Efficient Reconstruction of Depth Three Arithmetic Circuits with Top Fan-In Two

Gaurav Sinha ☑ 🈭

Adobe Research, Bangalore, India

— Abstract -

In this paper we develop efficient randomized algorithms to solve the black-box reconstruction problem for polynomials over finite fields, computable by depth three arithmetic circuits with alternating addition/multiplication gates, such that output gate is an addition gate with in-degree two. Such circuits naturally compute polynomials of the form $G \times (T_1 + T_2)$, where G, T_1, T_2 are product of affine forms computed at the first layer in the circuit, and polynomials T_1, T_2 have no common factors. Rank of such a circuit is defined to be the dimension of vector space spanned by all affine factors of T_1 and T_2 . For any polynomial f computable by such a circuit, rank(f) is defined to be the minimum rank of any such circuit computing it. Our work develops randomized reconstruction algorithms which take as input black-box access to a polynomial f (over finite field \mathbb{F}), computable by such a circuit. Here are the results.

- [Low rank]: When $5 \le rank(f) = O(\log^3 d)$, it runs in time $(nd^{\log^3 d} \log |\mathbb{F}|)^{O(1)}$, and, with high probability, outputs a depth three circuit computing f, with top addition gate having in-degree $\le d^{rank(f)}$.
- [High rank]: When $rank(f) = \Omega(\log^3 d)$, it runs in time $(nd \log |\mathbb{F}|)^{O(1)}$, and, with high probability, outputs a depth three circuit computing f, with top addition gate having in-degree two.

Prior to our work, black-box reconstruction for this circuit class was addressed in [33, 17, 36]. Reconstruction algorithm in [33] runs in time quasi-polynomial in $n, d, |\mathbb{F}|$ and that in [17] is quasi-polynomial in $d, |\mathbb{F}|$. Algorithm in [36] works only for polynomials over characteristic zero fields. Thus, ours is the first blackbox reconstruction algorithm for this class of circuits that runs in time polynomial in $\log |\mathbb{F}|$. This problem has been mentioned as an open problem in [11] (STOC 2012). In the high rank case, our algorithm runs in $(nd \log |\mathbb{F}|)^{O(1)}$ time, thereby significantly improving the existing algorithms in [33, 17].

2012 ACM Subject Classification Theory of computation \rightarrow Algebraic complexity theory

Keywords and phrases Arithmetic Circuits, Circuit Reconstruction

Digital Object Identifier 10.4230/LIPIcs.ITCS.2022.118

Related Version Full Version: https://eccc.weizmann.ac.il/report/2020/125/

Acknowledgements I would like to thank Vineet Nair for helping with organization and presentation of the paper. I would also like to thank Neeraj Kayal and Chandan Saha for helpful comments on an early presentation of this work. Neeraj Kayal shared the simple idea behind proof of Lemma 52 with me. Lastly, I would like to thank Anuja Sharan for proofreading the paper.

1 Introduction

Arithmetic circuits (Definition 1.1 in [34]) are Directed Acyclic Graphs (DAG), describing succinct ways of computing multivariate polynomials. Analogous to the exact learning problem for boolean circuits [2], black-box reconstruction problem (Section 5, [34]) has been asked for arithmetic circuits:

Given oracle (also known as black-box) access to a multivariate polynomial computable by an arithmetic circuit of size s, construct an explicit circuit (ideally poly(s) sized) that computes the same polynomial.

13th Innovations in Theoretical Computer Science Conference (ITCS 2022).

Editor: Mark Braverman; Article No. 118; pp. 118:1–118:33

In its most general setting, this problem is believed to be hard, as illustrated in Section 1.4 of [9] via an analogy with the boolean world. This is because the exact learning [2] of boolean circuits from membership queries is closely related to the Minimum Circuit Size Problem (MCSP), which, under certain cryptographic assumptions 1 was shown in [14] to not be in \mathbf{P} . In fact, under the same assumptions [1] showed that even approximating the minimum circuit size was not in P. Drawing an analogy from this, approximating the minimum circuit size for general arithmetic circuits might not be in P as well, implying the hardness of black-box reconstruction. We refer the reader to [9] for more details on the analogy. As a result of this, most of the research on black-box reconstruction has focused on restricted but interesting sub-classes of arithmetic circuits. One such natural restriction is that of depth three circuits which we study in this paper. These are layered circuits with three layers of alternating $\operatorname{plus}(\Sigma)$ gates and $\operatorname{product}(\Pi)$ gates. Reconstruction of $\Pi\Sigma\Pi$ circuits amounts to black-box polynomial factorization into sparse factors and efficient randomized algorithms that solve this are known [16]. However, no such algorithm is known for $\Sigma\Pi\Sigma$ circuits² (Definition 9). First non-trivial algorithm for this class which takes exponential time in the fan-in of the multiplication gates was given in [21]. Current state of the art reconstruction algorithms for this class either work in the average case [20] or puts further restrictions such as restricting the circuit class to be (set)-multilinear [33, 17, 4], or restricting the fan-in of the top addition gate (also called top fan-in) [33, 17, 36]. Therefore, even for the class of depth three circuits, reconstruction problem appears to be very challenging. In this paper we are interested in the latter restriction i.e. depth three circuits where fan-in of the top addition gate is assumed to be k = O(1). When k = 1, the polynomial computed by the circuit is a product of linear forms and black-box reconstruction can be easily performed using black-box factorization algorithm in [16]. However, the problem seems to become very challenging as soon as we go to circuits with k > 1. For k = 2, [33] designed a randomized reconstruction algorithm which was generalized³ in [17] to circuits with k = O(1). An important point to note is that while the algorithm in [33] is proper⁴, i.e., output also has top fan-in 2, the one in [17] is improper and output might have much larger top fan-in. Both these algorithms use fairly sophisticated techniques and have time complexity quasi-polynomial in d, $|\mathbb{F}|^5$ (even for k=2in [17]). Note that ideally we would want the time complexity to depend polynomially on $\log |\mathbb{F}|$, since $O(\log |\mathbb{F}|)$ bits can represent any scalar in the circuit. Therefore, even for k=2, designing algorithms which run in time polynomial in n^6 , d and $\log |\mathbb{F}|$ are not known. This was asked as an open problem in [11] (STOC 2012). In a recent work, [36] also considered the top fan-in 2 case, but over characteristic zero fields, and rank of input polynomial being $\Omega(1)$. Their algorithm runs in time polynomial in n, d, but their techniques do not work over finite fields. Based on the above, the following questions seem very natural to ask. (Q1) Does there exist a reconstruction algorithm for depth 3 circuits with top fan-in 2 (over a finite field \mathbb{F}), whose run-time is polynomial in $\log |\mathbb{F}|$? (Q2) Can such an algorithm be fully polynomial time (at-least in high rank case) i.e. runs in time (nd log $|\mathbb{F}|$)^{O(1)}? This will substantially improve results in [33, 17] for k=2. In this paper we resolve both of these questions.

¹ assuming the existence of cryptographically secure one-way functions

 $^{^2}$ from here on wards by depth three circuits we mean $\Sigma\Pi\Sigma$ circuits only

 $^{^3}$ algorithm in [17] is deterministic

⁴ when rank (Definition 13) of the input polynomial is $\Omega(\log^2 d)$

⁵ d is degree of Π gates and $|\mathbb{F}|$ is size of the underlying field

 $^{^{6}}$ n is the number of variables in the circuit

1.1 Our Results

Notation and Preliminaries

Let n,d denote positive integers and $\mathbb F$ be a finite field. We denote the sets $\{1,\ldots,n\}$ and $\{m,m+1,\ldots,n\}$ by [n] and [m,n] respectively. $\vec x$ denotes the tuple (or set) of variables (x_1,\ldots,x_n) and $\mathbb F[\vec x]$ denotes the ring of multivariate polynomials. For a set of linear forms $\ell_1,\ldots,\ell_k\in\mathbb F[\vec x]$, we use $\mathbb V(\ell_1,\ldots,\ell_k)$ to denote the subspace $\{a\in\mathbb F^n:\ell_1(a)=\ldots=\ell_k(a)=0\}$. For a subset of variables x_{i_1},\ldots,x_{i_k} , by $f_{|x_{i_1}=\alpha_{i_1},\ldots,x_{i_k}=\alpha_{i_k}}$ we denote the polynomial obtained on setting $x_{i_1}=\alpha_{i_1},\ldots,x_{i_k}=\alpha_{i_k}$ in f. As given in Lemma 3.5 of [7], every depth three circuit C of rank r, computing an n-variate, degree d polynomial f can be converted into a homogeneous depth three circuit C_{hom} over $\leq n+1$ variables and rank $\leq r+1$, such that its multiplication gates have in-degree d. Section 1.5 of [35] implies that black-box access to C_{hom} can be simulated efficiently using black-box access to f and integers f, f. Also there is a simple and efficient algorithm to obtain f from f from f Hence, from now onwards we only consider homogeneous depth three circuits f from f Hence, from now onwards we only consider homogeneous depth three circuits f from f hence, from now onwards we only consider homogeneous depth three circuits f from f hence, from now onwards we only consider homogeneous depth three circuits f from f hence, from now onwards we only consider homogeneous depth three circuits f from f hence, from now onwards we only consider homogeneous depth three circuits f from f hence, from now onwards we only consider homogeneous depth three circuits f from f hence, from now onwards we only consider homogeneous depth three circuits f has a finite field.

- ▶ Theorem 1 (Low rank reconstruction). There exists a randomized algorithm which takes as input integers n, d and black-box access to a polynomial f computable by a $\Sigma\Pi\Sigma(2, n, d, \mathbb{F})$ circuit $(5 \le rank(f) = O(\log^3 d))$, runs in time $(nd^{\log^3 d} \log |\mathbb{F}|)^{O(1)}$ and with probability 1 o(1), outputs a $\Sigma\Pi\Sigma(k, n, d, \mathbb{F})$ $(k \le d^{rank(f)})$ circuit computing f.
- ▶ Theorem 2 (High rank reconstruction). There exists a randomized algorithm which takes as input integers n, d and black-box access to a polynomial f computable by a $\Sigma\Pi\Sigma(2, n, d, \mathbb{F})$ circuit $(rank(f) = \Omega(\log^3 d))$, runs in time $(nd \log |\mathbb{F}|)^{O(1)}$ and, with probability 1 o(1), outputs a $\Sigma\Pi\Sigma(2, n, d, \mathbb{F})$ circuit computing f.

We allow algorithms to query input polynomial at points in a $(nd)^{O(1)}$ sized extension \mathbb{K} of \mathbb{F} . Here are some remarks on the above results.

- Theorems 1 and 2 completely resolve (Q1). Therefore we solve an open problem from [11]. Theorem 2 resolves (Q2) in the high rank case $(\Omega(\log^3 d))$ and thus both theorems substantially improve the overall reconstruction time complexity for this circuit class (as compared to [33] and [17]).
- A crucial component of our proofs is a new structural result (Proposition 5), which might be of independent interest. We show that for f computable by a $\Sigma\Pi\Sigma(2, n, d, \mathbb{F})$ circuit $(rank(f) \geq 5)$, the set of co-dimension 2 subspaces of \mathbb{F}^n on which the "non-linear" part (Definition 3) of f vanishes, has size $d^{O(1)}$, and can be computed efficiently.
- In order to prove Theorem 2, we develop an interesting result related to Sylvester Gallai (SG) type configurations (Definition 17) and present it in Proposition 8. We believe it might be of independent interest. Similar results called Quantitative SG theorems are known (Theorem 5.1.2 and Section 5.3 in [6]). These quantitative versions prove bounds on number of ordinary lines through a point, whereas our theorem considers dimension of the space spanned by the union of ordinary lines through a point.
- When rank(f) = 1, f factors into a product of linear forms and can be reconstructed efficiently using Lemma 23. So only rank(f) = 2, 3, 4 are not covered by our algorithms.
- We note that when $\operatorname{char}(\mathbb{F}) > d$ or 0, Lemma 19 ([5, 18]) gives an algorithm for Theorem 1 i.e. low rank reconstruction. But, this only works for fields with large characteristic, whereas Algorithm 1 in our paper is independent of the characteristic of the field.

- We would like to highlight that derandomizing our algorithms seems rather difficult. Theorem 5 in [37] implies that any proper and efficient reconstruction algorithms for (set)-multilinear $\Sigma\Pi\Sigma(2,n,d,\mathbb{F})$ circuits with running time polynomial in $\log |\mathbb{F}|$ can be deterministically converted (in time polynomial in $\log |\mathbb{F}|$). into a square root oracle over \mathbb{F} . This is a well studied problem [25, 10, 32, 8, 27, 18, 38] and till date no deterministic algorithm with running time having polynomial dependence in $\log |\mathbb{F}|$ is known.
- We conjecture that, for k = O(1), our algorithms can be generalized to proper (at least in the high rank case) reconstruction algorithms (with time complexity polynomial in $\log |\mathbb{F}|$) for $\Sigma \Pi \Sigma(k, n, d, \mathbb{F})$ circuits. Some crucial parts to be generalized/refined are (a) Proposition 5 to higher co-dimension sub-spaces, and (b) The "gluing" algorithm (Algorithm 5 in [33]) used in Algorithm 5, which merges factors of restrictions of the input polynomial and reconstructs one of the product gates. Recall that the known algorithms for this class are either exponential time in in-degree of product gates [21] or are improper and run in quasi-polynomial time in d, $|\mathbb{F}|$ [17].
- Note that as proved in Corollary 7 of [33], $\Sigma\Pi\Sigma(2,n,d,\mathbb{F})$ circuit for a polynomial f is unique when $rank(f) = \Omega(\log^2 d)$. In fact, for smaller ranks, it is easy to construct example polynomials computable by multiple $\Sigma\Pi\Sigma(2,n,d,\mathbb{F})$ circuits. Therefore, for low rank polynomials, in the absence of uniqueness, proper reconstruction might be far fetched. Moreover, many of our techniques such as construction of a candidate set of linear forms (Algorithm 3) that help in proper reconstruction only work in the high rank case. As a result we split our results into the low rank and high rank cases.
- when $rank(f) = \Omega(1)$. They construct a set of linear forms modulo which the polynomial factorizes completely into linear forms. This is done using Brills equations [12] which construct a system of polynomial equations whose solutions characterize polynomials that decompose into product of linear forms. As derived in Appendix B of [35], computation of Brills equations involve division by multiples of d and therefore they are not likely to directly work over finite fields of general characteristic. To the best of our knowledge, analogous equations for polynomials over finite fields are not well studied. On the other hand, we construct a set of candidate linear forms in a much simpler way by looking at co-dimension 2 subspaces where f vanishes. Another difference between the two techniques is during the "gluing" process of Algorithm 5. In [36, 35] the gluing is done using δSG_k theorems [3] which prove existence of many "ordinary" k-flats. On the other hand we construct a large independent set of linear forms dividing one of the product gates and use it along with the "gluing" technique from [33] which depends on lower bounds for locally decodable codes.

Next, we state our proposition regarding the number of co-dimension 2 spaces on which the non-linear part of f vanishes. In order to do so we first give a few definitions that are used.

- ▶ **Definition 3** (Linear and Non-linear parts). Let $f \in \mathbb{F}[\vec{x}]$. We define Lin(f), called the linear part of f to be the product (with multiplicity) of all linear polynomials dividing f and NonLin(f) called the non-linear part of f as $NonLin(f) = \frac{f}{Lin(f)}^7$.
- ▶ Definition 4. Let $f \in \mathbb{F}[\vec{x}]$. For any co-dimension 2 space $W = \mathbb{V}(\ell_1, \ell_2) \subset \mathbb{F}^n$, we say that f vanishes on W, if, for isomorphism $\Phi : \mathbb{F}[\vec{x}] \to \mathbb{F}[\vec{x}]$ mapping $\ell_1 \mapsto x_1, \ell_2 \mapsto x_2$, the polynomial $\Phi(f)_{|x_1=0,x_2=0}$ is identically zero. This is well defined, i.e. if we take some

⁷ Lin(f), NonLin(f) are unique up to scalar factors which are constrained such that $f = Lin(f) \times NonLin(f)$.

other linear forms ℓ'_1, ℓ'_2 such that $W = \mathbb{V}(\ell'_1, \ell'_2)$ and some other isomorphism Φ' mapping $\ell'_1 \mapsto x_1, \ell'_2 \mapsto x_2$, then $\Phi(f)_{|x_1=0,x_2=0} = 0 \Leftrightarrow \Phi'(f)_{|x_1=0,x_2=0} = 0$. For any polynomial f, we define S(f) to be the set of all co-dimension 2 sub-spaces $W \subset \mathbb{F}^n$ such that f vanishes on W.

- ▶ Proposition 5. Let $f \in \mathbb{F}[\vec{x}]$ be a polynomial computable by a $\Sigma\Pi\Sigma(2, n, d, \mathbb{F})$ circuit with $rank(f) \geq 5$. The following are true.
- 1. $|\mathcal{S}(NonLin(f))| \leq 3d^7$.
- 2. \exists a randomized algorithm that takes as input black-box access to f along with integers n, d, runs in time $(nd \log |\mathbb{F}|)^{O(1)}$ and, outputs a set \mathcal{S} (of size $\leq 3d^7$) containing tuples of independent linear forms in $\mathbb{F}[\vec{x}]$ such that with probability 1 o(1),

$$\{\mathbb{V}(\ell_1,\ell_2): (\ell_1,\ell_2) \in \mathcal{S}\} = \mathcal{S}(NonLin(f)).$$

Next we state Proposition 8 about ordinary lines and the space spanned by them, that was mentioned in remarks following the theorems. This requires definitions of proper sets and ordinary lines which we provide below.

- ▶ **Definition 6** (Proper set, Section 5.3, [6]). We call a set of points $v_1, \ldots, v_m \in \mathbb{F}^n$ proper if no two points are a constant multiple of each other and the zero point is not in the set (i.e. it is a subset of the projective space).
- ▶ **Definition 7** (Ordinary line, Section 5.1, [6]). Let $S \subset \mathbb{F}^n$ be a proper set. For any $t \in \mathbb{F}^n$ and $s \in S$, such that $t \notin sp\{s\}$, the vector space $sp\{t,s\}$ is called an ordinary line from t into S, iff $sp\{t,s\} \cap S \subseteq \{t,s\}$. Define O(t,S) to be the set of ordinary lines from t into S.
- ▶ Proposition 8. Let $S \subset \mathbb{F}^n$ be a proper set (Definition 6) and $\mathcal{T} \subset \mathbb{F}^n$ be any **LI** set of size $\geq \log |S| + 2$. Then $\exists t \in \mathcal{T}$, such that union of all elements of $\mathcal{O}(t, S)$ spans a high dimensional space. More precisely,

$$dim(\sum_{W \in \mathcal{O}(t,\mathcal{S})} W) \ge \frac{dim(sp(\mathcal{S}))}{\log |\mathcal{S}| + 2}.$$

Next, in Sections 1.2 and 1.3, we provide some definitions and notations and known results respectively, which we use throughout the paper. Following this, in Section 1.4, we describe the key technical ideas used in our main algorithms.

1.2 Notations and definitions

Throughout the paper [n] will denote the set $\{1,\ldots,n\}$, [m,n] will denote the set $\{m,m+1,\ldots,n-1,n\}$ and $\mathbb F$ will denote a finite field. We use calligraphic letters like $\mathcal B,\mathcal P,\mathcal Q,\mathcal R,\mathcal S,\mathcal T,\mathcal X$ to denote sets. $\vec x,\vec y,\vec u$ are used to represent column vectors or tuples of variables. Unless otherwise specified, $\vec x$ will denote the tuple (x_1,\ldots,x_n) . Bold capital letters $\mathbf A, \mathbf B$ are used to represent matrices. $\mathbb F[\vec x]$ denotes the ring of polynomials in variables $\vec x=(x_1,\ldots,x_n)$ with coefficients in field $\mathbb F$. Capital letters like $G,H,T_1,T_2,S_1,S_2,U,U_i$ are used to denote polynomials that are a product of linear forms. Small letters f,g,h,u,ℓ are also used to denote polynomials and linear forms. Let g,f be any two polynomials, then, g divides f is denoted by $g \mid f$ and g does not divide g is denoted by $g \nmid f$. We use short-hand g for linearly dependent, g for linearly independent, g for left hand side, g for right hand side and iff for if and only if.

- ▶ Definition 9 (Depth 3 circuit, $\Sigma\Pi\Sigma$). A depth 3 circuit is a layered arithmetic circuit with three layers of nodes labelled by arithmetic operations, defined on a finite number of variables. First and third (Σ) layers have addition nodes and second (Π) layer has multiplication nodes. Top layer has a single addition node.
- ▶ Definition 10 (Homogeneous Depth 3 circuit, $\Sigma\Pi\Sigma(k,n,d,\mathbb{F})$). A $\Sigma\Pi\Sigma(k,n,d,\mathbb{F})$ circuit is a depth three circuit such that the first (Σ) layer computes linear forms on n variables, there are k multiplication nodes at the second (Π) layer all having in-degree d, and the addition node at third (Σ) layer can only have incoming edges from the k multiplication nodes at second layer. Any circuit belonging to this class naturally computes an n-variate polynomial $f = M_1 + \ldots + M_k$, where M_i , $i \in [k]$ are product of linear forms computed at the multiplication gates and $deg(M_1) = \ldots = deg(M_k) = d$.
- ▶ Definition 11 (Simple $\Sigma\Pi\Sigma(k, n, d, \mathbb{F})$ circuit). Let C be a $\Sigma\Pi\Sigma(k, n, d, \mathbb{F})$ circuit computing polynomial $f = M_1 + \ldots + M_k$ as described in Definition 10. We say that C is simple if $gcd(M_1, \ldots, M_k) = 1$.
- ▶ **Definition 12** (Minimal $\Sigma\Pi\Sigma(k, n, d, \mathbb{F})$ circuit). Let C be a $\Sigma\Pi\Sigma(k, n, d, \mathbb{F})$ circuit computing the polynomial $f = M_1 + \ldots + M_k$ as described in Definition 10. We say that C is minimal if no proper sub collection of polynomials M_1, \ldots, M_k sums to zero.
- ▶ Definition 13 (Rank of $\Sigma\Pi\Sigma(2, n, d, \mathbb{F})$ circuit, Section 1.3 in [33]). Let C be a $\Sigma\Pi\Sigma(2, n, d, \mathbb{F})$ circuit computing the polynomial $f = M_1 + M_2$ as described in Definition 10. If $G = \gcd(M_1, M_2)$, then f can be written as $f = G \times T_1 + G \times T_2$ where G, T_1, T_2 are product of linear forms with $\gcd(T_1, T_2) = 1$. Rank of C is then defined as
 - $rank(C) = dim(sp\{linear form \ \ell \in \mathbb{F}[\vec{x}] : \ell \mid T_1 \times T_2\})$
- ▶ **Definition 14** (Rank of polynomial). For any polynomial $f \in \mathbb{F}[\vec{x}]$ computable by a $\Sigma\Pi\Sigma(2,n,d,\mathbb{F})$ circuit, its rank, called rank(f) is defined as the minimum of rank(C) over all $\Sigma\Pi\Sigma(2,n,d,\mathbb{F})$ circuits computing f.
- ▶ **Definition 15.** Let $f \in \mathbb{F}[\vec{x}]$. For any co-dimension 1 space $W \subset \mathbb{F}^n$, we say that f factorizes into non-zero linear forms on W, if, for linear form ℓ_1 such that $W = \mathbb{V}(\ell_1)$, and isomorphism $\Phi : \mathbb{F}[\vec{x}] \to \mathbb{F}[\vec{x}]$ mapping $\ell_1 \mapsto x_1$, the polynomial $\Phi(f)_{|x_1=0}$ is a non-zero product of linear forms in $\mathbb{F}[x_2,\ldots,x_n]$. It is easy to see that this is well defined, i.e. if we take some other linear form ℓ_1' such that $W = \mathbb{V}(\ell_1')$ and some other isomorphism Φ' mapping $\ell_1' \mapsto x_1$ then $\Phi(f)_{|x_1=0}$ is a non-zero product of linear forms $\Leftrightarrow \Phi'(f)_{|x_1=0}$ is a non-zero product of linear forms.
- ▶ Definition 16 (Candidate linear forms). Let $f \in \mathbb{F}[\vec{x}]$. Let ℓ be a linear form and $W = \mathbb{V}(\ell)$. Suppose f factorizes into non-zero linear forms on W, and there exist linear forms ℓ_1, ℓ_2 with ℓ, ℓ_1, ℓ_2 being LI, such that f vanishes on co-dimension 2 subspaces $\mathbb{V}(\ell, \ell_1), \mathbb{V}(\ell, \ell_2)$. Then, ℓ , considered as a point in the projective space, is called a candidate linear form. The set of candidate linear forms is denoted by $\mathcal{L}(f)$. It is easy to see that $|\mathcal{L}(f)| \leq |\mathcal{S}(f)|^2$.
- ▶ **Definition 17** (Sylvester Gallai (SG) configuration, Definition 5.3.1, [6]). A proper set $S = \{s_1, \ldots, s_m\} \subset \mathbb{F}^n$ is called an SG configuration if for every $i \neq j \in [n], \exists k \in [n] \setminus \{i, j\}$ with s_i, s_i, s_k **LD**.
- ▶ **Definition 18** (Number of essential variables, restated from [4]). Let $f(\vec{x}) \in \mathbb{F}[\vec{x}]$. We say that $f(\vec{x})$ has $m \ (\leq n)$ essential variables if there exist an invertible matrix $A \in \mathbb{F}^{(n \times n)}$ such that $f(A \cdot \vec{x})$ depends only on m variables.

1.3 Known results

▶ Lemma 19 ([5, 19]). Let n, d be positive integers and \mathbb{F} be a field with $char(\mathbb{F}) > d$ or 0. There is a randomized algorithm that takes as input black-box access to an n-variate degree d polynomial $f(\vec{x}) \in \mathbb{F}[\vec{x}]$ having m essential variables and computable by a circuit of size s, that runs in time $(nds)^{O(1)}$ and outputs an invertible matrix $A \in \mathbb{F}^{(n \times n)}$ such that $f(A \cdot \vec{x})$ depends only on the first m-variables.

- ▶ Lemma 20 (Solving polynomial equations, Implied from [13, 24]). There is a randomized algorithm that takes as input n variate polynomials f_1, \ldots, f_m each of degree $\leq d$. If the system of equations defined by setting all these polynomials simultaneously to zero, has finitely many solutions in $\bar{\mathbb{F}}$ and all solutions are in \mathbb{F}^n , then the algorithm computes all solutions with probability $1 \exp(-mnd \log |\mathbb{F}|)$. Running time of the algorithm is $(md^n \log |\mathbb{F}|)^{O(1)}$.
- ▶ Lemma 21 (Schwartz Zippel Lemma, [31, 39]). Let $p(x_1, ..., x_n)$ be a polynomial of total degree d such that it is not identically zero. Let $S \subset \mathbb{F}$ be any finite set. For $s_1, ..., s_n$ picked independently and uniformly from S, $Pr[p(s_1, ..., s_n) = 0] \leq \frac{d}{|S|}$.
- ▶ Lemma 22 (Randomized polynomial identity test, Section 1, Lemma 1.2 in [28]). \exists a randomized algorithm that takes as input integer n and black-box access to a degree d, n-variate polynomial f with coefficients in \mathbb{F}_q , runs in time $(nd \log q)^{O(1)}$ and outputs either 'yes' or 'no' such that,

$$\begin{array}{ll} \textit{output is `yes'} & \textit{if } f \equiv 0 \\ \textit{Pr}[\textit{output is `no'}] \geq 1 - o(1) & \textit{if } f \not\equiv 0 \\ \end{array}$$

- ▶ Lemma 23 ($\Sigma\Pi\Sigma(k,n,d,\mathbb{F})$ deterministic polynomial identity test, Theorem 1 in [29]). \exists a deterministic algorithm that takes as input black-box access to a degree d, n-variate polynomial f computable by a $\Sigma\Pi\Sigma(k,n,d,\mathbb{F})$ circuit, runs in time $(nd^k \log |\mathbb{F}|)^{O(1)}$ and, outputs 'yes' if $f \equiv 0$ and 'no' if $f \not\equiv 0$.
- ▶ Lemma 24 ($\Sigma\Pi\Sigma(k,n,d,\mathbb{F})$ Rank bound, Theorem 1.7 in [30]). Let C be a $\Sigma\Pi\Sigma(k,n,d,\mathbb{F})$ circuit, over an arbitrary field \mathbb{F} , that is simple, minimal and zero. Then, $rank(C) < 3k^2 + \frac{k^2}{4} \log d$.
- ▶ Lemma 25 (Black-box multivariate polynomial interpolation, Theorem 11 in [22]). Let n, m, d be parameters and \mathbb{F} be a finite field. \exists a deterministic algorithm that runs in time $(nmd \log |\mathbb{F}|)^{O(1)}$, and outputs a set S of points in \mathbb{F}^n , such that given black-box access to any polynomial $f \in \mathbb{F}[x_1, \ldots, x_n]$ with at most m monomials, the coefficients of all monomials can be recovered in $(nmd \log |\mathbb{F}|)^{O(1)}$ time using evaluations from the set $\{f(s) : s \in S\}$.
- ▶ Lemma 26 (Effective Hilbert irreducibility / Quantitative Bertini theorem, Corollary 2 [15], Remarks 11.5.33, 11.5.66 [26], Theorem 1.1 [23]). Let \mathbb{F} be a perfect field and $g(\vec{x}) \in \mathbb{F}[\vec{x}]$ be a degree d irreducible polynomial. Pick tuples, $\mathbf{a} = (a_2, \ldots, a_n)$, $\mathbf{b} = (b_1, \ldots, b_n)$, $\mathbf{c} = (c_1, \ldots, c_n)$ such that every a_i, b_j, c_k is chosen uniformly randomly and independently from a set $S \subset \mathbb{F}$. Consider the bi-variate restriction

$$\hat{g}(X,Y) = g(X + b_1Y + c_1, a_2X + b_2Y + c_2, \dots a_nX + b_nY + c_n)$$

Then $P[(\mathbf{a}, \mathbf{b}, \mathbf{c}) \in S^{n-1} \times S^n \times S^n : \hat{g}(X, Y) \text{ is not irreducible }] \leq \frac{2d^4}{|S|}$.

▶ Lemma 27 (Black-box multivariate polynomial factorization, [16]). \exists a randomized algorithm that takes as input black-box access to a degree d, n-variate polynomial f with coefficients in \mathbb{F} , runs in time $(nd \log |\mathbb{F}|)^{O(1)}$ and outputs black-box access to polynomials f_1, \ldots, f_m $(m \leq d)$ along with integers e_1, \ldots, e_m such that,

$$Pr[f \equiv f_1^{e_1} \dots f_m^{e_m} \bigwedge f_1, \dots, f_m \text{ are irreducible}] \ge 1 - o(1).$$

▶ Corollary 28 (Decomposition into linear and non-linear factors). \exists a randomized algorithm that takes as input black-box access to a degree d, n-variate polynomial f with coefficients in \mathbb{F} , runs in time $(nd \log |\mathbb{F}|)^{O(1)}$ and outputs a list $\{\ell_1, \ldots, \ell_s\}$ $(s \leq d)$ of affine forms along with black-box access to a polynomial NonLin(f) such that,

$$Pr[f \equiv l_1 \dots l_s NonLin(f) \land NonLin(f) \text{ has no linear factors}] \geq 1 - o(1).$$

Proof. This follows from Lemma 27 in a straight forward. We simply interpolate the irreducible factors f_i as linear forms ℓ_i and test whether $f_i - \ell_i \equiv 0$ using Lemma 22. The factors which pass the test are the linear factors and the remaining constitute NonLin(f).

1.4 Key technical ideas

The algorithms mentioned in Theorems 1 and 2 are provided in Algorithms 1 and 2 respectively. In this section we discuss the key technical ideas used. Missing details are supplied in the subsequent sections. Proof of Propositions 5 and 8 are directly provided in Sections 4 and 5 respectively and not discussed here for brevity. As described in Definition 13, we write $f = G \times (T_1 + T_2)$ where G, T_1, T_2 are product of linear forms and $gcd(T_1, T_2) = 1$. We know that $Lin(f) \times NonLin(f) = f = G \times (T_1 + T_2)$.

1.4.1 Theorem 1: Key ideas for Algorithm 1

The algorithm mentioned in Theorem 1 is presented in Algorithm 1 and its correctness/complexity is discussed in Section 2. We describe the main ideas now. Since NonLin(f) has no linear factors and Lin(f), G are product of linear forms, NonLin(f) divides $T_1 + T_2$ implying that $NonLin(f) = h(y_1, \ldots, y_r)$, for some homogeneous polynomial h over \mathbb{F} and independent linear forms y_1, \ldots, y_r spanning the set of linear factors of $T_1 \times T_2$ (here r = rank(f)). Clearly NonLin(f) is non-constant, otherwise rank of f would not be >= 5. Using Corollary 28, with high probability, we get black-box access to NonLin(f) and its degree t. If we also had access to (a) the integer r = rank(f), and (b) a $d^{O(1)}$ sized set \mathcal{L} of linear forms containing required y_1, \ldots, y_r , then we could just iterate over all r sized subsets $\{y_1, \ldots, y_r\}$ of \mathcal{L} and using deterministic multivariate black-box interpolation (Lemma 25) compute polynomial $h(y_1,\ldots,y_r)$ as a sum of degree t monomials in y_1,\ldots,y_r which is trivially computed by a $\Sigma\Pi\Sigma(t^r,n,t,\mathbb{F})$ circuit. We can then multiply all linear factors of Lin(f), obtained using Corollary 28, to all multiplication gates of this circuit resulting in a $\Sigma\Pi\Sigma(t^r, n, d, \mathbb{F})$ circuit for f. So we only need to argue about the required access described above. We do not know rank(f) but we know that $rank(f) = O(\log^3 d)$. Therefore, we try all values of r in $[O(\log^3 d)]$. To get access to the set \mathcal{L} , we use results in Proposition 5. It guarantees that the set of co-dimension 2 subspaces on which NonLin(f) vanishes, has size $d^{O(1)}$ and also efficiently constructs a set \mathcal{S} that comprises of tuples of linear forms representing such codimension 2 spaces. Using S, we define $\mathcal{L} = \{\ell_1 : \exists \ell_2 \text{ such that } (\ell_1, \ell_2) \in S \text{ or } (\ell_2, \ell_1) \in S\}$. \mathcal{L} is easily constructed from \mathcal{S} . Also $|\mathcal{S}| = d^{O(1)}$ implies $|\mathcal{L}| = d^{O(1)}$. In Lemma 2, we show that \mathcal{L} contains an independent set $\{y_1,\ldots,y_r\}$ of linear forms that spans the set of linear

factors of $T_1 \times T_2$. Basically, for any linear form ℓ_1 dividing T_1 , we show there is a linear form ℓ_2 dividing T_2 (and vice versa) such that NonLin(f) vanishes on $\mathbb{V}(\ell_1,\ell_2)$. This gives rise to a tuple $(\ell'_1,\ell'_2) \in \mathcal{S}$ (i.e. $\ell'_1,\ell'_2 \in \mathcal{L}$) such that $sp\{\ell_1,\ell_2\} = sp\{\ell'_1,\ell'_2\}$. Let \mathcal{L}' be the collection of all such ℓ'_1,ℓ'_2 . By construction $\mathcal{L}' \subset \mathcal{L}$ and $sp\{\mathcal{L}'\} = sp\{\text{linear form } \ell : \ell \mid T_1 \times T_2\}$. Now we can take y_1,\ldots,y_r to be any basis of \mathcal{L}' . At the end we perform a randomized polynomial identity test to check whether the reconstructed circuit computes the input polynomial or not. This guarantees that with probability 1 - o(1), no incorrect reconstruction is returned. At the same time, for correct r and \mathcal{L} , by the above technique, with probability 1 - o(1), we recover the correct circuit which will pass the test. Our algorithm takes $(nd^{\log^3 d} \log |\mathbb{F}|)^{O(1)}$ time. Full details can be found in Section 2.

Comparison with algorithm in [33]

The broad idea for low rank⁸ reconstruction given in Algorithm 3 of [33] is similar to ours. However, their algorithm runs in time quasi-polynomial in n, d and $|\mathbb{F}|$. The main reason is that they search for the required basis $\{y_1, \ldots, y_r\}$ of linear forms (Step 2 of Algorithm 3 in [33]) by iterating over the entire set of linear forms in $O(\log^2 d)$ many variables. This makes their algorithm quasi-polynomial time with respect to $|\mathbb{F}|$, since this set has size $|\mathbb{F}|^{O(\log^2 d)}$. As described above, our algorithm performs a more efficient search by searching within the $d^{O(1)}$ sized set \mathcal{L} , that is efficiently constructed. This leads to a polynomial time dependence on $\log |\mathbb{F}|$ which is ideal as $O(\log |\mathbb{F}|)$ bits can represent each scalar in the circuit.

1.4.2 Theorem 2: Key ideas for Algorithm 2

The algorithm mentioned in Theorem 2 is presented in Algorithm 2. Its correctness and time complexity are discussed in Section 3. Our algorithms crucially utilize the set of "candidate linear forms" which are defined in Definition 16. This definition further requires us to define what it means for a polynomial to factorize into non-zero linear forms on a co-dimension 1 subspace which is defined in Definition 15. Next, we present a reconstruction algorithm solving a corner case, where one of T_1, T_2 is power of a linear form (up to scalar multiplication). Then we discuss the general case algorithm which is run if the corner case fails to reconstruct. In this case, linear factors of both T_1, T_2 span at least a two dimensional space.

Corner case - One of T_1, T_2 is power of a linear form

Formal statement is provided in Lemma 36 and corner case reconstruction algorithm is given in Algorithm 4. We sketch the idea here. If one of T_1, T_2 is power of a linear form, then we prove in Claim 37 that Lin(f) = G and $NonLin(f) = T_1 + T_2$. The basic idea is that if $T_1 + T_2$ has a non trivial linear factor ℓ , then span of any any linear factor of T_1 and ℓ will contain some linear factor of T_2 . This can be used to show that dimension of $sp\{\text{linear form } \ell : \ell \mid T_1\}$ and $sp\{\text{linear form } \ell : \ell \mid T_2\}$ can differ by at most 1. Since $rank(f) = \Omega(\log^3 d)$, we arrive at a contradiction to our assumption in this case. Therefore, using Corollary 28 we get black-box access to $T_1 + T_2$, its degree t, and the entire list of linear factors (with multiplicity) of G. Lets assume that for some $t \in [2]$, $t \in [2]$, $t \in [2]$, $t \in [2]$ is power of some linear form. If we also had access to $t \in [2]$ a linear factor $t \in [2]$ and $t \in [2]$ is zized set $t \in [2]$ of scalars such that $t \in [2]$ for some $t \in [2]$ and try to

⁸ their low rank case assumes $rank(f) = O(\log^2 d)$. we assume $rank(f) = O(\log^3 d)$.

factorize black-box of $T_1 + T_2 - \delta \ell_1^t$, using Corollary 28. If factorization gives all linear factors, we would have obtained a $\Sigma\Pi\Sigma(2, n, t, \mathbb{F})$ circuit for $T_1 + T_2$. Combining this with linear factors of G gives a $\Sigma\Pi\Sigma(2, n, d, \mathbb{F})$ circuit for f. So we only need to argue about the required access. In Claim 38, we show that a linear factor ℓ_1 of T_i belongs to $\mathcal{L}(NonLin(f))$ that we defined in Definition 16. To see this, notice that since $NonLin(f) = T_i + T_{3-i}$, it will factorize into a non-zero product of linear forms on $\mathbb{V}(\ell_1)$ for any linear factor ℓ_1 of T_i . Since rank of $T_i + T_{3-i}$ is $\Omega(\log^3 d)$, we easily obtain linear factors ℓ_2, ℓ_3 of T_{3-i} such that ℓ_1, ℓ_2, ℓ_3 satisfy conditions required by Definition 16 $\Rightarrow \ell_1 \in \mathcal{L}(NonLin(f))$. Definition 16 and Proposition 5 imply that $\mathcal{L}(NonLin(f))$ has size $d^{O(1)}$ and Algorithm 3 efficiently constructs it. So we search for ℓ_1 in this set. To construct set \mathcal{X} containing δ where $T_i = \delta \ell_1^t$, we restrict $T_i + T_{3-i}$ to $\mathbb{V}(\ell_1)$, and obtain two **LI** factors ℓ_2, ℓ_3 of the restriction of T_{3-i} using Corollary 28. These factors will exists since $rank(f) = \Omega(\log^3 d)$. For simplicity map $\ell_1 \mapsto x_1, \ell_2 \mapsto x_2, \ell_3 \mapsto x_3$. Our polynomial has the form $NonLin(f) = \delta x_1^t + (x_2 - \beta x_1)(x_3 - \gamma x_1)T'_{3-i}$, for some scalars β, γ and product of linear forms T'_{3-i} . To find δ , we observe that this polynomial depends on x_3 but becomes independent on plugging $x_2 = \beta x_1$. We first set x_4, \ldots, x_n to random values in F and use multivariate interpolation from Lemma 25, to represent this new polynomial as a degree t polynomial in $\mathbb{F}[x_1, x_2, x_3]$. Then we solve for a fresh variable β such that setting $x_2 = \beta x_1$, makes this polynomial independent of x_3 . This is done by collecting all coefficients $(\in \mathbb{F}[\beta])$ of monomials containing x_3 and solving the system of equations they define. This system has $d^{O(1)}$ many solutions, since all polynomials are univariate with degree $d^{O(1)}$. All solutions to this system are computed using algorithm given in Lemma 20. We plug these β s back into coefficient of x_1^t and obtain a $d^{O(1)}$ sized set \mathcal{X} containing δ . At the end, using polynomial identity testing algorithm in Lemma 23, we deterministically check whether the reconstruction is correct or not. Thus, for choices of ℓ_1, \mathcal{X} , where the circuit was not correct, we don't output anything and for the right values of ℓ_1, \mathcal{X} , by the algorithm described above, we correctly reconstruct the circuit. Our algorithm takes $(nd \log |\mathbb{F}|)^{O(1)}$ time.

General case - Both T_1, T_2 have at least 2 independent linear factors

This is the more general case of our algorithm and is tried after the above mentioned corner case fails to provide a reconstruction. Our algorithm tries to find an $\Omega(\log d)$ sized set of linear forms such that all linear forms in this set divide the same T_i . Once such a set is found we use it to reconstruct all linear forms dividing $G \times T_{3-i}$ and using this the entire circuit. We break down our key ideas below.

We first explain, how one can complete the reconstruction given access to such a set. Formal statement is given in Lemma 41 and algorithm is provided in Algorithm 5. The basic idea is as follows. Without loss of generality, we assume the independent set of linear forms is the set of variables x_1, \ldots, x_t where $t = \Omega(\log d)$ and that all of these divide T_1 . Therefore, $Lin(f) \times NonLin(f) = f = G \times (x_1 \dots x_t T_1' + T_2)$, where T_1' is a product of linear forms and $gcd(T_1', T_2) = 1$. Without loss of generality we also assume that no x_i divides f since we can divide f by largest power of all the x_i . The idea is to construct all linear factors of $G \times T_2$ by first computing all linear factors of $(G \times T_2)_{|x_i=0}$ for $i \in [t]$ and then gluing these factorizations together. Linear factors of $(G \times T_2)_{|x_i=0}$ can be easily computed by applying Corollary 28 to the black-box computing $f_{|x_i=0}$. Clearly for each i the multi-sets of linear factors will have the same (i.e. deg(f)) number of elements. These multi-sets are glued using Algorithm 5 from [33]. The idea behind this algorithm

⁹ we add them back after reconstruction of this new polynomial is complete

is to find a linear form ℓ_1 dividing $(G \times T_2)_{|x_1=0}$ (with multiplicity say k), and an integer $2 \leq i \leq t$ such that there are exactly k linear factors $\ell_i^1, \ldots, \ell_i^k$ (could be multiples of each other) of $(G \times T_2)_{|x_i=0}$ such that $\ell_1|_{x_i=0}$ and $\ell_i|_{x_1=0}$ are scalar multiples. Once such ℓ_i , and ℓ_i^j , $j \in [k]$ are found, ℓ_1 is glued with each ℓ_i^j by comparing coefficients and k glued linear forms dividing $G \times T_2$ are obtained. Then ℓ_1 (with all its multiplicity) and all ℓ_i^j , $j \in [k]$ are removed from their respective multi-sets. This process is repeated until the multi-sets are empty. When the multi-sets are non-empty, such ℓ_1 and i always exist. If not, then in Theorem 33 of [33], they show that a lower bound on length of linear 2-query locally decodable codes gets violated. Details are provided inside proof of Theorem 29 in [33] and for cleaner presentation we do not repeat it here. At the end, all linear factors (with multiplicity) of $G \times T_2$ are known. To know $G \times T_2$ completely, we still need to know the appropriate constant to multiply to the product of these linear factors. For this, we restrict all linear forms in our computed multi-set to $x_1 = 0$ and compare with the multi-set of linear factors of $(G \times T_2)_{|_{x_1=0}}$ which we had already computed earlier. Now we can factorize the black-box for $f - G \times T_2$ and recover all linear factors of $G \times T_1$ and construct a $\Sigma\Pi\Sigma(2, n, d, \mathbb{F})$ circuit for f. Finally using polynomial identity test in Lemma 23, we can check whether this circuit correctly computes f or not, and only output a

Now, we come back to our process of finding the **LI** set utilized above. We use the set of candidate linear forms $\mathcal{L}(NonLin(f))$ efficiently constructed using Algorithm 3. In Parts 1 and 2 of Lemma 44 (which uses Proposition 8), we show existence of a linear form $\ell \in \mathcal{L}(NonLin(f))$ and a **LI** set $\mathcal{B} \subset \mathcal{L}(NonLin(f))$ of size $\Omega(\log d)$ such that ℓ and all linear forms in \mathcal{B} divide $T_1 \times T_2$. Moreover, $\forall \ell' \in \mathcal{B}, sp\{\ell, \ell'\}$ does not contain any other 10 linear factor of $T_1 \times T_2$, and any linear factor of $T_1 + T_2$. Using this, in Part 3 of Lemma 44, we show that for $\ell' \in \mathcal{B}$, NonLin(f) vanishes on $\mathbb{V}(\ell,\ell')$ iff ℓ,ℓ' divide different T_i . This is used to split \mathcal{B} into two parts, with linear forms in each part dividing the same T_i . One of these would be $\Omega(\log d)$ in size giving us the required LI set. Full details can be found in Part 3 of Lemma 44. We use the existence of ℓ , \mathcal{B} in Algorithm 5 in the following way. For every ℓ in $\mathcal{L}(NonLin(f))$ using the construction of \mathcal{B} in parts 1,2 of Lemma 44, we construct a O(rank(f)) sized collection of sets containing \mathcal{B} . For each candidate \mathcal{B} in this collection, we apply the test (from part 3 of Lemma 44) mentioned above to divide it into two parts \mathcal{U}, \mathcal{V} . The larger set is provided to the previous algorithm (details in Algorithm 5) to reconstruct the circuit. In the end, we use deterministic polynomial identity test to reject incorrect constructions. The existence of ℓ , \mathcal{B} and the test above, make sure that for the correct choices, we will output the correct circuit.

Comparison with algorithm in [33]

As described above, if we have access to an $\Omega(\log d)$ sized set of linear forms such that all of them divide the same T_i , our algorithm exactly matches the one given in Algorithm 5 of [33]. The main difference¹¹ is in the way such a set is created. In Steps 1, 2 of Algorithm 4 in [33], they iterate over all possible $\Omega(\log d)$ sized sets of linear forms inside an $\Omega(\log^2 d + \log^2 n)$ sized random subspace of \mathbb{F}^n . Such a brute force search considers $|\mathbb{F}|^{\Omega(\log d(\log^d + \log^2 n))}$ many sets leading to a quasi polynomial time complexity in n, d and $|\mathbb{F}|$. Using $\mathcal{L}(NonLin(f))$,

¹⁰ apart from ℓ, ℓ'

¹¹ also we assume rank to be $\Omega(\log^3 d)$ whereas [33] assumes it to be $\Omega(\log^2 d)$ for high rank reconstruction

in Lemma 44 we are able to create a small collection of sets of independent linear forms, such that at least one set in this collection has size $\Omega(\log d)$ and comprises of linear forms all of which divide the same T_i . Construction of this collection has required new structural techniques from Proposition 5 and Proposition 8. Searching through this small collection and rejection of incorrect reconstructions by a deterministic polynomial identity test lead to an overall running time of $(nd \log |\mathbb{F}|)^{O(1)}$ which is a huge improvement compared to [33].

2 Low Rank Reconstruction: Proof of Theorem 1

Algorithm 1 Low rank reconstruction.

Input - Black-box access to f, integers n, d.

Output - $\Sigma\Pi\Sigma$ circuit C or #.

- 1. Using Corollary 28 with inputs as black-box access to f and integers n, d, compute list of linear factors ℓ_1, \ldots, ℓ_s and black-box access to NonLin(f). Compute degree of NonLin(f) as t=d-s. Using this black-box and integers n, t as input to Algorithm 6, obtain set \mathcal{S} containing tuples of linear forms representing co-dimension 2 subspaces of \mathbb{F}^n on which NonLin(f) vanishes (i.e. $\mathcal{S}(NonLin(f))$).
- 2. Construct set \mathcal{L} of linear forms ℓ , such that for some ℓ' either (ℓ, ℓ') or (ℓ', ℓ) is in \mathcal{S} . For each $r \in [O(\log^3 d)]$, iterate over all r sized \mathbf{LI} subsets $\{y_1, \ldots, y_r\} \subset \mathcal{L}$. Construct isomorphism Γ mapping $y_i \mapsto x_i, i \in [r]$. Simulate black-box for $\Gamma(NonLin(f))$ and using Lemma 25 interpolate it as a linear combination of degree t monomials in $\mathbb{F}[x_1, \ldots, x_r]$, obtaining a polynomial $h(x_1, \ldots, x_r)$.
- 3. By creating appropriate multiplication/addition gates, construct a $\Sigma\Pi\Sigma(t^r,n,d,\mathbb{F})$ circuit C that computes polynomial $f'=\ell_1\times\ldots\times\ell_s\times h(y_1,\ldots,y_r)$. Using randomized polynomial identity test from Lemma 22, check if f-f'=0. If yes, **Return** C. If no, try the next r sized subset in Step 2. If all r sized subsets have been tried, r=r+1.

We present the low rank reconstruction algorithm required by Theorem 1 in Algorithm 1. We analyze its correctness and running-time here. Using correctness of Corollary 28 and Algorithm 6, at the end of step 1, with probability 1-o(1), we have obtained a blackbox computing NonLin(f), degree t of NonLin(f), and all linear factors ℓ_1, \ldots, ℓ_s (with multiplicity) of f. Next, we show that, for some $r \leq rank(f)$ and linear forms y_1, \ldots, y_r , Step 2 computes a polynomial $h(x_1, \ldots, x_r)$ such that $NonLin(f) = h(y_1, \ldots, y_r)$. In order to do so we prove the following lemma.

▶ Lemma 29. Let r = rank(f). \exists LI subset $\{y_1, \ldots, y_r\} \subset \mathcal{L}$ such that it spans the set of linear factors of $T_1 \times T_2$, implying existence of the polynomial h.

Proof. Since $rank(f) \geq 5$, we know that NonLin(f) is a non-constant polynomial. Consider any linear form $\ell \mid T_i$ for some $i \in [2]$. We will show that there is some $\ell' \mid T_{3-i}$ such that NonLin(f) vanishes on the co-dimension 2 subspace $\mathbb{V}(\ell,\ell')$. Assuming this is true, we know there is a tuple $(\ell_1,\ell_2) \in \mathcal{S}$ such that $\mathbb{V}(\ell,\ell') = \mathbb{V}(\ell_1,\ell_2) \Rightarrow sp(\{\ell,\ell'\}) = sp(\{\ell_1,\ell_2\})$. By construction of set \mathcal{L} , $\ell_1,\ell_2 \in \mathcal{L}$. By going over different ℓ dividing $T_1 \times T_2$ this process would give a list of 2m $(m = deg(T_1) = deg(T_2))$ linear forms $\{\ell_1,\ldots,\ell_{2m}\} \subset \mathcal{L}$ such that

 $sp(\{\text{linear form } \ell : \ell \mid T_1 \times T_2\}) \subset sp(\{\ell_1, \dots, \ell_{2m}\}) \subset sp(\{\text{linear form } \ell : \ell \mid T_1 \times T_2\})$

Since $sp(\{\text{linear form } \ell : \ell \mid T_1 \times T_2\})$ is rank(f) dimensional we get that there are r LI linear forms $y_1, \ldots, y_r \in \{\ell_1, \ldots, \ell_{2m}\} \subset \mathcal{L}$ and the proof would be complete. So we only

need to show that $\exists \ \ell' \mid T_{3-i}$ such that NonLin(f) vanishes on the co-dimension 2 subspace $\mathbb{V}(\ell,\ell')$. To see this, let L be the product of all linear factors of T_1+T_2 . Let Φ be an isomorphism mapping $\ell \mapsto x_1$. On setting $x_1=0$, we get, $\Phi(L)_{|x_1=0} \times \Phi(NonLin(f))_{|x_1=0}=\Phi(T_{3-i})_{|x_1=0} \neq 0$. The non zeroness comes from the fact that $\gcd(T_1,T_2)=1$. The above equation implies (using unique factorization in the ring $\mathbb{F}[x_2,\ldots,x_n]$) that there is some linear form $\ell' \mid T_{3-i}$ such that $\Phi(\ell')_{|x_1=0}$ divides $\Phi(NonLin(f))_{|x_1=0}$. Now, define the isomorphism Δ mapping $x_1 \mapsto x_1, \Phi(\ell') \mapsto x_2$. This can be defined since x_1 and $\Phi(\ell')$ are $\mathbf{L}\mathbf{I}$ (otherwise ℓ divides ℓ' violating $\gcd(T_1,T_2)=1$). Applying Δ to the fact that $\Phi(\ell')_{|x_1=0}$ divides $\Phi(NonLin(f))_{|x_1=0}$, we get that $\Delta(\Phi(\ell')_{|x_1=0}) \mid \Delta(\Phi(NonLin(f))_{|x_1=0})$. Since Δ fixes x_1 , we get $\Delta(\Phi(\ell'))_{|x_1=0} \mid \Delta(\Phi(NonLin(f)))_{|x_1=0}$. So there is polynomial g such that $\Delta(\Phi(NonLin(f)))_{|x_1=0} = \Delta(\Phi(\ell'))_{|x_1=0} \times g$. Now setting $x_2=0$ on both sides will send the $\mathbf{R}\mathbf{H}\mathbf{S}$ to 0 since $\Delta \circ \Phi$ maps $\ell \mapsto x_1, \ell' \mapsto x_2$. Therefore $\Delta(\Phi(NonLin(f)))_{|x_1=0,x_2=0}=0$, and so using Definition 4 one can see that NonLin(f) vanishes on the co-dimension 2 subspace $\mathbb{V}(\ell,\ell')$.

 $h(y_1,\ldots,y_r)$ naturally exhibits a $\Sigma\Pi\Sigma(t^r,n,t,\mathbb{F})$ circuit. This can be seen as follows. Addition gates at the bottom layer will compute linear forms y_1, \ldots, y_r . For each monomial, there will be one multiplication gate. If x_j^k is the largest power of x_j dividing some monomial, then there will be k connections from y_i to the multiplication gate corresponding to this monomial. Finally, the top layer is connected to all the multiplication gates and weight on such an edge is equal to the coefficient of the monomial the multiplication gate corresponded to. Step 3 just multiplies this circuit with all the linear factors and therefore computes a candidate $\Sigma\Pi\Sigma(t^r, n, d, \mathbb{F})$ circuit for f. Randomized polynomial identity test in Step 3 ensures that with high probability we output a correct $\Sigma\Pi\Sigma(t^r, n, d, \mathbb{F})$ circuit for f. If for some r and linear forms y_1, \ldots, y_r , an incorrect circuit gets constructed, probability that it will be outputted is o(1). There are at most $(d^{\log^3 d} \log^3 d)^{O(1)}$ many such bad settings of r and y_1, \ldots, y_r . Using boosting with independent runs of randomized polynomial identity test, we can make error exponentially small in nd so that overall the probability of error still remains o(1) by union bound \Rightarrow with probability 1 - o(1) all these bad settings will be rejected. For r = rank(f) and the correct LI set $\{y_1, \ldots, y_r\}$ (i.e. one spanning all linear factors of $T_1 \times T_2$), we have seen that with probability 1 - o(1), a correct circuit will be constructed which will always pass the randomized polynomial identity test and will be returned. So overall with probability 1 - o(1), a correct $\Sigma\Pi\Sigma(t^r, n, d, \mathbb{F})$ circuit for f will be returned. Next we discuss the time complexity of the above algorithm.

▶ Lemma 30. Algorithm 1 takes $(nd^{\log^3 d} \log |\mathbb{F}|)$ time.

Proof. Time complexity of Corollary 28 and Algorithm 6 imply that Step 1 takes $(nd \log |\mathbb{F}|)^{O(1)}$ time. \mathcal{L} can be constructed in $(nd \log |\mathbb{F}|)^{O(1)}$ time since it involves iterating over the $d^{O(1)}$ sized set \mathcal{S} . Our search for the correct r = rank(f) and linear forms y_1, \ldots, y_r takes $(nd^{\log^3 d} \log |\mathbb{F}|)^{O(1)}$ time in the worst case and multivariate interpolation (Lemma 25) also takes the same amount of time in the worst case. Step 3 multiplies linear factors to all the gates in the circuit for NonLin(f) and therefore takes $(nd^{\log^3 d} \log |\mathbb{F}|)^{O(1)}$ time and therefore overall time complexity is $(nd^{\log^3 d} \log |\mathbb{F}|)^{O(1)}$.

3 High Rank Reconstruction: Proof of Theorem 2

The algorithm in Theorem 2 is presented in Algorithm 2. This algorithm further calls Algorithms 3, 4 and 5. We present and analyze them in Sections 3.1, 3.2 and 3.3 respectively. Correctness of our algorithm heavily relies on Lemma 44, which we prove in Section 3.4.

Algorithm 2 High rank reconstruction.

Input - Black-box access to f, integers n, d. Output - $\Sigma \Pi \Sigma(2, n, d, \mathbb{F})$ circuit C or #.

- 1. Run Algorithm 4 with inputs as black-box access to f along with integers n, d. If output is a circuit C, **Return** C. If output was #, go to the next step.
- 2. Using Corollary 28 with input as black-box access to f and integers n, d, compute list of linear factors ℓ_1, \ldots, ℓ_s and black-box access to NonLin(f). Compute the degree of NonLin(f) as t = d s.
- 3. Using Algorithm 3 with inputs as black-box access to f and integers n, d, construct the set $\mathcal{L}(NonLin(f))$. For each $\ell \in \mathcal{L}(NonLin(f))$ consider all linear forms $\ell' \in \mathcal{L}(NonLin(f))\setminus\{\ell\}$ such that $sp\{\ell,\ell'\}$ does not intersect $\mathcal{L}(NonLin(f))$ at any point other than ℓ,ℓ' . Find a maximal independent set \mathcal{X} of such ℓ 's and continue if $|\mathcal{X}| = \Omega(\log^2 d)$. If no such ℓ exists, **Return** #. Otherwise, partition \mathcal{X} into equal parts of size $\Omega(\log d)$ each and iterate over all parts \mathcal{B} .
 - a. Initialize sets $\mathcal{U}, \mathcal{V} \leftarrow \phi$. Iterate over all linear forms $\ell' \in \mathcal{B}$. Define an isomorphism Φ mapping $\ell \mapsto x_1, \ell' \mapsto x_2$ and using Lemma 22, check if $\Phi(NonLin(f))_{|x_1=0,x_2=0} \equiv 0$. If yes, add ℓ' to \mathcal{U} else add it to \mathcal{V} . Select $r = 60 \log d + 61$ linear forms y_1, \ldots, y_r from the larger of \mathcal{U}, \mathcal{V} .
 - b. Run Algorithm 5 with inputs as black-box access to f, integers n, d and linear forms y_1, \ldots, y_r . If it returns a $\Sigma\Pi\Sigma(2, n, d, \mathbb{F})$ circuit C, **Return** C. Else, go to the next partition \mathcal{B} and then to the next linear form ℓ in the search.

4. Return

Now, we discuss the correctness and time complexity of Algorithm 2. Step 1 tries to solve a corner case where one of T_1, T_2 is power of a linear form. By correctness of Algorithm 6, we know that, if this corner case is satisfied, then with probability 1 - o(1), the correct $\Sigma\Pi\Sigma(2, n, d, \mathbb{F})$ circuit is returned. Also Algorithm 6 never returns an incorrect circuit. Therefore with high probability Step 1 will complete the reconstruction if the corner case condition holds. If it does not hold this algorithm will always proceed to Step 2. Also, if it does not return a circuit we can assume that with high probability the corner case does not hold and therefore linear factors of each T_i span at least a two dimensional space. By correctness of Corollary 28, we know that with probability 1 - o(1), Step 2 correctly obtains a black-box computing NonLin(f), its degree t and correctly identifies all linear factors of f with multiplicity. Correctness of the next step is proved in the following lemma.

▶ **Lemma 31.** If outputs of Steps 1 and 2 are correct, then with probability 1 - o(1), Step 3 computes a $\Sigma\Pi\Sigma(2, n, d, \mathbb{F})$ circuit computing f.

Proof. By correctness of Algorithm 3, we know that the set $\mathcal{L}(NonLin(f))$ is correctly computed. Our algorithm goes through all linear forms $\ell \in \mathcal{L}(NonLin(f))$ and for each such linear form goes through $\Omega(\log d)$ sized sets which are parts of a partition of the set \mathcal{X} defined using ℓ . In Step 3(b), correctness of Algorithm 5 ensures that if a circuit is returned for any choice of ℓ , \mathcal{B} , it is always correct. So all we need to show is that for some choice of ℓ , \mathcal{B} , Algorithm 5 will return the correct circuit with high probability. We know from correctness of Algorithm 5 that if the linear forms y_1, \ldots, y_r (that are given as input to it), all divide the same T_i and are independent, then with high probability a correct circuit will be returned. Therefore, now all we need to show is that there is some choice of ℓ , \mathcal{B} , for which the constructed y_1, \ldots, y_r are independent linear forms dividing the same T_i . Since we

have assumed that output of Step 1 is correct, f does not satisfy the corner case implying that linear factors of each T_i span at least a two dimensional space and therefore Lemma 44 can be applied. Parts 1, 2, 3 of Lemma 44 prove that such ℓ , \mathcal{B} exist for which the test in Step 3(a) creates a partition $\mathcal{U} \cup \mathcal{V} = \mathcal{B}$ such that linear forms in \mathcal{U} divide T_j and linear forms in \mathcal{V} divide T_{3-j} for some $j \in [2]$. Since $|\mathcal{B}| = \Omega(\log d)$, one of \mathcal{U}, \mathcal{V} has size $\Omega(\log d)$. By construction \mathcal{B} is **LI** and thus both \mathcal{U}, \mathcal{V} are **LI**. Therefore y_1, \ldots, y_r with $r = \Omega(\log d)$ are independent linear forms dividing the same T_i . This completes the proof.

Now we discuss the time complexity of the above algorithm.

▶ Lemma 32. Algorithm 2 takes $(nd \log |\mathbb{F}|)^{O(1)}$ time.

Proof. Time complexity of Algorithm 4 and Corollary 28 imply that Steps 1 and 2 take $O(nd\log |\mathbb{F}|)^{O(1)}$ time. By Algorithm 3 we know that the set $\mathcal{L}(NonLin(f))$ has $d^{O(1)}$ size. We iterate over all $\ell \in \mathcal{L}(NonLin(f))$ and for each ℓ' check if $sp\{\ell,\ell'\}$ intersects $\mathcal{L}(NonLin(f))$ at any other point. This can be done in $(nd\log |\mathbb{F}|)^{O(1)}$ time. From these ℓ' , we can simply check linear independence of linear forms and create a maximal set in \mathcal{X} in $(nd\log |\mathbb{F}|)^{O(1)}$ time. Creating a partition of \mathcal{X} , iterating over all parts \mathcal{B} , and isomorphism can be created in $(nd\log |\mathbb{F}|)^{O(1)}$ time. Isomorphism can be efficiently applied to the black-box computing NonLin(f) by taking every input through Φ before applying the black-box. By time complexity of algorithm in Lemma 22, the check in Step $\mathfrak{Z}(a)$ takes $(nd\log |\mathbb{F}|)^{O(1)}$ time. Time complexity of Algorithm 5 implies that Step $\mathfrak{Z}(b)$ takes $(nd\log |\mathbb{F}|)^{O(1)}$ time. Therefore overall Algorithm 2 takes $(nd\log |\mathbb{F}|)^{O(1)}$ time.

In the next subsection, we explain construction of the candidate linear forms (Definition 16).

3.1 Computing Candidate Linear forms

Here is a lemma summarizing the construction of set $\mathcal{L}(NonLin(f))$ of candidate linear forms (Definition 16).

▶ **Lemma 33.** There exists a randomized algorithm that takes as input integers n, d and black-box access to f, runs in time $(nd \log |\mathbb{F}|)^{O(1)}$, and outputs a set \mathcal{L} of linear forms such that $Pr[\mathcal{L} = {}^{12}\mathcal{L}(NonLin(f))] = 1 - o(1)$.

Algorithm for this lemma is provided in Algorithm 3. We prove its correctness now. By correctness of Corollary 28, we know that Step 1 correctly obtains black-box access to NonLin(f), its degree t and linear factors (with multiplicity) of f with probability 1-o(1). Similarly by correctness of Algorithm 6, we know that with probability 1-o(1), the set \mathcal{S} representing elements of $\mathcal{S}(NonLin(f))$ is correctly computed. We prove correctness of the next two steps in the following lemma.

▶ **Lemma 34.** Assuming Step 1 works correctly, with probability 1 - o(1), the output \mathcal{L} of Algorithm 3 is the same¹³ as $\mathcal{L}(NonLin(f))$.

Proof. Consider any $\ell \in \mathcal{L}(NonLin(f))$. By definition of the set $\mathcal{L}(NonLin(f))$, we know that there are linear forms ℓ_1, ℓ_2 with ℓ, ℓ_1, ℓ_2 **LI**, such that the co-dimension 2 subspaces $\mathbb{V}(\ell, \ell_1), \mathbb{V}(\ell, \ell_2) \in \mathcal{S}(NonLin(f))$. So some tuples (p_1, q_1) and (p_2, q_2) corresponding to these two subspaces will be present in \mathcal{S} and will be encountered in Step 2. Note that $\mathbb{V}(p_1, q_1) =$

 $^{^{12}}$ up to scalar multiplication of linear forms in the sets

 $^{^{13}}$ the linear forms in this output are correct upto scalar multiplication

Algorithm 3 Candidate linear forms.

Input - Black-box access to polynomial f, integers n, d. **Output -** A set of linear forms \mathcal{L} .

- 1. Using Corollary 28 with inputs as black-box access to f and integers n, d, obtain list of linear factors ℓ_1, \ldots, ℓ_s and access to black-box computing NonLin(f). Compute degree of NonLin(f) as t = d s. Using Algorithm 6, compute the set S of tuples of linear forms representing co-dimension 2 subspaces on which NonLin(f) vanishes.
- 2. Initialize $\mathcal{L} \leftarrow \phi$. \forall pairs of tuples $(p_1, q_1), (p_2, q_2) \in \mathcal{S}$, check if $sp\{p_1, q_1\} \cap sp\{p_2, q_2\}$ is one dimensional. For this we construct the $n \times 4$ matrix M with its columns containing coefficients of p_1, q_1, p_2, q_2 respectively and then check by gaussian elimination whether rank of M is 3 or not. If yes, the same gaussian elimination can be used to obtain the one dimensional space of solutions to Mv = 0 for $v \in \mathbb{F}^4$. Fixing one such non-zero solution $u = (\alpha_1, \alpha_2, \alpha_3, \alpha_4)^T$ then gives us a scalar multiple of ℓ as $\alpha_1 p_1 + \alpha_2 q_1$. If no scalar multiple of $\alpha_1 p_1 + \alpha_2 q_1$ is already present in \mathcal{L} , then we add it to \mathcal{L} .
- 3. For each $\ell \in \mathcal{L}$, check whether NonLin(f) restricted to $\mathbb{V}(\ell)$ factorizes into a non-zero product of linear forms (See Definition 15). This can be done by defining an isomorphism Φ mapping $\ell \mapsto x_1$, simulating black-box computing $\Phi(NonLin(f))_{|x_1=0}$. Using Lemma 22, check if this black-box computes the 0 polynomial. If 'yes', remove ℓ from \mathcal{L} . Otherwise, using Corollary 28, with inputs as this restricted black-box and integers n, t, compute list of linear factors and check whether there are t of them. If not, then remove ℓ from \mathcal{L} . Finally, **Return** \mathcal{L} .

 $\mathbb{V}(\ell,\ell_1)$ and $\mathbb{V}(p_2,q_2) = \mathbb{V}(\ell,\ell_2)$ implies that $sp\{p_1,q_1\} = sp\{\ell,\ell_1\}$ and $sp\{p_2,q_2\} = sp\{\ell,\ell_2\}$ further implying that $sp\{p_1,q_1\} \cap sp\{p_2,q_2\} = sp\{\ell\}$. This implies that there are scalars $\alpha_1,\alpha_2,\alpha_3,\alpha_4$ such that $\alpha_1p_1+\alpha_2q_1+\alpha_3p_2+\alpha_4q_2=0$, giving us the system of equations as described in the algorithm. In order for the intersection to be one dimensional, the matrix M should have rank 3. We check that using gaussian elimination which also gives the one dimensional set of solutions. Any non-zero solution $(\alpha_1,\alpha_2,\alpha_3,\alpha_4)$ will then give a linear form $\alpha_1p_1+\alpha_2q_1$ in the intersection which will be a scalar multiple of ℓ . Thus, Step 2 identifies a scalar multiple of ℓ and adds it to \mathcal{L} . Step 3 just checks whether NonLin(f) factorizes as a product of non-zero linear forms on $\mathbb{V}(\ell)$ (see Definition 15). Correctness of Step 3 is implied by correctness of Lemma 22 and Corollary 28. Since $\ell \in \mathcal{L}(NonLin(f))$, it will pass this test and remain in \mathcal{L} . Now consider any $\ell \in \mathcal{L}$ that is returned. In Steps 2 and 3 we have checked whether it satisfies the conditions required for it to be in $\mathcal{L}(NonLin(f))$ or not and therefore correctly output $\mathcal{L}(NonLin(f))$ with high probability.

▶ **Lemma 35.** Algorithm 3 takes $(nd \log |\mathbb{F}|)^{O(1)}$ time.

Proof. Time complexity of Corollary 28 and Algorithm 6 imply that Step 1 takes $(nd\log |\mathbb{F}|)^{O(1)}$ time. By first part of Proposition 5, we know that $|\mathcal{S}| \leq 3d^7$ and therefore going over pairs of elements of \mathcal{S} takes $O(nd\log |\mathbb{F}|)^{O(1)}$ time. Gaussian elimination on matrix M takes $(n\log |\mathbb{F}|)^{O(1)}$ time for each pair of tuples. After Step 2 we will have at most $|\mathcal{S}|^2$ many elements in \mathcal{L} leading to a size of $d^{O(1)}$. In Step 3 for every $\ell \in \mathcal{L}$, the construction of Φ , simulation of black-box for $\Phi(NonLin(f))_{|x_1=0}$ are done in $(n\log |\mathbb{F}|)^{O(1)}$ time. Time complexity of algorithm provided in Lemma 22 which tests whether this new polynomial is identically zero or not is $(nd\log |\mathbb{F}|)^{O(1)}$. Finally, time complexity of Corollary 28 implies that in time $(nd\log |\mathbb{F}|)^{O(1)}$ we can check whether it has t linear factors or not. Therefore overall Algorithm 3 takes $(nd\log |\mathbb{F}|)^{O(1)}$ time.

Algorithm 4 Corner case.

Input - Black-box access to polynomial f, integers n, d.

Output - A $\Sigma\Pi\Sigma(2, n, d, \mathbb{F})$ circuit or #.

1. Using Corollary 28 with inputs as black-box access to f and integers n, d compute linear factors $\hat{\ell}_1, \ldots, \hat{\ell}_s$ and get access to black-box computing NonLin(f). Compute degree of NonLin(f) as t = d - s. Using Algorithm 3, compute set $\mathcal{L}(NonLin(f))$.

- **2.** Iterate over $\ell_1 \in \mathcal{L}(NonLin(f))$. Construct an isomorphism Φ mapping $\ell_1 \mapsto x_1$.
 - a. Simulate black-box for $\Phi(NonLin(f))|_{\{x_1=0\}}$ and using Corollary 28 identify two **LI** factors say ℓ_2, ℓ_3 . Construct another isomorphism Δ mapping $x_1 \mapsto x_1, \ell_2 \mapsto x_2, \ell_3 \mapsto x_3$. Pick $\alpha_4, \ldots, \alpha_n$ uniformly randomly from \mathbb{F} . Simulate black-box for

$$g(x_1, x_2, x_3) = \Delta(\Phi(NonLin(f)))|_{\{x_4 = \alpha_4, \dots, x_n = \alpha_n\}}$$

- **b.** Using Lemma 25, interpolate g in monomial basis of $\mathbb{F}[x_1, x_2, x_3]$. Substitute $x_2 = yx_1$ in all monomials and rearrange to get a representation in $\mathbb{F}[y][x_1, x_3]$. Equate coefficient polynomials of monomials containing x_3 to 0 and solve the resulting system of equations using Lemma 20. If all ℓ_1 s have been tried and no solution was obtained, **Return** #. Otherwise, for each solution, evaluate coefficient polynomial of x_1^t , creating a set of scalars.
- c. Iterate over all δs in the set of scalars obtained above. Simulate black-box for $NonLin(f) \delta \ell_1^t$ and using Corollary 28 check if it has t linear factors say $\ell_{s+1}, \ldots, \ell_{s+t}$. If not, then go to the next δ . If all δ have been tried, go to next $\ell_1 \in \mathcal{L}(NonLin(f))$. If all $\ell_1 s$ have been tried, **Return** #. Otherwise, simulate black-box for f f', where

$$f' = \hat{\ell}_1 \times \ldots \times \hat{\ell}_s \times (\delta \ell_1^t + \ell_{s+1} \times \ldots \times \ell_{s+t})$$

and using Lemma 23 for $\Sigma\Pi\Sigma(4, n, d, \mathbb{F})$ circuits, check if $f - f' \equiv 0$. If output is 'yes', construct $\Sigma\Pi\Sigma(2, n, d, \mathbb{F})$ circuit C computing f'. **Return** C. If not, then go to next δ . If all δ have been tried, go to next $\ell_1 \in \mathcal{L}(NonLin(f))$. If all ℓ_1 s have been tried, **Return** #.

3.2 Reconstruction when T_1 (or T_2) = αy_1^t

This is a corner case of our problem and needs slightly different techniques. Here is a lemma summarizing the reconstruction algorithm in this case.

▶ Lemma 36. If for some $i \in [2]$, $T_i = \alpha y_1^t$ for some linear form y_1 and $\alpha \in \mathbb{F}$, then \exists a randomized algorithm that takes as input integers n, d and black-box access to polynomial f, runs in time $(nd \log |\mathbb{F}|)^{O(1)}$, and with probability 1 - o(1) outputs a $\Sigma \Pi \Sigma(2, n, d, \mathbb{F})$ circuit computing f.

Algorithm is provided in Algorithm 4. Now we prove its correctness. By correctness of Corollary 28, with probability 1 - o(1), Step 1 correctly obtains the black-box for NonLin(f), its degree t and the multi-set of all linear factors of f. If we assume that these are correct, then by correctness of Algorithm 3, with probability 1 - o(1), Step 1 also correctly computes the set $\mathcal{L}(NonLin(f))^{14}$ of linear forms. In order to prove the correctness of Step 2 we give two claims, both of which are proved in Appendix A. The first claim says that in this corner

¹⁴ all linear forms are correct up to scalar multiple.

case, NonLin(f) is actually the same as $T_1 + T_2$ (up to scalar multiplication) and the second claim guarantees that some scalar multiple of y_1 actually belongs to the set $\mathcal{L}(NonLin(f))$. Here are the formal statements.

 \triangleright Claim 37. Assume $T_i = \alpha y_1^t$, for some $i \in [2]$, $\alpha \in \mathbb{F}$ and linear form y_1 . Then Lin(f) = G (up to scalar factor). This also means that NonLin(f) and $T_1 + T_2$ are equal up to a scalar factor.

 \triangleright Claim 38. Assume $T_i = \alpha y_1^t$, for some $i \in [2]$, $\alpha \in \mathbb{F}$ and linear form y_1 , then some scalar multiple of y_1 belongs to $\mathcal{L}(NonLin(f))$.

We proceed in our correctness proof assuming that these claims are true. Assuming that Step 1 was correct, we show that Step 2 returns the correct circuit with high probability. Note that in Step 2(c), using Lemma 23, we check whether the reconstructed circuit is correct or not. This ensures that we only return a correct circuit. Our algorithm in Steps 2(b), 2(c) tries all linear forms in $\mathcal{L}(NonLin(f))$ and for each such linear form it constructs a set of scalars. So basically the algorithm iterates over possibilities of ℓ_1, δ with the hope of finding one such that $T_i = \delta \ell_1^t$. If we can show that for some value of ℓ_1, δ with high probability a correct $\Sigma \Pi \Sigma(2, n, d, \mathbb{F})$ circuit is reconstructed, we will be done. We show this for ℓ_1 being the scalar multiple of y_1 that belongs to $\mathcal{L}(NonLin(f))$ (guaranteed by Claim 38) in the following lemma.

▶ Lemma 39. For ℓ_1 , the scalar multiple of y_1 in $\mathcal{L}(NonLin(f))$, the set of scalars constructed in Step 2(b) contains a scalar δ such that $T_i = \alpha y_1^t = \delta \ell_1^t$ and with probability 1 - o(1) correctly reconstructs a $\Sigma\Pi\Sigma(2, n, d, \mathbb{F})$ circuit computing f.

Proof. We know that NonLin(f) restricted to the co-dimension 1 subspace $\mathbb{V}(\ell_1)$ factors into a non-zero product of linear forms. By correctness of Corollary 28, we know that all linear factors of $\Phi(NonLin(f))_{|x_1=0}$ can be computed. By Claim 37, we know that this is the same as $\Phi(T_{3-i})_{|x_1=0}$ up to scalar multiplication. Since $rank(f) = \Omega(\log^3 d)$ and linear factors of T_i span a 1 dimensional space, factors of this polynomial will span an $\Omega(\log^3 d)$ dimensional space and therefore we will be able to find at least two **LI** factors ℓ_2, ℓ_3 in $\mathbb{F}[x_2, \ldots, x_n]$. This means that the polynomial $\Phi(NonLin(f))$ looks like

$$\Phi(NonLin(f)) = \delta \ell_1^t + (\ell_2 - \beta x_1)(\ell_3 - \gamma x_1) \prod_{i=4}^{t+1} \ell_i,$$

for some scalars β, γ and linear forms $\ell_4, \ldots, \ell_{t+1}$ in $\mathbb{F}[x_1, \ldots, x_n]$. Recall the isomorphism Δ used in the algorithm, mapping $x_1 \mapsto x_1, \ell_2 \mapsto x_2, \ell_3 \mapsto x_3$. Black-box computing the polynomial $\Delta(\Phi(NonLin(f)))$ can be constructed by taking every input of blackbox through the isomorphisms. The new polynomial now looks like

$$\Delta(\Phi(NonLin(f))) = \delta x_1^t + (x_2 - \beta x_1)(x_3 - \gamma x_1) \prod_{i=4}^{t+1} \Delta(\ell_i),$$

Finally, we plug in uniform random values for the variables x_4, \ldots, x_n . By Lemma 21 we know that with probability 1-o(1) the polynomial $\prod_{i=4}^{t+1} \Delta(\ell_i)$ will not be identically zero and we will be left with a non-zero polynomial $g(x_1, x_2, x_3) = \delta x_1^t + (x_2 - \beta x_1)(x_3 - \gamma x_1) \prod_{i=4}^{t+1} u_i$ computable by a $\Sigma \Pi \Sigma(2, 3, d, \mathbb{F})$ circuit, where u_i are affine forms in $\mathbb{F}[x_1, x_2, x_3]$. Using the above black-box, we get access to black-box for g and then using deterministic multivariate interpolation (Lemma 25), interpolate it as a degree t polynomial in the monomial basis

of $\mathbb{F}[x_1, x_2, x_3]$. g depends on variable x_3 . So substituting $x_2 = yx_1$ for a fresh variable y, and solving for common zeros of all coefficient (of monomials involving x_3) univariate polynomials in $\mathbb{F}[y]$ would give us a set of scalars containing β . Note that, since our system has only univariate polynomials, all of degree $d^{O(1)}$, it can have at most $d^{O(1)}$ solutions. By correctness of algorithm in Lemma 20, with probability 1 - o(1), this set would be correctly computed. Now substitution of $x_2 = \beta x_1$ would recover δ as coefficient of x_1^t . By correctness of Corollary 28, with probability 1 - o(1), we will be able to completely factorize the black-box $NonLin(f) - \delta \ell_1^t$ into a product of t linear factors giving us the correct T_{3-i} . By correctness of Step 1, we know all linear factors of f, were correctly computed and therefore for scalar multiple ℓ_1 of y_1 and the computed scalar δ , with probability 1 - o(1), we reconstruct a correct $\Sigma\Pi\Sigma(2, n, d, \mathbb{F})$ circuit for f.

Now we discuss the time complexity of the above algorithms.

▶ **Lemma 40.** Algorithm 4 takes $(nd \log |\mathbb{F}|)^{O(1)}$ time.

Proof. Time complexity of Corollary 28 and Algorithm 3 imply that Step 1 takes $(nd \log |\mathbb{F}|)^{O(1)}$ time. In Step 2, the outer iteration is over all linear forms in $\mathcal{L}(NonLin(f))$ which has size $d^{O(1)}$ (clear from Definition 16 and explanation given in Algorithm 3). Step 2(a) involves simulations of black-boxes post application of isomorphism and setting values for some variables. It also involves using Corollary 28 to compute all linear factors. All these steps take $(nd \log |\mathbb{F}|)^{O(1)}$ time. Finding **LI** pair of linear forms out of all linear factors is also done in $(nd \log |\mathbb{F}|)^{O(1)}$ time. Step 3 involves trivariate interpolation (Lemma 25) which takes $(d \log |\mathbb{F}|)^{O(1)}$ time and by time complexity of Lemma 20 solutions of the system of univariate polynomials (all have degree $d^{O(1)}$) are also found in $(nd \log |\mathbb{F}|)^{O(1)}$ time. The set of solutions is $d^{O(1)}$ sized since a univariate polynomial of degree s has at most s roots over a field. Therefore Step 2(b) takes $(nd \log |\mathbb{F}|)^{O(1)}$ time and creates a set of scalars of size $d^{O(1)}$. Step 2(c) iterates over this $d^{O(1)}$ sized set. Simulation of black-box and factorization using Corollary 28 take $(nd \log |\mathbb{F}|)^{O(1)}$ time. Blackbox for f - f' is constructed in $(nd \log |\mathbb{F}|)^{O(1)}$ time and by time complexity of algorithm in Lemma 23, it can be checked to be 0 or not in $(nd \log |\mathbb{F}|)^{O(1)}$ time. Therefore overall Algorithm 4 takes $(nd \log |\mathbb{F}|)^{O(1)}$ time.

3.3 Reconstruction with LI set dividing T_i given

Suppose we are given **LI** linear forms $u_1, \ldots, u_t, t > 60 \log d + 61$, such that for some $i \in [2]$, all the u_i s divide T_i . Then \exists an efficient reconstruction algorithm as described below.

▶ Lemma 41. There exists a randomized algorithm which takes as input integers n, d, black-box access to polynomial f computable by a $\Sigma\Pi\Sigma(2, n, d, \mathbb{F})$ circuit and LI linear forms $u_1, \ldots, u_t, t > 60 \log d + 61$ (for some $i \in [2]$, all u_j s divide T_i), runs in time $(nd \log |\mathbb{F}|)^{O(1)}$ and with probability 1 - o(1) outputs a $\Sigma\Pi\Sigma(2, n, d, \mathbb{F})$ circuit computing f.

We present the algorithm for proving the above lemma in Algorithm 5. We use Algorithm 5 (we call this the merge algorithm) of [33] in Step 2. More details on this merge algorithm can be found in Algorithm 5 and Theorem 29 of [33]. Now we prove correctness of our algorithm. Black-box computing $\Phi(f)$ is simulated by passing every input through Φ first. Correctness of Corollary 28 imply that with probability 1 - o(1), all linear factors of $\Phi(f)$ and black-box access to $\Phi(NonLin(f))$ are correctly computed. From these linear forms, we remove any linear form ℓ that are divisible by some x_i . However we will keep the scalar ℓ/x_i . The black-box obtained by multiplying the black-box of $\Phi(NonLin(f))$ returned by Corollary 28 with these scalars and black-boxes computing the remaining linear factors

Algorithm 5 LI linear factors of a multiplication gate are known.

Input - Black-box access to f, integers n, d, linear forms $u_1, \ldots, u_t, t > 60 \log d + 61$. **Output** - A $\Sigma \Pi \Sigma(2, n, d, \mathbb{F})$ circuit C or #.

- 1. Construct isomorphism Φ mapping $u_i \mapsto x_i, i \in [t]$ and simulate black-box computing $\Phi(f)$. Using Corollary 28 with inputs as black-box computing $\Phi(f)$ and integers n, d, obtain all its linear factors (with multiplicity) along with access to black-box computing $\Phi(NonLin(f))$. By traversing through the factors identify e_i , the largest power of x_i that divides $\Phi(f)$. Using this set of factors and black-box computing $\Phi(f)$, simulate black-box computing $g = \Phi(f) / \prod x_i^{e_i}$.
- 2. For each $i \in [t]$, simulate black-box computing $g_{|\{x_i=0\}}$ and using Corollary 28 with inputs as this black-box, compute its factors. If there are non linear factors, **Return** #. Otherwise, store factors in multi-set \mathcal{U}_i . Using Algorithm 5 in [33] merge the multi-sets \mathcal{U}_i together to obtain a multiset \mathcal{U} comprising of all linear factors of one of the product gates in the $\Sigma\Pi\Sigma(2, n, s, \mathbb{F})$ circuit computing g (here s is some integer $\leq d$).
- 3. Construct the multi-set $\mathcal{U}' = \{\ell_{|_{\{x_1=0\}}} : \ell \in \mathcal{U}\}$. Check if this multi-set \mathcal{U}' and \mathcal{U}_1 contain same linear forms (upto multiplicity). If not, **Return** #. Otherwise compute scalar $\alpha = \prod_{\ell \in \mathcal{U}_1} \ell / \prod_{\ell \in \mathcal{U}'} \ell$ by matching linear forms between $\mathcal{U}', \mathcal{U}_1$.
- 4. Simulate black-box computing $g \alpha \prod_{\ell \in \mathcal{U}} \ell$ and factorize this polynomial using Corollary 28. If all factors are not linear, **Return** #. Otherwise, store factors in multi-set \mathcal{V} . Apply Φ^{-1} to all linear forms in \mathcal{U}, \mathcal{V} . Simulate black-box for f f', where $f' = \prod_{i=1}^t u_i^{e_i} \times (\alpha \prod_{\ell \in \mathcal{U}} \ell + \prod_{\ell \in \mathcal{V}} \ell)$. Using Lemma 23 for $\Sigma \Pi \Sigma(4, n, d, \mathbb{F})$ circuits, check if $f f' \equiv 0$. If output is 'yes', construct $\Sigma \Pi \Sigma(2, n, d, \mathbb{F})$ circuit C computing f' and **Return** C. If not, **Return** #.

simulates black-box access to $g = \Phi(f)/\prod_{i=1}^t x_i^{e_i}$. g is a $\Sigma \Pi \Sigma(2, n, s, \mathbb{F})$ circuit for some integer $s \leq d$. Assuming that Step 1 is correct, simulation of black-boxes $g_{|_{\tau=0}}, i \in [t]$ can be done. Correctness of Corollary 28 implies that with probability 1 - o(1) all multi-sets \mathcal{U}_i are correctly computed. By correctness of Algorithm 5 in [33], we know that these multi-sets are glued together to obtain a multi-set \mathcal{U} containing all linear factors of one of the product gates S_2 of g (we are assuming that $g = S_1 + S_2$ where S_1, S_2 are product of linear forms and $x_i \mid S_1$ for $i \in [t]$.). Note that the algorithm only recovers all linear factors of S_2 and therefore it still needs to recover an appropriate scalar α (see algorithm) to completely recover S_2 . Note that $g_{|x_1=0}=S_{2|x_1=0}\neq 0$. Therefore we can compare the multi-set of linear forms in \mathcal{U}_1 with the multi-set of linear forms $\mathcal{U}' = \{\ell_{|_{x_1=0}} : \ell \in \mathcal{U}\}$. All linear forms will match up to scalar multiplication giving us the scalar α . By correctness of Corollary 28, we know that with probability 1 - o(1), we will be able to correctly factor $g - \alpha \prod_{\ell \in \mathcal{U}} \ell$ and collect them in multi-set \mathcal{V} . Finally at the end, we can apply Φ^{-1} and multiply by $\prod_{i=1}^t u_i^{t_i}$ and correctly recover the $\Sigma\Pi\Sigma(2,n,d,\mathbb{F})$ circuit with probability 1-o(1). Note that in Step 4, by correctness of Lemma 23, we know that we can deterministically check whether the constructed circuit is correct or not and only return a correct circuit. Now we discuss the time complexity of the above algorithm.

▶ Lemma 42. Algorithm 5 runs in time $(nd \log |\mathbb{F}|)^{O(1)}$ time.

Proof. Isomorphism Φ is constructed in $(n \log |\mathbb{F}|)^{O(1)}$ time. Time complexity of Corollary 28 implies that $(nd \log |\mathbb{F}|)^{O(1)}$ time is spent on factorizing $\Phi(f)$. Removing powers of $x_i, i \in [t]$ again requires scanning through the linear factors and takes $(nd \log |\mathbb{F}|)^{O(1)}$. Black-box

for $g = \Phi(f)/\prod_{i=1}^t x_i^{e_i}$ is then created by multiplying outputs of all the black-boxes for any input and therefore is also simulated in $(nd \log |\mathbb{F}|)^{O(1)}$ time. Therefore Step 1 takes $(nd \log |\mathbb{F}|)^{O(1)}$ time. Restrictions of black-box g to $x_i = 0, i \in [t]$ can be simulated by passing inputs through the restriction and therefore takes $(nd \log |\mathbb{F}|)^{O(1)}$ time. Time complexity of Corollary 28 implies that factorization of $g_{|x_i=0}$ can be done in $(nd \log |\mathbb{F}|)^{O(1)}$ time. Running time of Algorithm 5 in [33] is $(nd \log |\mathbb{F}|)^{O(1)}$ and therefore the multi-set \mathcal{U} is created in $(nd \log |\mathbb{F}|)^{O(1)}$ time. Therefore Step 2 takes $(nd \log |\mathbb{F}|)^{O(1)}$ time overall. Step 3 involves iterating through the linear forms in \mathcal{U} , restricting them to $x_1 = 0$, giving multi-set \mathcal{U}' , and then comparing the $d^{O(1)}$ sized multi-sets \mathcal{U}' and \mathcal{U} to obtain the appropriate scalar α . All these steps can be executed in polynomial time leading to a time complexity of $(nd \log |\mathbb{F}|)^{O(1)}$ for Step 3. Black-box computing polynomial $g - \alpha \prod_{\ell \in \mathcal{U}} \ell$ can be simulated in $(nd \log |\mathbb{F}|)^{O(1)}$ time by going through each of the involved (black-boxes) polynomials and then computing the output after algebraic operations. Time complexity of Corollary 28 implies that the factorization of this black-box can be done in $(nd \log |\mathbb{F}|)^{O(1)}$ time. Finally computing the black-box for f' and simulating black-box for f - f' can similarly be done in $(nd \log |\mathbb{F}|)^{O(1)}$ time. By time complexity of algorithm in Lemma 23, we know that in time $(nd \log |\mathbb{F}|)^{O(1)}$, we can deterministically test whether f - f' is the zero polynomial or not. Therefore Step 4 also takes time $(nd \log |\mathbb{F}|)^{O(1)}$. So, overall Algorithm 5 runs in time $(nd \log |\mathbb{F}|)^{O(1)}$.

3.4 Identify LI Set Dividing T_i

In this subsection, our goal is to prove a lemma (Lemma 44) that plays a crucial role in Algorithm 2 (explained in Section 1.4.2) in optimizing the search for a large **LI** set of linear forms dividing one of T_1, T_2 . As we mentioned earlier, [33] compute such an independent set by using a brute force search (Algorithm 4, [33]) on the space of linear forms over many variables, and therefore take quasi-polynomial time even before using this set in Algorithm 5 (of [33]). We significantly improve the search using candidate linear forms $\mathcal{L}(NonLin(f))$ and ordinary lines (see Definition 7) among them. First, in Section 3.4.1 below we give intuition about why set $\mathcal{L}(NonLin(f))$ approximates the set of linear factors of $T_1 \times T_2$ and then in Lemma 44, Section 3.4.2 use this set to construct the required **LI** set.

3.4.1 Candidate set approximates set of linear forms dividing T_1, T_2

In order to quantify how close the candidate set $\mathcal{L}(NonLin(f))$ is to the set of linear forms in the input circuit, we define some new sets.

$$\mathcal{L}_{good} = \{ \ell \in \mathcal{L}(NonLin(f)) : \ell \mid T_1 \times T_2 \}, \qquad \mathcal{L}_{bad} = \mathcal{L}(NonLin(f)) \setminus \mathcal{L}_{good},$$

$$\mathcal{L}_{others} = \{\ell \mid T_1 \times T_2 : sp(\ell) \cap \mathcal{L}(NonLin(f)) = \phi\} \quad \text{and} \quad \mathcal{L}_{factors} = \{\ell : \ell \mid T_1 + T_2\}$$

For all sets, we only keep linear forms upto scalar multiplication and therefore treat them as proper sets (Definition 6). \mathcal{L}_{good} contains all candidate linear forms which also divide one of the two gates T_1, T_2 . \mathcal{L}_{bad} are candidates which do not divide T_1 or T_2 . \mathcal{L}_{other} are linear forms dividing one of the gates but not captured (even up to scalar multiplication) in the candidate set and $\mathcal{L}_{factors}$ contain linear forms that divide $T_1 + T_2$. In the following claim, we show that \mathcal{L}_{good} is high dimensional and $\mathcal{L}_{bad}, \mathcal{L}_{other}$ are low dimensional quantifying the closeness of $\mathcal{L}(NonLin(f))$ to the set of linear forms dividing $T_1 \times T_2$. We also show that $\mathcal{L}_{factors}$ is low dimensional. For better exposition, proof is provided in Appendix A.

⇒ Claim 43. The following claim is true about these newly constructed sets.

- 1. $dim(sp(\mathcal{L}_{factors})) \leq \log d + 2$,
- 2. $dim(sp(\mathcal{L}_{good})) \geq rank(f) 2$,
- 3. $dim(sp(\mathcal{L}_{bad})) \leq \log d + 2$, and
- 4. $dim(sp(\mathcal{L}_{others})) \leq 2$.

3.4.2 Proof of Lemma 44

In this subsection, we prove Lemma 44 which was used by Algorithm 2. Recall the definition of the set of ordinary lines (Definition 7) and that $rank(f) = \Omega(\log^3 d)$.

▶ Lemma 44. *The following are true.*

- 1. $\exists \ \ell \in \mathcal{L}_{good} \ such that the set of linear forms \ \ell' \in \mathcal{L}(NonLin(f)) \setminus \{\ell\} \ for which sp\{\ell,\ell'\} \ intersects \ \mathcal{L}(NonLin(f)) \ only \ at \ \{\ell,\ell'\} \ (i.e. \ sp\{\ell,\ell'\} \ is \ an \ ordinary \ line into \ \mathcal{L}(NonLin(f))), \ spans \ a \ space \ of \ dimension \ at \ least \ \Omega(\log^2 d). \ Let \ \mathcal{X} \ be \ some \ maximal \ independent \ subset \Rightarrow |\mathcal{X}| = \Omega(\log^2 d).$
- 2. Every partition of \mathcal{X} into $\Omega(\log d)$ equal parts of size $\Omega(\log d)$ each, contains a part \mathcal{B} such that $\mathcal{B} \subset \mathcal{L}_{good}$ and $\forall \ell' \in \mathcal{B}$, $sp\{\ell,\ell'\}$ is an ordinary line into $\mathcal{L}_{good}, \mathcal{L}_{bad}, \mathcal{L}_{others}, \mathcal{L}_{factors}$.
- **3.** Let $\ell' \in \mathcal{B}$ and assume $\ell \mid T_i$. Let Φ be an isomorphism mapping $\ell \mapsto x_1, \ell' \mapsto x_2$, then, $\Phi(NonLin(f))_{|x_1=0,x_2=0} = 0 \Leftrightarrow \ell' \text{ divides } T_{3-i}$.

Proof. We prove all parts one by one.

1. Let $\mathcal{T} \subset \mathcal{L}_{good}$ be a **LI** set of size $126 \log d + 2$ (exists by Claim 43). Applying Proposition 5 on $\mathcal{L}(NonLin(f))$ and \mathcal{T} implies that $\exists \ell \in \mathcal{T}$ such that

$$dim(\sum_{W \in \mathcal{O}(\ell, \mathcal{L}(NonLin(f)))} W) \ge \frac{dim(sp(\mathcal{L}(NonLin(f))))}{126 \log d + 2} \ge \frac{dim(sp(\mathcal{L}_{good}))}{126 \log d + 2} = \Omega(\log^2 d)$$

Thus, the set of linear forms $\ell' \in \mathcal{L}(NonLin(f)) \setminus \{\ell\}$ for which $sp\{\ell,\ell'\}$ intersects $\mathcal{L}(NonLin(f))$ only at $\{\ell,\ell'\}$, spans a space of dimension at least $\Omega(\log^2 d)$. Let \mathcal{X} be a maximal independent subset $\Rightarrow |\mathcal{X}| = \Omega(\log^2 d)$.

- 2. Consider any partition of \mathcal{X} into $\Omega(\log d)$ parts of size $\Omega(\log d)$ each. We first claim that $\Omega(\log d)$ parts in \mathcal{X} are inside \mathcal{L}_{good} . If not, then $\Omega(\log d)$ parts intersect $\mathcal{L}_{bad} \Rightarrow dim(sp(\mathcal{L}_{bad})) = \Omega(\log d)$, contradicting Claim 43. Now we only deal with these $\Omega(\log d)$ parts inside \mathcal{L}_{good} . Since \mathcal{L}_{good} , $\mathcal{L}_{bad} \subset \mathcal{L}(NonLin(f))$, we see that $\forall \ell'$ in any of these parts, $sp\{\ell,\ell'\}$ is an ordinary line in \mathcal{L}_{good} , \mathcal{L}_{bad} as required. Next we show that out of the $\Omega(\log d)$ parts inside \mathcal{L}_{good} , \exists a part \mathcal{B} such that $\forall \ell' \in \mathcal{B}$, $sp\{\ell,\ell'\}$ is an ordinary line in \mathcal{L}_{others} , $\mathcal{L}_{factors}$, thereby completing the proof. If not, then $\exists \Omega(\log d)$ many ℓ' s, each belonging to a different part among the $\Omega(\log d)$ parts, such that $sp\{\ell,\ell'\}$ intersects $\mathcal{L}_{others} \cup \mathcal{L}_{factors}$ at a linear form outside $sp\{\ell\} \cup sp\{\ell'\}$ say ℓ'' . Since all the $\Omega(\log d)$ ℓ' s are independent, the ℓ'' s span a space of dimension $\Omega(\log d) \Rightarrow dim(sp(\mathcal{L}_{others} \cup \mathcal{L}_{factors})) = \Omega(\log d)$, contradicting Claim 43.
- **3.** Since $\ell \mid T_i$, we know that $x_1 \mid \Phi(T_i)$. Therefore, the following equation holds:

$$\Phi(L)_{|x_1=0,x_2=0}\Phi(NonLin(f))_{|x_1=0,x_2=0}=\Phi(T_i)_{|x_1=0,x_2=0}+\Phi(T_{3-i})_{|x_1=0,x_2=0}=\Phi(T_{3-i})_{|x_1=0,x_2=0}.$$

Here L is the product of all linear factors of $T_1 + T_2$ i.e. $L = Lin(T_1 + T_2)$. First, we assume that $\Phi(NonLin(f))_{|x_1=0,x_2=0} = 0$. This implies using the above equation that $\Phi(T_{3-i})_{|x_1=0,x_2=0} = 0$. Therefore there is a linear form $\ell'' \mid T_{3-i}$ such that $\ell'' \in sp\{\ell,\ell'\}$. If ℓ'' is not a scalar multiple of ℓ or ℓ' , by construction of ℓ , ℓ' in parts 1 and 2 of this

lemma, we know that no scalar multiple of ℓ'' can belong to \mathcal{L}_{good} or \mathcal{L}_{others} and therefore it cannot divide $T_1 \times T_2$ which is a contradiction since it divides T_{3-i} . Therefore, ℓ'' has to be a scalar multiple of ℓ or ℓ' . It cannot be scalar multiple of ℓ since $\ell \mid T_i$ and $gcd(T_i, T_{3-i}) = 1$. Therefore ℓ'' and ℓ' are scalar multiples implying that ℓ' divides T_{3-i} as needed. Next, for the converse, we assume that $\ell' \mid T_{3-i}$. Again, using the equation we gave at the beginning of this part, we get that,

$$\Phi(L)_{|x_1=0,x_2=0}\Phi(NonLin(f))_{|x_1=0,x_2=0} = \Phi(T_i)_{|x_1=0,x_2=0} + \Phi(T_{3-i})_{|x_1=0,x_2=0} = 0.$$

Therefore, since $\mathbb{F}[x_3,\ldots,x_n]$ is an integral domain, either polynomial $\Phi(L)_{|x_1=0,x_2=0}=0$ or polynomial $\Phi(NonLin(f))_{|x_1=0,x_2=0}=0$. Assume that $\Phi(L)_{|x_1=0,x_2=0}=0$. This implies that there is some linear factor ℓ'' of T_1+T_2 such that $\ell''\in sp\{\ell,\ell'\}$. Since $gcd(T_1,T_2)=1$ and $\ell\mid T_i,\ell'\mid T_{3-i}$, the linear form ℓ'' cannot be a scalar multiple of ℓ or ℓ' . So we found a linear form on $sp\{\ell,\ell'\}$ different from scalar multiples of ℓ , ℓ' , such that some scalar multiple of ℓ'' belongs to $\mathcal{L}_{factors}$. By construction of ℓ , ℓ' in parts 1 and 2 of this lemma, we know that this cannot hold. Therefore our assumption is wrong and polynomial $\Phi(NonLin(f))_{|x_1=0,x_2=0}=0$ completing the proof.

4 Proof of Proposition 5

In this section we prove Proposition 5. Part 1 is proved in Section 4.1. Algorithm for Part 2 is presented in Algorithm 6 and its correctness/complexity are analyzed in Section 4.2.

4.1 Proof of Part 1

Let $W=\mathbb{V}(\ell,\ell')\subset\mathbb{F}^n$ be a co-dimension 2 subspace on which NonLin(f) vanishes i.e. $W\in\mathcal{S}(NonLin(f))$. Let Φ be an isomorphism mapping $\ell\mapsto x_1,\ell'\mapsto x_2$. Since NonLin(f) divides T_1+T_2 we get that $\Phi(T_1)_{|x_1=0,x_2=0}+\Phi(T_2)_{|x_1=0,x_2=0}=0$. This implies that either $\Phi(T_1)_{|x_1=0,x_2=0}=\Phi(T_2)_{|x_1=0,x_2=0}=0$, or $\Phi(T_1)_{|x_1=0,x_2=0}=-\Phi(T_2)_{|x_1=0,x_2=0}\neq 0$. We prove the following lemma which implies the bound.

▶ Lemma 45. The following are true.

- 1. $\#\{W \in \mathcal{S}(NonLin(f)) : \Phi(T_1)_{|_{x_1=0,x_2=0}} = \Phi(T_2)_{|_{x_1=0,x_2=0}} = 0\} \le d^2.$ 2. $\#\{W \in \mathcal{S}(NonLin(f)) : \Phi(T_1)_{|_{x_1=0,x_2=0}} = -\Phi(T_2)_{|_{x_1=0,x_2=0}} \ne 0\} \le d^5 + d^7.$
- **Proof.** First we prove 1. The statement implies that there are linear forms $\ell_1 \mid T_1$ and $\ell_2 \mid T_2$ such that $\Phi(\ell_1)_{\mid_{x_1=0,x_2=0}} = \Phi(\ell_2)_{\mid_{x_1=0,x_2=0}} = 0$. Also, ℓ_1,ℓ_2 are **LI** since $\gcd(T_1,T_2) = 1$ implying that $sp\{\Phi(\ell_1),\Phi(\ell_2)\} = sp\{x_1,x_2\}$. On inverting via Φ this implies that $sp\{\ell_1,\ell_2\} = sp\{\ell,\ell'\}$, which further implies that $\mathbb{V}(\ell_1,\ell_2) = \mathbb{V}(\ell,\ell') = W$. There can be at most d^2 such d^2 such
- ▶ Lemma 46. There exists a set \mathcal{A} of co-dimension 1 subspaces of \mathbb{F}^n with $|\mathcal{A}| \leq d^4 + d^6$ such that for every $W \in \mathcal{S}(NonLin(f))$ satisfying $\Phi(T_1)_{|_{x_1=0,x_2=0}} = -\Phi(T_2)_{|_{x_1=0,x_2=0}} \neq 0$, $\exists \ V \in \mathcal{A} \ with \ W \subset V$.

Assuming Lemma 46, we complete the proof as follows. For every $W \in \mathcal{S}(NonLin(f))$ satisfying $\Phi(T_1)_{|x_1=0,x_2=0} = -\Phi(T_2)_{|x_1=0,x_2=0} \neq 0$, we consider the co-dimension 1 subspace V given by Lemma 46 such that $W \subset V$. Without loss of generality we assume $V = \mathbb{V}(x_1)$. We can now find a linear form ℓ_3 such that $W = \mathbb{V}(x_1,\ell_3)$ and coeffcient of x_1 in ℓ_3 is 0 i.e. $\ell_3 = \ell_3|_{x_1=0}$. Since NonLin(f) vanishes on W we know that $\Psi(NonLin(f))|_{x_1=0,x_2=0}$ for isomorphism Ψ

Algorithm 6 Compute co-dimension 2 subspaces on which NonLin(f) vanishes.

Input - Black-box access to polynomial f, integers n, d. **Output** - A set S of tuples of independent linear forms in $\mathbb{F}[x_1, \ldots, x_n]$.

- 1. Create n linear forms $\hat{\ell}_1, \ldots, \hat{\ell}_n$, such that the n^2 scalars used as coefficients in them are sampled uniformly randomly independently from \mathbb{F} . If these linear forms are $\mathbf{L}\mathbf{I}$, define isomorphism Φ mapping $x_i \mapsto \hat{\ell}_i, i \in [n]$. Simulate black-box for $g = \Phi(f)$. For $i \in [5, n]$, simulate black-box access for the polynomials $g_i = g_{|x_5=0,\ldots,x_{i-1}=0,x_{i+1}=0,\ldots,x_n=0} \in \mathbb{F}[x_1,x_2,x_3,x_4,x_i]$. Next, for each $i \in [5,n]$ using Corollary 28 with inputs as black-box access to g_i along with integers 5,d obtain black-box access to $NonLin(g_i)$ and integer s denoting the number of linear factors of g_i . Define t=d-s. Using multivariate interpolation (Lemma 25), interpolate $NonLin(g_i)$ as a degree t polynomial in the monomial basis of $\mathbb{F}[x_1,x_2,x_3,x_4,x_i]$.
- 2. Substitute $x_1 = y_3x_3 + y_4x_4 + y_ix_i$, and $x_2 = z_3x_3 + z_4x_4 + z_ix_i$ in $NonLin(g_i)$ to obtain a polynomial in $\mathbb{F}[y_3, y_4, y_i, z_3, z_4, z_i][x_3, x_4]$. Find common solutions to the system of polynomial equations defined by setting all coefficient polynomials $(\in \mathbb{F}[y_3, y_4, y_i, z_3, z_4, z_i])$ to zero. Initialize a set $\mathcal{S}_i \leftarrow \phi$ and for each solution $(y_3, y_4, y_i, z_3, z_4, z_i)$ of the system above add tuple $(x_1 y_3x_3 y_4x_4 y_ix_i, x_2 z_3x_3 z_4x_4 z_ix_i)$ to \mathcal{S}_i .
- 3. Construct isomorphism Δ mapping $x_1 \mapsto x_1, x_2 \mapsto x_2, x_3 \mapsto x_3, x_4 \mapsto x_4$ and for $i \in [5.n]$, $x_i \mapsto x_i + \alpha_{i,3}x_3 + \alpha_{i,4}x_4$. The scalars $\alpha_{i,3}, \alpha_{i,4}, i \in [5, n]$ are sampled uniformly randomly independently from \mathbb{F} . Note that Δ can be viewed as an isomorphism on $\mathbb{F}[x_1, \dots, x_n]$ as well as on each $\mathbb{F}[x_1, x_2, x_3, x_4, x_i]$ for $i \in [5, n]$.
- 4. Initialize a set $\mathcal{S} \leftarrow \phi$. Iterate over all tuples $(x_1 \ell_1^5, x_2 \ell_2^5) \in \mathcal{S}_5$. Initialize $\ell_1 \leftarrow \ell_1^5, \ell_2 \leftarrow \ell_2^5$. Iterate over $i \in [6, n]$. Search for tuple $(x_1 \ell_1^i, x_2 \ell_2^i) \in \mathcal{S}_i$ such that tuples $(x_1 \Delta(\ell_1^5)_{|x_5=0}, x_2 \Delta(\ell_2^5)_{|x_5=0}) = (x_1 \Delta(\ell_1^i)_{|x_i=0}, x_2 \Delta(\ell_2^i)_{|x_i=0})$. If multiple or none such tuples are found in \mathcal{S}_i then break out of this loop and go to the next tuple in the outer iteration. If only one such tuple is found then update $\ell_1 \leftarrow \ell_1 \alpha x_i$ and $\ell_2 \leftarrow \ell_2 \beta x_i$ where α, β are coefficients of x_i in $x_1 \ell_1^i, x_2 \ell_2^i$ respectively. At the end of iteration on i, update $\mathcal{S} \leftarrow \mathcal{S} \cup \{(x_1 \ell_1, x_2 \ell_2)\}$.
- 5. For each $(\ell_1,\ell_2) \in \mathcal{S}$, construct isomorphism Ψ mapping $\ell_1 \mapsto x_1,\ell_2 \mapsto x_2$. Simulate black-box access to polynomial $\Psi(NonLin(g))|_{x_1=0,x_2=0}$. Using randomized polynomial identity test given in Lemma 22 with input as the above black-box and integer n, check if it is identically the zero polynomial. If 'no', remove the tuple from \mathcal{S} , else replace it with $(\Phi^{-1}(\ell_1), \Phi^{-1}(\ell_2))$. Return \mathcal{S} .

mapping $x_1 \mapsto x_1, \ell_3 \mapsto x_2$. This also implies that x_2 divides $\Psi(NonLin(f))_{|x_1=0}$. Since Ψ keeps x_1 fixed this polynomial is same as $\Psi(NonLin(f)_{|x_1=0})$. Inverting Ψ we get that ℓ_3 divides $NonLin(f)_{|x_1=0}$. There are at most d linear factors (upto scalar multiplication) of any degree d polynomial, thus there are $\leq d$ such possible ℓ_3 . By going ever all choices of V we get that there are at most $(d^4 + d^6) \times d$ many such W, completing our proof.

4.2 Analysis of Algorithm 6

Before going to the correctness of Algorithm 6, we state a few useful lemmas. These are repeatedly used in our correctness and time complexity proofs.

- **Lemma 47.** With probability 1 o(1) over random choices in Step 1, the following hold.
- 1. $\hat{\ell}_1, \dots \hat{\ell}_n$ constructed in Step 1 are LI.
- **2.** NonLin(f) vanishes on $\mathbb{V}(\ell_1, \ell_2)$ iff NonLin(g) vanishes on $\mathbb{V}(\Phi(\ell_1), \Phi(\ell_2))$.

- **3.** Polynomial g_i has a $\Sigma\Pi\Sigma(2,5,d,\mathbb{F})$ circuit and $rank(g_i)=5$.
- 4. $NonLin(g_i) = NonLin(g)|_{x_5=0,\dots,x_{i-1}=0,x_{i+1}=0,\dots,x_{n=0}}$
- **5.** $\forall \ \mathbb{V}(\ell_1,\ell_2) \in \mathcal{S}(NonLin(g)), \ \exists \ linear \ forms \ \ell'_1,\ell'_2 \in \mathbb{F}[x_3,\ldots,x_n] \ such \ that \ \mathbb{V}(\ell_1,\ell_2) = \mathbb{V}(x_1-\ell'_1,x_2-\ell'_2).$
- **6.** Let $\mathbb{V}(x_1 \ell_1, x_2 \ell_2) \in \mathcal{S}(NonLin(g))$ with $\ell_1, \ell_2 \in \mathbb{F}[x_3, \dots, x_n]$. Then, $NonLin(g_i)$ vanishes on the co-dimension 2 subspace $\mathbb{V}(x_1 \ell_1^i, x_2 \ell_2^i)$. Here $\ell_j^i = \ell_j|_{x_5=0,\dots,x_{i-1}=0,x_{i+1}=0,\dots,x_n=0}$.
- ▶ **Lemma 48.** With probability 1 o(1) over the random choices in Step 3, the following holds. $\forall i \in [5, n]$ and \forall pairs of distinct tuples $(x_1 \ell_1, x_2 \ell_2)$, $(x_1 \ell'_1, x_2 \ell'_2)$ in S_i , $(x_1 \Delta(\ell_1)_{|x_i=0}, x_2 \Delta(\ell_2)_{|x_i=0}) \neq (x_1 \Delta(\ell'_1)_{|x_i=0}, x_2 \Delta(\ell'_2)_{|x_i=0})$.

For better presentation we prove these lemmas in Appendix C. Now, we prove correctness of Algorithm 6. By Part 1 of Lemma 47, the linear forms constructed in Step 1 are LI and therefore isomorphism Φ can be correctly constructed using them. Using this isomorphism, simulation of black-box for g (by passing every input through the isomorphism) is straight forward. Further simulation of black-boxes computing the q_i s is also straight forward (by setting $x_5 = 0, \dots, x_{i-1} = 0, x_{i+1} = 0, \dots, x_n = 0$ in the input to black-box). From Parts 4,5 of Lemma 47, we know that g_i exhibits $\Sigma \Pi \Sigma(2,5,d,\mathbb{F})$ circuit of rank 5 and $NonLin(g_i) = NonLin(g)_{|x_5=0,\dots,x_{i-1}=0,x_{i+1}=0,\dots,x_n=0}$, implying that all g_i and g have the same number of linear factors s and degree of all polynomials $NonLin(g_i)$ are equal (=t) which is also the same as degree of NonLin(q). By correctness of Algorithm 1, with probability 1 - o(1), Step 1 correctly obtains black-box computing $NonLin(g_i)$ and its degree t. Since all g_i are 5- variate using deterministic multivariate interpolation (Lemma 25), we can interpolate their black-boxes as degree t polynomials in the monomial basis of $\mathbb{F}[x_1, x_2, x_3, x_4, x_i]$. Therefore, at the end of Step 1, we would have correct monomial representations of all the g_i . Next, using Part 5 of Lemma 47, we know that any codimension 2 subspace on which NonLin(g) vanishes has the form $\mathbb{V}(x_1-\ell_1,x_2-\ell_2)$ with $\ell_1, \ell_2 \in \mathbb{F}[x_3, \dots, x_n]$. In Part 6 of Lemma 47, we show that $NonLin(g_i)$ vanishes on the co-dimension 2 space $\mathbb{V}(x_1 - \ell_1^i, x_2 - \ell_2^i)$, where for $j \in [2]$ and $i \in [5, n]$, ℓ_j^i are restrictions of ℓ_j to $x_5 = 0, \dots, x_{i-1} = 0, x_{i+1} = 0, \dots, x_n = 0$. Since these co-dimension 2 subspaces have the particular form $\mathbb{V}(x_1 - \ell_1^i, x_2 - \ell_2^i)$, substituting $x_1 = \ell_1^i, x_2 = \ell_2^i$ in $NonLin(g_i)$ should give 0. Step 2 uses this observation and computes all possible ℓ_1^i, ℓ_2^i by solving the system of polynomial equations we get on substitution. By correctness of Lemma 20, we can compute all such solutions. Therefore, the set S_i contain tuples corresponding to all co-dimension 2 spaces of the form $\mathbb{V}(x_1-u_1,x_2-u_2)$ (with linear forms $u_1,u_2\in\mathbb{F}[x_3,x_4,x_i]$) on which $NonLin(g_i)$ vanishes. In the next lemma, we show that these S_i are then glued in Steps 3 and 4 to create set S which contains tuples corresponding to elements of S(NonLin(f)).

▶ **Lemma 49.** Step 4 outputs a set S, such that with probability 1 - o(1), it contains tuples of linear forms representing all co-dimension 2 subspaces on which NonLin(g) vanishes.

Proof. Let $\mathbb{V}(x_1-\ell_1,x_2-\ell_2)\in\mathcal{L}(NonLin(g))$. By Part 6 of Lemma 47 we know that $NonLin(g_i)$ vanishes on the co-dimension 2 subspace $\mathbb{V}(x_1-\ell_1^i,x_2-\ell_2^i)$ where for $j\in[2]$, $\ell_j^i=\ell_j|_{x_5=0,\dots,x_{i-1}=0,x_{i+1}=0,\dots,x_n=0}$. Therefore the tuples $(x_1-\ell_1^i,x_2-\ell_2^i)$ belong to \mathcal{S}_i computed at Step 2. Observe that, for $i\in[6,n]$ we glue tuple $(x_1-\ell_1^5,x_2-\ell_2^5)$ with tuple $(x_1-\ell_1^i,x_2-\ell_2^i)$ only if the latter is the only tuple in \mathcal{S}_i satisfying, $(x_1-\Delta(\ell_1^5)_{|x_5=0},x_2-\Delta(\ell_2^5)_{|x_5=0})=(x_1-\Delta(\ell_1^i)_{|x_i=0},x_2-\Delta(\ell_2^i)_{|x_i=0})$. Here Δ is the isomorphism constructed in Step 3. So all we need to show is that, there is no other tuple $(x_1-\ell_1^{i'},x_2-\ell_2^{i'})\in\mathcal{S}_i$ with $\ell_1^{i'},\ell_2^{i'}$ being linear forms in $\mathbb{F}[x_3,x_4,x_i]$ such that, $x_1-\Delta(\ell_1^5)_{|x_5=0}=x_1-\Delta(\ell_1^{i'})_{|x_i=0}$ and x_2-

 $\Delta(\ell_2^5)_{|x_5=0} = x_2 - \Delta(\ell_2^{i'})_{|x_i=0}.$ If there was such a tuple, comparing the equations above gives $(x_1 - \Delta(\ell_1^i)_{|x_i=0}, x_2 - \Delta(\ell_2^i)_{|x_i=0}) = (x_1 - \Delta(\ell_1^{i'})_{|x_i=0}, x_2 - \Delta(\ell_2^{i'})_{|x_i=0}), \text{ which contradicts Lemma 48. Therefore tuple } (x_1 - \ell_1^5, x_2 - \ell_2^5) \text{ gets correctly glued with each such tuple } (x_1 - \ell_1^i, x_2 - \ell_2^i) \text{ for } i \in [6, n] \text{ leading to construction of tuple } (x_1 - \ell_1, x_2 - \ell_2) \text{ which is added to } \mathcal{S}.$

Assuming we correctly glued the S_i into set S, Step 5, only retains tuples for which NonLin(g) actually vanishes on the corresponding co-dimension 2 subspace. By correctness of Lemma 22, this is done correctly and only the right tuples are retained. By Part 1 of Lemma 47, in order to get set S(NonLin(f)) from S(NonLin(g)), we only need to invert all linear forms present in the elements (tuples) of S. Therefore, with probability 1 - o(1), the set of tuples representing co-dimension 2 subspaces on which NonLin(f) vanishes is correctly computed.

▶ **Lemma 50.** Algorithm 6 runs in $(nd \log |\mathbb{F}|)^{O(1)}$ time.

Proof. Assuming that sampling of a uniformly random scalar from \mathbb{F} takes O(1) time, the n linear forms are created in $(n \log |\mathbb{F}|)^{O(1)}$ time. Checking whether the linear are independent can be done in $(n \log |\mathbb{F}|)^{O(1)}$ time by gaussian elimination on the matrix defined by the n^2 coefficients of these linear forms. Black-boxes for g and g_i are simulated in $(n \log |\mathbb{F}|)^{O(1)}$ time by passing each input through Φ and then restricting to $x_5 = 0, \ldots, x_{i-1} = 0, x_{i+1} = 0, \ldots, x_n = 0$. Time complexity of Corollary 28 implies that black-box access to all $NonLin(q_i)$ along with their degrees t = d - s can be obtained in $(nd \log |\mathbb{F}|)^{O(1)}$ time. Multivariate interpolation (Lemma 25) on the 5 variate polynomials of degree t each is done in $(nd \log |\mathbb{F}|)^{O(1)}$ time. Therefore Step 1 takes $(nd \log |\mathbb{F}|)^{O(1)}$ time. Each g_i has $d^{O(1)}$ non-zero coefficients in the monomial representation. Substitutions lead to $d^{O(1)}$ many coefficient polynomials in $\mathbb{F}[y_3, y_4, y_i, z_3, z_4, z_i]$ with every polynomial having degree $d^{O(1)}$. By Part 2 of Lemma 47, every g_i has a $\Sigma\Pi\Sigma(2,5,d,\mathbb{F})$ circuit and has rank 5, therefore, by Part 1 of Proposition 5, number of co-dimension 2 subspaces on which they vanish are $d^{O(1)}$. Therefore our system of equations has at most $d^{O(1)}$ solutions since they characterize such co-dimension 2 subspaces of a certain form. By time complexity of Lemma 20, for each g_i all solutions to such a system can be computed in $(d \log |\mathbb{F}|)^{O(1)}$ time leading to \mathcal{S}_i . Therefore in time $(nd \log |\mathbb{F}|)^{O(1)}$ time all S_i are computed in Step 2. Step 3 involves sampling O(n) many uniformly random scalars and construction of the isomorphism Δ can be done in $(n \log |\mathbb{F}|)^{O(1)}$ time. In Step 4, we iterate over all tuples in S_5 and then iterate over $i \in [6, n]$ trying to match our tuple with tuples in the S_i . Since each tuple in S_5 is matched to at most one tuple in each S_i , for each tuple in S_5 , we go over all the set $S_i, i \in [6, n]$ just once. Therefore, overall we take $(nd \log |\mathbb{F}|)^{O(1)}$ time in this step. Also, since each tuple in \mathcal{S}_5 , creates at most one tuple $(x_1 - \ell_1, x_2 - \ell_2)$ to be added to S, we create at most $d^{O(1)}$ such tuples leading to $|\mathcal{S}| = d^{O(1)}$. In Step 5, for each tuple in \mathcal{S} , construction of isomorphism Ψ and black-box access to $\Psi(NonLin(g))_{|_{x_1=0,x_2=0}}$ can be created in $(nd \log |\mathbb{F}|)^{O(1)}$ time. By time complexity of algorithm in Lemma 22, in time $(nd \log |\mathbb{F}|)^{O(1)}$ we can check whether this black-box computes the 0 polynomial or not. Finally application of Φ^{-1} to tuples in \mathcal{S} can be done in $(nd \log |\mathbb{F}|)^{O(1)}$ time. Our final set returned has size $d^{O(1)}$ as it is a subset of the set we created in Step 4. Therefore, overall Algorithm 6 takes $(nd \log |\mathbb{F}|)^{O(1)}$ time.

5 Proof of Proposition 8

Proof of Proposition 8 follows from Lemma 51 which in turn is proved using Lemma 52. Recall definition of set of ordinary lines (Definition 7).

▶ Lemma 51. Let $S \subset \mathbb{F}^n$ be a proper set (Definition 6) and $\mathcal{T} \subset \mathbb{F}^n$ be any LI set of size $\log |S| + 2$. Then, $sp(S) \subseteq \sum_{t \in \mathcal{T}} \sum_{W \in \mathcal{O}(t,S)} W$.

▶ Lemma 52. Let $S(\neq \phi) \subset \mathbb{F}^n$ be a proper set and $\mathcal{T} \subset \mathbb{F}^n$ be LI such that for every $t \in \mathcal{T}$, there is no ordinary line (Definition 7) from t into S. Then $|\mathcal{T}| \leq \log |\mathcal{S}| + 1$.

By taking dimension of both sides in the containment $sp(S) \subseteq \sum_{t \in \mathcal{T}} \sum_{W \in \mathcal{O}(t,S)} W$, applying union bound on the **RHS** and assuming $t \in \mathcal{T}$ maximizes $dim(\sum_{W \in \mathcal{O}(t,S)} W)$, we get $dim(\sum_{W \in \mathcal{O}(t,S)} W) \ge \frac{dim(sp(S))}{\log |S| + 2}$, which proves Proposition 8. Therefore, we prove Lemma 51 next.

Proof of Lemma 51. Let V be the vector space $\sum_{t \in \mathcal{T}} \sum_{W \in \mathcal{O}(t,\mathcal{S})} W$. We define set $\mathcal{S}' = \mathcal{S} \setminus V$. \mathcal{S}' is a proper set. We will show that $\mathcal{S}' = \phi \Rightarrow sp(\mathcal{S}) \subset V$. If not, we show that there cannot be any ordinary line from \mathcal{T} into \mathcal{S}' . Suppose there is some such line $sp\{t,s\}$ where $t \in \mathcal{T}$ and $s \in \mathcal{S}'$ are not scalar multiples. Since it is an ordinary line into \mathcal{S}' , we get that $sp\{s,t\} \cap \mathcal{S}' \subset sp\{s\} \cup sp\{t\}$. Now, if $sp\{s,t\} \cap V \subset sp\{s\} \cup sp\{t\}$, then $\mathcal{S} = \mathcal{S}' \cup (\mathcal{S} \cap V) \Rightarrow sp\{s,t\} \cap \mathcal{S} \subset sp\{s\} \cup sp\{t\}$. Therefore it is an ordinary line into \mathcal{S} . But all such lines are subsets of $V \Rightarrow s \in V$ which is a contradiction since $s \in \mathcal{S}'$ which is disjoint from V. In the other case (i.e. $sp\{s,t\} \cap V \not\subset sp\{s\} \cup sp\{t\}$), there is some $v \in sp\{s,t\} \cap V$ such that $v \notin sp\{s\} \cup sp\{t\}$. Therefore t, s, v are t D but t, s and s, v are not t so t so t which is disjoint from t into t so t so t which is again a contradiction since t spaces t into t such that t spaces t such that t spaces t spaces

Proof of Lemma 52. Let $|\mathcal{T}| = d$ and $|\mathcal{S}| = m$. We present a counting argument by building a one-to-one function mapping subsets of [d-1] into \mathcal{S} . Such a function implies that $m \geq 2^{d-1}$ and we'll be done. To construct such a function, fix $s \in \mathcal{S}$ and let $\mathcal{T} = \{t_1, \ldots, t_d\}$. Without loss of generality assume that s, t_1, \ldots, t_{d-1} are **LI**. For **LI** vectors $u_1, \ldots, u_m \in \mathbb{F}^n$, we say that $u \in \mathbb{F}^n$ is in the interior of $sp\{u_1, \ldots, u_m\}$, if there exist non zero $\alpha_i \in \mathbb{F}$, $i \in [m]$, such that $u = \alpha_1 u_1 + \ldots + \alpha_m u_m$. We use the following claim.

 \triangleright Claim 53. For any $\mathcal{P} \subset [d-1], \exists s_{\mathcal{P}} \in \mathcal{S}$, in the interior of $sp\{\{t_i : i \in \mathcal{P}\} \cup \{s\}\}\}$.

We can see that the function mapping $\mathcal{P} \subset [d-1]$ to $s_{\mathcal{P}} \in \mathcal{S}$, is one-to-one since for sets $\mathcal{P}, \mathcal{Q} \subset [d-1]$, which differ at some $j \in [d-1]$, exactly one of $s_{\mathcal{P}}, s_{\mathcal{Q}}$ has a non-zero coefficient of t_j , implying they are different. This completes the proof.

Proof of Claim 53. We prove by induction on $|\mathcal{P}|$. For $|\mathcal{P}| = 0$, define $s_{\mathcal{P}} = s$ and we are done. Lets assume the claim is true for $|\mathcal{P}| = k - 1$. We prove it for $|\mathcal{P}| = k$. Consider any element $p \in \mathcal{P}$ and let $\mathcal{R} = \mathcal{P} \setminus \{p\}$. By induction, we know $\exists s_{\mathcal{R}}$ in the interior of $sp\{\{t_i : i \in \mathcal{R}\} \cup \{s\}\}$. Since there is no ordinary line from any $t \in \mathcal{T}$ into \mathcal{S} , the line $sp\{t_p, s_{\mathcal{R}}\}$ contains $s_{\mathcal{P}} \in \mathcal{S}$ such that $s_{\mathcal{P}} \notin sp\{t_p\} \cup sp\{s_{\mathcal{R}}\} \Rightarrow s_{\mathcal{P}} = \alpha t_p + \beta s_{\mathcal{R}}$ with $\alpha, \beta \in \mathbb{F}$ being non-zero scalars $\Rightarrow s_{\mathcal{P}}$ is in the interior of $sp\{\{t_i : i \in \mathcal{P}\} \cup \{s\}\}$.

References

Eric Allender and Shuichi Hirahara. New insights on the (non-)hardness of circuit minimization and related problems. *ACM Trans. Comput. Theory*, 11(4), September 2019. doi:10.1145/3349616.

- 2 Dana Angluin. Queries and concept learning. Mach. Learn., 2(4):319–342, April 1988. doi:10.1023/A:1022821128753.
- Boaz Barak, Zeev Dvir, Avi Wigderson, and Amir Yehudayoff. Rank bounds for design matrices with applications to combinatorial geometry and locally correctable codes. In *Proceedings of the Forty-Third Annual ACM Symposium on Theory of Computing*, STOC '11, pages 519–528, New York, NY, USA, 2011. Association for Computing Machinery. doi:10.1145/1993636.1993705.
- 4 Vishwas Bhargava, Shubhangi Saraf, and Ilya Volkovich. Reconstruction algorithms for low-rank tensors and depth-3 multilinear circuits. *CoRR*, abs/2105.01751, 2021. arXiv:2105.01751.
- 5 Enrico Carlini. Reducing the number of variables of a polynomial. In Mohamed Elkadi, Bernard Mourrain, and Ragni Piene, editors, *Algebraic Geometry and Geometric Modeling*, pages 237–247, Berlin, Heidelberg, 2006. Springer Berlin Heidelberg.
- 6 Zeev Dvir. Incidence theorems and their applications. Foundations and Trends® in Theoretical Computer Science, 6(4):257–393, 2012. doi:10.1561/0400000056.
- 7 Zeev Dvir and Amir Shpilka. Locally decodable codes with 2 queries and polynomial identity testing for depth 3 circuits. In *Proceedings of the Thirty-Seventh Annual ACM Symposium on Theory of Computing*, STOC '05, pages 592–601, New York, NY, USA, 2005. Association for Computing Machinery. doi:10.1145/1060590.1060678.
- 8 Shuhong Gao, Erich Kaltofen, and Alan G.B. Lauder. Deterministic distinct-degree factorization of polynomials over finite fields. *Journal of Symbolic Computation*, 38(6):1461–1470, 2004. doi:10.1016/j.jsc.2004.05.004.
- 9 Ankit Garg, Neeraj Kayal, and Chandan Saha. Learning sums of powers of low-degree polynomials in the non-degenerate case. In 2020 IEEE 61st Annual Symposium on Foundations of Computer Science (FOCS), pages 889–899, 2020. doi:10.1109/F0CS46700.2020.00087.
- Shafi Goldwasser and Silvio Micali. Probabilistic encryption. *Journal of Computer and System Sciences*, 28(2):270–299, 1984. doi:10.1016/0022-0000(84)90070-9.
- Ankit Gupta, Neeraj Kayal, and Satyanarayana V. Lokam. Reconstruction of depth-4 multilinear circuits with top fan-in 2. In *Proceedings of the 44th Symposium on Theory of Computing Conference, STOC 2012, New York, NY, USA, May 19 22, 2012*, pages 625–642, 2012. doi:10.1145/2213977.2214035.
- M. M. Kapranov I. M. Gelfand and A. Zelevinsky. Discriminants, resultants and multidimensional determinants. The Mathematical Gazette, 79(485):439-440, 1995. doi:10.2307/3618356.
- Douglas John Ierardi. The Complexity of Quantifier Elimination in the Theory of an Algebraically Closed Field. PhD thesis, Cornell University, USA, 1989. AAI9001370.
- Valentine Kabanets and Jin-Yi Cai. Circuit minimization problem. In Proceedings of the Thirty-Second Annual ACM Symposium on Theory of Computing, STOC '00, pages 73–79, New York, NY, USA, 2000. Association for Computing Machinery. doi:10.1145/335305.335314.
- Erich Kaltofen. Effective noether irreducibility forms and applications. In *Proceedings of the Twenty-third Annual ACM Symposium on Theory of Computing*, STOC '91, pages 54–63, New York, NY, USA, 1991. ACM. doi:10.1145/103418.103431.
- 16 Erich Kaltofen and Barry M. Trager. Computing with polynomials given by black boxes for their evaluations: Greatest common divisors, factorization, separation of numerators and denominators. J. Symb. Comput., 9:301–320, 1990.
- 17 Zohar S. Karnin and Amir Shpilka. Reconstruction of generalized depth-3 arithmetic circuits with bounded top fan-in. In *Proceedings of the 2009 24th Annual IEEE Conference on Computational Complexity*, CCC '09, pages 274–285, Washington, DC, USA, 2009. IEEE Computer Society. doi:10.1109/CCC.2009.18.
- 18 Neeraj Kayal. Derandomizing some algebraic and number-theoretic algorithms. PhD Thesis, IIT Kanpur, January 2006.
- 19 Neeraj Kayal. Efficient algorithms for some special cases of the polynomial equivalence problem. In Proceedings of the Twenty-Second Annual ACM-SIAM Symposium on Discrete Algorithms, SODA '11, pages 1409–1421, USA, 2011. Society for Industrial and Applied Mathematics.

20 Neeraj Kayal and Chandan Saha. Reconstruction of non-degenerate homogeneous depth three circuits. In STOC, 2018.

- Adam R. Klivans and Amir Shpilka. Learning arithmetic circuits via partial derivatives. In Bernhard Schölkopf and Manfred K. Warmuth, editors, *Learning Theory and Kernel Machines*, pages 463–476, Berlin, Heidelberg, 2003. Springer Berlin Heidelberg.
- 22 Adam R. Klivans and Daniel Spielman. Randomness efficient identity testing of multivariate polynomials. In *Proceedings of the Thirty-Third Annual ACM Symposium on Theory of Computing*, STOC '01, pages 216–223, New York, NY, USA, 2001. Association for Computing Machinery. doi:10.1145/380752.380801.
- 23 S. Kopparty, S. Saraf, and A. Shpilka. Equivalence of polynomial identity testing and deterministic multivariate polynomial factorization. In *Computational Complexity (CCC)*, 2014 IEEE 29th Conference on, pages 169–180, June 2014. doi:10.1109/CCC.2014.25.
- Daniel Lazard. Solving systems of algebraic equations. SIGSAM Bull., 35(3):11–37, September 2001. doi:10.1145/569746.569750.
- 25 Arjen Lenstra, H. Lenstra, and Lovász László. Factoring polynomials with rational coefficients. Mathematische Annalen, 261, December 1982. doi:10.1007/BF01457454.
- 26 Gary L. Mullen and Daniel Panario. Handbook of Finite Fields. Chapman & Hall/CRC, 1st edition, 2013.
- Michael O. Rabin. How to exchange secrets with oblivious transfer, 2005. Harvard University Technical Report 81 talr@watson.ibm.com 12955 received 21 Jun 2005. URL: http://eprint.iacr.org/2005/187.
- 28 Nitin Saxena. Progress on polynomial identity testing. Bulletin of the EATCS, 99:49–79, 2009.
- Nitin Saxena and C. Seshadhri. Blackbox identity testing for bounded top fanin depth-3 circuits: The field doesn't matter. In *Proceedings of the Forty-third Annual ACM Symposium on Theory of Computing*, STOC '11, pages 431–440, New York, NY, USA, 2011. ACM. doi:10.1145/1993636.1993694.
- 30 Nitin Saxena and C. Seshadhri. From sylvester-gallai configurations to rank bounds: Improved blackbox identity test for depth-3 circuits. J. ACM, 60(5), October 2013. doi:10.1145/2528403.
- J. T. Schwartz. Fast probabilistic algorithms for verification of polynomial identities. *J. ACM*, 27(4):701–717, October 1980. doi:10.1145/322217.322225.
- 32 Victor Shoup. A fast deterministic algorithm for factoring polynomials over finite fields of small characteristic. In *Proceedings of the 1991 International Symposium on Symbolic and Algebraic Computation*, ISSAC '91, pages 14–21, New York, NY, USA, 1991. Association for Computing Machinery. doi:10.1145/120694.120697.
- 33 Amir Shpilka. Interpolation of depth-3 arithmetic circuits with two multiplication gates. SIAM J. Comput., 38:2130–2161, 2007.
- Amir Shpilka and Amir Yehudayoff. Arithmetic circuits: A survey of recent results and open questions. Foundations and Trends® in Theoretical Computer Science, 5(3–4):207–388, 2010. doi:10.1561/0400000039.
- 35 Gaurav Sinha. Blackbox Reconstruction of Depth Three Circuits with Top Fan-In Two. PhD thesis, California Institute of Technology, Pasadena, CA, USA, 2016. doi:10.7907/Z92N507D.
- Gaurav Sinha. Reconstruction of real depth-3 circuits with top fan-in 2. In *Proceedings of the 31st Conference on Computational Complexity*, CCC '16, pages 31:1–31:53, Germany, 2016. Schloss Dagstuhl–Leibniz-Zentrum fuer Informatik. doi:10.4230/LIPIcs.CCC.2016.31.
- 37 Ilya Volkovich. A guide to learning arithmetic circuits. In Vitaly Feldman, Alexander Rakhlin, and Ohad Shamir, editors, 29th Annual Conference on Learning Theory, volume 49 of Proceedings of Machine Learning Research, pages 1540–1561, Columbia University, New York, New York, USA, 23–26 June 2016. PMLR. URL: http://proceedings.mlr.press/v49/volkovich16.html.
- 38 Joachim von zur Gathen and Jürgen Gerhard. Modern Computer Algebra. Cambridge University Press, 3 edition, 2013. doi:10.1017/CB09781139856065.

39 Richard Zippel. Probabilistic algorithms for sparse polynomials. In *Proceedings of the International Symposiumon on Symbolic and Algebraic Computation*, EUROSAM '79, pages 216–226, Berlin, Heidelberg, 1979. Springer-Verlag.

A Proof of Claims 37, 38 and 43

A.1 Proofs of Claims 37 and 38

In these claims we are given that $T_i = \alpha y_1^t$ for some $i \in [2], \alpha \in \mathbb{F}$ and linear form y_1 .

- 1. To see the proof of Claim 37, consider any linear factor ℓ of $T_1 + T_2$. $\ell \nmid T_1, T_2$ since $\gcd(T_1, T_2) = 1$. Let Φ be an isomorphism mapping $\ell \mapsto x_1$. Setting $x_1 = 0$, we get that $\Phi(T_1)_{|x_1=0} = -\Phi(T_2)_{|x_1=0} \neq 0$. Both sides are non-zero products of linear forms in $\mathbb{F}[x_2, \ldots, x_n]$. Therefore, by unique factorization we can match factors (upto scalar multiplication). This implies that $\dim(\{\text{linear form } \ell : \ell \mid T_1\})$ and $\dim(\{\text{linear form } \ell : \ell \mid T_2\})$ cannot differ from each other by more than 1. But since $\operatorname{rank}(f) = \Omega(\log^3 d)$, this cannot happen since one of the T_i s spans a one dimensional space. Therefore $T_1 + T_2$ has no linear factors and we are done.
- 2. To see proof of Claim 38, without loss of generality assume $y_1 \mid T_1$. Define isomorphism Φ mapping $y_1 \mapsto x_1$. Using Claim 37 we know that $0 \neq \Phi(T_2)_{|x_1=0} = (\Phi(T_1) + \Phi(T_2))_{|x_1=0} = \Phi(NonLin(f))_{|x_1=0}$. So first condition of Definition 16 is satisfied. As argued in Claim 37, $rank(f) \geq \Omega(\log^3 d) \Rightarrow$ linear forms dividing T_2 , span a $\Omega(\log^3 d)$ dimensional space. Since $\Phi(T_2)_{|x_1=0}$ is non-zero, its factors also span $\Omega(\log^3 d)$ dimensional space and so there exist two **L1** factors y_2, y_3 of T_2 such that NonLin(f) vanishes on both $\mathbb{V}(y_1, y_2)$ and $\mathbb{V}(y_1, y_3)$. This implies that second condition of Definition 16 is also satisfied. Therefore, some scalar multiple of $y_1 \in \mathcal{L}(NonLin(f))$.

A.2 Proof of Claim 43

- 1. $dim(sp(\mathcal{L}_{factors})) \leq \log d + 2$: By definition $\mathcal{L}_{factors}$ is the set of all factors of $T_1 + T_2$. Consider any **LI** subset $\mathcal{Z} \subset \mathcal{L}_{factors}$ and let $\ell \in \mathcal{Z}$. Define isomorphism Φ mapping $\ell \mapsto x_1$. Setting $x_1 = 0$ in $\Phi(T_1) + \Phi(T_2)$ gives $\Phi(T_1)_{|x_1=0} = -\Phi(T_2)_{|x_1=0} \neq 0$. By unique factorization in ring $\mathbb{F}[x_2, \ldots, x_n]$, for every linear form $\ell_1 \mid T_1 \exists \ell_2 \mid T_2$ such that $\ell_2 \in sp\{\ell, \ell_1\}$. Since $\ell_2 \notin sp\{\ell\} \cup sp\{\ell_1\}$, this means that $sp\{\ell, \ell_1\}$ is not an ordinary line from ℓ into the proper set \mathcal{L} containing linear factors of T_1, T_2 . This set has size $\leq 2d$. Since ℓ was arbitrary in \mathcal{Z} , there are no ordinary lines from \mathcal{Z} into \mathcal{L} . So using Lemma 52 we get that $|\mathcal{Z}| \leq \log |\mathcal{L}| + 1 = \log d + 2$, completing the proof.
- 2. $dim(sp(\mathcal{L}_{good})) \geq rank(f) 2$ and $\mathcal{L}_{others} \leq 2$: Define $V_i = \{\text{linear form } \ell : \ell \mid T_i\}$. We break the proof into two cases. Note that linear forms dividing T_1, T_2 satisfy first condition of Definition 16. So whenever we are trying to show that they belong to $\mathcal{L}(NonLin(f))$, we only prove that they satisfy second condition of Definition 16.
 - a. First we discuss the case $dim(V_i) \geq \log d + 5 \ \forall i \in [2]$. Let H be such that $T_1 + T_2 = H \times NonLin(f)$. Let $\ell_1 \mid T_1$ and Φ be isomorphism mapping $\ell_1 \mapsto x_1$, then, we see that $\Phi(T_2)_{\mid x_1=0} = \Phi(H)_{\mid x_1=0} \times \Phi(NonLin(f))_{\mid x_1=0} \neq 0$. Dimension of span of linear factors of $\Phi(T_2)_{\mid x_1=0}$ is at least $\log d + 4$ by assumption in this case. By previous part, $dim(sp(\mathcal{L}_{factors})) \leq \log d + 2 \Rightarrow \Phi(NonLin(f))_{\mid x_1=0}$ has two independent linear factors. Using these we can satisfy second condition of Definition 16 for $\ell_1 \Rightarrow$ some scalar multiple of $\ell_1 \in \mathcal{L}(NonLin(f))$. The same argument can be repeated for a linear factor $\ell_2 \mid T_2$. Thus all linear factors of $T_1 \times T_2$ are in $\mathcal{L}(NonLin(f))$ (upto scalar multiplication) $\Rightarrow dim(\mathcal{L}_{good}) = rank(f)$. This also implies that $dim(\mathcal{L}_{others}) = 0$.

b. In the case, $\exists i \in [2]$ such that $dim(V_i) \leq \log d + 4 \Rightarrow dim(V_{3-i}) = \Omega(\log^3 d)$. Using an argument similar to the one in proof of Claim 37, $NonLin(f) = T_1 + T_2$. Consider any basis $\{\ell_1, \ldots, \ell_r\}$ of $V_1 + V_2$. If $dim(V_i) \geq 3 \ \forall i \in [2]$, then using a similar argument as before, we can show that all ℓ_i satisfy second condition in Definition 16 $\Rightarrow dim(\mathcal{L}_{good}) = rank(f) \Rightarrow dim(\mathcal{L}_{others}) = 0$. In case for some $i \in [2]$, $dim(V_i) = 2$ (recall we have assumed $dim(V_i) \geq 2$ in the statement of Claim 43), then all linear forms dividing T_{3-i} are not contained in V_i and hence satisfy second condition of Definition 16. Thus $dim(\mathcal{L}_{good}) \geq rank(f) - 2$ and $dim(\mathcal{L}_{others}) \leq 2$.

3. $dim(sp(\mathcal{L}_{bad})) \leq \log d + 2$: Assume $dim(\mathcal{L}_{bad}) \geq \log d + 3$. Consider the proper set \mathcal{L} containing all linear factors of $T_1, T_2 \Rightarrow |\mathcal{L}| \leq 2d \Rightarrow |\mathcal{L}_{bad}| \geq \log |\mathcal{L}| + 2$. Let $\mathcal{T} \subset \mathcal{L}_{bad}$ be a **LI** set of size $\log |\mathcal{L}| + 2$. Then by Proposition 5, $\exists t \in \mathcal{T}$ such that ordinary lines from t into \mathcal{L} span a space of dimension $\geq \frac{dim(sp(\mathcal{L}))}{\log |\mathcal{L}| + 2} \geq \frac{rank(f)}{\log d + 3} = \Omega(\log^2 d)$. Since $t \in \mathcal{L}_{bad}$, restricting $T_1 + T_2$ to $\mathbb{V}(t)$ (see Definition 15) gives some non-zero product of linear factors, say H. Let Φ be an isomorphism mapping $t \mapsto x_1$. Then $\Phi(T_1)_{|x_1=0} + \Phi(T_2)|_{x_1=0} - H = 0$. This gives an identically zero $\Sigma\Pi\Sigma(3,n,d,\mathbb{F})$ circuit. Since $t \in \mathcal{L}_{bad}$, it does not divide $T_1, T_2 \Rightarrow$ the above circuit is minimal (Definition 12). After cancelling common linear forms from the three gates $\Phi(T_1)_{|x_1=0}, \Phi(T_2)_{|x_2=0}, H$, we have a simple (Definition 11) and minimal, identically zero $\Sigma\Pi\Sigma(3,n,d,\mathbb{F})$ circuit. The $\Omega(\log^2 d)$ ordinary lines from t into \mathcal{L} imply that after cancelling the common linear forms, the simple minimal circuit has rank $\Omega(\log^2 d)$ which is a contradiction to Lemma 24. Thus we conclude that $dim(sp(\mathcal{L}_{bad})) \leq \log d + 2$.

B Proof of Lemma 46

Let $T_i = \prod_{j=1}^m \ell_{i,j}$ where $\ell_{i,j}$ are linear forms. We know that $\prod_{j=1}^m \Phi(\ell_{1,j})_{|_{x_1=0,x_2=0}} = -\prod_{j=1}^m \Phi(\ell_{2,j})_{|_{x_1=0,x_2=0}} \neq 0$. Note that $\Phi(\ell_{i,j})_{|_{x_1=0,x_2=0}}$ can be thought of as linear forms over $\mathbb F$ in n-2 variables, and by using unique factorization of polynomials over $\mathbb F$, without loss of generality we can assume $\Phi(\ell_{1,j})_{|_{x_1=0,x_2=0}} = \beta_j \Phi(\ell_{2,j})_{|_{x_1=0,x_2=0}}$ for some $0 \neq \beta_j \in \mathbb F$. Since Φ is an isomorphism, we get that $U_j = sp\{\ell_{1,j},\ell_{2,j}\}$ intersects $U = sp\{\ell_1,\ell_2\}$ non-trivially. Since $\Phi(\ell_{i,j})_{|_{x_1=0,x_2=0}} \neq 0$ and both U,U_j are 2 dimensional, we get that $U \neq U_j \Rightarrow U \cap U_j$ is 1 dimensional. We split the proof into two cases:

- There exist two distinct spaces, say U_i, U_j such that $U \cap U_i = U \cap U_j$: This implies $U \cap U_i \subset U_i \cap U_j$. The space $U_i \cap U_j$ is 1 dimensional since U_i, U_j are distinct, say $U_i \cap U_j = sp\{\ell\}$. Both sides of the containment $U \cap U_i \subset U_i \cap U_j$ are 1 dimensional implying $U_i \cap U_j = U \cap U_i \subset U = sp\{\ell_1, \ell_2\}$. This further implies that $\ell \in U \Rightarrow W \subset \mathbb{V}(\ell) = V$. There are $\leq d^4$ choices for such U_i, U_j and therefore d^4 possibilities for such V.
- \forall distinct $U_i, U_j, U \cap U_i \neq U \cap U_j$: Vector space $U \cap U_i + U \cap U_j$ is 2 dimensional, since it is a sum of disjoint 1 dimensional spaces. U is also 2 dimensional $\Rightarrow U = U \cap U_i + U \cap U_j \subset U_i + U_j$. Using statement of Proposition 5, we know that, $5 \leq rank(f) = dim(sp\{\ell_{i,j}\}) = dim(\sum_{j=1}^{m} U_j) \leq \sum_{j=1}^{m} dim(U_j)$. Since $dim(U_i + U_j) \leq 4$, $\exists U_k$ such that $U_k \not\subset U_i + U_j$. Note that this would imply that $U_k \cap (U_i + U_j)$ has dimension ≤ 1 . Since $U \subset U_i + U_j$, we get that $U_k \cap U \subset U_k \cap (U_i + U_j)$. Both sides are 1 dimensional. Writing $U_k \cap (U_i + U_j) = sp\{\ell\} \Rightarrow \ell \in U \Rightarrow W \subset V(\ell) = V$. There are $\leq d^6$ choices for U_i, U_j, U_k and so $\leq d^6$ possibilities for such V.

 \mathcal{A} is collection of all Vs obtained above. $|\mathcal{A}| \leq d^4 + d^6$ and \mathcal{A} satisfies the required conditions.

C Proofs of Lemmas in Algorithm 6

C.1 Proof of Lemma 47

We prove each part one by one below. Let $\hat{\ell}_i = \sum_{j=1}^n \alpha_{i,j} x_j, i \in [n]$ be the n linear forms that were constructed using the uniformly randomly independently samples $\alpha_{i,j}, i \in [n], j \in [n]$. Recall that Φ maps $x_i \mapsto \hat{\ell}_i$. Let Γ be a homomorphism from $\mathbb{F}[x_1, \dots, x_n] \to \mathbb{F}[x_1, x_2, x_3, x_4, x_i]$ that sets $x_5 = 0, \dots, x_{i-1} = 0, x_{i+1} = 0, \dots, x_n = 0$.

- 1. This is equivalent to showing that with probability 1 o(1), matrix $(\alpha_{i,j})_{(i,j) \in [n] \times [n]}$ is invertible. This is further equivalent to showing that the determinant polynomial of this matrix is non-zero which follows from Lemma 21.
- 2. Consider any isomorphism Ψ mapping $\ell_1 \mapsto x_1, \ell_2 \mapsto x_2$, then $\Psi \circ \Phi^{-1}$ is an isomorphism mapping $\Phi(\ell_1) \mapsto x_1, \Phi(\ell_2) \mapsto x_2$. Further, $\Psi(NonLin(f)) = \Psi \circ \Phi^{-1}(\Phi(NonLin(f)))$. Setting $x_1 = 0, x_2 = 0 \Rightarrow \Psi(NonLin(f))|_{x_1 = 0, x_2 = 0} = \Psi \circ \Phi^{-1}(\Phi(NonLin(f)))|_{x_1 = 0, x_2 = 0} \Rightarrow NonLin(f)$ vanishes on $\mathbb{V}(\ell_1, \ell_2)$ iff $\Phi(NonLin(f))$ vanishes on subspace $\mathbb{V}(\Phi(\ell_1), \Phi(\ell_2))$. Since Φ is an isomorphism, irreducible factors of f remain irreducible on applying Φ , thereby implying that $\Phi(NonLin(f)) = NonLin(\Phi(f)) = NonLin(g)$.
- 3. Recall $f = G \times (T_1 + T_2)$, with G, T_1, T_2 being product of linear forms and $gcd(T_1, T_2) = 1$. Since Φ is an isomorphism, we get that $g = \Phi(G) \times (\Phi(T_1) + \Phi(T_2))$. Since Φ is an isomorphism, $gcd(\Phi(T_1), \Phi(T_2)) = 1$. Therefore we get $g_i = \Gamma(g) = \Gamma(\Phi(G))(\Gamma(\Phi(T_1)) + \Gamma(\Phi(T_2))$. Next, consider linear forms $\ell = \sum_{j=1}^n a_j x_j$ and $\ell' = \sum_{j=1}^n a'_j x_j$ such that $\ell \mid T_1$ and $\ell' \mid T_2$. Applying Φ to these linear forms we get, $\Phi(\ell) = \sum_{k=1}^n \sum_{j=1}^n a_j \alpha_{j,k} x_k$. Therefore coefficients of x_1, x_2 in $\Gamma(\Phi(\ell))$ are $\sum_{j=1}^n a_j \alpha_{j,1}, \sum_{j=1}^n a_j \alpha_{j,2}$ respectively and those in $\Gamma(\Phi(\ell'))$ are $\sum_{j=1}^n a'_j \alpha_{j,1}, \sum_{j=1}^n a'_j \alpha_{j,2}$. We argue that vectors $(\sum_{j=1}^n a_j \alpha_{j,1}, \sum_{j=1}^n a_j \alpha_{j,2})$ and $(\sum_{j=1}^n a'_j \alpha_{j,1}, \sum_{j=1}^n a'_j \alpha_{j,2})$ are not scalar multiples with probability 1 o(1). This

is equivalent to showing that the determinant $\begin{vmatrix} \sum_{j=1}^n a_j \alpha_{j,1} & \sum_{j=1}^n a_j \alpha_{j,2} \\ \sum_{j=1}^n a_j' \alpha_{j,1} & \sum_{j=1}^n a_j' \alpha_{j,2} \end{vmatrix}$ is non-zero. If ℓ, ℓ' are not scalar multiples, this determinant is not an identically zero polynomial

If ℓ, ℓ' are not scalar multiples, this determinant is not an identically zero polynomial in the $\alpha_{j,k}, j \in [n], k \in [2]$ and therefore probability (over the random choices of $\alpha_{j,k}$) that the determinant is non-zero = 1 - o(1). Therefore with probability 1 - o(1), $\Gamma(\Phi(\ell))$ and $\Gamma(\Phi(\ell'))$ are not scalar multiples. Since ℓ, ℓ' are arbitrary linear factors of T_1, T_2 respectively, by union bound with probability 1 - o(1), $gcd(\Gamma(\Phi(T_1)), \Gamma(\Phi(T_2))) = 1$ implying that all g_i exhibit $\Sigma\Pi\Sigma(2, 5, d, \mathbb{F})$ circuit. Since $rank(f) = \Omega(\log^2 d)$, we know that $dim(sp\{\text{linear form } \ell : \ell \mid T_1 \times T_2\}) \geq 5$, therefore, by a similar argument (using Lemma 21), we get that $\{\Gamma(\Phi(\ell)) : \text{linear form } \ell \mid T_1 \times T_2\}$ spans a 5 dimensional space. This set is same as $\{\text{linear form } \ell : \ell \mid \Gamma(\Phi(T_1)) \times \Gamma(\Phi(T_2))\}\} \Rightarrow rank(g_i) = 5 \ \forall i \in [5, n]$.

- 4. By effective Hilberts irreducibility theorem (Lemma 26), with probability 1-o(1) over the $\alpha_{i,j}, i \in [n], j \in [n]$, the irreducible factors of $\Phi(f)(x_1, \ldots, x_n) = f(\Phi(x_1), \ldots, \Phi(x_n))$ remain irreducible on setting $x_5 = 0, \ldots, x_{i-1} = 0, x_{i+1} = 0, \ldots, x_n = 0$ i.e. on applying Γ . This implies that $NonLin(\Gamma(\Phi(f))) = \Gamma(NonLin(\Phi(f)))$. The **LHS** is $NonLin(g_i)$ and **RHS** is $NonLin(g)|_{x_5=0,\ldots,x_{i-1}=0,x_{i+1}=0,\ldots,x_n=0}$.
- 5. Let $\mathbb{V}(\hat{\ell}_1,\hat{\ell}_2)$ belong to $\mathcal{S}(NonLin(f))$. Assume $\hat{\ell}_1 = \sum_{j=1}^n a_j x_j$ and $\hat{\ell}_2 = \sum_{j=1}^n b_j x_j$, Then we get that $\Phi(\hat{\ell}_1) = \sum_{k=1}^n (\sum_{j=1}^n a_j \alpha_{j,k}) x_k$ and $\Phi(\hat{\ell}_2) = \sum_{k=1}^n (\sum_{j=1}^n b_j \alpha_{j,k}) x_k$. We define $c_k = \sum_{j=1}^n a_j \alpha_{j,k}$ and $d_k = \sum_{j=1}^n b_j \alpha_{j,k}$ for $k \in [n]$. Therefore $\Phi(\hat{\ell}_1) = \sum_{k=1}^n c_k x_k$ and $\Phi(\hat{\ell}_2) = \sum_{k=1}^n d_k x_k$. Now we define linear forms $\ell_3 = d_2 \Phi(\hat{\ell}_1) c_2 \Phi(\hat{\ell}_2)$ and $\ell_4 = -d_1 \Phi(\hat{\ell}_1) + c_1 \Phi(\hat{\ell}_2)$. Note that $d_2 c_1 c_2 d_1$ is a polynomial in $\alpha_{j,k}, j \in [n], k \in [2]$. Like in the previous part, unless $\hat{\ell}_1, \hat{\ell}_2$ are **LD** this polynomial is not

identically 0. Therefore with probability 1-o(1) over the uniformly randomly chosen linear forms in Step 1, $d_2c_1-c_2d_1\neq 0$. This also means that ℓ_3,ℓ_4 are \mathbf{LI} and $\mathbb{V}(\ell_3,\ell_4)=\mathbb{V}(\Phi(\hat{\ell}_1),\Phi(\hat{\ell}_2))$. Analyzing ℓ_3,ℓ_4 we see that $\ell_3=(d_2c_1-c_2d_1)x_1+\sum_{k=3}^n(d_2c_k-c_2d_k)x_k$ and $\ell_4=(d_2c_1-c_2d_1)x_2+\sum_{k=3}^n(d_kc_1-c_kd_1)x_k$. Define $\ell_1'=-\sum_{k=3}^n\frac{d_2c_k-c_2d_k}{d_2c_1-c_2d_1}x_k$, and $\ell_2'=-\sum_{k=3}^n\frac{d_kc_1-c_kd_1}{d_2c_1-c_2d_1}x_k$, further implying that $\mathbb{V}(\ell_1,\ell_2)=\mathbb{V}(x_1-\ell_1',x_2-\ell_2')$ with $\ell_1',\ell_2'\in\mathbb{F}[x_3,\ldots,x_n]$. Now since $\mathcal{S}(NonLin(f))$ has size $d^{O(1)}$, by union bound, with probability 1-o(1), we can prove all of this for every $\mathbb{V}(\hat{\ell}_1,\hat{\ell}_2)\in\mathcal{S}(NonLin(f))$. Now, given any $\mathbb{V}(\ell_1,\ell_2)\in\mathcal{S}(NonLin(g))$, by Part 2 of this Lemma, we know that $\mathbb{V}(\ell_1,\ell_2)\in\mathcal{S}(NonLin(g))$ iff $\mathbb{V}(\Phi^{-1}(\ell_1),\Phi^{-1}(\ell_2))\in\mathcal{S}(NonLin(g))$. So we can use our argument for $\hat{\ell}_1=\Phi^{-1}(\ell_1)$, and $\hat{\ell}_2=\Phi^{-1}(\ell_2)$, thereby completing the proof.

6. Let $\mathbb{V}(\ell_1,\ell_2) \in \mathcal{S}(NonLin(g))$ and $\ell_j^i = \ell_j|_{x_5=0,\dots,x_{i-1}=0,x_{i+1}=0,\dots,x_n=0}$. By previous part we know that $\exists \ell_1',\ell_2' \in \mathbb{F}[x_3,\dots,x_n]$ such that $\mathbb{V}(\ell_1,\ell_2) = \mathbb{V}(x_1-\ell_1',x_2-\ell_2')$. Let Θ be an isomorphism mapping $x_1-\ell_1'\mapsto x_1,x_2-\ell_2'\mapsto x_2$ and for $j\in[3,n],x_j\mapsto x_j$. Similarly let Θ' be isomorphism on $\mathbb{F}[x_1,x_2,x_3,x_4,x_i]$ mapping $x_1-\ell_1''\mapsto x_1,x_2-\ell_2''\mapsto x_2$ and for $j\in\{3,4,i\},\ x_j\mapsto x_j$. Finally let Γ be the homomorphism from $\mathbb{F}[x_1,\dots,x_n]$ to $\mathbb{F}[x_1,x_2,x_3,x_4,x_i]$ mapping $x_j\mapsto 0\ \forall\ j\in[5,i-1]\cup[i+1,n]$. It is easy to see that $\Gamma\circ\Theta=\Theta'\circ\Gamma$. We know that NonLin(g) vanishes on $\mathbb{V}(x_1-\ell_1',x_2-\ell_2')$, therefore $\Theta(NonLin(g))_{|x_1=0,x_2=0}=0$, implying that $\Gamma(\Theta(NonLin(g))_{|x_1=0,x_2=0})=0$. We know that Γ fixes x_1,x_2 therefore we can set $x_1=0,x_2=0$ after applying Γ , thereby giving $\Gamma(\Theta(NonLin(g)))_{|x_1=0,x_2=0}=0$. $\Gamma\circ\Theta=\Theta'\circ\Gamma\Rightarrow\Theta'(\Gamma(NonLin(g)))_{|x_1=0,x_2=0}=0$. Now, Part 4 of this lemma gives $NonLin(g_i)=\Gamma(NonLin(g))$. Using this we get, $\Theta'(NonLin(g_i))_{|x_1=0,x_2=0}=0$. Therefore $NonLin(g_i)$ vanishes on $\mathbb{V}(x_1-\ell_1'',x_2-\ell_2'')$.

C.2 Proof of Lemma 48

Fix $i \in [6, n]$. Consider a pair of distinct tuples $(x_1 - \ell_1, x_2 - \ell_2)$, $(x_1 - \ell'_1, x_2 - \ell'_2)$ in S_i . By construction, $\ell_1, \ell_2, \ell'_1, \ell'_2 \in \mathbb{F}[x_3, x_4, x_i]$. So we assume that, $\ell_1 = a_3x_3 + a_4x_4 + a_ix_i$, $\ell_2 = b_3x_3 + b_4x_4 + b_ix_i$, $\ell'_1 = a'_3x_3 + a'_4x_4 + a'_ix_i$ and $\ell'_2 = b'_3x_3 + b'_4x_4 + b'_ix_i$. Therefore,

$$\Delta(\ell_1) = (a_3 + \alpha_{i,3}a_i)x_3 + (a_4 + \alpha_{i,4}a_i)x_4 + a_ix_i, \Delta(\ell_2) = (b_3 + \alpha_{i,3}b_i)x_3 + (b_4 + \alpha_{i,4}b_i)x_i + b_ix_i,$$

$$\Delta(\ell_1') = (a_3' + \alpha_{i,3}a_i')x_3 + (a_4' + \alpha_{i,4}a_i')x_4 + a_i'x_i, \Delta(\ell_2') = (b_3' + \alpha_{i,3}b_i')x_3 + (b_4' + \alpha_{i,4}b_i')x_4 + b_i'x_i$$

If $(\Delta(\ell_1)_{|x_i=0}, \Delta(\ell_2)_{|x_i=0}) = (\Delta(\ell_1')_{|x_i=0}, \Delta(\ell_2')_{|x_i=0})$, then we get a system of linear equations in $\alpha_{i,3}, \alpha_{i,4}$ which can be simplified to get $\alpha_{i,3}(a_i-a_i')=a_3'-a_3, \alpha_{i,4}(a_i-a_i')=a_4'-a_4, \alpha_{i,3}(b_i-b_i')=b_3'-b_3, \alpha_{i,4}(b_i-b_i')=b_4'-b_4$. Since tuples (ℓ_1,ℓ_2) and (ℓ_1',ℓ_2') are distinct, at least one of $(a_3'-a_3), (a_i-a_i'), (a_4'-a_4), (b_i-b_i'), (b_3'-b_3), (b_4'-b_4)$ is non-zero implying that at least one linear equation is not identically zero. By Lemma 21, we then know that with probability 1-o(1) over the uniformly random choices of $\alpha_{i,3}, \alpha_{i,4}$ the equation cannot be zero. Therefore with probability $1-o(1), (\Delta(\ell_1)_{|x_i=0}, \Delta(\ell_2)_{|x_i=0}) \neq (\Delta(\ell_1')_{|x_i=0}, \Delta(\ell_2')_{|x_i=0})$. Using Part 3 of Lemma 47, we know that $\operatorname{rank}(\operatorname{NonLin}(g_i)) = 5$ implying that $|\mathcal{S}_i| = d^{O(1)}$. So we can take a union bound over all pairs of tuples in \mathcal{S}_i . Finally, we take a union bound over all i and guarantee that with probability 1-o(1), the statement in this lemma holds.