# Matchings, Critical Nodes, and Popular Solutions 

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#### Abstract

We consider a matching problem in a marriage instance $G$. Every node has a strict preference order ranking its neighbors. There is a set $C$ of prioritized or critical nodes and we are interested in only those matchings that match as many critical nodes as possible. Such matchings are useful in several applications and we call them critical matchings. A stable matching need not be critical. We consider a well-studied relaxation of stability called popularity. Our goal is to find a popular critical matching, i.e., a weak Condorcet winner within the set of critical matchings where nodes are voters. We show that popular critical matchings always exist in $G$ and min-size/max-size such matchings can be efficiently computed.


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## 1 Introduction

We consider a matching problem in a bipartite graph $G=(A \cup B, E)$ on $n$ nodes and $m$ edges where every node ranks its neighbors in a strict order of preference. Such a graph is also called a marriage instance. We seek an optimal matching in $G$ and the classical notion of optimality for matchings in such an instance is stability introduced by Gale and Shapley [9] in 1962. A matching $M$ is stable if there is no edge that blocks $M$ where an edge $(a, b)$ is said to block $M$ if $a$ and $b$ prefer each other to their respective assignments in $M$.

Stable matchings always exist in a marriage instance and the Gale-Shapley algorithm finds one in linear time. The Gale-Shapley algorithm and its many-to-one generalization have been used to match students to schools and colleges $[1,2,17]$ and graduating medical students to hospitals [4, 21]. All stable matchings in $G$ match the same set of nodes [10]. As discussed in [3], in the medical matching scheme in Scotland, a stable matching left several students unmatched. There was a matching that matched all the students, however this matching admitted some blocking edges. Thus there are real-world applications where the size of the matching is more important than the absence of blocking edges.

More generally, there are applications where certain nodes are prioritized or critical and the number of critical nodes that get matched is of primary importance. One such application is the assignment of sailors to billets in the US Navy [22, 26]. Here every sailor has to be matched to a billet and some critical billets cannot be left vacant. So such billets and all the sailors are the critical nodes here. Allocation problems in humanitarian organizations constitute more such applications, see e.g., [24, 25].

Motivated by such applications, we consider the following model where we are given a marriage instance $G=(A \cup B, E)$ along with a set $C \subseteq A \cup B$ of critical nodes. The number of critical nodes that get matched is the most important attribute of a matching. An admissible or critical matching is one that matches as many critical nodes as possible.

- Definition 1. A matching $M$ in $G$ is critical if there is no matching in $G$ that matches more critical nodes than $M$.

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A stable matching need not be critical. When stable matchings are not critical, a natural alternative is to seek a critical matching that admits the least number of blocking edges. However this is an NP-hard problem [3]. It was shown there that finding a maximum matching (so every node is critical here) that admits the minimum number of blocking edges is NP-hard; moreover, this is NP-hard to approximate within $n^{1-\varepsilon}$, for any $\varepsilon>0$. This motivates relaxing the problem of finding a critical matching with the least number of blocking edges to finding one that satisfies a more relaxed variant of stability. Popularity is a natural relaxation of stability that captures welfare in a collective sense.

We say node $v$ prefers matching $M$ to matching $N$ if $v$ prefers its partner in $M$ to its partner in $N$ and being left unmatched is the worst choice for any node. We can compare any pair of matchings $M$ and $N$ by holding an election between them where every node casts a vote for the matching in $\{M, N\}$ that it prefers and it abstains from voting if it is indifferent between $M$ and $N$. Let $\phi(M, N)$ (resp., $\phi(N, M)$ ) be the number of votes for $M$ (resp., $N$ ) in the $M$ versus $N$ election. Matching $N$ is more popular than matching $M$ if $\phi(N, M)>\phi(M, N)$.

- Definition 2. A matching $M$ is popular if $\Delta(N, M) \leq 0$ for all matchings $N$ in $G$, where $\Delta(N, M)=\phi(N, M)-\phi(M, N)$.

Thus a matching $M$ is popular if there is no matching that is more popular than $M$. The notion of popularity was introduced in 1975 by Gärdenfors [11] where he observed that every stable matching is popular. It is easy to decide if there is a popular matching that is also critical - it is known that any node that is matched in some popular matching has to be matched in any max-size popular matching [12]. A max-size popular matching can be computed in linear time [14]. However as was the case with stable matchings, it can be the case that no popular matching is critical. Consider the following example where $A=\left\{a_{0}, a_{1}, a_{2}\right\}$ and $B=\left\{b_{0}, b_{1}, b_{2}\right\}$. Node preferences are described below.

$$
\begin{array}{lll}
a_{0}: b_{1} & a_{1}: b_{1} \succ b_{2} \succ b_{0} & a_{2}: b_{1} \succ b_{2} \\
b_{0}: a_{1} & b_{1}: a_{1} \succ a_{2} \succ a_{0} & b_{2}: a_{1} \succ a_{2}
\end{array}
$$

The node $a_{0}$ has only one neighbor $b_{1}$. The node $a_{1}$ regards $b_{1}$ as its top choice, $b_{2}$ as its second choice, and $b_{0}$ as its third choice. The node $a_{2}$ regards $b_{1}$ as its top choice and $b_{2}$ as its second choice. The preferences of nodes in $B$ are symmetric to those in $A$.

The above instance has only one stable matching $S=\left\{\left(a_{1}, b_{1}\right),\left(a_{2}, b_{2}\right)\right\}$. This instance has one more popular matching $P=\left\{\left(a_{1}, b_{2}\right),\left(a_{2}, b_{1}\right)\right\}$. Suppose $C=\left\{a_{0}, a_{1}\right\}$ is the set of critical nodes. Then neither $S$ nor $P$ is critical. Here $M_{0}=\left\{\left(a_{0}, b_{1}\right),\left(a_{1}, b_{2}\right)\right\}, M_{1}=$ $\left\{\left(a_{0}, b_{1}\right),\left(a_{1}, b_{0}\right)\right\}$, and $M_{2}=\left\{\left(a_{0}, b_{1}\right),\left(a_{1}, b_{0}\right),\left(a_{2}, b_{2}\right)\right\}$ are the critical matchings. Thus there need not exist any popular matching that is critical.

A natural alternative is to ask for a critical matching $M$ such that there is no critical matching more popular than $M$. Given that the number of critical nodes that get matched is more important than node preferences, elections that involve non-critical matchings are not relevant since by the definition of our setting, any critical matching is better than any non-critical matching. So the desired matchings are the critical ones and any pair of critical matchings can be compared by holding an election between them. Thus we are only interested in elections between pairs of critical matchings.

- Definition 3. A critical matching $M$ is a popular critical matching in $G$ if $\Delta(N, M) \leq 0$ for any critical matching $N$.

A popular critical matching is a weak Condorcet winner $[5,18]$ in the voting instance where every critical matching is a candidate and nodes are voters. The relation "more popular than" is not transitive, i.e., there may be cycles with respect to this relation, so weak Condorcet winners need not exist in every voting instance. It might be the case that for any critical matching, there is a "more popular" critical matching. Interestingly, it was shown in [14] that popular maximum matchings (i.e., $C=A \cup B$ ) always exist in $G$. Does this positive result hold for every $C \subset A \cup B$ ? So the following questions are relevant:

- For any $C \subset A \cup B$, does a popular critical matching always exist in $G$ ?
- Is it easy to find one?
- Is it easy to find a max-size popular critical matching?

In this paper we show positive answers to all the above questions. Recall that $|E|=m$.

- Theorem 4. For any $C \subset A \cup B$, popular critical matchings always exist in $G=(A \cup B, E)$ and a max-size such matching can be computed in $O(|C| m+m)$ time.

We first show the following result. Then we extend this algorithm to show Theorem 4.

- Theorem 5. Given a marriage instance $G=(A \cup B, E)$ along with a subset $C$ of critical nodes, a min-size popular critical matching in $G$ can be computed in $O(|C| m+m)$ time.


### 1.1 Background and related results

Algorithmic questions in popular matchings have been well-studied during the last decade and we refer to [6] for a survey. Popular matchings always exist in a marriage instance and efficient algorithms are known to find min-size/max-size popular matchings in a marriage instance $[9,13,14]$. A size-popularity trade-off was shown in [14] to efficiently find matchings whose unpopularity is bounded from above and size is bounded from below. As shown there, this implies that a maximum matching that is popular within the set of maximum matchings always exists and can be efficiently computed. So $C=A \cup B$ in [14] while $C=\emptyset$ in the Gale-Shapley algorithm. Thus for the two extreme cases of $C$, it was known that popular critical matchings always exist and can be efficiently computed.

A related problem is the hospital-residents problem with lower quotas. This is a many-toone matching problem where every node has a strict preference order over its neighbors and every hospital has a capacity; moreover certain hospitals have lower quotas which denotes the minimum number of residents that have to be matched to this hospital in any feasible matching. It was shown in [19] that whenever feasible matchings exist, a matching that is popular among feasible matchings always exists and a max-size such matching can be computed in polynomial time. Very recently and independent of our work, the above result was generalized in [20] to the setting where certain residents are marked and every marked resident has to be matched in any feasible matching.

Hardness results for "almost stable" critical matchings. Several hardness results for finding almost stable maximum matchings (so every vertex is critical) in a marriage instance were shown in [3]. It was shown there that even if all preference lists were restricted to be of length at most 3 , finding a maximum matching that admits the minimum number of blocking edges is NP-hard. An alternative approach is to count the number of nodes that are involved in blocking edges [8, 23]. The problem of finding a maximum matching that minimizes this number is also NP-hard to compute/approximate, as shown in [3].

### 1.2 Techniques

We use the machinery of stable matchings and LP-duality to show our results. We construct a new marriage instance $G^{\prime}=\left(A^{\prime} \cup B^{\prime}, E^{\prime}\right)$ on $O(|C| n+n)$ nodes and $O(|C| m+m)$ edges such that any stable matching in $G^{\prime}$ corresponds to a popular critical matching in $G$. The instance $G^{\prime}$ resembles instances used in $[7,14,16]$ to compute max-size popular matchings and popular maximum matchings.

We now give a quick overview of the popular maximum matching algorithm from [14]. This algorithm partitions the node set $A \cup B$ into levels so that any stable matching in this "graph with levels" corresponds to a popular maximum matching in $G$. To begin with, all nodes are in some level $\ell$ and the Gale-Shapley algorithm is run on this instance. If the stable matching leaves some nodes in $A$ unmatched then all unmatched nodes in $A$ are promoted to level $\ell+1$. Once promoted to level $\ell+1$, each such node starts proposing all over again - it will be the case that every node in $B$ prefers higher level neighbors to lower level neighbors. So some of these promoted nodes may find partners.

This may "un-match" some nodes in $A$ initially matched in level $\ell$. These nodes continue proposing as per the Gale-Shapley algorithm and any node in $A$ that is unsuccessful in finding a partner in level $\ell$ gets promoted to level $\ell+1$. Any node in $A$ that does not find a partner even as a level $\ell+1$ node gets promoted to level $\ell+2$ and so on. It was shown in [14] that $|A|$ levels suffice to construct a maximum matching that is popular within the set of maximum matchings.

Our algorithms. If all the critical nodes are in $A$ then the above algorithm easily generalizes to solving the popular critical matching problem by promoting only critical nodes in $A$ to higher levels and non-critical nodes in $A$ will always remain in level $\ell$. However we need to deal with critical nodes in the set $B$ as well. For this, our new idea is the following: critical nodes in $B$ that are left unmatched in the Gale-Shapley algorithm in level $\ell$ get demoted to level $\ell-1$. It will be the case that every node in $A$ prefers lower level neighbors to higher level neighbors. So in fact, the Gale-Shapley algorithm should begin by nodes in $A$ proposing to lower level neighbors first (before the ones in level $\ell$ ).

Thus the main difference between our instance $G^{\prime}$ and the earlier instance from [14] (explicitly described in [16]) is that there is non-uniformity among the nodes now. All the nodes in $A \cup B$ are permitted in only one intermediate level, i.e., level $\ell$. Non-critical nodes in $A$ are excluded from levels higher than $\ell$ and non-critical nodes in $B$ are excluded from levels lower than $\ell$. We show that any stable matching in $G^{\prime}$ corresponds to a min-size popular critical matching in $G$. We construct another instance $G^{\prime \prime}$ such that the entire node set $A \cup B$ is permitted in two levels: level $\ell$ and level $\ell+1$. We show that any stable matching in $G^{\prime \prime}$ corresponds to a max-size popular critical matching in $G$. When $C=\emptyset$, the instance $G^{\prime \prime}$ is the same as the instance from [7] whose stable matchings correspond to max-size popular matchings in $G$.

Our proofs of correctness. We prove the correctness of our algorithms via the LP method by constructing witnesses that certify "popularity within the set of critical matchings" for our matchings. These witnesses are solutions to certain linear programs. Such witnesses are known for popular matchings [15] and popular maximum matchings [16]. Our witnesses are a little more complicated since our primal LP involves more constraints (due to criticality) and so the dual LP has more variables.

The dual LP solutions that we show (see Lemma 11 and Lemma 16) allow us to give simple proofs of correctness and enable us to show (using complementary slackness) that our two algorithms respectively compute min-size and max-size popular critical matchings in $G$.

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By contrast, the proof of correctness of the popular maximum matching algorithm in [14] was combinatorial; popular maximum matchings were characterized in terms of forbidden alternating paths and cycles and it was shown that there was no forbidden alternating path or cycle with respect to the matching returned.

Organization of the paper. Section 2 describes our witness for a popular critical matching. The min-size and max-size popular critical matching algorithms are given in Section 3 and Section 4, respectively.

## 2 A witness for a popular critical matching

Our input consists of a marriage instance $G=(A \cup B, E)$ with strict preferences and a set $C \subseteq A \cup B$ of critical nodes. We first characterize critical matchings.

- Lemma 6. A matching $M$ in $G$ is critical if and only if there is no alternating path $p$ with respect to $M$ that satisfies either of the conditions given below:

1. $p$ is an augmenting path with respect to $M$ and at least one endpoint of $p$ is in $C$.
2. $p$ has even length with exactly one endpoint in $C$ and this node is left unmatched in $M$.

Proof. Let $M$ be a matching with an alternating path $p$ such that either (i) $p$ is an augmenting path wrt $M$ and at least one endpoint of $p$ is in $C$ or (ii) $p$ has even length with exactly one endpoint in $C$ and this node is left unmatched in $M$. Then $M \oplus p$ matches at least one more critical node than $M$. Thus $M$ cannot be a critical matching.

Conversely, suppose $M$ is not a critical matching. Let $N$ be a critical matching. Consider $M \oplus N$. Since $N$ matches more critical nodes than $M$, there has to be an alternating path $p$ in $M \oplus N$ where $N$ matches more critical nodes than $M$. So $p$ has an endpoint in $C$ that is matched in $N$ and not in $M$. If the other endpoint of $p$ is unmatched in $M$ then $p$ is an augmenting path wrt $M$; else the other endpoint is matched in $M$ and this endpoint is not in $C$ since $N$ matches more critical nodes than $M$ in the alternating path $p$.

So either (i) $p$ is an augmenting path wrt $M$ and at least one endpoint of $p$ is in $C$ or (ii) $p$ has even length with exactly one endpoint in $C$, which is left unmatched in $M$.

Let $M$ be any critical matching in $G$. Let $k_{A}$ (resp., $k_{B}$ ) denote the number of nodes in $C_{A}=C \cap A$ (resp., $C_{B}=C \cap B$ ) that are matched in $M$. The following lemma will be very useful to us.

Lemma 7. Every matching in $G$ matches at most $k_{A}$ nodes in $C_{A}$ and at most $k_{B}$ nodes in $C_{B}$.

Proof. Suppose not. Let $N$ be a matching in $G$ that matches more than $k_{A}$ nodes in $C_{A}$. Then there is an alternating path $p$ in $M \oplus N$ where $N$ matches more nodes of $C_{A}$ than the critical matching $M$. If the length of $p$ is odd then $p$ is an augmenting path wrt $M$ whose at least one endpoint is in $C$. But this is a forbidden structure for any critical matching (by Lemma 6).

So the length of $p$ is even. Then the other endpoint of $p$ (the one matched in $M$ and unmatched in $N$ ) is in $A$, call this node $v$. Since $N$ matches more nodes of $C_{A}$ than $M$ in the path $p$, the node $v$ cannot be in $C_{A}$. Hence $p$ is an even length alternating path with exactly one endpoint in $C$ and this node is left unmatched in $M$. This is again a forbidden structure for any critical matching (by Lemma 6). Thus we get a contradiction. The proof when $N$ matches more than $k_{B}$ nodes in $C_{B}$ is analogous.

A linear program for popular critical matchings. It will be convenient to assume that each node considers itself as its last choice neighbor. Let $\tilde{G}$ denote the graph $G$ augmented with self-loops. Any matching $M$ in $G$ can be regarded as a perfect matching $\tilde{M}$ in $\tilde{G}$ by augmenting $M$ with appropriate self-loops. Corresponding to $M$, an edge weight function $\mathrm{wt}_{M}$ in the graph $\tilde{G}$ can be defined. Let $\mathrm{wt}_{M}(u, u)=0$ if $u$ is left unmatched in $M$, i.e., if $(u, u)$ is in $\tilde{M}$; else $\mathrm{wt}_{M}(u, u)=-1$. For any edge $(a, b) \in E$ :
let $\mathrm{wt}_{M}(a, b)= \begin{cases}2 & \text { if }(a, b) \text { blocks } M ; \\ -2 & \text { if both } a \text { and } b \text { prefer their respective partners in } M \text { to each other; } \\ 0 & \text { otherwise. }\end{cases}$
For any $e \in E$, note that $\mathrm{wt}_{M}(e)$ is the sum of votes of the endpoints of $e$ for each other versus their respective partners in $\tilde{M}$; each vote is in $\{ \pm 1,0\}$ where 1 is "more preferred to" and so on. For any node $u$, let $\delta(u)$ be the set of edges incident to $u$ in $G$.

Consider the following linear program (LP1). Note that Lemma 7 implies that all critical matchings in $G$ match $k_{A}$ nodes in $C_{A}$ and $k_{B}$ nodes in $C_{B}$. This is used in constraint (2).

$$
\begin{equation*}
\operatorname{maximize} \sum_{e \in \tilde{E}} \mathrm{wt}_{M}(e) \cdot x_{e} \tag{LP1}
\end{equation*}
$$

subject to

$$
\begin{align*}
& \sum_{e \in \delta(u) \cup\{u, u\}} x_{e}=1 \quad \forall u \in A \cup B  \tag{1}\\
& \sum_{a \in C_{A}} \sum_{e \in \delta(a)} x_{e}=k_{A} \quad \text { and } \quad \sum_{b \in C_{B}} \sum_{e \in \delta(b)} x_{e}=k_{B}  \tag{2}\\
& x_{e} \geq 0 \quad \forall e \in E \cup\{(u, u): u \in A \cup B\} . \tag{3}
\end{align*}
$$

We know from Lemma 7 that $\sum_{a \in C_{A}} \sum_{e \in \delta(a)} x_{e} \leq k_{A}$ and $\sum_{b \in C_{B}} \sum_{e \in \delta(b)} x_{e} \leq k_{B}$ are valid inequalities for the matching polytope of $\tilde{G}$. So the feasible region of (LP1) defines a face of the perfect matching polytope of $\tilde{G}$ and hence it is integral. Every integral point in this face corresponds to a critical matching and every critical matching (augmented with self-loops at unmatched nodes) belongs to this face. Thus (LP1) computes a max-weight matching $\tilde{N}$, where $N$ is a critical matching in $G$.

Consider the dual LP. This is (LP2) given below. The dual variables are $y_{u}$ for $u \in A \cup B$ along with $z_{A}$ and $z_{B}$.

$$
\begin{equation*}
\operatorname{minimize} \sum_{u \in A \cup B} y_{u}+\left(k_{A} \cdot z_{A}\right)+\left(k_{B} \cdot z_{B}\right) \tag{LP2}
\end{equation*}
$$

subject to

$$
\begin{align*}
y_{a}+y_{b} & \geq \operatorname{wt}_{M}(a, b)  \tag{4}\\
y_{a}+y_{b}+z_{A} & \geq \operatorname{wt}_{M}(a, b)  \tag{5}\\
y_{a}+y_{b}+z_{B} & \geq \operatorname{wt}_{M}(a, b) \quad \forall(a, b) \in E \text { where } a \in C_{A}, b \notin C_{B}  \tag{6}\\
y_{a}+y_{b}+z_{A}+z_{B} & \geq \operatorname{wt}_{M}(a, b) \quad \forall(a, b) \in E \text { where } a \notin C_{A}, b \in C_{B}  \tag{7}\\
y_{u} & \geq \operatorname{wt}_{M}(u, u) \quad \forall u \in A \cup B . \tag{8}
\end{align*}
$$

Proposition 8. Let $M$ be a critical matching such that the optimal value of (LP2) is at most 0 . Then $M$ is a popular critical matching.

Proof. The optimal value of (LP1) is $\max _{N} \mathrm{wt}_{M}(\tilde{N})$, where $N$ is a critical matching in $G$. It follows from the definition of the function $\mathrm{wt}_{M}$ that $\mathrm{wt}_{M}(\tilde{N})=\phi(N, M)-\phi(M, N)=$ $\Delta(N, M)$ for any matching $N$ in $G$. Thus the optimal value of (LP1) is $\max _{N} \Delta(N, M)$, where $N$ is a critical matching. If the optimal value of (LP2) is at most 0 then the optimal value of (LP1) is also at most 0 (by weak duality). This means $\Delta(N, M) \leq 0$ for every critical matching $N$.

We will use Proposition 8 to prove the correctness of our algorithms in Section 3 and Section 4. That is, we will construct matchings $M$ such that there exist feasible solutions $(\vec{y}, \vec{z})$ to (LP2) with $\sum_{u \in A \cup B} y_{u}+\left(k_{A} \cdot z_{A}\right)+\left(k_{B} \cdot z_{B}\right)=0$.

## 3 An algorithm for a popular critical matching

Let $G=(A \cup B, E)$ be the given marriage instance and let $C \subseteq A \cup B$ be the set of critical nodes. Recall the overview of our algorithm given in Section 1.2. We want to partition the node set $A \cup B$ into levels so that any stable matching in this new graph corresponds to a popular critical matching in $G$.

Recall that we use $C_{A}=C \cap A$ (resp., $C_{B}=C \cap B$ ) to denote the set of critical nodes in $A$ (resp., $B$ ). Let $\left|C_{A}\right|=\alpha$ and $\left|C_{B}\right|=\beta$. There will be $\alpha+\beta+1$ levels indexed $0, \ldots, \alpha+\beta$.

A new instance $\boldsymbol{G}^{\prime}=\left(\boldsymbol{A}^{\prime} \cup \boldsymbol{B}^{\prime}, \boldsymbol{E}^{\prime}\right)$. We now describe a new instance $G^{\prime}$ whose stable matchings will map to popular critical matchings in $G$. The set $A^{\prime}$ is described below.

- For every $a \in C_{A}$, the set $A^{\prime}$ has $\alpha+\beta+1$ copies of $a$ : call these nodes $a_{0}, a_{1}, \ldots, a_{\alpha+\beta}$.
- For every $a \in A \backslash C_{A}$, the set $A^{\prime}$ has $\beta+1$ copies of $a$ : call these nodes $a_{0}, a_{1}, \ldots, a_{\beta}$.

Thus $A^{\prime}=\cup_{a \in C_{A}}\left\{a_{0}, a_{1}, \ldots, a_{\alpha+\beta}\right\} \cup_{a \in A \backslash C_{A}}\left\{a_{0}, a_{1}, \ldots, a_{\beta}\right\}$. Define the set $B^{\prime}$ as follows. $B^{\prime}=\left\{b^{\prime}: b \in B\right\} \cup_{a \in C_{A}}\left\{d_{1}(a), \ldots, d_{\alpha+\beta}(a)\right\} \cup_{a \in A \backslash C_{A}}\left\{d_{1}(a), \ldots, d_{\beta}(a)\right\}$.

The set $\left\{b^{\prime}: b \in B\right\}$ is a copy of the set $B$. Along with nodes in $\left\{b^{\prime}: b \in B\right\}$, the set $B^{\prime}$ contains dummy nodes (the $d$-nodes). Such dummy nodes were first used in [7] and they make it easy for us to describe "promotions" from one level to another.

When $a \in C_{A}$, there are $\alpha+\beta+1$ copies of $a$ in $A^{\prime}$ and the set $B^{\prime}$ has $d_{1}(a), \ldots, d_{\alpha+\beta}(a)$. We will set preferences such that in any stable matching in $G^{\prime}, \alpha+\beta$ copies of $a$ have to be matched to these dummy nodes. Similarly, when $a \in A \backslash C_{A}$, there are $\beta+1$ copies of $a$ in $A^{\prime}$ and the set $B^{\prime}$ has $d_{1}(a), \ldots, d_{\beta}(a)$. We will set preferences such that in any stable matching in $G^{\prime}, \beta$ copies of $a$ have to be matched to these dummy nodes. Thus in any stable matching in $G^{\prime}$, for each $a \in A$, at most one node among all $a_{i}$ 's is "free" to be matched to a neighbor in $\left\{b^{\prime}: b \in B\right\}$.

The edge set. Corresponding to each $(a, b) \in E$, we will have the following edges in $E^{\prime}$. There are four cases here depending on whether $a$ is in $C_{A}$ or not and $b$ is in $C_{B}$ or not.

1. $a \notin C_{A}$ and $b \notin C_{B}$ : there is exactly one edge $\left(a_{\beta}, b^{\prime}\right)$ in $E^{\prime}$ that corresponds to $(a, b)$.
2. $a \notin C_{A}$ and $b \in C_{B}$ : there are $\beta+1$ edges $\left(a_{i}, b^{\prime}\right)$ in $E^{\prime}$ where $0 \leq i \leq \beta$.
3. $a \in C_{A}$ and $b \notin C_{B}$ : there are $\alpha+1$ edges $\left(a_{i}, b^{\prime}\right)$ in $E^{\prime}$ where $\beta \leq i \leq \alpha+\beta$.
4. $a \in C_{A}$ and $b \in C_{B}$ : there are $\alpha+\beta+1$ edges $\left(a_{i}, b^{\prime}\right)$ in $E^{\prime}$ where $0 \leq i \leq \alpha+\beta$.

For each $a \in A$, the set $E^{\prime}$ also has the following edges:

- if $a \in C_{A}$ then $\left(a_{i-1}, d_{i}(a)\right)$ and $\left(a_{i}, d_{i}(a)\right)$ for $1 \leq i \leq \alpha+\beta$;
- if $a \in A \backslash C_{A}$ then $\left(a_{i-1}, d_{i}(a)\right)$ and $\left(a_{i}, d_{i}(a)\right)$ for $1 \leq i \leq \beta$.

For any $i$, the preference order of $d_{i}(a)$ is $a_{i-1} \succ a_{i}$.

Preference orders. Consider $a \in A$. Let $a$ 's preference order in $G$ be $b_{1} \succ \cdots \succ b_{k}$. Suppose $\left\{c_{1}, \ldots, c_{r}\right\}=\left\{b_{1}, \ldots, b_{k}\right\} \cap C$. That is, $c_{1}, \ldots, c_{r}$ are $a$ 's critical neighbors. Let $a$ 's preference order among these nodes be $c_{1} \succ \cdots \succ c_{r}$.

- $a_{0}$ 's preference order in $G^{\prime}$ is $c_{1}^{\prime} \succ \cdots \succ c_{r}^{\prime} \succ d_{1}(a)$.
- For $1 \leq i \leq \beta-1, a_{i}$ 's preference order is $d_{i}(a) \succ c_{1}^{\prime} \succ \cdots \succ c_{r}^{\prime} \succ d_{i+1}(a)$.
- For $a \notin C_{A}$ : the preference order of $a_{\beta}$ is $d_{\beta}(a) \succ b_{1}^{\prime} \succ \cdots \succ b_{k}^{\prime}$.
- For $a \in C_{A}$ :
= for $\beta \leq i \leq \alpha+\beta-1$, the preference order of $a_{i}$ is $d_{i}(a) \succ b_{1}^{\prime} \succ \cdots \succ b_{k}^{\prime} \succ d_{i+1}(a)$.
= the preference order of $a_{\alpha+\beta}$ is $d_{\alpha+\beta}(a) \succ b_{1}^{\prime} \succ \cdots \succ b_{k}^{\prime}$.
For $a \in A$, other than the dummy nodes, observe that it is only copies of critical neighbors that are present in the preference list of $a_{i}$ for $0 \leq i \leq \beta-1$.

For $a \notin C_{A}$, observe that copies of all neighbors of $a$, i.e., $b_{1}^{\prime}, \ldots, b_{k}^{\prime}$, are present only in the preference list of $a_{\beta}$. For $a \in C_{A}$, copies of all neighbors of $a_{i}$ are present in the preference list of $a_{i}$ for $\beta \leq i \leq \alpha+\beta$.

Consider any $b \in B$. Let $b$ 's preference order in $G$ be $a \succ \cdots \succ z$. Let $\left\{a^{\prime}, \ldots, z^{\prime}\right\}=$ $\{a, \ldots, z\} \cap C$. Let $b$ 's preference order among its critical neighbors be $a^{\prime} \succ \cdots \succ z^{\prime}$. Suppose $b \notin C_{B}$. Then the preference order of $b^{\prime}$ in $G^{\prime}$ is:

$$
\underbrace{a_{\alpha+\beta}^{\prime} \succ \cdots \succ z_{\alpha+\beta}^{\prime}}_{\text {level } \alpha+\beta \text { neighbors }} \succ \cdots \succ \underbrace{a_{\beta+1}^{\prime} \succ \cdots \succ z_{\beta+1}^{\prime}}_{\text {level } \beta+1 \text { neighbors }} \succ \underbrace{a_{\beta} \succ \cdots \succ z_{\beta}}_{\text {level } \beta \text { neighbors }}
$$

So $b^{\prime}$ prefers any subscript or level $i$ neighbor to any level $j$ neighbor for $i>j$. Note that copies of only critical neighbors are present in level $i$ for $\beta+1 \leq i \leq \alpha+\beta$ and copies of all neighbors of $b$, i.e., $a, \ldots, z$, are present only in level $\beta$.

Suppose $b \in C_{B}$. Then the preference order of $b^{\prime}$ in $G^{\prime}$ is:

$$
\underbrace{a_{\alpha+\beta}^{\prime} \succ \cdots \succ z_{\alpha+\beta}^{\prime}}_{\text {level } \alpha+\beta \text { neighbors }} \succ \cdots \succ \underbrace{a_{\beta+1}^{\prime} \succ \cdots \succ z_{\beta+1}^{\prime}}_{\text {level } \beta+1 \text { neighbors }} \succ \underbrace{a_{\beta} \succ \cdots \succ z_{\beta}}_{\text {level } \beta \text { neighbors }} \succ \cdots \succ \underbrace{a_{0} \succ \cdots \succ z_{0}}_{\text {level } 0 \text { neighbors }}
$$

Note that copies of only critical neighbors are present in level $i$ for $\beta+1 \leq i \leq \alpha+\beta$ and copies of all neighbors of $b$ are present in level $i$ for $0 \leq i \leq \beta$.

The matching $M$. For any stable matching $M^{\prime}$ in $G^{\prime}$, define $M \subseteq E$ to be the set of edges obtained by deleting edges in $M^{\prime}$ that are incident to dummy nodes and replacing any edge $\left(a_{i}, b^{\prime}\right) \in M^{\prime}$ with the original edge $(a, b) \in E$.

For any $a \in A$ and all $i \geq 1$, the dummy node $d_{i}(a)$ is the top choice neighbor for $a_{i}$, hence the stable matching $M^{\prime}$ has to match all dummy nodes. Thus at most one node among all the $a_{i}$ 's can be matched in $M^{\prime}$ to a neighbor in $\left\{b^{\prime}: b \in B\right\}$. So $M$ is a matching in $G$. Theorem 9 (proved below) is our main theorem in this section.

- Theorem 9. For any stable matching $M^{\prime}$ in $G^{\prime}$, the corresponding matching $M$ is a min-size popular critical matching in $G$.

Since a stable matching always exists in $G^{\prime}$, popular critical matchings always exist in $G$. Thus the first part of Theorem 4 follows. The time taken to construct $G^{\prime}$ and to compute a stable matching in $G^{\prime}$ is $O(|C| m+m)$. Thus Theorem 5 follows from Theorem 9.

We will prove Theorem 9 now. As done in [14], it will be useful to partition the set $A \cup B$ into subsets as described below (see Fig. 1). We will partition the set of all nodes in $A$ that are matched in $M$ into $A_{0} \cup \cdots \cup A_{\alpha+\beta}$ where for $0 \leq i \leq \alpha+\beta: A_{i}=\left\{a \in A:\left(a_{i}, b^{\prime}\right) \in M^{\prime}\right.$

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for some $b \in B\}$, i.e., $A_{i}$ is the collection of those $a$ 's such that $a_{i}$ is matched in $M^{\prime}$ to a neighbor in $\left\{b^{\prime}: b \in B\right\}$. Add unmatched nodes in $C_{A}$ to $A_{\alpha+\beta}$ and add unmatched nodes in $A \backslash C_{A}$ to $A_{\beta}$.

Similarly, partition the set of all nodes in $B$ that are matched in $M$ into $B_{0} \cup \cdots \cup B_{\alpha+\beta}$ where for $0 \leq i \leq \alpha+\beta$ : $B_{i}=\left\{b:\left(a_{i}, b^{\prime}\right) \in M^{\prime}\right.$ for some $\left.a \in A_{i}\right\}$, i.e., $B_{i}$ is the collection of those $b^{\prime}$ 's such that the partner of $b^{\prime}$ in $M^{\prime}$ is a subscript $i$ node. Add unmatched nodes in $C_{B}$ to $B_{0}$ and add unmatched nodes in $B \backslash C_{B}$ to $B_{\beta}$.


Figure $1 A=A_{0} \cup \cdots \cup A_{\alpha+\beta}$ and $B=B_{0} \cup \cdots \cup B_{\alpha+\beta}$ and $M \subseteq \cup_{i=0}^{\alpha+\beta}\left(A_{i} \times B_{i}\right)$. Red nodes are outside $C$ and green nodes are in $C$. All red (i.e., non-critical) nodes are in $\cup_{i \leq \beta} A_{i} \cup_{i \geq \beta} B_{i}$ and unmatched red nodes are in $A_{\beta} \cup B_{\beta}$.

Lemma 10. $M$ is a critical matching in $G$.
The proof of Lemma 10 (given in the appendix) uses Lemma 6 and is similar to the proof that the popular maximum matching algorithm in [14] finds a maximum matching. Lemma 11 is the main technical result here.

- Lemma 11. $M$ is a popular critical matching in $G$.

Proof. We will use Proposition 8. Let $(\vec{y}, \vec{z})$ be defined as follows.

1. Set $z_{A}=-2 \alpha$ and $z_{B}=-2 \beta$.
2. Set $y_{u}=0$ for all unmatched nodes $u$. For matched nodes $u$, we will set $y$-values as follows. For $0 \leq i \leq \alpha+\beta$ do:

- for $a \in A_{i}$ : if $a \in C_{A}$ then set $y_{a}=2 \alpha+2 \beta-2 i$; else set $y_{a}=2 \beta-2 i$.
= for $b \in B_{i}$ : if $b \in C_{B}$ then set $y_{b}=2 i$; else set $y_{b}=2 i-2 \beta$.
Lemma 12. $\langle\vec{y}, \vec{z}\rangle$ defined above is a feasible solution to (LP2).

The proof of Lemma 12 is given below (after the proof of Lemma 11). We will now show that $\sum_{u \in A \cup B} y_{u}+\left(k_{A} \cdot z_{A}\right)+\left(k_{B} \cdot z_{B}\right)=0$. Consider any edge $(a, b) \in M$. So there is some $i \in\{0, \ldots, \alpha+\beta\}$ such that $a \in A_{i}$ and $b \in B_{i}$.

1. If $a \notin C_{A}$ and $b \notin C_{B}$ then $y_{a}+y_{b}=(2 \beta-2 i)+(2 i-2 \beta)=0$.
2. If $a \in C_{A}$ and $b \notin C_{B}$ then $y_{a}+y_{b}+z_{A}=(2 \alpha+2 \beta-2 i)+(2 i-2 \beta)-2 \alpha=0$.
3. If $a \notin C_{A}$ and $b \in C_{B}$ then $y_{a}+y_{b}+z_{B}=(2 \beta-2 i)+2 i-2 \beta=0$.
4. If $a \in C_{A}$ and $b \in C_{B}$ then $y_{a}+y_{b}+z_{A}+z_{B}=(2 \alpha+2 \beta-2 i)+2 i-2 \alpha-2 \beta=0$.

Recall that $k_{A}$ (resp., $k_{B}$ ) is the number of nodes from $C_{A}$ (resp., $C_{B}$ ) that get matched in any critical matching. Since $M$ is a critical matching (by Lemma 10), it matches $k_{A}$ nodes from $C_{A}$ and $k_{B}$ nodes from $C_{B}$. So added up over all edges $(a, b)$ in $M$, the left hand sides of the four equations above sum to $\sum_{u \in V} y_{u}+\left(k_{A} \cdot z_{A}\right)+\left(k_{B} \cdot z_{B}\right)$, where $V \subseteq A \cup B$ is the set of nodes matched in $M$. Since all the right hand sides are 0 , this sum is 0 . For any unmatched node $u$, we set $y_{u}=0$. So $\sum_{u \in A \cup B} y_{u}+\left(k_{A} \cdot z_{A}\right)+\left(k_{B} \cdot z_{B}\right)=0$. Hence $M$ is a popular critical matching in $G$ (by Proposition 8).

Proof of Lemma 12. For any node $u$, we claim that $y_{u} \geq 0$. Recall that $y_{a}=2 \alpha+2 \beta-2 i$ for a matched critical node $a \in A_{i}$ and $y_{b}=2 i$ for a matched critical node $b \in B_{i}$. Since $0 \leq i \leq \alpha+\beta$, we have $2 \alpha+2 \beta-2 i \geq 0$ and $2 i \geq 0$. Thus for any matched node $u \in C$, $y_{u} \geq 0$.

For any matched node $a \in A \backslash C_{A}$, observe that $a \in A_{i}$ for some $i \leq \beta$, so $2 \beta-2 i \geq 0$. For any matched node $b \in B \backslash C_{B}$, observe that $b \in B_{i}$ for some $i \geq \beta$, so $2 i-2 \beta \geq 0$. We set $y_{u}=0$ for any unmatched node $u$. Hence $y_{u} \geq 0 \geq \mathrm{wt}_{M}(u, u)$ for all $u \in A \cup B$. Thus constraint (8) holds.

We will now show that $\langle\vec{y}, \vec{z}\rangle$ satisfies constraints (4)-(7). For any $a \in C_{A}$, let $y_{a}^{\prime}=y_{a}+z_{A}$. For any $b \in C_{B}$, let $y_{b}^{\prime}=y_{b}+z_{B}$. For any node $u \notin C$, let $y_{u}^{\prime}=y_{u}$.

- We have $y_{a}^{\prime}=2 \beta-2 i$ for any matched $a \in A_{i}$ and $y_{b}^{\prime}=2 i-2 \beta$ for any matched $b \in B_{i}$.
- For any unmatched $a \in A: y_{a}^{\prime}=-2 \alpha$ if $a \in C_{A}$ and $y_{a}^{\prime}=0$ otherwise.
- For any unmatched $b \in B: y_{b}^{\prime}=-2 \beta$ if $b \in C_{B}$ and $y_{b}^{\prime}=0$ otherwise.

We will now show that $y_{a}^{\prime}+y_{b}^{\prime} \geq \mathrm{wt}_{M}(a, b)$ for all $(a, b) \in E$. Let $a \in A_{i}$ and $b \in B_{j}$. This proof is split into 4 parts: (1) $i \leq j-1$, (2) $i=j$, (3) $i=j+1$, and (4) $i \geq j+2$.

1. Consider any edge $(a, b)$ where $a \in A_{i}, b \in B_{j}$ and $i \leq j-1$.

- If $a$ and $b$ are matched nodes then $y_{a}^{\prime}+y_{b}^{\prime}=(2 \beta-2 i)+(2 j-2 \beta)=2(j-i) \geq 2 \geq$ $\mathrm{wt}_{M}(a, b)$ since $\mathrm{wt}_{M}(e) \in\{ \pm 2,0\}$ for all $e \in E$.
- Suppose $a$ is unmatched. Then $a \notin C_{A}$; otherwise $i=\alpha+\beta$ and so $j \geq \alpha+\beta+1$ which is not possible. So $a \notin C_{A}$ and we have $y_{a}^{\prime}=0$ and $i=\beta$. Since $j \geq \beta+1$, we have $y_{b}^{\prime}=2 j-2 \beta \geq 2$. Thus $y_{a}^{\prime}+y_{b}^{\prime} \geq 2 \geq \mathrm{wt}_{M}(a, b)$.
- Suppose $b$ is unmatched. Then $b \notin C_{B}$; otherwise $j=0$ and so $i \leq-1$ which is not possible. So $b \notin C_{B}$ and we have $y_{b}^{\prime}=0$ and $j=\beta$. Since $i \leq \beta-1$, we have $y_{a}^{\prime}=2 \beta-2 i \geq 2$. Thus $y_{a}^{\prime}+y_{b}^{\prime} \geq 2 \geq \mathrm{wt}_{M}(a, b)$.

2. Let $a \in A_{i}, b \in B_{j}$ where $i=j$. For any $b \in B$, within subscript $i$ neighbors, the preference order of $b^{\prime}$ in $G^{\prime}$ is the same as $b$ 's preference order among these neighbors in
$G$. Thus $M$ restricted to $A_{i} \cup B_{i}$ is stable and so $\mathrm{wt}_{M}(a, b) \in\{-2,0\}$.

- If $a$ and $b$ are matched nodes then $y_{a}^{\prime}+y_{b}^{\prime}=(2 \beta-2 i)+(2 i-2 \beta)=0$.
- Suppose $a$ is unmatched.
= If $a \in C_{A}$ then $y_{a}^{\prime}=-2 \alpha$ and $i=\alpha+\beta$. So $y_{b}^{\prime}=2(\alpha+\beta)-2 \beta=2 \alpha$. Thus $y_{a}^{\prime}+y_{b}^{\prime}=-2 \alpha+2 \alpha=0$.
= If $a \notin C_{A}$ then $y_{a}^{\prime}=0$ and $i=\beta$. The node $b$ has to be matched since $M^{\prime}$ is stable (and thus maximal) in $G^{\prime}$. So $y_{b}^{\prime}=2 i-2 \beta=0$. Thus $y_{a}^{\prime}+y_{b}^{\prime}=0$.
- Suppose $b$ is unmatched.
- If $b \in C_{B}$ then $y_{b}^{\prime}=-2 \beta$ and $i=0$. So $y_{a}^{\prime}=2 \beta-2 i=2 \beta$. Thus $y_{a}^{\prime}+y_{b}^{\prime}=$ $2 \beta-2 \beta=0$.
- If $b \notin C_{B}$ then $y_{b}^{\prime}=0$ and $i=\beta$. The node $a$ has to be matched since $M^{\prime}$ is stable (and thus maximal) in $G^{\prime}$. So $y_{a}^{\prime}=2 \beta-2 i=0$. Thus $y_{a}^{\prime}+y_{b}^{\prime}=0$.
Thus we have $y_{a}^{\prime}+y_{b}^{\prime}=0 \geq \mathrm{wt}_{M}(a, b)$ in all the cases.

3. Let $a \in A_{i}, b \in B_{j}$ where $i=j+1$. Observe that $\left(a_{j}, d_{j+1}(a)\right) \in M^{\prime}$, i.e., $a_{j}$ is matched to its least preferred neighbor $d_{j+1}(a)$. The stability of $M^{\prime}$ implies that $\left(u_{j}, b^{\prime}\right) \in M^{\prime}$ for some neighbor $u_{j}$ that $b^{\prime}$ prefers to $a_{j}$. Also $b^{\prime}$ prefers $a_{j+1}$ to $u_{j}$, so $a_{j+1}$ has to prefer $M^{\prime}\left(a_{j+1}\right)$ to $b^{\prime}$. Hence both $a$ and $b$ are matched in $M$ to neighbors that they prefer to each other. So wt $M_{M}(a, b)=-2$. Thus $y_{a}^{\prime}+y_{b}^{\prime}=(2 \beta-2(j+1))+(2 j-2 \beta)=-2=\mathrm{wt}_{M}(a, b)$.
4. If $a \in A_{i}, b \in B_{j}$ where $i \geq j+2$ then $\left(a_{j+1}, d_{j+2}(a)\right) \in M^{\prime}$, i.e., $a_{j+1}$ is matched to its least preferred neighbor $d_{j+2}(a)$. This means the edge $\left(a_{j+1}, b^{\prime}\right)$ blocks $M^{\prime}$ - this is because $b^{\prime}$ prefers $a_{j+1}$ to its assignment in $M^{\prime}$ : this is either a subscript $j$ neighbor or $b^{\prime}$ is left unmatched in $M^{\prime}$. Since the blocking edge ( $a_{j+1}, b^{\prime}$ ) contradicts $M^{\prime}$ 's stability, there is no $(a, b) \in E$ where $a \in A_{i}, b \in B_{j}$ and $i \geq j+2$.
Thus we have $y_{a}^{\prime}+y_{b}^{\prime} \geq \mathrm{wt}_{M}(a, b)$ for all $(a, b) \in E$. This completes the proof of Lemma 12.

Min-size popular critical matching. Lemma 12 showed that $(\vec{y}, \vec{z})$ is a feasible solution to (LP2). In fact, ( $\vec{y}, \vec{z})$ is an optimal solution to (LP2) since $\tilde{M}$ is a feasible solution to (LP1) and $\operatorname{wt}_{M}(\tilde{M})=0=\sum_{u \in A \cup B} y_{u}+\left(k_{A} \cdot z_{A}\right)+\left(k_{B} \cdot z_{B}\right)$. This will be useful in Lemma 13.

- Lemma 13. $M$ is a min-size popular critical matching in $G$.

Proof. Let $N$ be a critical matching of size smaller than $|M|$. Then there is some node $u$ that is matched in $M$ but unmatched in $N$. So the self-loop $(u, u)$ is in the perfect matching $\tilde{N}$. For any node $u$ matched in $M$, we have $y_{u}>\operatorname{wt}_{M}(u, u)$. This is because $y_{u} \geq 0$ while $\mathrm{wt}_{M}(u, u)=-1$. So the self-loop $(u, u)$ is slack with respect to the dual optimal solution $(\vec{y}, \vec{z})$. Then complementary slackness implies that $\tilde{N}$ cannot be a primal optimal solution. The optimal value of (LP1) is 0 , so this means $\mathrm{wt}_{M}(\tilde{N})<0$, i.e., $\Delta(N, M)<0$. Hence the critical matching $M$ is more popular than $N$. Thus $N$ cannot be a popular critical matching. So $M$ is a min-size popular critical matching in $G$.

## 4 Finding a max-size popular critical matching

In this section we consider the problem of finding a max-size popular critical matching in $G=(A \cup B, E)$ where $C \subseteq A \cup B$ is the given critical set. We will construct a new instance $G^{\prime \prime}=\left(A^{\prime \prime} \cup B^{\prime \prime}, E^{\prime \prime}\right)$ which will be a minor variant of the instance $G^{\prime}$ seen in Section 3. The instance $G^{\prime}$ was motivated by considering that we ran the Gale-Shapley algorithm with all nodes in level $\ell$ (note that $\ell=\beta$ ) and promoted unmatched critical nodes in $A$ to higher levels and demoted unmatched critical nodes in $B$ to lower levels.

The instance $G^{\prime \prime}$ can be motivated by considering that we will run the max-size popular matching algorithm [14] (also called the 2-level Gale-Shapley algorithm) with all the nodes in level $\beta$. This promotes certain nodes to level $\beta+1$; all unmatched nodes in $A$ are in level $\beta+1$ and all unmatched nodes in $B$ are in level $\beta$. Now let us promote unmatched critical nodes in $A$ to higher levels and demote unmatched critical nodes in $B$ downwards.

The instance $G^{\prime \prime}$. The instance $G^{\prime \prime}=\left(A^{\prime \prime} \cup B^{\prime \prime}, E^{\prime \prime}\right)$ has one extra level compared to $G^{\prime}$. - For every $a \in C_{A}$, the set $A^{\prime \prime}$ has $\alpha+\beta+2$ copies of $a$ : call them $a_{0}, a_{1}, \ldots, a_{\alpha+\beta+1}$.

- For every $a \in A \backslash C_{A}$, the set $A^{\prime \prime}$ has $\beta+2$ copies of $a$ : call them $a_{0}, a_{1}, \ldots, a_{\beta+1}$.

So $A^{\prime \prime}=\cup_{a \in C_{A}}\left\{a_{0}, a_{1}, \ldots, a_{\alpha+\beta+1}\right\} \cup_{a \in A \backslash C_{A}}\left\{a_{0}, a_{1}, \ldots, a_{\beta+1}\right\}$. The set $B^{\prime \prime}$ is defined as follows. $B^{\prime \prime}=\left\{b^{\prime}: b \in B\right\} \cup_{a \in C_{A}}\left\{d_{1}(a), \ldots, d_{\alpha+\beta+1}(a)\right\} \cup_{a \in A \backslash C_{A}}\left\{d_{1}(a), \ldots, d_{\beta+1}(a)\right\}$.

As before, $\left\{b^{\prime}: b \in B\right\}$ is a copy of the set $B$; along with nodes in $\left\{b^{\prime}: b \in B\right\}$, the set $B^{\prime \prime}$ contains $\alpha+\beta+1$ dummy nodes $d_{1}(a), \ldots, d_{\alpha+\beta+1}(a)$ for $a \in C_{A}$ and $\beta+1$ dummy nodes $d_{1}(a), \ldots, d_{\beta+1}(a)$ for $a \in A \backslash C_{A}$.

The edge set. Corresponding to each $(a, b) \in E$, we have the following edges in $E^{\prime \prime}$. As before, there are four cases depending on whether $a$ (similarly, $b$ ) is critical or not.

1. $a \notin C_{A}$ and $b \notin C_{B}$ : there are two edges $\left(a_{\beta}, b^{\prime}\right)$ and $\left(a_{\beta+1}, b^{\prime}\right)$ that correspond to $(a, b)$.
2. $a \notin C_{A}$ and $b \in C_{B}$ : there are $\beta+2$ edges $\left(a_{i}, b^{\prime}\right)$ where $0 \leq i \leq \beta+1$.
3. $a \in C_{A}$ and $b \notin C_{B}$ : there are $\alpha+2$ edges $\left(a_{i}, b^{\prime}\right)$ where $\beta \leq i \leq \alpha+\beta+1$.
4. $a \in C_{A}$ and $b \in C_{B}$ : there are $\alpha+\beta+2$ edges $\left(a_{i}, b^{\prime}\right)$ where $0 \leq i \leq \alpha+\beta+1$.

For $a \in A \backslash C_{A}$, the set $E^{\prime \prime}$ has the edges $\left(a_{i-1}, d_{i}(a)\right)$ and $\left(a_{i}, d_{i}(a)\right)$ where $1 \leq i \leq \beta+1$. For $a \in C_{A}$, the set $E^{\prime \prime}$ has the edges $\left(a_{i-1}, d_{i}(a)\right)$ and $\left(a_{i}, d_{i}(a)\right)$ where $1 \leq i \leq \alpha+\beta+1$. For any $i \geq 1$, the preference order of $d_{i}(a)$ is $a_{i-1} \succ a_{i}$.

Preference orders. Let $a$ 's preference order in $G$ be $b_{1} \succ \cdots \succ b_{k}$. Let $\left\{c_{1}, \ldots, c_{r}\right\}=$ $\left\{b_{1}, \ldots, b_{k}\right\} \cap C$. That is, $c_{1}, \ldots, c_{r}$ are $a$ 's critical neighbors. It will be the case that only these nodes can be neighbors of $a_{0}, \ldots, a_{\beta-1}$. Let $a$ 's preference order among these nodes be $c_{1} \succ \cdots \succ c_{r}$.

- $a_{0}$ 's preference order is $c_{1}^{\prime} \succ \cdots \succ c_{r}^{\prime} \succ d_{1}(a)$.
- For $1 \leq i \leq \beta-1$, the preference order of $a_{i}$ is $d_{i}(a) \succ c_{1}^{\prime} \succ \cdots \succ c_{r}^{\prime} \succ d_{i+1}(a)$.
- For $a \notin C_{A}$ :
- the preference order of $a_{\beta}$ is $d_{\beta}(a) \succ b_{1}^{\prime} \succ \cdots \succ b_{k}^{\prime} \succ d_{\beta+1}(a)$;
- the preference order of $a_{\beta+1}$ is $d_{\beta+1}(a) \succ b_{1}^{\prime} \succ \cdots \succ b_{k}^{\prime}$.
- For $a \in C_{A}$ :
- for $\beta \leq i \leq \alpha+\beta$, the preference order of $a_{i}$ is $d_{i}(a) \succ b_{1}^{\prime} \succ \cdots \succ b_{k}^{\prime} \succ d_{i+1}(a)$;
= the preference order of $a_{\alpha+\beta+1}$ is $d_{\alpha+\beta+1}(a) \succ b_{1}^{\prime} \succ \cdots \succ b_{k}^{\prime}$.
Consider any $b \in B$. Let its preference order in $G$ be $a \succ \cdots \succ z$. Let $b$ 's critical neighbors be $a^{\prime}, \ldots, z^{\prime}$ and let $b$ 's preference order among them be $a^{\prime} \succ \cdots \succ z^{\prime}$.

Suppose $b \notin C_{B}$. Then the preference order of $b^{\prime}$ is

$$
\underbrace{a_{\alpha+\beta+1}^{\prime} \succ \cdots \succ z_{\alpha+\beta+1}^{\prime}}_{\text {level } \alpha+\beta+1 \text { neighbors }} \succ \cdots \succ \underbrace{a_{\beta+2}^{\prime} \succ \cdots \succ z_{\beta+2}^{\prime}}_{\text {level } \beta+2 \text { neighbors }} \succ \underbrace{a_{\beta+1} \succ \cdots \succ z_{\beta+1}}_{\text {level } \beta+1 \text { neighbors }} \succ \underbrace{a_{\beta} \succ \cdots \succ z_{\beta}}_{\text {level } \beta \text { neighbors }}
$$

Note that copies of only critical neighbors are present in level $i$ for $\beta+2 \leq i \leq \alpha+\beta+1$ and copies of all neighbors of $b$, i.e., $a, \ldots, z$, are present only in levels $\beta$ and $\beta+1$.

Suppose $b \in C_{B}$. Then the preference order of $b^{\prime}$ is

$$
\underbrace{a_{\alpha+\beta+1}^{\prime} \succ \cdots \succ z_{\alpha+\beta+1}^{\prime}}_{\text {level } \alpha+\beta+1 \text { neighbors }} \succ \cdots \succ \underbrace{a_{\beta+2}^{\prime} \succ \cdots \succ z_{\beta+2}^{\prime}}_{\text {level } \beta+2 \text { neighbors }} \succ \underbrace{a_{\beta+1} \succ \cdots \succ z_{\beta+1}}_{\text {level } \beta+1 \text { neighbors }} \succ \cdots \succ \underbrace{a_{0} \succ \cdots \succ z_{0}}_{\text {level } 0 \text { neighbors }}
$$

Note that copies of only critical neighbors are present in level $i$ for $\beta+2 \leq i \leq \alpha+\beta+1$ and copies of all neighbors of $b$ are present in level $i$ for $0 \leq i \leq \beta+1$.


Figure $2 A=A_{0} \cup \cdots \cup A_{\alpha+\beta+1}$ and $B=B_{0} \cup \cdots \cup B_{\alpha+\beta+1}$ and $M \subseteq \cup_{i=0}^{\alpha+\beta+1}\left(A_{i} \times B_{i}\right)$. Red nodes are outside $C$ and green nodes are in $C$. All red (i.e., non-critical) nodes are in $\cup_{i \leq \beta+1} A_{i} \cup_{i \geq \beta} B_{i}$; unmatched red nodes are in $A_{\beta+1} \cup B_{\beta}$.

The matching $\boldsymbol{M}$. For any stable matching $M^{\prime \prime}$ in $G^{\prime \prime}$, define $M \subseteq E$ to be the set of edges obtained by deleting edges in $M^{\prime \prime}$ that are incident to dummy nodes and replacing any edge $\left(a_{i}, b^{\prime}\right) \in M^{\prime \prime}$ with the original edge $(a, b) \in E$. For each $a \in A$, the stable matching $M^{\prime \prime}$ matches at most one node among all $a_{i}$ 's to a neighbor in $\left\{b^{\prime}: b \in B\right\}$ (the other $a_{i}$ 's have to be matched to dummy nodes). So $M$ is a matching in $G$.

- Theorem 14. For any stable matching $M^{\prime \prime}$ in $G^{\prime \prime}$, the corresponding matching $M$ is a max-size popular critical matching in $G$.

We will prove Theorem 14 by first showing that $M$ is a critical matching (see Lemma 15), then that $M$ is a popular critical matching (see Lemma 16), and finally that $M$ is a max-size popular critical matching (see Lemma 19). The proof of Lemma 15 is similar to the proof of Lemma 10 and is given in the appendix.

- Lemma 15. $M$ is a critical matching in $G$.

We will now prove that $M$ is a popular critical matching. In order to show this, our analysis is totally analogous to our analysis in Section 3. As done there, we partition the set of all nodes in $A$ that are matched in $M$ into $A_{0} \cup \cdots \cup A_{\alpha+\beta+1}$ where for $0 \leq i \leq \alpha+\beta+1$ : $A_{i}=\left\{a \in A:\left(a_{i}, b^{\prime}\right) \in M^{\prime \prime}\right.$ for some $\left.b \in B\right\}$, i.e., $A_{i}$ is the set of all $a$ 's in $A$ such that $a_{i}$ is matched in $M^{\prime \prime}$ to a neighbor in $\left\{b^{\prime}: b \in B\right\}$. Add unmatched nodes in $C_{A}$ to the set $A_{\alpha+\beta+1}$ and unmatched nodes in $A \backslash C_{A}$ to the set $A_{\beta+1}$ (see Fig. 2).

Partition the set of all nodes in $B$ that are matched in $M$ into $B_{0} \cup \cdots \cup B_{\alpha+\beta+1}$ where for $0 \leq i \leq \alpha+\beta+1: B_{i}=\left\{b:\left(a_{i}, b^{\prime}\right) \in M^{\prime \prime}\right.$ for some $\left.a \in A_{i}\right\}$, i.e., $b^{\prime}$ 's partner in $M^{\prime \prime}$ is a subscript $i$ node. Add unmatched nodes in $C_{B}$ to the set $B_{0}$ and unmatched nodes in $B \backslash C_{B}$ to the set $B_{\beta}$.

- Lemma 16. $M$ is a popular critical matching in $G$.

Proof. We will use Proposition 8 here. Let $(\vec{y}, \vec{z})$ be defined as follows.

1. Set $z_{A}=-2 \alpha$ and $z_{B}=-2 \beta$. Set $y_{u}=0$ for all unmatched nodes $u$.
2. For matched nodes $u$, we will set $y$-values as follows.
= For $a \in A_{i}$ : if $a \in C_{A}$ then set $y_{a}=2 \alpha+2 \beta-2 i+1$; else set $y_{a}=2 \beta-2 i+1$.
= For $b \in B_{i}$ : if $b \in C_{B}$ then set $y_{b}=2 i-1$; else set $y_{b}=2 i-2 \beta-1$.

- Lemma 17. $\langle\vec{y}, \vec{z}\rangle$ defined above is a feasible solution to (LP2).

The proof of Lemma 17 is given below. We will now show that $\sum_{u \in A \cup B} y_{u}+\left(k_{A} \cdot z_{A}\right)+$ $\left(k_{B} \cdot z_{B}\right)=0$. Consider any edge $(a, b) \in M$. There is some $i \in\{0, \ldots, \alpha+\beta+1\}$ such that $a \in A_{i}$ and $b \in B_{i}$.

1. If $a \notin C_{A}$ and $b \notin C_{B}$ then $y_{a}+y_{b}=(2 \beta-2 i+1)+(2 i-2 \beta-1)=0$.
2. If $a \in C_{A}$ and $b \notin C_{B}$ then $y_{a}+y_{b}+z_{A}=(2 \alpha+2 \beta-2 i+1)+(2 i-2 \beta-1)-2 \alpha=0$.
3. If $a \notin C_{A}$ and $b \in C_{B}$ then $y_{a}+y_{b}+z_{B}=(2 \beta-2 i+1)+(2 i-1)-2 \beta=0$.
4. If $a \in C_{A}$ and $b \in C_{B}$ then $y_{a}+y_{b}+z_{A}+z_{B}=(2 \alpha+2 \beta-2 i+1)+(2 i-1)-2 \alpha-2 \beta=0$.

Recall that $k_{A}$ (resp., $k_{B}$ ) is the number of nodes from $C_{A}$ (resp., $C_{B}$ ) that get matched in any critical matching. Since $M$ is a critical matching (by Lemma 15), added up over all edges $(a, b)$ in $M$, the left hand sides of the four equations above sum to $\sum_{u \in V} y_{u}+\left(k_{A} \cdot z_{A}\right)+\left(k_{B} \cdot z_{B}\right)$, where $V \subseteq A \cup B$ is the set of nodes matched in $M$. Since all the right hand sides are 0 , this sum is 0 . For any unmatched node $u$, we set $y_{u}=0$. Hence $\sum_{u \in A \cup B} y_{u}+\left(k_{A} \cdot z_{A}\right)+\left(k_{B} \cdot z_{B}\right)=0$. Thus $M$ is a popular critical matching in $G$ (by Proposition 8).

Proof of Lemma 17. For any unmatched node $u$, we have $\operatorname{wt}_{M}(u, u)=0$ and we set $y_{u}=0$. For any matched node $u$, we have $\mathrm{wt}_{M}(u, u)=-1$ and we will now show that $y_{u} \geq-1$. Since $0 \leq i \leq \alpha+\beta+1$, we have $2 \alpha+2 \beta-2 i+1 \geq-1$ and $2 i-1 \geq-1$. Thus for any matched critical node $u$, we have $y_{u} \geq-1$.

For any matched $a \in A \backslash C_{A}$, observe that $a \in A_{i}$ for some $0 \leq i \leq \beta+1$, so $y_{a}=$ $2 \beta-2 i+1 \geq-1$. For any matched $b \in B \backslash C_{B}$, observe that $b \in B_{i}$ for some $\beta \leq i \leq \alpha+\beta$, so $y_{a}=2 i-2 \beta-1 \geq-1$. Hence $y_{u} \geq \mathrm{wt}_{M}(u, u)$ for all $u \in A \cup B$. Thus constraint (8) holds.

We will now show that $\langle\vec{y}, \vec{z}\rangle$ satisfies constraints (4)-(7). For any $a \in C_{A}$, let $y_{a}^{\prime}=y_{a}+z_{A}$ and for any $b \in C_{B}$, let $y_{b}^{\prime}=y_{b}+z_{B}$. For any node $u \notin C$, let $y_{u}^{\prime}=y_{u}$.

- We have $y_{a}^{\prime}=2 \beta-2 i+1$ for any matched $a \in A$ and $y_{b}^{\prime}=2 i-2 \beta-1$ for any matched $b \in B$.
- For any unmatched $a \in A: y_{a}^{\prime}=-2 \alpha$ if $a \in C_{A}$ and $y_{a}^{\prime}=0$ otherwise.
- For any unmatched $b \in B: y_{b}^{\prime}=-2 \beta$ if $b \in C_{B}$ and $y_{b}^{\prime}=0$ otherwise.

We are now ready to show that $y_{a}^{\prime}+y_{b}^{\prime} \geq \mathrm{wt}_{M}(a, b)$ for all $(a, b) \in E$. Let $a \in A_{i}$ and $b \in B_{j}$. As done in the proof of Lemma 12, this proof is split into 4 parts: (1) $i \leq j-1$, (2) $i=j$, (3) $i=j+1$, and (4) $i \geq j+2$.

1. Consider any edge $(a, b)$ where $a \in A_{i}, b \in B_{j}$, and $i \leq j-1$.
= If $a$ and $b$ are matched nodes then $y_{a}^{\prime}+y_{b}^{\prime}=(2 \beta-2 i+1)+(2 j-2 \beta-1)=2(j-i) \geq$ $2 \geq \mathrm{wt}_{M}(a, b)$.

- Suppose $a$ is unmatched. Observe that $a \in A \backslash C_{A}$; otherwise $i=\alpha+\beta+1$ and so $j \geq \alpha+\beta+2$ which is not possible. Since $a \in A \backslash C_{A}$, we have $y_{a}^{\prime}=0$ and $i=\beta+1$. Since $j \geq \beta+2$, we have $y_{b}^{\prime}=2 j-2 \beta-1 \geq 3$. Thus $y_{a}^{\prime}+y_{b}^{\prime} \geq 3>\mathrm{wt}_{M}(a, b)$.
- Suppose $b$ is unmatched. Observe that $b \in B \backslash C_{B}$; otherwise $j=0$ and so $i \leq-1$ which is not possible. Since $b \in B \backslash C_{B}$, we have $y_{b}^{\prime}=0$ and $j=\beta$. Since $i \leq \beta-1$, we have $y_{a}^{\prime}=2 \beta-2 i+1 \geq 3$. Thus $y_{a}^{\prime}+y_{b}^{\prime} \geq 3>\mathrm{wt}_{M}(a, b)$.

2. Consider any $(a, b) \in E$ where $a \in A_{i}$ and $b \in B_{i}$. For any $b \in B$, within subscript $i$ neighbors, the preference order of $b^{\prime}$ in $G^{\prime \prime}$ is the same as $b$ 's preference order among these neighbors in $G$. Thus $M$ restricted to $A_{i} \cup B_{i}$ is stable and so wt ${ }_{M}(a, b) \leq 0$.

- If $a$ and $b$ are matched nodes then $y_{a}^{\prime}+y_{b}^{\prime}=(2 \beta-2 i+1)+(2 i-2 \beta-1)=0$.
- Suppose $a$ is unmatched.
= If $a \in C_{A}$ then $y_{a}^{\prime}=-2 \alpha$ and $i=\alpha+\beta+1$. So $y_{b}^{\prime}=2(\alpha+\beta+1)-2 \beta-1=2 \alpha+1$. Thus $y_{a}^{\prime}+y_{b}^{\prime}=-2 \alpha+2 \alpha+1=1$.
= If $a \notin C_{A}$ then $y_{a}^{\prime}=0$ and $i=\beta+1$. So $y_{b}^{\prime}=2(\beta+1)-2 \beta-1=1$. Thus $y_{a}^{\prime}+y_{b}^{\prime}=1$.
- Suppose $b$ is unmatched.
= If $b \in C_{B}$ then $y_{b}^{\prime}=-2 \beta$ and $i=0$. So $y_{a}^{\prime}=2 \beta+1$. Thus $y_{a}^{\prime}+y_{b}^{\prime}=2 \beta+1-2 \beta=1$.
= If $b \notin C_{B}$ then $y_{b}^{\prime}=0$ and $i=\beta$. So $y_{a}^{\prime}=2 \beta-2 \beta+1=1$. Thus $y_{a}^{\prime}+y_{b}^{\prime}=1$.
Thus we have $y_{a}^{\prime}+y_{b}^{\prime} \geq 0 \geq \mathrm{wt}_{M}(a, b)$ in all the cases.

3. Let $b \in B_{j}$ where $i=j+1$. As argued in the proof of Lemma 12 , case 3 , for any edge $(a, b)$ where $a \in A_{j+1}$ and $b \in B_{j}$, we have wt ${ }_{M}(a, b)=-2$. So both $a$ and $b$ are matched in $M$ to neighbors they prefer to each other. So $y_{a}^{\prime}+y_{b}^{\prime}=(2 \beta-2 i+1)+(2(i-1)-2 \beta-1)=$ $-2=\mathrm{wt}_{M}(a, b)$.
4. There is no edge $(a, b)$ where $b \in B_{j}$ and $i \geq j+2$; otherwise ( $a_{j+1}, b^{\prime}$ ) would block $M^{\prime \prime}$ as shown in the proof of Lemma 12, case 4 .

Thus we have shown that $y_{a}^{\prime}+y_{b}^{\prime} \geq \mathrm{wt}_{M}(a, b)$ for all $(a, b) \in E$. This completes the proof of Lemma 17.

Max-size popular critical matching. Observe that ( $\vec{y}, \vec{z}$ ) is an optimal solution to (LP2) since $\tilde{M}$ is a feasible solution to (LP1) and $\mathrm{wt}_{M}(\tilde{M})=0=\sum_{u \in A \cup B} y_{u}+\left(k_{A} \cdot z_{A}\right)+\left(k_{B} \cdot z_{B}\right)$. We will use the notation $y_{v}^{\prime}$ for $v \in A \cup B$ used in the proof of Lemma 17. Recall that for any $a \in C_{A}, y_{a}^{\prime}=y_{a}+z_{A}$ and for any $b \in C_{B}, y_{b}^{\prime}=y_{b}+z_{B}$. For any node $u \notin C, y_{u}^{\prime}=y_{u}$. We will show the following claim below.
$\triangleright$ Claim 18. For any edge $(a, b)$ where $a$ or $b$ is unmatched, $y_{a}^{\prime}+y_{b}^{\prime}>\mathrm{wt}_{M}(a, b)$.
Proof. Consider any unmatched $a \in A$ and let $(a, b) \in E$. We already know from the proof of Lemma 17 that $y_{a}^{\prime}+y_{b}^{\prime} \geq \mathrm{wt}_{M}(a, b)$. Our goal now is to show that $y_{a}^{\prime}+y_{b}^{\prime}>\mathrm{wt}_{M}(a, b)$.

If $a \in C_{A}$ then $a \in A_{\alpha+\beta+1}$. Observe that $b \in B_{\alpha+\beta+1}$, otherwise the edge $\left(a_{\alpha+\beta+1}, b^{\prime}\right)$ would block $M^{\prime}$. So $y_{a}^{\prime}+y_{b}^{\prime}=-2 \alpha+2 \alpha+1=1$. Since wt $_{M}(a, b) \in\{0, \pm 2\}$, this means $y_{a}^{\prime}+y_{b}^{\prime}>\mathrm{wt}_{M}(a, b)$.

If $a \notin C_{A}$ then $a \in A_{\beta+1}$. Observe that $b \in \cup_{i \geq \beta+1} B_{i}$, otherwise the edge ( $a_{\beta+1}, b^{\prime}$ ) would block $M^{\prime}$. If $b \in B_{\beta+1}$ then $y_{a}^{\prime}+y_{b}^{\prime}=0+2(\beta+1)-2 \beta-1=1$ and so $y_{a}^{\prime}+y_{b}^{\prime}>\mathrm{wt}_{M}(a, b)$. If $b \in \cup_{i \geq \beta+2} B_{i}$ then $y_{a}^{\prime}+y_{b}^{\prime} \geq 0+2(\beta+2)-2 \beta-1=3>\mathrm{wt}_{M}(a, b)$.

Consider any unmatched $b \in B$ and let $(a, b) \in E$. If $b \in C_{B}$ then $b \in B_{0}$. Observe that $a \in A_{0}$, otherwise the edge $\left(a_{0}, b^{\prime}\right)$ would block $M^{\prime}$. So $y_{a}^{\prime}+y_{b}^{\prime}=2 \beta+1-2 \beta=1$. Since $\mathrm{wt}_{M}(a, b) \in\{0, \pm 2\}$, it follows that $y_{a}^{\prime}+y_{b}^{\prime}>\mathrm{wt}_{M}(a, b)$.

If $b \notin C_{B}$ then $b \in B_{\beta}$. Observe that $a \in \cup_{i \leq \beta} A_{i}$, otherwise the edge ( $a_{\beta}, b^{\prime}$ ) would block $M^{\prime}$. If $a \in A_{\beta}$ then $y_{a}^{\prime}+y_{b}^{\prime}=2 \beta-2 \beta+1=1$ and so $y_{a}^{\prime}+y_{b}^{\prime}>\mathrm{wt}_{M}(a, b)$. If $a \in \cup_{i \leq \beta-1} A_{i}$ then $y_{a}^{\prime}+y_{b}^{\prime} \geq 2 \beta-2(\beta-1)+1=3>\mathrm{wt}_{M}(a, b)$.

Thus every edge incident to a node left unmatched in $M$ is slack.
Lemma 19 follows easily from Claim 18.

- Lemma 19. $M$ is a max-size popular critical matching in $G$.

Proof. Consider any critical matching $N$ in $G$ such that $|N|>|M|$. So $N$ has to match a node that is unmatched in $M$, i.e., $N$ has to use a slack edge (by Claim 18). Since ( $\vec{y}, \vec{z}$ ) is an optimal solution to (LP2), it follows from complementary slackness that the perfect matching $\tilde{N}$, which is a feasible solution to (LP1), cannot be an optimal solution.

The optimal value of (LP1) is 0 , so this means $\mathrm{wt}_{M}(\tilde{N})<0$. In other words, $\Delta(N, M)<0$, i.e., the critical matching $M$ is more popular than $N$. Thus no critical matching larger than $M$ can be a popular critical matching. Hence $M$ is a max-size popular critical matching.

The time taken to compute $M$ is $O(|C| m+m)$, so the second part of Theorem 4 follows from Theorem 14. Recall that the first part of Theorem 4 was already shown in Section 3.

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## A Appendix: Missing Proofs

Before we prove Lemma 10, it will be useful to prove the following simple observation.

- Observation 20. For any critical node left unmatched in $M$, all its neighbors are in $A_{0} \cup B_{\alpha+\beta}$.

Proof. If $a \in C_{A}$ is unmatched in $M$ then $a_{\alpha+\beta}$ has to be unmatched in $M^{\prime}$. This is because for $0 \leq i \leq \alpha+\beta-1$, the node $a_{i}$ is $d_{i+1}(a)$ 's top choice neighbor, hence the stable matching $M^{\prime}$ has to match $a_{i}$. If $a$ has a neighbor $b$ in $B_{i}$ for $i \leq \alpha+\beta-1$ then the edge ( $a_{\alpha+\beta}, b^{\prime}$ ) blocks $M^{\prime}$, a contradiction to its stability in $G^{\prime}$. Thus $b \in B_{\alpha+\beta}$.

Suppose $b \in C_{B}$ is unmatched in $M$ and $b$ has a neighbor $a$ in $A_{i}$ for $i \geq 1$. This means $\left(a_{0}, d_{1}(a)\right)$ is in $M^{\prime}$. Recall that $d_{1}(a)$ is $a_{0}$ 's least preferred neighbor. So the edge $\left(a_{0}, b^{\prime}\right)$ blocks $M^{\prime}$, a contradiction to its stability in $G^{\prime}$. Thus $a \in A_{0}$.

Proof of Lemma 10. We will show there is no alternating path $p$ with respect to $M$ such that (i) $p$ is an augmenting path wrt $M$ and at least one endpoint of $p$ is in $C$ or (ii) $p$ has even length with exactly one endpoint in $C$ and this node is left unmatched in $M$. Then it follows from Lemma 6 that $M$ is a critical matching in $G$.

We will first show there is no augmenting path $p$ wrt $M$ with an endpoint in $C_{B}$. It follows from the definition of sets $A_{i}$ and $B_{i}$ that $M \subseteq \cup_{i=0}^{\alpha+\beta}\left(A_{i} \times B_{i}\right)$. An important property here is that there is no edge in $A_{i} \times B_{j}$ where $i \geq j+2$. See the proof of Lemma 12, case 4 which shows that such an edge contradicts the stability of $M^{\prime}$ in $G^{\prime}$.

The path $p$ starts in $B_{0}$ at an unmatched node $b \in C_{B}$ and all of $b$ 's neighbors are in $A_{0}$ (by Observation 20). The matched partners of $b$ 's neighbors are in $B_{0}$. The node after this can be in $A_{1}$ and its partner is in $B_{1}$ and so on. So the shortest alternating path from an unmatched $b \in B_{0}$ to an unmatched $a \in A$ (such a node is in $A_{\beta} \cup A_{\alpha+\beta}$ ) moves across sets as follows: [here $\left(A_{i}-B_{i}\right)$ refers to a matching edge in $A_{i} \times B_{i}$ ]

$$
B_{0}-\left(A_{0}-B_{0}\right)-\left(A_{1}-B_{1}\right)-\left(A_{2}-B_{2}\right)-\cdots-\left(A_{\beta-1}-B_{\beta-1}\right)-\cdots
$$

Since all nodes in sets $B_{i}$ for $0 \leq i \leq \beta-1$ are in $C_{B}$, this implies there are at least $\beta+1$ nodes of $C_{B}$ in $p$. However $\left|C_{B}\right|=\beta$. So there is no such augmenting path $p$ with respect to $M$.

The same argument shows that the shortest even length alternating path $p$ with an unmatched node in $C_{B}$ as one endpoint and any node in $B \backslash C_{B}$ (such a node is in $\cup_{i \geq \beta} B_{i}$ ) as another endpoint needs to have at least $\beta+1$ nodes of $C_{B}$ in it. However $\left|C_{B}\right|=\beta$. So there is no such alternating path $p$ with respect to $M$.

We will now show there is no augmenting path $p$ wrt $M$ with an endpoint in $C_{A}$. An argument analogous to the one given above shows that the shortest alternating path from an unmatched $a \in A_{\alpha+\beta}$ to an unmatched node $b \in B$ (such a node is in $B_{\beta} \cup B_{0}$ ) moves across sets as follows: [here $\left(B_{i}-A_{i}\right)$ refers to a matching edge in $B_{i} \times A_{i}$ ]

$$
A_{\alpha+\beta}-\left(B_{\alpha+\beta}-A_{\alpha+\beta}\right)-\left(B_{\alpha+\beta-1}-A_{\alpha+\beta-1}\right)-\cdots-\left(B_{\beta+1}-A_{\beta+1}\right)-\cdots
$$

Since all nodes in levels $A_{i}$ for $\beta+1 \leq i \leq \alpha+\beta$ are in $C_{A}$, this implies there are at least $\alpha+1$ nodes of $C_{A}$ in $p$. However $\left|C_{A}\right|=\alpha$. So there is no such augmenting path $p$ with respect to $M$.

The same argument shows that the shortest even length alternating path $p$ with an unmatched node in $C_{A}$ as one endpoint and any node in $A \backslash C_{A}$ (such a node is in $\cup_{i \leq \beta} A_{i}$ ) as another endpoint needs to have at least $\alpha+1$ nodes of $C_{A}$ in it. However $\left|C_{A}\right|=\alpha$. So there is no such alternating path $p$ with respect to $M$.

Thus there is no forbidden alternating path $p$ (as given in Lemma 6) with respect to $M$. Hence $M$ is a critical matching.

Proof of Lemma 15. We will use Lemma 6 to show that $M$ is a critical matching. We will show there is no alternating path $p$ with respect to $M$ such that: (i) $p$ is an augmenting path wrt $M$ and at least one endpoint of $p$ is in $C$ or (ii) $p$ has even length with exactly one endpoint in $C$ and this node is left unmatched in $M$.

We will first show there is no augmenting path $p$ wrt $M$ with an endpoint in $C_{B}$. Every unmatched node in $C_{B}$ is in $B_{0}$ and its neighbors are in $A_{0}$ (analogous to Observation 20).

It follows from the definitions of $A_{i}$ and $B_{i}$ that $M \subseteq \cup_{i=0}^{\alpha+\beta+1}\left(A_{i} \times B_{i}\right)$. Moreover there is no edge in $A_{i} \times B_{j}$ where $i \geq j+2$; otherwise the edge $\left(a_{j+1}, b^{\prime}\right)$ would block $M^{\prime \prime}$.

Thus the path $p$ starts in $B_{0}$ at an unmatched node $b \in C_{B}$ and the next node is in $A_{0}$. The matched partners of $b$ 's neighbors are in $B_{0}$. The node after this can be in $A_{1}$ and its partner is in $B_{1}$ and so on. So the shortest alternating path between an unmatched node $b \in B_{0}$ and an unmatched node $a \in A$ (such a node is in $A_{\beta+1} \cup A_{\alpha+\beta+1}$ ) moves across sets as follows (see Fig. 2):

$$
B_{0}-\left(A_{0}-B_{0}\right)-\left(A_{1}-B_{1}\right)-\left(A_{2}-B_{2}\right)-\cdots-\left(A_{\beta-1}-B_{\beta-1}\right)-\cdots
$$

Since all nodes in levels $B_{i}$ for $0 \leq i \leq \beta-1$ are in $C_{B}$, this implies there are at least $\beta+1$ nodes of $C_{B}$ in $p$. However $\left|C_{B}\right|=\beta$. So there is no such augmenting path $p$ with respect to $M$.

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The same argument shows that the shortest even length alternating path $p$ with an unmatched node in $C_{B}$ (such a node is in $B_{0}$ ) as one endpoint and any node in $B \backslash C_{B}$ (such a node is in $\cup_{i \geq \beta} B_{i}$ ) as another endpoint needs to have at least $\beta+1$ nodes of $C_{B}$ in it. However $\left|C_{B}\right|=\beta$. So there is no such alternating path $p$ with respect to $M$.

We will now show there is no augmenting path $p$ wrt $M$ with an endpoint in $C_{A}$. An argument analogous to the one given above shows that the shortest alternating path from an unmatched $a \in C_{A}$ (note that $a \in A_{\alpha+\beta+1}$ ) to an unmatched node in $B$ (such a node is in $B_{\beta} \cup B_{0}$ ) moves across sets as follows (see Fig. 2):

$$
A_{\alpha+\beta+1}-\left(B_{\alpha+\beta+1}-A_{\alpha+\beta+1}\right)-\left(B_{\alpha+\beta}-A_{\alpha+\beta}\right)-\left(B_{\alpha+\beta-1}-A_{\alpha+\beta-1}\right)-\cdots-\left(B_{\beta+2}-A_{\beta+2}\right)-\cdots
$$

Since all nodes in levels $A_{i}$ for $\beta+2 \leq i \leq \alpha+\beta+1$ are in $C_{A}$, this implies there are at least $\alpha+1$ nodes of $C_{A}$ in $p$. However $\left|C_{A}\right|=\alpha$. So there is no such augmenting path $p$ with respect to $M$.

The same argument shows that the shortest even length alternating path $p$ with an unmatched node in $C_{A}$ (such a node is in $A_{\alpha+\beta+1}$ ) as one endpoint and any node in $A \backslash C_{A}$ (such a node is in $\cup_{i \leq \beta+1} A_{i}$ ) as another endpoint needs to have at least $\alpha+1$ nodes of $C_{A}$ in it. However $\left|C_{A}\right|=\alpha$. So there is no such alternating path $p$ with respect to $M$.

Thus there is no forbidden alternating path $p$ (as given in Lemma 6) with respect to $M$. Hence $M$ is a critical matching in $G$.

