ weight on each point. This can be represented in $\mathcal{H}_{K}$ as $\Phi(P)=\frac{1}{|P|} \sum_{x \in P} \phi(x)$, known as the kernel mean [33]. Indeed, for any query point $p \in \mathbb{R}^{d}$, the inner product $\langle\Phi(P), \phi(p)\rangle_{\mathcal{H}_{K}}=\frac{1}{|P|} \sum_{x \in P} K(x, p)$ is precisely the kernel density estimate at $p$. For two point sets $P, Q \subset \mathbb{R}^{d}$ we define $\kappa(P, Q)=\frac{1}{|P|} \frac{1}{|Q|} \sum_{x \in P} \sum_{y \in Q} K(p, q)=\langle\Phi(P), \Phi(Q)\rangle_{\mathscr{H}_{K}}$.

Now the kernel distance [36, 26] (alternatively known as the current distance [23] or maximum mean discrepancy $[24,39]$ ) is defined

$$
\mathrm{D}_{K}(P, Q)=\|\Phi(P)-\Phi(Q)\|_{\mathcal{H}_{K}}=\sqrt{\kappa(P, P)+\kappa(Q, Q)-2 \kappa(P, Q)} .
$$

Under a slightly restricted class of kernels (a subset of p.d. kernels), called characteristic kernels [42], this distance is a metric. These include the Gaussian kernels which we focus on hereafter. This distance looks and largely acts like Euclidean distance; indeed, restricted to any finite-dimensional subspace, it is equivalent to Euclidean distance.

In data analysis and statistics, kernel mean is a compact way to represent a point set distribution. One can also use kernel distance to compare different point set as opposed to more expensive measure such as Wasserstein distance. In practice, there are various applications such as hypothesis test and geometric search (see section 4 for detail discussion) that use kernel distance as a core component. We suggest the reader refer to [38, 40] for more details on the statistical perspective of kernel distance. Therefore, making computation of the kernel distance scalable by a kernel distance embedding is of significant importance for those downstream applications. More generally, one can view oblivious kernel distance embedding as special case of oblivious subspace embedding for RKHS [32, 2], which gives a stronger guarantee than a subspace in the RKHS is preserved within relative error. However, many application of kernel distance do not require such a strong guarantee, which generally attain worse results (see below for more detail comparison)

So a natural question to ask is if this distance is preserved within relative error via some approximate lifting. Clearly RFFs guarantee additive $\varepsilon$-error. However, relate this problem to the Johnson-Lindenstrauss (JL) Lemma [25]: JL describe a family of random projections
from a high-dimensional space to a $D^{\prime}$-dimensional space which preserve ( $1+\varepsilon$ )-relative error on Euclidean distance, again with $D^{\prime}=O\left(\left(1 / \varepsilon^{2}\right) \log (n / \delta)\right)$ for any $\binom{n}{2}$ pairs of distances, succeed with probability $1-\delta$, but only guarantees additive error on inner products.

Moreover, it is possible to apply the JL Lemma to create such an approximate embedding. First for any set of $n$ points $X$, we can create $n \times n$ Gram matrix $K_{X}$ (that is positive definite), and decompose it to $K_{X}=B_{X} B_{X}^{T}$. Then each row $\left(B_{X}\right)_{i}$ in $B_{X}$ is the $n$-dimensional vector representation of the $i$ th data point, and the Euclidean distance $\left\|\left(B_{X}\right)_{i}-\left(B_{X}\right)_{j}\right\|_{2}$ is the kernel distance between data points $i$ and $j[31,8]$. Then we can apply JL on these rows $\left\{\left(B_{X}\right)_{i}\right\}$ to obtain such an approximate embedding. However, this embedding is not oblivious to the data (necessary for many big data settings like streaming) and still requires $\Omega\left(n^{2}\right)$ time just to create the Gram matrix, not to mention the time for decomposition.

Another recent approach [14] analyzed RFFs for this task, and shows that these approximate embeddings do guarantee relative error on the kernel distance, but only between each pair of points $x, p \in \mathbb{R}^{d}$ (e.g., so $\frac{\|\hat{\phi}(x)-\hat{\phi}(p)\|}{\mathrm{D}_{K}(x, p)} \in(1 \pm \varepsilon)$ ), and as we describe next many downstream analysis tasks require the distance preserved between point sets. Alternatively, if we assume $\mathrm{D}_{K}^{2}(P, Q)>\alpha$, then standard RFFs can provide a relative error guarantee using $\tilde{D}=O\left(\frac{1}{\varepsilon^{2} \alpha^{2}} \log \frac{1}{\delta}\right)$. However, such a large factor in $\alpha$ is undesirable, since typically $\alpha \ll \varepsilon$.

Our Results. We provide two sketches $G: \mathbb{R}^{d} \rightarrow \mathbb{R}^{D}$ for the Gaussian kernel, improving on work of Rahimi and Recht [37] and Avron et al. [9], which achieves almost relative error for kernel distance. Let $F(X)=\frac{1}{|X|} \sum_{x \in X} G(x)$ extend the sketch to point sets $X \subset \mathbb{R}^{d}$. Then we show that for two point sets $P, Q \subset \mathbb{R}^{d}$

$$
\left|\mathrm{D}_{K}^{2}(P, Q)-\|F(P)-F(Q)\|^{2}\right| \leq \varepsilon \mathrm{D}_{K}^{2}(P, Q)+\alpha
$$

As we can always reduce the dimension $G: \mathbb{R}^{d} \rightarrow \mathbb{R}^{D}$ using JL to about $D=1 / \varepsilon^{2}$, we focus on reducing the runtime dependence, in particular the dependence on $\alpha$.

In the first sketch (the GaussianSketch) to process a single point with $G(x)$ it takes $O\left(\frac{d^{2}}{\varepsilon^{2}} \log \frac{d}{\varepsilon}+d s\right)$ time, with $s=\Theta\left(\frac{\log \left(d \exp \left(d L^{2}\right) / \alpha\right)}{\log \left(\frac{1}{L^{2}} \log \left(d \exp \left(d L^{2}\right) / \alpha\right)\right)}\right)$, where $L$ describes the $\left(L_{\infty}\right)$ radius of the domain containing $X$. So the dependence on $1 / \alpha$ is less than a single logarithmic term.

The second sketch (the GaussianSketchHD) is useful when the dimension $d$ is potentially large (it turns out to be very similar to a recent sketch in [2], but our analysis is different). Then the runtime to compute $G(x)$ is $O\left(\frac{s^{3}}{\varepsilon^{2}} \log \frac{s}{\varepsilon}+s^{2} d\right)$ where $s=$ $\Theta\left(\frac{\log \left(4 \exp \left(2 R^{2}\right) / \alpha\right)}{\log \left(\frac{1}{R^{2}} \log \left(4 \exp \left(2 R^{2}\right) / \alpha\right)\right)}\right)$, and $R$ is the $\left(L_{2}\right)$ domain radius. Now the dependence on $1 / \alpha$ is still poly-logarithmic, but the dependence on dimension $d$ is linear.

For example, we can set $\alpha=n^{-C_{1}}, R=C_{2} \sqrt{\log n}$ and $L=C_{3} \sqrt{\log n}$ for some absolute constant $C_{1}, C_{2}, C_{3}$. In low dimension, we have $s=\Theta\left(\frac{\log n}{\log d}\right)$ and the running time is $O\left(\frac{d^{2}}{\varepsilon^{2}} \log \frac{d}{\varepsilon}+\frac{d \log n}{\log d}\right)$. In high dimension, we have $s=\Theta(\log n)$ and the running time is $O\left(\frac{1}{\varepsilon^{2}} \log ^{3} n \log (\log n / \varepsilon)+d \log ^{2} n\right)$.

Implications. Several concrete applications work direfctly on this kernel distance between point sets. First, the kernel two-sample test [24, 33] is a non-parametric way to perform hypothesis tests between two empirical distributions; simply, the null hypothesis of them being drawn from the same distribution is rejected if the kernel distance is sufficiently large. While the sketched kernel two-sample test has proven effective under additive error [48], when the significance threshold is $\Theta(1 / n)$, the RFF-based solutions require time $O\left(n^{2}\right)$, no better than brute force; but setting $\varepsilon$ constant and $\alpha=1 / n$, our sketches provide near-linear or almost-linear time runtimes. Second, devising a Locality Sensitive Hash (LSH) between
point sets (or geometrically-aware LSH for probability distributions) has lacked a great general solution. Despite progress in special cases (e.g., for polygons [13], curves [18]), more general distances between geometric distributions, like Earth-Mover distance require $\Omega(\log s)$ distortion on a domain with at least $s$ discrete points [7]. In general, an LSH requires relative error to properly provide $(1+\varepsilon)$-approximate nearest neighbor results. In Section 4 we specify how our new almost relative-error embeddings for the kernel distance provide efficient solutions for these applications.

Furthermore, this embedding can be composed with a Johnson-Lindenstrauss-type embedding $[25,3,4,1,46]$ to create an overall oblivious embedding of dimension roughly $O\left(\frac{1}{\varepsilon^{2}} \log \frac{1}{\delta}\right.$ ), that is with no dependence on $1 / \alpha$ or $d$ (or $n$ or domain radius $L$ or $R$ in the for each setting), and roughly the same guarantees.

### 1.1 Comparison to Other Recent Work on Large Data and Kernels

Recent related works on kernel approximation do not provide our guarantees; we survey here work that addresses similar problems, and often require similar sets of error parameters.

Approximated KDEs. Charikar and Siminelakis [12] describe a data structure of size $n \hat{D}$ and query time $\hat{D}$, which answers $\kappa(P, t)$ queries within $(1+\varepsilon)$-relative error as long as $\kappa(P, t)>\alpha$; it requires $\hat{D}=O\left(\frac{1}{\varepsilon^{2}} \frac{1}{\sqrt{\alpha}} \log \frac{1}{\delta} e^{O\left(\log ^{2 / 3} n \log \log n\right)}\right)$. However, this cannot argue much about how large $\mathrm{D}_{K}(P, Q)$ has to be for this to achieve relative error on the kernel distance since it could be $\mathrm{D}_{K}(P, Q)$ is small but $\kappa(P, t)$ and $\kappa(P, P)$ are both large. Moreover, its guarantees only work for a single point set $P$ with point queries $t$, not for two or more points sets $P, Q$, as we argue many downstream data analysis tasks require.

Approximated kernel regression. Avron et al. [9] modify the RFF embeddings using different sampling probability related to the statistical leverage in the kernel space. This approximates a $\lambda$-regularized kernel regression problem, creating a $\tilde{D}$-dimensional embedding; that is for an $n \times n$ gram matrix $K_{X}$, and a regularization parameter $\lambda$ it creates a $n \times \tilde{D}$ matrix $Z$ so $(1-\varepsilon)\left(K_{X}+\lambda I_{n}\right) \preceq Z Z^{*}+\lambda I_{n} \preceq(1+\varepsilon)\left(K_{X}+\lambda I_{n}\right)$, using $\tilde{D}=O\left(\frac{1}{\varepsilon^{2}}\left(L^{d} \log ^{d / 2}(n / \lambda)+\log ^{2 d}(n / \lambda)\right) \log \left(s_{\lambda}(\bar{K}) / \delta\right)\right)$. Following our forthcoming methods for analysis, one can modify this result to $(1+\varepsilon)$-approximate the kernel distance, with an additive $\alpha$ term, with an embedding of dimension $D=O\left(\frac{1}{\varepsilon^{2}}\left(L^{d} \log ^{d / 2} \frac{n}{\alpha}+\log ^{2 d} \frac{n}{\alpha}\right) \log \frac{n}{\delta}\right)$.

Also, Ahle et al. [2] recently showed that one can create such $\tilde{D}$-dimensional embedding where $\tilde{D}=O\left(\frac{1}{\varepsilon^{2}}\left(R^{2}+\log \frac{n}{\varepsilon \lambda}\right)^{5} s_{\lambda}\left(K_{X}\right)\right)$ in $O\left(\frac{1}{\varepsilon^{2}}\left(R^{2}+\log \frac{n}{\varepsilon \lambda}\right)^{6} s_{\lambda}\left(K_{X}\right)\right)$ time for each data point. Again, in our setting, one can interpret this result as $(1+\varepsilon)$-approximate the kernel distance, with an additive $\alpha$ term, in $O\left(\frac{1}{\varepsilon^{2}}\left(R^{2}+\log \frac{n}{\varepsilon \alpha}\right)^{6} s_{\alpha}\left(K_{X}\right)\right)$ time.

Compared to our bounds (adapted to our problem using our techniques), these depend on $n$ and $s_{\lambda}$ (ours do not), the low-d one is exponential in $d$ (ours is polynomial), and the other powers are larger.

Approximate Kernel PCA. Suppose we are given a data set $X=\left\{x_{1}, \ldots, x_{n}\right\} \subset \mathbb{R}^{d}$, and want to find a low rank (rank $k$ ) approximation of $X_{\phi}=\left\{\phi\left(x_{1}\right), \phi\left(x_{2}\right), \ldots, \phi\left(x_{n}\right)\right\} \in \mathcal{H}_{K}$. In particular, this can be described concretely in the context of the Gram matrix $K_{X}$ and its decomposition $B_{X} B_{X}^{T}$. Given any $n \times m$ matrix $M$, let $[M]_{k}$ be its best rank- $k$ approximation. A natural question is to find a rank- $k$ matrix $\tilde{K}_{X}$ so

$$
\left\|K_{X}-\tilde{K}_{X}\right\|_{F}^{2} \leq(1+\varepsilon)\left\|K_{X}-\left[K_{X}\right]_{k}\right\|_{F}^{2}
$$

While most previous work $[19,30,22,41,44]$ has focused on providing absolute (or additive) error bounds. For instance, they showed roughly $\left\|K_{X}-\tilde{K}_{X}\right\|_{F}^{2} \leq\left\|K_{X}-\left[K_{X}\right]_{k}\right\|_{F}^{2}+\varepsilon n$ using e.g., Nyström sampling and RFFs. More recently, Musco and Woodruff [35] for p.d. Gram matrices $K_{X}$ show how to efficiently find $\tilde{K}_{X}$ with relative error. This only requires $O\left(n k^{\omega-1} \cdot \operatorname{poly}(\log n / \varepsilon)\right)$ inspections of entries of $K_{X}$, where $\omega<2.373$ is the matrix multiplication exponent. This is not data oblivious, and uses properties of the p.d. matrix, so it does not provide an embedding sketch.

A closely related problem is approximate kernel PCA problem which is to find a $n \times k$ orthonormal matrix $V$ so that

$$
\left\|B_{X}-V V^{T} B_{X}\right\|_{F}^{2} \leq(1+\varepsilon)\left\|B_{X}-\left[B_{X}\right]_{k}\right\|_{F}^{2}
$$

The RKHS basis $V$, provides a compact and non-linear set of attributes to describe a complex data set $X$, and has many uses in analyzing complex data which lacks strong linear correlations. Musco and Woodruff [34] provide an algorithm with runtime $O(\mathrm{nnz}(X))+$ $\tilde{O}\left(n^{\omega+1.5}\left(\frac{k}{\sigma_{k+1} \varepsilon^{2}}\right)^{\omega-1.5}\right)$; which has polynomial dependence on $1 / \sigma_{k+1}$. They leave open whether this can be removed or reduced while maintaining only roughly $n \mathrm{nz}(X)$ dependence on $X$. The matrix $V$ returned by their algorithm can be used to approximate the matrix $K_{X}$ by writing $B_{X} P B_{X}^{T}$ where $P$ is the projection onto the row span of $V V^{T} B_{X}$.

Our techniques can be combined with the a sketch for the polynomial kernel [10] to explicitly solve for $V$ so

$$
\left\|B_{X}-V V^{T} B_{X}\right\|_{F}^{2} \leq(1+\varepsilon)\left\|B_{X}-\left[B_{X}\right]_{k}\right\|_{F}^{2}+\alpha
$$

with similar dimensions required for approximating the kernel distance; the $s$ parameter increases roughly by $\log n / \log \log n$. This is detailed in Appendix A. If the data size $n$ has a known bound, then this provides an oblivious sketch for this almost relative error kernel PCA problem. Moreover, replacing the $\sigma_{k+1}$ with $\varepsilon \alpha$, it almost answers the kernel PCA $\mathrm{nnz}(X)$ question of Musco and Woodruff [34] - however our algorithm does not depend on the number-of-non-zeros of $X$ through our sketches, so we leave as an open question if our sketches $G(x)$, particular the GaussianSketchHD or similar, can be generated in time $O(\operatorname{nnz}(x) \operatorname{polylog}(1 / \alpha)+n$ poly $(k, 1 / \varepsilon, \log (1 / \alpha))$.

## 2 The GaussianSketch and its Properties

In this section we describe our new sketches for approximate mapping from $\mathbb{R}^{d}$ to an RKHS associated with a Gaussian kernel. They are based on the RecursiveTensorSketch of Ahle et al. [2], so we first review its properties.

The RecursiveTensorSketch. We first introduce RecursiveTensorSketch hash family [2]. Given positive integers $n, m$ and $k$, RecursiveTensorSketch ${ }_{n, m, k}$ is the family of hash functions $T: \mathbb{R}^{n^{k}} \rightarrow \mathbb{R}^{m}$ as constructed in [2]. This hash family will be used to construct our main sketch and has the following guarantee [2]: suppose $u, v \in \mathbb{R}^{n^{k}}$ and picking $m=O\left(\frac{k}{\varepsilon^{2}}\right)$, then the expectation $\mathrm{E}(\langle T(u), T(v)\rangle)=\langle u, v\rangle$ and the variance $\operatorname{Var}(\langle T(u), T(v)\rangle) \leq \frac{\varepsilon^{2}}{10}\|u\|^{2}\|v\|^{2}$. Moreover, the running time of computing $T(x)$ for any $x \in \mathbb{R}^{n^{k}}$ is $O(k m \log m+k n)$.

The GaussianSketch. Now, we can define the hash family of the first sketch for the Gaussian kernel GaussianSketch. Given a vector $x \in \mathbb{R}^{d}$ and a positive integer $s$, we first define $d$ vectors $y_{x}^{(1)} \ldots, y_{x}^{(d)} \in \mathbb{R}^{s}$ such that $i$ th coordinate of $y_{x}^{(j)}$ is $\exp \left(-x_{j}^{2}\right) \sqrt{\frac{2^{i-1}}{(i-1)!}} x_{j}^{i-1}$. Given an integer $m$, define GaussianSketch ${ }_{m, s}$ to be the family of hash functions that if $G$ is in it, then $G(x)=T\left(y_{x}^{(1)} \otimes \cdots \otimes y_{x}^{(d)}\right)$ where $T$ is randomly chosen from RECURSIVETENSORSKETCH ${ }_{s, m, d}$.

Here, $x \otimes y$ is Kronecker product. Namely, given $x \in \mathbb{R}^{p}$ and $y \in \mathbb{R}^{q}, x \otimes y$ is a $p q$ dimensional vector indexed by two integers $i, j$ where $i=1, \ldots, p$ and $j=1, \ldots, q$ such that $(x \otimes y)_{i, j}=x_{i} \cdot y_{j}$. For notational convenience, we extend Kronecker product when $p$ and $q$ are infinity. Namely, given $\left\{x_{i}\right\}_{i=1}^{\infty}$ and $\left\{y_{j}\right\}_{j=1}^{\infty}$ are infinite sequences, $x \otimes y$ is also an infinite sequence indexed by two positive integers $i, j$ such that $(x \otimes y)_{i, j}=x_{i} \cdot y_{j}$. Also, denote $x^{\otimes k}=x \otimes x^{\otimes k-1}$ and $x^{\otimes 0}=1$.

The rationale for the GAUSSIANSKETCH comes from the following infinite expansion of the Gaussian kernel. Define $\bar{y}_{x}^{(j)}$ (for $j \in[d]$ ) as the infinite dimensional analog of $y_{x}^{(j)}$ with its $i$ th coordinate as $\exp \left(-x_{j}^{2}\right) \sqrt{\frac{2^{i-1}}{(i-1)!}} x_{j}^{i-1}$.

- Lemma 1. For $x, p \in \mathbb{R}^{d}$

$$
\begin{aligned}
& \exp \left(-\|x-p\|^{2}\right) \\
& =\sum_{j_{1}=0}^{\infty} \cdots \sum_{j_{d}=0}^{\infty}\left(\exp \left(-\|x\|^{2}\right)\left(\prod_{i=1}^{d} \sqrt{\frac{2^{j_{i}}}{j_{i}!}} x_{i}^{j_{i}}\right)\right)\left(\exp \left(-\|p\|^{2}\right)\left(\prod_{i=1}^{d} \sqrt{\frac{2^{j_{i}}}{j_{i}!}} p_{i}^{j_{i}}\right)\right) \\
& =\left\langle\bar{y}_{x}^{(1)} \otimes \cdots \otimes \bar{y}_{x}^{(d)}, \bar{y}_{p}^{(1)} \otimes \cdots \otimes \bar{y}_{p}^{(d)}\right\rangle .
\end{aligned}
$$

Proof.

$$
\begin{aligned}
& \exp \left(-\|x-p\|^{2}\right) \\
& =\exp \left(-\|x\|^{2}\right) \exp \left(-\|p\|^{2}\right) \exp (2\langle x, p\rangle) \\
& =\exp \left(-\|x\|^{2}\right) \exp \left(-\|p\|^{2}\right) \prod_{i=1}^{d} \exp \left(2 x_{i} p_{i}\right) \\
& =\exp \left(-\|x\|^{2}\right) \exp \left(-\|p\|^{2}\right) \prod_{i=1}^{d}\left(\sum_{j=0}^{\infty} \frac{1}{j^{\prime}}\left(2 x_{i} p_{i}\right)^{j}\right) \quad \text { by Taylor expansion of } \exp (\cdot) \\
& =\exp \left(-\|x\|^{2}\right) \exp \left(-\|p\|^{2}\right) \sum_{j_{1}=0}^{\infty} \cdots \sum_{j_{d}=0}^{\infty}\left(\prod_{i=1}^{d} \frac{1}{j_{i}!}\left(2 x_{i} p_{i}\right)^{j_{i}}\right) \\
& =\sum_{j_{1}=0}^{\infty} \cdots \sum_{j_{d}=0}^{\infty}\left(\exp \left(-\|x\|^{2}\right)\left(\prod_{i=1}^{d} \sqrt{\frac{2^{j_{i}}}{j_{i}!}} x_{i}^{j_{i}}\right)\right)\left(\exp \left(-\|p\|^{2}\right)\left(\prod_{i=1}^{d} \sqrt{\frac{2^{j_{i}}}{j_{i}!}} p_{i}^{j_{i}}\right)\right) \\
& =\left\langle\bar{y}_{x}^{(1)} \otimes \cdots \otimes \bar{y}_{x}^{(d)}, \bar{y}_{p}^{(1)} \otimes \cdots \otimes \bar{y}_{p}^{(d)}\right\rangle .
\end{aligned}
$$

Note that the Gaussian sketch takes as input one element of these inner products, but trimmed so that each $\bar{y}_{x}^{(j)}$ is trimmed to $y_{x}^{(j)}$ (without the ${ }^{-}$marker) that only has $s$ terms each.

The GaussianSketchHD. We can also define another hash family of sketches for the Gaussian kernel GaussianSketchHD, which works better for high dimension $d$, but will have worse dependence on other error and domain parameters. For $j=1, \ldots, s$, it will use $T_{j}$
as randomly chosen from RecursiveTensorSketch ${ }_{d, m_{j}, j-1}$. Given a vector $x \in \mathbb{R}^{d}$, a positive integer $s$, and $s$ positive integers $m_{1}, \ldots, m_{s}$, define GaussianSketchHD $m_{m_{1}, \ldots, m_{s}, s}$ to be the family of hash functions that if $G$ is in it, then $G(x) \in \mathbb{R}^{m}$ with $\left(m_{j-1}+1\right)$ th coordinate to $m_{j}$ th coordinate be $\sqrt{\frac{2^{j-1}}{(j-1)!}} \exp \left(-\|x\|^{2}\right) T_{j}\left(x^{\otimes j-1}\right)=T_{j}\left(z_{x}^{(j)}\right) \in \mathbb{R}^{m_{j}}$ where $z_{x}^{(j)}=\sqrt{\frac{2^{j-1}}{(j-1)!}} \exp \left(-\|x\|^{2}\right) x^{\otimes j-1} \in \mathbb{R}^{d^{j-1}}$ and $m=\sum_{j=1}^{s} m_{j}$. Denote $z_{x}$ the $\frac{d^{s}-1}{d-1}$ dimensional vector where the first coordinate is $z_{x}^{(1)}$, the next $d$ coordinates are $z_{x}^{(2)}$, the next $d^{2}$ coordinates are $z_{x}^{(3)}$, and so on. The GaussianSketchHD uses the following, a different infinite expansion of the Gaussian kernel (also explored by Cotter et al. [17]).

- Lemma 2. For $x, p \in \mathbb{R}^{d}$,

$$
\exp \left(-\|x-p\|^{2}\right)=\sum_{i=0}^{\infty}\left\langle\exp \left(-\|x\|^{2}\right) \sqrt{\frac{2^{i}}{i!}} x^{\otimes i}, \exp \left(-\|p\|^{2}\right) \sqrt{\frac{2^{i}}{i!} p^{\otimes i}}\right\rangle=\sum_{i=0}^{\infty}\left\langle z_{x}^{(i)}, z_{p}^{(i)}\right\rangle
$$

Proof.

$$
\begin{aligned}
& \exp \left(-\|x-p\|^{2}\right) \\
& =\exp \left(-\|x\|^{2}\right) \exp \left(-\|p\|^{2}\right) \exp (2\langle x, p\rangle) \\
& =\exp \left(-\|x\|^{2}\right) \exp \left(-\|p\|^{2}\right) \sum_{i=0}^{\infty} \frac{1}{j!}(2\langle x, p\rangle)^{j} \quad \text { by Taylor expansion of } \exp (\cdot) \\
& =\exp \left(-\|x\|^{2}\right) \exp \left(-\|p\|^{2}\right) \sum_{i=0}^{\infty} \frac{2^{j}}{j!}\left\langle x^{\otimes j}, p^{\otimes j}\right\rangle \\
& =\sum_{j=0}^{\infty}\left\langle\exp \left(-\|x\|^{2}\right) \sqrt{\frac{2^{j}}{j!}} x^{\otimes j}, \exp \left(-\|p\|^{2}\right) \sqrt{\frac{2^{i}}{j!}} p^{\otimes j}\right\rangle
\end{aligned}
$$

### 2.1 Concentration Bounds for GaussianSketch and GaussianSketchHD

The sketches will inherit the concentration properties of the RecursiveTensorSketch. Similar observations were recently observed by Ahle et al. [2]. Consider a weighted set of elements $X \subset \mathbb{R}^{d}$ with weights $\alpha_{x}$ for $x \in X$, and we use the general concentration bounds for these under the GaussianSketch.

- Lemma 3 ([2]). Let $G$ be a randomly chosen hash function in GaUSSIANSKETCH ${ }_{m, s}$ with $m=O\left(\frac{d}{\varepsilon^{2}}\right)$. Let $v=\sum_{x \in X} \alpha_{x} y_{x}^{(1)} \otimes \cdots \otimes y_{x}^{(d)}$, then $E\left[\left\|\sum_{x \in X} \alpha_{x} G(x)\right\|^{2}\right]=\|v\|^{2}$ and $\operatorname{Var}\left[\left\|\sum_{x \in X} \alpha_{x} G(x)\right\|^{2}\right] \leq \frac{\varepsilon^{2}}{10}\|v\|^{4}$ and hence with probability at least $9 / 10$ we have $\left|\left\|\sum_{x \in X} \alpha_{x} G(x)\right\|^{2}-\|v\|^{2}\right| \leq \varepsilon\|v\|^{2}$.

If $G$ is randomly chosen from GaussianSketchHD $m_{m_{1}, \ldots, m_{s}, s}$, then $G(x)=S z_{x}$, where $S$ is a $m \times \frac{d^{s}-1}{d-1}$ random matrix (recall $m=\sum_{j=1}^{s} m_{j}$ ) so, for the $\left(m_{i-1}+1\right)$ th row to the $m_{i}$ th row, and the $\left(\frac{d^{i-1}-1}{d-1}+1\right)$ th column to the $\frac{d^{i}-1}{d-1}$ th column forms a matrix $S_{i}$ where $T_{i}\left(z_{x}^{(i)}\right)=S_{i} z_{x}^{(i)}$, and the rest of entries are zero.

- Lemma 4 ([2]). Suppose $A, B$ has $\frac{d^{s}-1}{d-1}$ columns. Denote $A_{i}$ and $B_{i}$ be ith row of $A$ and $B$ respectively. By taking $m_{i}=O\left(\frac{i}{\varepsilon^{2}}\right)$, we have $\operatorname{Pr}\left[\left\|A B^{T}-A S^{T} S B^{T}\right\|_{F}^{2} \leq \varepsilon^{2}\|A\|_{F}^{2}\|B\|_{F}^{2}\right] \geq$ $1-\delta$.


### 2.2 Truncation Bounds for GaussianSketch and GaussianSketchHD

These sketches are effective when it is useful to analyze the effect of sketching a large data set $X$ of size $n$, and we desire to show the cumulative measured across all pairs of elements. For each sketch we expand these infinite sums, and determine the truncation parameter $s$ so the sum of terms past $s$ have a bounded effect.

In our analysis, we will use the following inequality which follows by standard calculus analysis, for any $\eta>0$,

$$
\begin{equation*}
\sum_{j=s}^{\infty} \frac{\eta^{j}}{j!} \leq \frac{\left(\sup _{y \in[-\eta, \eta]} \exp (y)\right) \eta^{s}}{s!} \leq \frac{\exp (\eta) \eta^{s}}{s!} \tag{1}
\end{equation*}
$$

The following expression also arises in our analysis.

- Lemma 5. For $\xi, a, b>0$, setting $s=\Theta\left(\frac{\log \frac{\xi \cdot a}{\alpha}}{\log \left(\frac{1}{b} \log \frac{\xi \cdot a}{\alpha}\right)}\right)$ then the we have $\xi \cdot a\left(\frac{b}{s}\right)^{s} \leq \alpha$.

Proof. By setting $\frac{s}{b}=C \frac{\gamma}{\log \gamma}$ for some large constant $C$ where $\gamma=\frac{1}{b} \log \frac{\xi a}{\alpha}$, we have

$$
\frac{s}{b} \log \frac{s}{b}=C \frac{\gamma}{\log \gamma} \log \left(C \frac{\gamma}{\log \gamma}\right)=\gamma \cdot C\left(1+\frac{\log C}{\log \gamma}-\frac{\log \log \gamma}{\log \gamma}\right) \geq \gamma=\frac{1}{b} \log \frac{\xi a}{\alpha} .
$$

Now, if we rearrange the inequality then $\xi \cdot a\left(\frac{b}{s}\right)^{s} \leq \alpha$.
Consider a point set $X=\left\{x^{(1)}, x^{(2)}, \ldots, x^{(n)}\right\} \subset \mathbb{R}^{d}$, denote $K_{X}$ as the $n \times n$ matrix with $\left(K_{X}\right)_{i, j}=\exp \left(-\left\|x^{(i)}-x^{(j)}\right\|^{2}\right)$. First truncate $K_{X}$ using Lemma 1 to obtain the $n \times n$ matrix $K_{X, s}^{\mathrm{GS}}$ with

$$
\begin{aligned}
&\left(K_{X, s}^{\mathrm{GS}}\right)_{i, j} \\
&=\sum_{j_{1}=0}^{s-1} \cdots \sum_{j_{d}=0}^{s-1}\left(\exp \left(-\left\|x^{(i)}\right\|^{2}\right)( \right.\left.\left.\prod_{a=1}^{d} \sqrt{\frac{2^{j_{a}}}{j_{a}!}}\left(x_{a}^{(i)}\right)^{j_{a}}\right)\right) \\
& \cdot\left(\exp \left(-\left\|x^{(j)}\right\|^{2}\right)\left(\prod_{a=1}^{d} \sqrt{\frac{2^{j_{a}}}{j_{a}!}}\left(p_{a}^{(j)}\right)^{j_{a}}\right)\right)
\end{aligned}
$$

- Lemma 6. Suppose $X \subset \mathbb{R}^{d}$ so for all $x^{(i)} \in X$ has $\left\|x^{(i)}\right\|_{\infty} \leq L$ for some $L>0$. Given a vector $w \in \mathbb{R}^{n}$ with $\left(\sum_{i=1}^{n}\left|w_{i}\right|\right)^{2} \leq \xi$, we have

$$
w^{T}\left(K_{X}-K_{X, s}^{\mathrm{GS}}\right) w \leq\left(\sum_{i=1}^{n}\left|w_{i}\right|\right)^{2} d \exp \left(2 d L^{2}\right)\left(\frac{2 e L^{2}}{s}\right)^{s} \leq \alpha
$$

where the last $\leq \alpha$ inequality follows from setting $s=s_{L, d, \alpha}=\Theta\left(\frac{\log \frac{\xi \cdot d \exp \left(2 d L^{2}\right)}{\alpha}}{\log \left(\frac{1}{2 e L^{2}} \log \frac{\xi \cdot d \exp \left(2 d L^{2}\right)}{\alpha}\right)}\right)$.
Proof. From Lemma 1, we have

$$
\begin{aligned}
& \left(K_{X}-K_{X, s}^{\mathrm{GS}}\right)_{i, j} \\
& =\sum_{\substack{j_{1}, \ldots, j_{d} \\
\text { one of } j_{b} \geq s}}\left(\exp \left(-\left\|x^{(i)}\right\|^{2}\right)\left(\prod_{a=1}^{d} \sqrt{\frac{2^{j_{a}}}{j_{a}!}}\left(x_{a}^{(i)}\right)^{j_{a}}\right)\right) \\
& \cdot\left(\exp \left(-\left\|x^{(j)}\right\|^{2}\right)\left(\prod_{a=1}^{d} \sqrt{\frac{2^{j_{a}}}{j_{a}!}}\left(x_{a}^{(j)}\right)^{j_{a}}\right)\right)
\end{aligned}
$$

Then we can analyze these in aggregate with respect to a test vector $z$. The first line uses the fact that a matrix $A$ (for instance with $A=K_{X}-K_{X, s}^{\mathrm{GS}}$ ) written as $\sum_{j}\left(\sum_{x_{i} \in X} \psi_{j}\left(x_{i}\right)\right)\left(\sum_{x_{i}^{\prime} \in X} \psi_{j}\left(x_{i}^{\prime}\right)\right)$ can be simplified $w^{T} A w=\sum_{j}\left(\sum_{x_{i} \in X} w_{i} \psi_{j}\left(x_{i}\right)\right)^{2}$.

$$
\begin{aligned}
& w^{T}\left(K_{X}-K_{X, s}^{G S}\right) w \\
& =\sum_{\substack{j_{1}, \ldots, j_{d} \\
\text { one of } j_{b} \geq s}}\left(\sum_{i=1}^{n} w_{i} \exp \left(-\left\|x^{(i)}\right\|^{2}\right)\left(\prod_{a=1}^{d} \sqrt{\frac{2^{j_{a}}}{j_{a}!}}\left(x_{a}^{(i)}\right)^{j_{a}}\right)\right)^{2} \\
& \leq \sum_{b=1}^{d} \sum_{\substack{j_{1}, \ldots, j_{d} \\
j_{b} \geq s}}\left(\sum_{i=1}^{n} w_{i} \exp \left(-\left\|x^{(i)}\right\|^{2}\right)\left(\prod_{a=1}^{d} \sqrt{\frac{2^{j_{a}}}{j_{a}!}}\left(x_{a}^{(i)}\right)^{j_{a}}\right)\right)^{2} \quad \quad \text { by union bound } \quad \quad \quad \text { assuming }\left\|x^{(i)}\right\|_{\infty} \leq L \\
& \leq \sum_{b=1}^{d} \sum_{\substack{j_{1}, \ldots, j_{d} \\
j_{b} \geq s}}\left(\sum_{i=1}^{n}\left|w_{i}\right|\left(\prod_{a=1}^{d} \sqrt{\frac{2^{j_{a}}}{j_{a}!}} L^{j_{a}}\right)\right)^{2} \quad \\
& \leq\left(\sum_{i=1}^{n}\left|w_{i}\right|\right)^{2}\left(\sum_{b=1}^{d} \sum_{\substack{j_{1}, \ldots, j_{d} \\
j_{b} \geq s}}\left(\prod_{a=1}^{d} \frac{\left(2 L^{2}\right)^{j_{a}}}{j_{a}!}\right)\right)
\end{aligned}
$$

The term $\sum_{b=1}^{d} \sum_{\substack{j_{1}, \ldots, j_{d} \\ j_{b} \geq s}}\left(\prod_{a=1}^{d} \frac{\left(2 L^{2}\right)^{j a}}{j_{a}!}\right)$ can be expressed as the follows.

$$
\begin{aligned}
& \sum_{\substack{d}}^{d} \sum_{\substack{j_{1}, \ldots, j_{d} \\
j_{b} \geq s}}\left(\prod_{a=1}^{d} \frac{\left(2 L^{2}\right)^{j_{a}}}{j_{a}!}\right) \\
& =\sum_{b=1}^{d}\left(\sum_{j_{1}=0}^{\infty} \frac{\left(2 L^{2}\right)^{j_{1}}}{j_{1}!}\right) \cdots\left(\sum_{j_{b}=s}^{\infty} \frac{\left(2 L^{2}\right)^{j_{b}}}{j_{b}!}\right) \ldots\left(\sum_{j_{d}=0}^{\infty} \frac{\left(2 L^{2}\right)^{j_{d}}}{j_{d}!}\right) \\
& =\sum_{b=1}^{d}\left(\prod_{\substack{a=1 \\
a \neq b}}^{d} \exp \left(2 L^{2}\right)\right)\left(\sum_{j_{b}=s}^{\infty} \frac{\left(2 L^{2}\right)^{j_{b}}}{j_{b}!}\right) \\
& \leq \sum_{b=1}^{d}\left(\exp \left((d-1) 2 L^{2}\right)\right) \frac{\exp \left(2 L^{2}\right)\left(2 L^{2}\right)^{s}}{s!} \\
& =\frac{d \exp \left(2 d L^{2}\right)\left(2 L^{2}\right)^{s}}{s!} \\
& \leq d \exp \left(2 d L^{2}\right)\left(\frac{2 e L^{2}}{s}\right)^{s}
\end{aligned}
$$

$$
\text { by the fact } s!\geq\left(\frac{s}{e}\right)^{s}
$$

Thus, we have

$$
\begin{aligned}
w^{T}\left(K_{X}-K_{X, s}^{\mathrm{GS}}\right) w & \leq\left(\sum_{i=1}^{n}\left|w_{i}\right|\right)^{2}\left(\sum_{\substack{b=1}}^{d} \sum_{\substack{j_{1}, \ldots, j_{d} \\
j_{b} \geq s}}\left(\prod_{a=1}^{d} \frac{\left(2 L^{2}\right)^{j_{a}}}{j_{a}!}\right)\right) \\
& \leq\left(\sum_{i=1}^{n}\left|w_{i}\right|\right)^{2} d \exp \left(2 d L^{2}\right)\left(\frac{2 e L^{2}}{s}\right)^{s} \\
& \leq \alpha
\end{aligned}
$$

where the last inequality follows Lemma 5 using $\xi=\left(\sum_{i=1}^{n}\left|w_{i}\right|\right)^{2}, a=d \exp \left(2 d L^{2}\right)$ and $b=2 e L^{2}$ 。

Now truncate $K_{X}$ based on Lemma 2 to obtain $K_{X, s}^{\mathrm{HD}}$ with

$$
\left(K_{X, s}^{\mathrm{HD}}\right)_{i, j}=\sum_{a=0}^{s-1}\left\langle\exp \left(-\left\|x^{(i)}\right\|^{2}\right) \sqrt{\frac{2^{a}}{a!}}\left(x^{(i)}\right)^{\otimes a}, \exp \left(-\left\|x^{(j)}\right\|^{2}\right) \sqrt{\frac{2^{a}}{a!}}\left(x^{(j)}\right)^{\otimes a}\right\rangle
$$

- Lemma 7. Define $\Lambda_{R}^{d}=\left\{x \in \mathbb{R}^{d} \mid\|x\|_{2} \leq R\right\}$. For a point set $X \subset \Lambda_{R}^{d}$, and a vector $w \in \mathbb{R}^{n}$ with $\left(\sum_{i=1}^{n}\left|w_{i}\right|\right)^{2} \leq \xi$, we have

$$
w^{T}\left(K_{X}-K_{X, s}^{H D}\right) w \leq\left(\sum_{i=1}^{n}\left|w_{i}\right|\right)^{2} \exp \left(2 R^{2}\right)\left(\frac{2 e R^{2}}{s}\right)^{s} \leq \alpha
$$

where the last $\leq \alpha$ inequality follows from setting $s=s_{R, \alpha}=\Theta\left(\frac{\log \frac{\xi \cdot \exp \left(2 R^{2}\right)}{\alpha}}{\log \left(\frac{1}{2 e R^{2}} \log \frac{\xi \cdot \exp p\left(2 R^{2}\right)}{\alpha}\right)}\right)$.
Proof. From Lemma 2, we have

$$
\left(K_{X}-K_{X, s}^{\mathrm{HD}}\right)_{i, j}=\sum_{a=s}^{\infty}\left\langle\exp \left(-\left\|p^{(i)}\right\|^{2}\right) \sqrt{\frac{2^{a}}{a!}}\left(p^{(i)}\right)^{\otimes a}, \exp \left(-\left\|p^{(j)}\right\|^{2}\right) \sqrt{\frac{2^{a}}{a!}}\left(p^{(j)}\right)^{\otimes a}\right\rangle
$$

Then we can analyze these in aggregate with respect to a test vector $z$. The first line uses the fact that a matrix $A$ (for instance with $A=K_{X}-K_{X, s}^{\mathrm{HD}}$ ) written as $\sum_{j}\left(\sum_{x_{i} \in X} \psi_{j}\left(x_{i}\right)\right)\left(\sum_{x_{i}^{\prime} \in X} \psi_{j}\left(x_{i}^{\prime}\right)\right)$ can be simplified $w^{T} A w=\sum_{j}\left(\sum_{x_{i} \in X} w_{i} \psi_{j}\left(x_{i}\right)\right)^{2}$.

$$
\begin{align*}
& w^{T}\left(K_{X}-K_{X, s}^{\mathrm{HD}}\right) w \\
& =\sum_{a=s}^{\infty}\left\|\sum_{i=1}^{n} w_{i} \exp \left(-\left\|x^{(i)}\right\|^{2}\right) \sqrt{\frac{2^{a}}{a!}}\left(x^{(i)}\right)^{\otimes a}\right\|^{2} \\
& \leq \sum_{a=s}^{\infty}\left(\sum_{i=1}^{n}\left|w_{i}\right|\left\|\exp \left(-\left\|x^{(i)}\right\|^{2}\right) \sqrt{\frac{2^{a}}{a!}}\left(x^{(i)}\right)^{\otimes a}\right\|\right)^{2} \\
& \leq \sum_{a=s}^{\infty}\left(\sum_{i=1}^{n}\left|w_{i}\right| \sqrt{\frac{2^{a}}{a!}} R^{a}\right)^{2} \quad \quad \text { assuming }\left\|x^{(i)}\right\| \leq R \\
& =\left(\sum_{i=1}^{n}\left|w_{i}\right|\right)^{2}\left(\sum_{a=s}^{\infty} \frac{\left(2 R^{2}\right)^{a}}{a!}\right) \quad \text { by }(1) \\
& \leq\left(\sum_{i=1}^{n}\left|w_{i}\right|\right)^{2} \frac{\exp \left(2 R^{2}\right)\left(2 R^{2}\right)^{s}}{s!}  \tag{1}\\
& \leq\left(\sum_{i=1}^{n}\left|w_{i}\right|\right)^{2} \exp \left(2 R^{2}\right)\left(\frac{2 e R^{2}}{s}\right)^{s} \quad \text { by the fact } s!\geq\left(\frac{s}{e}\right)^{s} \\
& \leq \alpha
\end{align*}
$$

where the last inequality follows Lemma 5 using $\xi=\left(\sum_{i=1}^{n}\left|w_{i}\right|\right)^{2}, a=\exp \left(2 R^{2}\right)$ and $b=2 e R^{2}$ 。

## 3 Application to the Gaussian Kernel Distance

Let $K: \mathbb{R}^{d} \times \mathbb{R}^{d} \rightarrow \mathbb{R}$ be Gaussian kernel. Namely, for any $x, y \in \mathbb{R}^{d}, K(x, y)=$ $\exp \left(-\|x-y\|^{2}\right)$. Given two point sets $P, Q \subset \mathbb{R}^{d}$, one can define a similarity function $\kappa(P, Q)=\frac{1}{|P|} \frac{1}{|Q|} \sum_{x \in P} \sum_{y \in Q} K(x, y)$ and a squared kernel distance

$$
\mathrm{D}_{K}^{2}(P, Q)=\kappa(P, P)-2 \kappa(P, Q)+\kappa(Q, Q)
$$

We make the important observation that the above formulation is equivalent to the following form which will be much simpler to fit within our framework:

$$
\mathrm{D}_{K}^{2}(P, Q)=\sum_{x \in P \cup Q} \sum_{y \in P \cup Q} \beta_{x} \beta_{y} \exp \left(-\|x-y\|^{2}\right)
$$

where $\beta_{x}$ is $\frac{1}{|P|}$ if $x \in P$ and $-\frac{1}{|Q|}$ if $x \in Q$.
We now express $\mathrm{D}_{K}^{2}(P, Q)$ as the infinite sum using Lemma 1 .

$$
\begin{aligned}
& \mathrm{D}_{K}^{2}(P, Q) \\
& =\sum_{x \in P \cup Q} \sum_{y \in P \cup Q} \beta_{x} \beta_{y} \exp \left(-\|x-y\|^{2}\right) \\
& =\sum_{x \in P \cup Q} \sum_{y \in P \cup Q} \beta_{x} \beta_{y} \sum_{j_{1}=0}^{\infty} \cdots \sum_{j_{d}=0}^{\infty}\left(\exp \left(-\|x\|^{2}\right)\left(\prod_{i=1}^{d} \sqrt{\frac{2^{j_{i}}}{j_{i}!}} x_{i}^{j_{i}}\right)\right) \\
& \quad \cdot\left(\exp \left(-\|y\|^{2}\right)\left(\prod_{i=1}^{d} \sqrt{\frac{2^{j_{i}}}{j_{i}!}} y_{i}^{j_{i}}\right)\right) \\
& =\sum_{j_{1}=0}^{\infty} \cdots \sum_{j_{d}=0}^{\infty}\left(\sum_{x \in P \cup Q} \beta_{x} \exp \left(-\|x\|^{2}\right)\left(\prod_{i=1}^{d} \sqrt{\frac{2^{j_{i}}}{j_{i}!}} x_{i}^{j_{i}}\right)\right)^{2} \\
& =\left\|\sum_{x \in P \cup Q} \beta_{x} \bar{y}_{x}^{(1)} \otimes \cdots \otimes \bar{y}_{x}^{(d)}\right\|^{2},
\end{aligned}
$$

where each $\bar{y}_{x}^{(j)}$ is an infinite dimension vector with $i$ th coordinate $\exp \left(-x_{j}^{2}\right) \sqrt{\frac{2^{i-1}}{(i-1)!}} x_{j}^{i-1}$.

- Theorem 8. For any $\varepsilon, R, \alpha>0$, let $G$ be randomly chosen from GaUSSIANSKETCH ${ }_{m, s}$ with $m=O\left(\frac{d}{\varepsilon^{2}}\right)$ and $s=\Theta\left(\frac{\log \frac{4 d \exp \left(2 d L^{2}\right)}{\alpha}}{\log \left(\frac{1}{2 e L^{2}} \log \frac{4 d \exp \left(2 d L^{2}\right)}{\alpha}\right)}\right)$. Let $\Omega_{L}^{d}=\left\{x \in \mathbb{R}^{d} \mid\|x\|_{\infty} \leq L\right\}$. Define a mapping function $F$ from any $X \subset \Omega_{L}^{d}$ so $F(X)=\sum_{x \in X} G(x)$, which is a vector in $\mathbb{R}^{m}$. Then for any $P, Q \subset \Omega_{L}^{d}$ with probability at least $9 / 10$

$$
\left|\|F(P)-F(Q)\|^{2}-D_{K}^{2}(P, Q)\right| \leq \varepsilon D_{K}^{2}(P, Q)+\alpha
$$

The mapping $G: \mathbb{R}^{d} \rightarrow \mathbb{R}^{m}$ can be computed in $O\left(\frac{d^{2}}{\varepsilon^{2}} \log \frac{d}{\varepsilon}+d s\right)$ time.
Proof. To analyze the GaussianSketch, we need to account for error from two sources: from the RecursiveTensorSketch (using Lemma 3) and parameter $m$, and from the truncation of the Taylor expansion at $s$ (using Lemma 6). In this case we analyze the following infinite expansion

$$
\mathrm{D}_{K}^{2}(P, Q)=\left\|\sum_{x \in P \cup Q} \beta_{x} \bar{y}_{x}^{(1)} \otimes \cdots \otimes \bar{y}_{x}^{(d)}\right\|^{2}
$$

where each $\bar{y}_{x}^{(j)}$ is an infinite dimension vector with $i$ th coordinate $\exp \left(-x_{j}^{2}\right) \sqrt{\frac{2^{i-1}}{(i-1)!}} x_{j}^{i-1}$.
Let $v=\sum_{x \in P \cup Q} \beta_{x} \bar{y}_{x}^{(1)} \otimes \cdots \otimes \bar{y}_{x}^{(d)}$. Then by Lemma 3 by setting $m=O\left(d / \varepsilon^{2}\right)$ we have with probability at least $9 / 10$ that

$$
\left|\left\|\sum_{x \in P \cup Q} \beta_{x} G(x)\right\|^{2}-\|v\|^{2}\right| \leq \varepsilon\|v\|^{2}
$$

Next note that $\left(\sum_{x \in P \cup Q}\left|\beta_{x}\right|\right)^{2} \leq 4=\xi$. So by Lemma 6 the truncation by only $s$ terms can be accounted for as

$$
\mathrm{D}_{K}^{2}(P, Q)-\|v\|^{2}=\beta^{T}\left(K_{P \cup Q}-K_{P \cup Q, s}^{\mathrm{GS}}\right) \beta \leq 4 d \exp \left(2 d L^{2}\right)\left(\frac{2 e L^{2}}{s}\right)^{2} \leq \alpha
$$

where $K_{P \cup Q}$ and $K_{P \cup Q, s}^{\mathrm{GS}}$ are defined as in Lemma 6 with $X=P \cup Q$.
Combining these together we have

$$
(1-\varepsilon)\left(\mathrm{D}_{K}^{2}(P, Q)-\alpha\right) \leq(1-\varepsilon)\|v\|^{2} \leq|F(P)-F(Q)| \leq(1+\varepsilon)\|v\|^{2} \leq(1+\varepsilon) \mathrm{D}_{K}^{2}(P, Q)
$$

and hence as desired

$$
\left|\|F(P)-F(Q)\|^{2}-\mathrm{D}_{K}^{2}(P, Q)\right| \leq \varepsilon \mathrm{D}_{K}^{2}(P, Q)+\alpha
$$

Recall that the running time of $G$ for mapping a point is

$$
O(d m \log m+d s)=O\left(\frac{d^{2}}{\varepsilon^{2}} \log \frac{d}{\varepsilon}+d s\right)
$$

Using the Gaussian Sketch HD for high dimensions. We first express $\exp \left(-\|x-y\|^{2}\right)$ as another infinite sum using Lemma 2. Starting with $\mathrm{D}_{K}^{2}(P, Q)=\sum_{x \in P \cup Q} \sum_{y \in P \cup Q} \beta_{x} \beta_{y} \exp \left(-\|x-y\|^{2}\right)$ where $\beta_{x}$ is $\frac{1}{|P|}$ if $x \in P$ and $-\frac{1}{|Q|}$ if $x \in Q$, we have

$$
\begin{aligned}
\mathrm{D}_{K}^{2}(P, Q) & =\sum_{x \in P \cup Q} \sum_{y \in P \cup Q} \beta_{x} \beta_{y}\left\langle\exp \left(-\|x\|^{2}\right) \sqrt{\frac{2^{i}}{i!}} x^{\otimes i}, \exp \left(-\|y\|^{2}\right) \sqrt{\frac{2^{i}}{i!}} y^{\otimes i}\right\rangle \\
& =\sum_{i=0}^{\infty}\left\|\sum_{x \in P \cup Q} \beta_{x} \exp \left(-\|x\|^{2}\right) \sqrt{\frac{2^{i}}{i!}} x^{\otimes i}\right\|^{2} .
\end{aligned}
$$

- Theorem 9. For any $\varepsilon, R, \alpha>0$, let $G$ be randomly chosen from

GAUSSIANSKETCHHD $m_{m_{1}, \ldots, m_{s}, s}$ with $m_{i}=O\left(\frac{i}{\varepsilon^{2}}\right)$ and $s=\Theta\left(\frac{\log \frac{4 \exp \left(2 R^{2}\right)}{\alpha}}{\log \left(\frac{1}{2 e R^{2}} \log \frac{4 \exp \left(2 R^{2}\right)}{\alpha}\right)}\right)$. Let $\Lambda_{R}^{d}=\left\{x \in \mathbb{R}^{d} \mid\|x\|_{2} \leq R\right\}$. Define a mapping function $F$ from any $X \subset \Lambda_{L}^{d}$ so $F(X)=$ $\sum_{x \in X} G(x)$, which is a vector in $\mathbb{R}^{m}$ where $m=\sum_{i=1}^{s} m_{i}$. Then for any $P, Q \subset \Lambda_{R}^{d}$ with probability at least 9/10

$$
\left|\|F(P)-F(Q)\|^{2}-D_{K}^{2}(P, Q)\right| \leq \varepsilon D_{K}^{2}(P, Q)+\alpha
$$

The mapping $G: \mathbb{R}^{d} \rightarrow \mathbb{R}^{m}$ can be computed in $O\left(\frac{s^{3}}{\varepsilon^{2}} \log \frac{s}{\varepsilon}+s^{2} d\right)$ time.
Proof. Suppose $G(x) \in \mathbb{R}^{m}$ with $\left(m_{i-1}+1\right)$ th coordinate to $m_{i}$ th coordinate be $\sqrt{\frac{2^{i-1}}{(i-1)!}} \exp \left(-\|x\|^{2}\right) T_{i}\left(x^{\otimes i-1}\right)$. Here, $T_{i}$ is randomly chosen from RecursiveTensorSketch ${ }_{d, m_{i}, i-1}$ for $i=1, \ldots, s$.

We first need to invoke Lemma 4 to inherit the appropriate concentration bounds from the RecursiveTensorSketch. We use $t \times \frac{d^{s}-1}{d-1}$ matrices $A$ and $B$ as just row vectors with $t=1$, and let $A=B$. In particular, define this single row as $z=\sum_{x \in P \cup Q} \beta_{x}\left[z_{x}^{(1)}, z_{x}^{(2)}, \ldots, z_{x}^{(s)}\right]$, then the conclusion of Lemma 4 is that with probability at least $1-\delta$

$$
\left|\|z\|^{2}-\left\|\sum_{x \in P \cup Q} \beta_{x} G(x)\right\|^{2}\right|^{2}=\| \| z\left\|^{2}-z S^{T} S z^{T}\right\|_{F}^{2} \leq \varepsilon^{2}\|z\|^{4}
$$

So by Lemma 7 the truncation by only $s$ terms can be accounted for as

$$
\left.\mathrm{D}_{K}^{2}(P, Q)-\|z\|^{2}=\beta^{T}\left(K_{P \cup Q}-K_{P \cup Q, s}^{\mathrm{HD}}\right)\right) \beta \leq 4 d \exp \left(2 d L^{2}\right)\left(2 e L^{2} / s\right)^{2} \leq \alpha
$$

where $K_{P \cup Q}$ and $K_{P \cup Q, s}^{\mathrm{HD}}$ are defined as in Lemma 7 with $X=P \cup Q$.
Combining these together we have

$$
(1-\varepsilon)\left(\mathrm{D}_{K}^{2}(P, Q)-\alpha\right) \leq(1-\varepsilon)\|z\|^{2} \leq\|F(P)-F(Q)\|^{2} \leq(1+\varepsilon)\|z\|^{2} \leq(1+\varepsilon) \mathrm{D}_{K}^{2}(P, Q)
$$

and hence as desired

$$
\left|\|F(P)-F(Q)\|^{2}-\mathrm{D}_{K}^{2}(P, Q)\right| \leq \varepsilon \mathrm{D}_{K}^{2}(P, Q)+\alpha
$$

Recall that the running time of $G$ for mapping a point is $O\left(\sum_{i=1}^{s} i m_{i} \log m_{i}+i d\right)=$ $O\left(\sum_{i=1}^{s} \frac{i^{2}}{\varepsilon^{2}} \log \frac{i}{\varepsilon}+i d\right)=O\left(\frac{s^{3}}{\varepsilon^{2}} \log \frac{s}{\varepsilon}+s^{2} d\right)$.

## 4 Extensions and Data Analysis Implications

There are many data analysis applications where useful sketched bounds almost immediately follow from this new embedding. Before we begin, we start by improving the dimensionality of the embedding with a simple post-processing. We can applying a Johnson-Lindenstrauss-type embedding $[25,3,4,1]$ to the $m$-dimensional space to obtain $O\left(1 / \varepsilon^{2}\right)$-dimensional space that, with constant probability, preserves the distance of a pair of point sets. Furthermore, we can use median trick to boost the success probability to $1-\delta$ by running $O\left(\log \frac{1}{\delta}\right)$ independent copies. For applications in kernel two-sample hypothesis testing and nearest neighbor searching, setting $\delta$ depends on the number of queries $q$ we make, for instances the bounded number needed for $k$-means clustering [16], now applied to kernel $k$-means. These results are useful for reducing the storage space of data representations. Recall that the running time of JL embedding from $m$-dimensional space to $\rho$-dimensional space is $O\left(m \log \rho+\rho^{2}\right)[3,4]$.

### 4.1 Kernel Two-Sample Test

The kernel two-sample test [24] is a "non-parametric" hypothesis test between two probability distributions represented by finite samples $P$ and $Q$; let $n=|P \cup Q|$. Then this test simply calculates $\mathrm{D}_{K}(P, Q)$, and if the value is large enough it rejects the null hypothesis that $P$ and $Q$ represent the same distribution. Since its introduction a few year ago it has seen many applications and relations; see the recent 140 page survey [33]. Zhao and Deng [48] proposed to speed this test up for large sets using RFFs which improves runtime and in some cases even statistical power. While several improvements are suggested [47] including using FastFood [29], these all only provide additive $\varepsilon$-error.

Consider $P \sim \mu_{P}$ and $Q \sim \mu_{Q}$. If $\mu_{P}=\mu_{Q}$, then empirical distributions $P, Q$ may have $\mathrm{D}_{K}(P, Q)=\Theta(1 / n)$. Hence distinguishing the case of $\mu_{P}=\mu_{Q}$ from them not being equal would either require additive error $\varepsilon=\Theta(1 / n)$, or relative $(1+\varepsilon)$-error with a minimum $\Theta(1 / n)$ additive error. RFFs would require $\Theta\left(1 / \varepsilon^{2}\right)=\Theta\left(n^{2}\right)$ dimensions, so one may just as well compute $\mathrm{D}_{K}(P, Q)$ exactly in $O\left(n^{2}\right)$ time. In our approach, we can set $\varepsilon$ to be a constant (say $\varepsilon=0.2$ ) and $\alpha$ to be $\Theta(1 / n)$. Assuming a constant region diameter, the total running time is $O\left(\frac{n \log n}{\log \log n}\right)$ in the low dimensional case (by Theorem 8) or $O\left(\frac{n \log ^{2} n(\log n+d)}{\log ^{2} \log n}\right)$ in the high dimensional case (by Theorem 9).

Another way to determine if $\mathrm{D}_{K}(P, Q)$ should estimate $P$ and $Q$ as distinct, is to run permutation tests. That is for some large number (e.g., $q=1000$ ) of trials, select two sets $P_{j}, Q_{j}$ iid from $P \cup Q$, of size $|P|$ and $|Q|$ respectively. For each generated pair we calculate
(or estimate using Theorem 8 or Theorem 9) the value of $\mathrm{D}_{K}\left(P_{j}, Q_{j}\right)$, and then use the 95 th-percentile of these values as a threshold. Note since each $P_{j}, Q_{j}$ is drawn from the same domain as $P, Q$, then the guarantees on the accuracy of the featurized estimate carries over directly even under a large $q$ number of permutations.

### 4.2 LSH for Point Sets, Geometric Distributions

The new results also allow us to immediately design LSH and nearest neighbor structures for the kernel distance by relying on standard Euclidean LSH [6]. Building a search engine for low-dimensional shapes [21] has long been a goal in computational geometry and geometric modeling. A difficulty arises in that many of the best-known shape distance measures require an alignment (e.g., Frechet [20,5] or earth movers [11]) which creates many challenges in designing LSH-type procedures. Some methods have been designed, but with limitations, e.g., on point set size for earth mover distance [7] or number of segments in curves for discrete Frechet [18]. The kernel distance provides an alternative distance for shapes, low-dimensional distributions, or curves [26]; it can encode normals or tangents as well to encode direction information of curves [23]. That is, given two shapes composed of (or approximated by) point sets $P_{i}, P_{j}$, the distance between the shapes is simply $\mathrm{D}_{K}\left(P_{i}, P_{j}\right)$.

Given a family of point sets $\mathcal{P}=\left\{P_{1}, P_{2}, \ldots, P_{N}\right\}$ such that each $P_{i} \subset \mathbb{R}^{d}$ has size at most $n$, an $\varepsilon$-approximate nearest neighbor of a query point set $Q$ is a point set $\hat{P} \in \mathcal{P}$ so that $\mathrm{D}_{K}(\hat{P}, Q) \leq(1+\varepsilon) \min _{P_{j} \in \mathcal{P}} \mathrm{D}_{K}\left(P_{j}, Q\right)$. Here, we assume that $\mathrm{D}_{K}\left(P_{i}, P_{j}\right) \geq \alpha^{\prime}$ for any $i \neq j$. For $\varepsilon \leq 1 / 2$, we can embed each $P_{j}$ to $F\left(P_{j}\right) \in \mathbb{R}^{D}$, and then invoke the key result from Andoni and Indyk [6] for a $c^{\prime}$-approximate nearest neighbor, so the total error factor is $c^{\prime}(1+\varepsilon)$. Overall, we can retrieve a $c$-approximate nearest neighbor (setting $c=c^{\prime}(1+\varepsilon)$ ) to a query $Q \subset \mathbb{R}^{d}$ with $O\left(D N^{1 / c^{2}+o(1)}\right)$ query time after using $O\left(D N^{1+1 / c^{2}+o(1)}\right)$ space and $O\left(D N^{1+1 / c^{2}+o(1)}+N\left(\frac{n \log \frac{1}{\varepsilon \alpha^{\prime}}}{\log \log \frac{1}{\varepsilon \alpha^{\prime}}}+\frac{1}{\varepsilon^{2}} \log \frac{1}{\varepsilon}\right)\right)$ preprocessing when $d$ is small or $O\left(D N^{1+1 / c^{2}+o(1)}+N n\left(\frac{\log ^{2} \frac{1}{\varepsilon \alpha^{\prime}}\left(\log \frac{1}{\varepsilon \alpha^{\prime}}+d\right)}{\varepsilon^{2} \log ^{2} \log \frac{1}{\varepsilon \alpha^{\prime}}}\right)\right)$ preprocessing when $d$ is large, both assuming a data region with constant diameter.

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## A Gaussian Kernel PCA

Let $k$ be a positive integer and $\varepsilon>0$. Avron et al. [10] provide the following algorithm. Suppose $S$ and $T$ are randomly chosen from RecursiveTensorSketch ${ }_{s, m, d}$ and RECURSIVETENSORSKETCH $_{s, r, d}$ respectively where $m=\Theta\left(d\left(k^{2}+\frac{k}{\varepsilon}\right)\right)$ and $r=\Theta\left(\frac{d m^{2}}{\varepsilon^{2}}\right)$. Given $n$ vectors $v^{(1)}, \ldots, v^{(n)} \in \mathbb{R}^{s^{d}}$, compute $n \times m$ matrix $M$ with $i$ th row as $S\left(v^{(i)}\right)$ and $n \times r$ matrix $N$ that $i$ th row as $T\left(v^{(i)}\right)$. Let $U$ be the orthonormal basis for column space of $M$ and $W$ be $m \times k$ matrix containing top $k$ left singular vector of $U^{T} N$. Finally, return $V=U W$. This algorithm has the following guarantee.

- Lemma 10 ([10] with straightforward modification). Given a $n$-by-s ${ }^{d}$ matrix A, a positive integer $k$ and $\varepsilon>0$. The above algorithm that has rows of $A$ as input returns a matrix $V$ such that

$$
\left\|A-V V^{T} A\right\|_{F}^{2} \leq(1+\varepsilon)\left\|A-[A]_{k}\right\|_{F}^{2}
$$

where $[A]_{k}$ is the best rank-k approximation of $A$.
Now, we can directly modify the above algorithm into our context for rank- $k$ Gaussian low-rank approximation. Given a point set $X=\left\{x_{1}, \ldots, x_{n}\right\} \subset \mathbb{R}^{d}$ and a positive integer $s$. Suppose $G$ and $H$ are randomly chosen from GaussianSketch $m, s$ and GaussianSketch ${ }_{r, s}$ respectively. Recall that $m=\Theta\left(d\left(k^{2}+\frac{k}{\varepsilon}\right)\right)$ and $r=\Theta\left(\frac{d m^{2}}{\varepsilon^{2}}\right)$. Compute the $n \times m$ matrix $M$ with $i$ th row as $G\left(x_{i}\right)$ and $n \times r$ matrix $N$ with $i$ th row as $H\left(x_{i}\right)$. Let $U$ be the orthonormal basis for column space of $M$ and $W$ be $m \times k$ matrix containing top $k$ left singular vector of $U^{T} N$. Finally, return $V=U W$.

- Theorem 11. Let $\varepsilon, L, \alpha>0$ and $s=\Theta\left(\frac{\left.\log \frac{4 n^{2} d \exp \left(2 d L^{2}\right)}{\log \left(\frac{1}{2 e L^{2}} \log \frac{4 n^{2} d \exp \left(2 d L^{2}\right)}{\alpha}\right)}\right) \text {. For } \Omega_{L}^{d}=\left\{x \in \mathbb{R}^{d} \mid\right.}{\mid}\right.$ $\left.\|x\|_{\infty} \leq L\right\}$ and $X \subset \Omega_{L}^{d}$, and let $A_{X}$ be a pd matrix with elements $\left(A_{X}\right)_{i, j}=K\left(x_{i}, x_{j}\right)=$ $\exp \left(-\left\|x_{i}-x_{j}\right\|^{2}\right)$ for $x_{i}, x_{j} \in X$ and factorization $A_{X}=B_{X} B_{X}^{T}$. Then with constant probability

$$
\left\|B_{X}-V V^{T} B_{X}\right\|_{F}^{2} \leq(1+\varepsilon)\left\|B_{X}-\left[B_{X}\right]_{k}\right\|_{F}^{2}+\alpha
$$

The runtime to compute $V$ is $O\left(n d s+n \frac{d^{4}\left(k^{2}+\frac{k}{\varepsilon}\right)^{3}}{\varepsilon^{2}}\right)$.
Proof. Let $v_{x}^{(i)}$ be a vector in $\mathbb{R}^{s}$ with $j$ th coordinate to be $\exp \left(-x_{i}^{2}\right) \sqrt{\frac{2^{j-1}}{(j-1)!}} x_{i}^{j-1}$ for any $x \in \mathbb{R}^{d}$.

By Lemma 10, taking $A_{s}$ as an $n \times s^{d}$ matrix with $i$ th row as $v_{x_{i}}^{(1)} \otimes \cdots \otimes v_{x_{i}}^{(d)}$. We have

$$
\left\|A_{s}-V V^{T} A_{s}\right\|_{F}^{2} \leq(1+\varepsilon)\left\|A_{s}-\left[A_{s}\right]_{k}\right\|_{F}^{2}
$$

From Lemma $6, v^{T}\left(B_{X} B_{X}^{T}-A_{s} A_{s}^{T}\right) v \leq\left(\sum_{i=1}^{n}\left|v_{i}\right|\right)^{2} d \exp \left(2 d L^{2}\right)\left(\frac{2 e L^{2}}{s}\right)^{s} \leq \alpha / n$. To see this expression is at most $\alpha / n$, first observe that columns of $V$ are orthonormal, and therefore, the norm of each row of $I-V V^{T}$ is at most 2. Hence, $\left(\sum_{i=1}^{n}\left|v_{i}\right|\right)^{2} \leq 4 n$. Then the choice of $s$ and Lemma 5 with $\xi=4 n^{2}, a=d \exp \left(2 d L^{2}\right)$ and $b=2 e L^{2}$ complete this derivation.

We now have

$$
\begin{aligned}
\left\|B_{X}-V V^{T} B_{X}\right\|_{F}^{2} & =\operatorname{Tr}\left(\left(I-V V^{T}\right) B_{X} B_{X}^{T}\left(I-V V^{T}\right)^{T}\right) \\
& \leq\left\|A_{s}-V V^{T} A_{s}\right\|_{F}^{2}+\operatorname{Tr}\left(\left(I-V V^{T}\right)\left(B_{X} B_{X}^{T}-A_{s} A_{s}^{T}\right)\left(I-V V^{T}\right)^{T}\right) \\
& \leq\left\|A_{s}-V V^{T} A_{s}\right\|_{F}^{2}+\alpha
\end{aligned}
$$

On the other hand, by Lemma $1, B_{X} B_{X}^{T}-A_{s} A_{s}^{T}$ is still positive definite. Therefore,

$$
\begin{aligned}
& \left\|A_{s}-\left[A_{s}\right]_{k}\right\|_{F}^{2} \\
& =\left\|A_{s}-U U^{T} A_{s}\right\|_{F}^{2} \quad \text { where } U \text { is the matrix of top- } k \text { left singular vectors of } A_{s} \\
& \leq\left\|A_{s}-U^{\prime} U^{\prime T} A_{s}\right\|_{F}^{2} \quad \text { where } U \text { is the matrix of top- } k \text { left singular vectors of } B_{X} \\
& =\left\|B_{X}-\left[B_{X}\right]_{k}\right\|_{F}^{2}-\operatorname{Tr}\left(\left(I-U^{\prime} U^{\prime T}\right)\left(B_{X} B_{X}^{T}-A_{s} A_{s}^{T}\right)\left(I-U^{\prime} U^{\prime T}\right)\right) \\
& \leq\left\|B_{X}-\left[B_{X}\right]_{k}\right\|_{F}^{2} \quad \text { recall that } B_{X} B_{X}^{T}-A_{s} A_{s}^{T} \text { is positive definite }
\end{aligned}
$$

We can plug in everything.

$$
\begin{aligned}
\left\|B_{X}-V V^{T} B_{X}\right\|_{F}^{2} & \leq\left\|A_{s}-V V^{T} A_{s}\right\|_{F}^{2}+\alpha \\
& \leq\left\|A_{s}-\left[A_{s}\right]_{k}\right\|_{F}^{2}+\alpha \\
& \leq\left\|B_{X}-\left[B_{X}\right]_{k}\right\|_{F}^{2}+\alpha
\end{aligned}
$$

To see the running time, it takes $O(d(s+m \log m))$ to compute $G(\cdot)$ and $O(d(s+r \log r))$ time to compute $H(\cdot)$, and hence $n$ times as much to compute matrices $M$ and $N$. We can compute the basis $U$ of $M$ in $O\left(n m^{2}\right)$ time, and the projection $U^{T} N$ in $O(n r m)$ time. The basis $W$ takes $O\left(r m^{2}\right)$ time, and the final low rank basis $V=U W$ takes $O(n m k)$ time. Thus the total runtime is $O\left(n d(s+m \log m+r \log r)+n m^{2}+n r m+r m^{2}+n m k\right)=$ $O(n d(s+r m))$ using that $r>m^{2}>k^{4}$ that $m>\log r$, and assuming $n>r$. Now using $m=O\left(d\left(k^{2}+k / \varepsilon\right)\right)$ and $r=O\left(d m^{2} / \varepsilon^{2}\right)=O\left(d^{3}\left(k^{4}+k^{2} / \varepsilon^{2}\right) / \varepsilon^{2}\right)$ and we have a total time of $O\left(n d s+n \frac{d^{4}\left(k^{2}+\frac{k}{\varepsilon}\right)^{3}}{\varepsilon^{2}}\right)$.

Gaussian Low Rank Approximation with Gaussian Sketch HD in High Dimensions. Now, we can also modify the above algorithm into our context for rank- $k$ Gaussian low-rank approximation in another way. Given a point set $X=\left\{x_{1}, \ldots, x_{n}\right\} \subset \mathbb{R}^{d}$ and a positive integer $s$. Suppose $G$ and $H$ are randomly chosen from GaussianSketchHD ${ }_{m_{1}, \ldots, m_{s}, s}$ and GAUSSIANSKETCHHD $r_{1}, \ldots, r_{s}, s$ respectively. Here, $m_{i}=\Theta\left(i\left(k^{2}+\frac{k}{\varepsilon}\right)\right)$ and $r_{i}=\Theta\left(\frac{i m^{2}}{\varepsilon^{2}}\right)$ where $m=\sum_{i=1}^{s} m_{i}$. Compute the $n \times m$ matrix $M$ with $i$ th row as $G\left(x_{i}\right)$ and $n \times r$ matrix $N$ with $i$ th row as $H\left(x_{i}\right)$. Let $U$ be the orthonormal basis for column space of $M$ and $W$ be $m \times k$ matrix containing top $k$ left singular vector of $U^{T} N$. Finally, return $V=U W$.

Note that a hash function in GaussianSketchHD is not directly applying a hash function in RecursiveTensorSketch. Therefore, Lemma 10 cannot be directly applied. However, we can still exploit the structure of it in order to prove the same lemma.

As Avron et al. [10] suggest, it is generally possible by combining Lemma 4 and arguments in $[10,15,27]$. We have the following lemma. Here, denote $A_{s}$ is a $n \times \frac{d^{s}-1}{d-1}$ matrix that $i$ th row as $z_{x_{i}}$ for given point set $X=\left\{x_{1}, x_{2} \ldots, x_{n}\right\} \subset \mathbb{R}^{d}$.

- Lemma 12. Given a point set $X \subset \mathbb{R}^{d}$, a positive integer $k$ and $\varepsilon>0$. The above algorithm returns a matrix $V$ such that

$$
\left\|A_{s}-V V^{T} A_{s}\right\|_{F}^{2} \leq(1+\varepsilon)\left\|A_{s}-\left[A_{s}\right]_{k}\right\|_{F}^{2}
$$

where $[A]_{k}$ is the best rank-k approximation of $A$.
Before getting into Lemma 12, the following lemma from [10] which is implied by Lemma 4 would be helpful.

- Lemma 13 ([10] implied by Lemma 4 with straightforward modification). For any positive integer $k^{\prime}$, given any $\frac{d^{s}-1}{d-1} \times k^{\prime}$ matrix $B$ with orthonormal columns, we have $\left\|B^{T} S^{T} S B-I\right\|_{2} \leq$ $\varepsilon$. Here, $S$ is randomly chosen from GaUSSIANSKETCHHD $D_{n_{1}, \ldots, n_{s}, s}$ where $n_{i}=\frac{i k^{\prime 2}}{\varepsilon^{2}}$.

Proof. (of Lemma 12)
In the proof of Theorem 3.1 from [15], the only properties of $S$ used are

- Given any $\frac{d^{s}-1}{d-1} \times k$ matrix $B$ with orthonormal columns, we have $\left\|B^{T} S^{T} S B-I\right\|_{2} \leq \varepsilon_{0}$ for some constant $\varepsilon_{0}>0$
- For any two matrices $A, B$ with $\frac{d^{s}-1}{d-1}$ columns, $\left\|A B^{T}-A S^{T} S B^{T}\right\|_{F} \leq \sqrt{\frac{\varepsilon}{k}}\|A\|_{F}\|B\|_{F}$

The first property can be shown by Lemma 13 since we pick $m_{i}=\Omega\left(i k^{2}\right)$ and the second property can be shown by Lemma 4 since we pick $m_{i}=\Omega\left(\frac{i k}{\varepsilon}\right)$. Also, Theorem 3.1 of [15] implies Lemma 4.2 of [15] which means there is a matrix $Z$ such that $\left\|U Z-A_{s}\right\|_{F} \leq$ $(1+\varepsilon)\left\|A_{s}-\left[A_{s}\right]_{k}\right\|_{F}$ in our context. Combining Lemma 4.3 of [15], we have

$$
\begin{equation*}
\left\|U\left[U^{T} A_{s}\right]-A_{s}\right\|_{F} \leq(1+\varepsilon)\left\|A_{s}-\left[A_{s}\right]_{k}\right\|_{F} \tag{2}
\end{equation*}
$$

Now, Lemma 13 implies Lemma 2.1 from [27] and further implies

$$
\begin{equation*}
\left\|W W^{T} U^{T} A_{s}-A_{s}\right\|_{f} \leq(1+\varepsilon)\left\|A_{s}-\left[A_{s}\right]_{k}\right\|_{F} \tag{3}
\end{equation*}
$$

by setting $k^{\prime}$ in Lemma 13 be $m$ and picking $r_{i}=\Theta\left(\frac{3^{i} m^{2}}{\varepsilon^{2}}\right)$. Using equation (2) and (3) in the proof of Theorem 1.1 from [27], we have our conclusion $\left\|A_{s}-U W W^{T} U^{T} A_{s}\right\|_{F}^{2}=$ $\left\|A_{s}-V V^{T} A_{s}\right\|_{F}^{2} \leq(1+\varepsilon)\left\|A_{s}-\left[A_{s}\right]_{k}\right\|_{F}^{2}$.

- Theorem 14. Let $\varepsilon, R, \alpha>0$ and $s=\Theta\left(\frac{\log \frac{4 n^{2} \exp \left(2 R^{2}\right)}{\alpha}}{\log \left(\frac{1}{2 e R^{2}} \log \frac{4 n^{2} \exp \left(2 R^{2}\right)}{\alpha}\right)}\right)$. For $\Lambda_{R}^{d}=\left\{x \in \mathbb{R}^{d} \mid\right.$ $\left.\|x\|_{2} \leq R\right\}$ and $X \subset \Lambda_{R}^{d}$, and let $A_{X}$ be a pd matrix with elements $\left(A_{X}\right)_{i, j}=K\left(x_{i}, x_{j}\right)=$ $\exp \left(-\left\|x_{i}-x_{j}\right\|^{2}\right)$ for $x_{i}, x_{j} \in X$ and factorization $A_{X}=B_{X} B_{X}^{T}$. Then with constant probability

$$
\left\|B_{X}-V V^{T} B_{X}\right\|_{F}^{2} \leq(1+\varepsilon)\left\|B_{X}-\left[B_{X}\right]_{k}\right\|_{F}^{2}+\alpha
$$

The runtime to compute $V$ is $O\left(n d s^{2}+n \frac{3^{4 s}\left(k^{2}+\frac{k}{\varepsilon}\right)^{3}}{\varepsilon^{2}}\right)$.
Proof. By Lemma 12, we have

$$
\left\|A_{s}-V V^{T} A_{s}\right\|_{F}^{2} \leq(1+\varepsilon)\left\|A_{s}-\left[A_{s}\right]_{k}\right\|_{F}^{2}
$$

From Lemma $7, v^{T}\left(B_{X} B_{X}^{T}-A_{s} A_{s}^{T}\right) v \leq\left(\sum_{i=1}^{n}\left|v_{i}\right|\right)^{2} \exp \left(2 R^{2}\right)\left(\frac{2 e R^{2}}{s}\right)^{s} \leq \alpha / n$ with our setting of $s$ as long as $\left(\sum_{i=1}^{n}\left|v_{i}\right|\right)^{2} \leq 4 n$. Indeed the columns of $V$ are orthonormal, so the norm of each row of $I-V V^{T}$ is at most 2, and thus $\left(\sum_{i=1}^{n}\left|v_{i}\right|\right)^{2} \leq 4 n$.

We now have

$$
\begin{aligned}
\left\|B_{X}-V V^{T} B_{X}\right\|_{F}^{2} & =\operatorname{Tr}\left(\left(I-V V^{T}\right) B_{X} B_{X}^{T}\left(I-V V^{T}\right)^{T}\right) \\
& \leq\left\|A_{s}-V V^{T} A_{s}\right\|_{F}^{2}+\operatorname{Tr}\left(\left(I-V V^{T}\right)\left(B_{X} B_{X}^{T}-A_{s} A_{s}^{T}\right)\left(I-V V^{T}\right)^{T}\right) \\
& \leq\left\|A_{s}-V V^{T} A_{s}\right\|_{F}^{2}+n \cdot(\alpha / n)
\end{aligned}
$$

Also by Lemma 2, $B_{X} B_{X}^{T}-A_{s} A_{s}^{T}$ is still positive definite. Therefore,

$$
\begin{aligned}
& \left\|A_{s}-\left[A_{s}\right]_{k}\right\|_{F}^{2} \\
& =\left\|A_{s}-U U^{T} A_{s}\right\|_{F}^{2} \quad \text { where } U \text { is the matrix of top- } k \text { left singular vectors of } A_{s} \\
& \leq\left\|A_{s}-U^{\prime} U^{\prime T} A_{s}\right\|_{F}^{2} \quad \text { where } U^{\prime} \text { is the matrix of top- } k \text { left singular vectors of } B_{X} \\
& =\left\|B_{X}-\left[B_{X}\right]_{k}\right\|_{F}^{2}-\operatorname{Tr}\left(\left(I-U^{\prime} U^{\prime T}\right)\left(B_{X} B_{X}^{T}-A_{s} A_{s}^{T}\right)\left(I-U^{\prime} U^{\prime T}\right)\right) \\
& \leq\left\|B_{X}-\left[B_{X}\right]_{k}\right\|_{F}^{2} \quad \text { recall that } B_{X} B_{X}^{T}-A_{s} A_{s}^{T} \text { is positive definite }
\end{aligned}
$$

We can plug in everything.

$$
\begin{aligned}
\left\|B_{X}-V V^{T} B_{X}\right\|_{F}^{2} & \leq\left\|A_{s}-V V^{T} A_{s}\right\|_{F}^{2}+\alpha \\
& \leq\left\|A_{s}-\left[A_{s}\right]_{k}\right\|_{F}^{2}+\alpha \\
& \leq\left\|B_{X}-\left[B_{X}\right]_{k}\right\|_{F}^{2}+\alpha
\end{aligned}
$$

To see the running time, it takes $O\left(\sum_{i=1}^{s} i\left(d+m_{i} \log m_{i}\right)\right)$ to compute $G(\cdot)$ and $O\left(\sum_{i=1}^{s} i\left(d+r_{i} \log r_{i}\right)\right)$ time to compute $H(\cdot)$. Using that $r_{i}>m_{i}^{2}>k^{4}$ and $m_{i}>1 / \varepsilon$ then it takes less time to compute $H(\cdot)$ than $G(\cdot)$, and this runtime is $O\left(d s^{2}+s^{2} r_{s} \log r_{s}\right)=$ $O\left(d s^{2}+s^{2} r \log r\right)$ since the $r_{i}$ values are exponentially increasing in $i$, and so $r_{s}=O(r)$ for $r=\sum_{i=1}^{s} r_{i}$. The time to compute $M$ and $N$ is $n$ time longer.

We can compute the basis $U$ of $M$ in $O\left(n m^{2}\right)$ time, and the projection $U^{T} N$ in $O(n r m)$ time - this step is the post-sketch bottlneck. The basis $W$ takes $O\left(r m^{2}\right)$ time, and the final low rank basis $V=U W$ takes $O(n m k)$ time. Thus the total runtime is $O\left(n\left(d s^{2}+s^{2} r \log r\right)+\right.$ $\left.n m^{2}+n r m+r m^{2}+n m k\right)=O\left(n\left(d s^{2}+r m\right)\right)$ using that $r>m^{2}>k^{4}$ that $m>s^{2} \log r$, and assuming $n>r$. Now using $m=O\left(s^{2}\left(k^{2}+k / \varepsilon\right)\right)$ and $r=O\left(s m^{2} / \varepsilon^{2}\right)=O\left(s^{3}\left(k^{4}+k^{2} / \varepsilon^{2}\right) / \varepsilon^{2}\right)$ and we have a total time of $O\left(n d s^{2}+n s^{4}\left(k^{2}+\frac{k}{\varepsilon}\right)^{3} / \varepsilon^{2}\right)$.

