# Diamonds for Security: A Non-Interleaving Operational Semantics for the Applied Pi-Calculus 

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#### Abstract

We introduce a non-interleaving structural operational semantics for the applied $\pi$-calculus and prove that it satisfies the properties expected of a labelled asynchronous transition system (LATS). LATS have well-studied relations with other standard non-interleaving models, such as Mazurkiewicz traces or event structures, and are a natural extension of labelled transition systems where the independence of transitions is made explicit. We build on a considerable body of literature on located semantics for process algebras and adopt a static view on locations to identify the parallel processes that perform a transition. By lifting, in this way, work on CCS and $\pi$-calculus to the applied $\pi$-calculus, we lay down a principled foundation for reusing verification techniques such as partial-order reduction and non-interleaving equivalences in the field of security. The key technical device we develop is the notion of located aliases to refer unambiguously to a specific output originating from a specific process. This light mechanism ensures stability, avoiding disjunctive causality problems that parallel extrusion incurs in similar non-interleaving semantics for the $\pi$-calculus.


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## 1 Introduction

The purpose of this paper is to give a principled foundation for methods from concurrency theory that are gaining traction in the verification of security properties. Tools used in the security domain have applied partial-order-based techniques, notably partial-order reduction (POR), to improve their efficiency, thereby increasing the size of the systems that can be analyzed $[6,7,8,17,18,21,27,38]$. To date, much of that work is tool-driven and guided by examples. However, without a solid foundation, we cannot be certain that the methods employed are correct, and hence, if an untested example is presented, the tool might produce incorrect results or fail to apply reductions where they might well have been applied.

This paper fulfils what we believe to be an important role: drawing from decades of theory on the topic of non-interleaving semantics for process algebras, we bring essential concurrency concepts to the security verification community. In particular, we aim for a semantics that is operational, rather than denotational, to stay close to the existing semantics employed by the main tools in the security community, so that our work may easily be adopted. As in the non-interleaving tradition, we define a concept of event as an enhancement of actions. The

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notion of independence is then defined on events in a straightforward way using the structure of the events only. This enables the implementation of techniques such as partial-order reduction on the fly.

The applied $\pi$-calculus [1, 43] has become instrumental in leveraging theoretical process calculi to certify and verify security protocols $[4,10,14,31,33,36]$. Its syntax can describe a variety of interactions between the processes involved in a security protocol, stressing the study of the communication of complex messages. Abstracting away from cryptographic primitives with an equational theory allows tools to focus on problems arising due to the information flow in security protocols, while its flexibility allows a large variety of situations to be modelled. Its inductive structure lends itself to automation of the analysis and verification of protocols used in production thanks to tools such as ProVerif [10], DEEPSEC [17], Akiss [16], Sapic [35], SAT-Equiv [19] and SPEC [46], which have flavours of the applied $\pi$-calculus as their input language.

Labelled asynchronous transition systems (LATS) are a non-interleaving model of concurrency, which, because they extend transition systems in a natural way, are suited to being the objects generated by our structural operational semantics for the applied $\pi$-calculus. The word asynchronous does not refer to the type of communication between processes: it is a nod to the Petri net literature, where independent transitions are said to act asynchronously [41]. LATS were introduced by Bednarczyk [9] and Shields [45], and have been well studied in the concurrency literature [28,29,51]. They are generally required to satisfy properties such as event determinism, and to provide an independence relation that satisfies what we call concurrency diamonds. Developing a LATS is also an important prerequisite for further methods to be developed such as non-interleaving process equivalences.

Endowing the applied $\pi$-calculus with a structural operational semantics that defines a labelled asynchronous transition system gives us a concrete path towards applying noninterleaving concurrency techniques to security problems such as the verification of security protocols. This requires us to import and mix ideas from different communities and lines of work, and to carefully design "the right fit" to prove seamlessly the desired properties of a LATS. We believe our proposal to be not only elegant, but also enlightening in the way it sidesteps "traditional" problems stemming from the $\pi$-calculus, such as the need to represent some forms of extrusion with disjunctive causality [20,30]. In particular, in our theory there is never any ambiguity about which outputs an event is causally dependent on, in contrast to the traditional semantics for the $\pi$-calculus [11] where, if two outputs concurrently extrude the same name that is then later used, then the semantics does not record from which output the name originates.

Our proposal is also lightweight - our events consist simply of a location (a binary string indicating where in the binary tree of parallel and choice components the event originates) and an action label - and provides event determinism almost for free. Avoiding disjunctive causality will allow our model to be related to more standard concurrency models such as safe Petri nets or prime event structures.

Outline. Sect. 2 recalls the abstract concept of a LATS. Sect. 3 introduces a syntax for the applied $\pi$-calculus. Sect. 4 explains the design of our non-interleaving structural operational semantics. Sect. 5 presents the main result: that our non-interleaving structural operational semantics is a labelled asynchronous transition system. Sect. 6 situates this work in the literature, particularly in relation to POR for the applied $\pi$-calculus. The appendices provide example derivations and outline the key elements of the proof of the main theorem.

## 2 Our Target Model: Labelled Asynchronous Transition Systems

A labelled asynchronous transition system is a labelled transition system enriched with an independence relation on events $I$ that satisfies what we call diamond properties. Standard labelled transition systems, such as those obtained from structural operational semantics of process algebras such as CCS, $\pi$-calculus, and applied $\pi$-calculus, are labelled with actions, indicating, e.g., the input or output action of a process. Labelled asynchronous transition systems (LATS), in contrast, are labelled with events, which contain more information, sufficient to distinguish between events that are triggered in different ways but share the same action label. We denote states (which usually in process algebras are process terms) by capital letters, events by small letters, and transitions between states labelled with an event as $A \xrightarrow{e} B$. We illustrate the properties of LATS using standard $\pi$-calculus notation. The reader familiar with the $\pi$-calculus may safely skip the following info box.

Key features of the $\boldsymbol{\pi}$-calculus: We assume for now only some familiarity with $\pi$-calculus features, some of which we informally recall here. Later, in Sect. 3, we extend this to the applied $\pi$-calculus and define formally its semantics:

- Name restriction $\nu x . P$ binds occurrences of variable $x$ in $P$, indicating that $x$ is a freshly generated name. Importantly, an observer (who may be an attacker) cannot know (e.g., by guessing) which name was generated, without intercepting a communication of this name on a public channel.
- An output prefix $\bar{x}\langle y\rangle . P$ indicates that the variable $y$ is output on a channel $x$, before continuing to execute process $P$. Such outputs may only be observed if the channel is known to the observer, either because $x$ is a free variable or is a fresh name that has previously been output.
- An input prefix $x(y) . P$ indicates that a channel $x$ is used to receive a message, which is always a variable representing a name in the $\pi$-calculus. Notably, a fresh name may only be received if it has previously been output. The process then continues to execute $P$, but with occurrences of variable $y$ in $P$ replaced by the variable received, e.g., as $P\{z / y\}$ if $z$ was received along $x$.
- Parallel composition $P \mid Q$ indicates that processes $P$ and $Q$ execute in separate locations, possibly communicating with each other by synchronising an input and output on the same channel name, whether or not the channel is known to an observer. The precise meaning of parallel composition is the main subject of the interleaving/non-interleaving spectrum of process semantics.
- The match prefix $[x=y] P$ should be read as, "if $x$ and $y$ are the same variable (due to a prior input action for example) then $P$ can execute."
- The process 0 represents termination. We follow standard conventions such as omitting the deadlock process 0 when it is preceded by an action (e.g., output or input) prefix. A distinguishing feature of the $\pi$-calculus is that the scope of a name restriction is mobile in the sense that it can expand when a message containing the variable it binds is output. We assume that action prefixes and name restriction bind stronger than parallel composition.

To begin with, a LATS must satisfy the following property, which ensures that, in any given state, any two (co-initial) transitions labelled with the same event are actually the same transition (up to some minimal congruence relation $\equiv$, quotienting the set of states).

- Definition 1 (event determinism). A LATS satisfies event determinism whenever

$$
\text { If } A_{0} \equiv A_{1}, A_{0} \xrightarrow{e} B_{0} \text { and } A_{1} \xrightarrow{e} B_{1} \text {, then } B_{0} \equiv B_{1} \text {. }
$$

For example, for a processes $\bar{c}\langle n\rangle \mid \bar{c}\langle n\rangle$ consisting of two parallel threads both sending $n$ on channel $c$, a LATS must label the two output transitions differently, which is not guaranteed by standard labelled transition systems.

The other two properties a LATS must satisfy are the diamond properties (sometimes called "sideways diamond" [42] and "square property" [37]), which ensure that events considered to be independent with respect to the independence relation $I$ can permute. The first diamond property ensures that two independent events labelling (co-initial) transitions from the same state can be performed in either order without affecting the outcomes.

- Definition 2 (diamond property 1). A LATS satisfies diamond property 1 whenever

$$
\text { If } e_{0} I e_{1}, A \xrightarrow{e_{0}} B_{0}, \text { and } A \xrightarrow{e_{1}} B_{1} \text { then } \exists C_{0}, C_{1} \text { s.t. } B_{0} \xrightarrow{e_{1}} C_{0}, B_{1} \xrightarrow{e_{0}} C_{1} \text { and } C_{0} \equiv C_{1} \text {. }
$$

The second diamond property concerns independent events labelling (composable) transitions in consecutive states, ensuring such transitions may be permuted.

- Definition 3 (diamond property 2). A LATS satisfies diamond property 2 whenever

$$
\text { If } e_{0} I e_{1}, A \xrightarrow{e_{0}} B_{0} \text {, and } B_{0} \xrightarrow{e_{1}} C_{0} \text {, then } \exists B_{1}, C_{1} \text { s.t. } A \xrightarrow{e_{1}} B_{1}, B_{1} \xrightarrow{e_{0}} C_{1} \text { and } C_{0} \equiv C_{1} \text {. }
$$

Observe that all of the above properties only concern co-initial or composable transitions, i.e., transitions from the same state or adjacent states. We use the following example to illustrate why this is significant: $\nu n .(\bar{c}\langle n\rangle \mid c(x) \cdot[x=n] \overline{\mathrm{ok}}\langle\mathrm{ok}\rangle)$. For any execution of this process in which the event corresponding to $\overline{\mathrm{ok}}\langle\mathrm{ok}\rangle$ occurs, the two events corresponding to $\bar{c}\langle n\rangle$ and $c(x)$ must have both occurred previously. Since we work with an early semantics, strictly speaking we have one event for each possible instantiation of the variable $x$ in the input $c(x)$. Structural (a.k.a. prefixing) causality ensures that the event corresponding to $\overline{\mathrm{ok}}\langle\mathrm{ok}\rangle$ should not be independent from any of the input events corresponding to $c(x)$, since this part (or location) of the process must execute the latter to be able to access the former. Link (a.k.a. name) causality ensures that the event corresponding to $\bar{c}\langle n\rangle$ should not be independent from the input event corresponding to $c(x)$ when $x$ is instantiated with the name $n$, which would also enable the guard $x=n$. Taken together, those two causalities ensure that our expectations regarding the concurrency inherent in $\pi$-calculi are met.

In contrast to the above observations, although the events corresponding to $\bar{c}\langle n\rangle$ and $\overline{\mathrm{ok}}\langle\mathrm{ok}\rangle$, in the above example, are causaly dependent on each other by transitivity, when defining a LATS, we are free to allow them to be defined as "independent", since these events can never be executed concurrently or consecutively, and hence they will never be considered together in a diamond property. This is a reason why LATS are suited for defining a non-interleaving structural operational semantics, as there is no need to compute global dependencies between events: local calculations are enough to determine whether consecutive events are concurrent. If global dependencies are required, they are established by unfoldings of LATS into event structures and Petri nets [39].

The relatively light requirements on the independence relation, as explained above, justifies why LATS offer an attractive take on structural operational semantics. A structural operational semantics makes transitions easy to compute, and an easy to compute independence relation facilitates partial-order reduction, that drastically reduces the number of states to explore when verifying concurrent processes [3, 18]. An easily calculated independence relation also facilitates the checking of non-interleaving variants of equivalences, e.g., distinguishing $\bar{c}\langle n\rangle \mid \bar{c}\langle n\rangle$ from $\bar{c}\langle n\rangle . \bar{c}\langle n\rangle$ (the autoconcurrency problem). Causality in the $\pi$-calculus has been explored in related work [11, 20, 22, 34, 40].

| Processes: |  |  | Guarded processes: |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $P, Q, R::=$ | 0 | deadlock | $G, H::=$ | $M(x) . P$ | input prefix |
|  | $\nu x . P$ | new |  | $\bar{M}\langle N\rangle . P$ | output prefix |
|  | $P \mid Q$ | parallel |  | $[M=N] G$ | match |
|  | $G$ | guarded process |  | $[M \neq N] G$ | mismatch |
|  | $!P$ | replication |  | $G+H$ | choice |

Extended processes: $\quad$| $\quad A, B, C::=$ | $\sigma \mid P$ | active process |  |
| ---: | :--- | ---: | ---: |
|  | $\mid$ | $\nu x . A$ | new |

Figure 1 Syntax of processes with guarded choice and of extended processes.

## 3 A Syntax for the Applied $\pi$-Calculus

We detail the syntax for the applied $\pi$-calculus we employ in Fig. 1 - which is close to the one used in tools such as e.g., ProVerif [1, 10]. Variables are denoted by lowercase roman letters such as $x, y, z$ (generally reserved for input variables), $a, b, c$ (generally reserved for channel names) $m, n$, (generally reserved for nonces and keys). All variables are the same syntactic category, but we are careful to distinguish variables from aliases, ranging over $\alpha, \beta, \gamma$. Traditionally in the applied $\pi$-calculus, aliases are also simply variables, but they play a special role in this theory. We will explain the notion of alias properly in Sect. 4.2.

Variables, aliases and function symbols - discussed below - are used to build messages, denoted by $M, N, K$. In processes, denoted by $P, Q, R$, variables, but not aliases, can be bound by input prefix $M(x) . P$ or fresh name binders $\nu x . P$, where the latter is used to indicate which variables - in this case, $x$ - are treated as opaque names, such as private keys hidden from an attacker observing the process. We use sequences of names $\nu \vec{x} . P$ to abbreviate multiple name binders defined inductively such that $\nu \epsilon \cdot P=P$ and $\nu x, \vec{y} \cdot P=\nu x . \nu \vec{y} \cdot P$, where $\epsilon$ is the empty sequence.

As standard, a substitution $\sigma, \theta$ or $\rho$ is a function with a domain $(\operatorname{dom}(\sigma)=\{\alpha: \alpha \neq \alpha \sigma\})$ and a range $(\operatorname{ran}(\sigma)=\{\alpha \sigma: \alpha \in \operatorname{dom}(\sigma)\})$ that can be applied to messages as suffixes, e.g., $\operatorname{fst}(\alpha)\left\{\left\{^{\langle m, n\rangle} / \alpha\right\}=\mathrm{fst}(\langle m, n\rangle)\right.$. We write id for the identity substitution, with dom(id) $=$ $\operatorname{ran}(\mathrm{id})=\emptyset$. Substitutions can be composed, notated $\sigma \circ \theta$, and are applied in reverse to function composition, thus $M(\sigma \circ \theta)=(M \sigma) \theta$. When applied to processes, substitutions are capture-avoiding with respect to processes $\nu x . P$ and $a(x) . P$ that bind $x$ in $P$. In this work, active substitutions, which map aliases in their finite domain to messages containing no aliases (hence are idempotent, i.e., $\sigma \circ \sigma=\sigma$ ), play a central role.

The ability to choose any function symbols to construct messages is the real flexibility of the applied $\pi$-calculus, allowing many message theories to be encoded, representing cryptographic functions by defining an equational theory $E$, containing equations such as for the decryption function $\operatorname{dec}\left(\{M\}_{K}, K\right)={ }_{E} M$ or first projection of a pair $\mathrm{fst}(\langle M, N\rangle)={ }_{E} M$. This clean design allows us to separate problems related to the semantics of processes, as explored in this paper, from problems associated with conducting proofs in the presence of specific choices of message theories. Thus we never fix a specific message theory in this paper, and any we provide is just to make examples more digestible.

Extended processes, ranging over $A, B, C$, offer a compact way of representing a process along with the messages and names that have been sent. In extended processes, the messages already sent are represented by active substitutions; and the scope of fresh name binders
are enlarged to include the substitution, so that they may bind variables in both the substitutions representing messages that have been output and in the continuation processes. In an extended process $A=\nu \vec{x} .(\sigma \mid P)$, we assume, in this work, a normal form, where aliases do not appear in processes. This has the effect that the active substitution $\sigma$ in the extended process $A$ has already been applied to $P$.

- Definition 4 (free variables and aliases). A variable x (resp. an alias $\alpha$ ) is free in a message $M$ if $x \in \mathrm{fv}(M)$ (resp. $\alpha \in \mathrm{fa}(M)$ ) for

$$
\begin{array}{lll}
\operatorname{fv}\left(f\left(M_{1}, \ldots M_{n}\right)\right)=\cup_{i=1}^{n} \operatorname{fv}\left(M_{i}\right) & \operatorname{fv}(x)=\{x\} & \operatorname{fv}(\alpha)=\emptyset \\
\operatorname{fa}\left(f\left(M_{1}, \ldots M_{n}\right)\right)=\cup_{i=1}^{n} \operatorname{fa}\left(M_{i}\right) & \operatorname{fa}(x)=\emptyset & \operatorname{fa}(\alpha)=\{\alpha\} .
\end{array}
$$

The fv function extends in the standard way to (extended) processes, letting $\mathrm{fv}(\nu x . P)=$ $\mathrm{fv}(P) \backslash\{x\}$ and $\mathrm{fv}(M(x) . P)=\mathrm{fv}(M) \cup(\mathrm{fv}(P) \backslash\{x\})$, and similarly for $\mathrm{fv}(A)$.

- Definition 5 (fresh). We say a variable $x$ is fresh for a message $M$ (resp. process $P$, extended process $A$ ), written $x \# M$ (resp. $x \# P, x \# A$ ) whenever $x \notin \mathrm{fv}(M)$ (resp. $x \notin \mathrm{fv}(P), x \notin \mathrm{fv}(A))$, and similarly for aliases. Freshness extends point-wise to lists of entities, i.e., $x_{1}, x_{2}, \ldots x_{m} \# M_{1}, M_{2}, \ldots, M_{n}$, denotes the conjunction of all $x_{i} \# M_{j}$ for all $1 \leq i \leq m$ and $1 \leq j \leq n$.
- Definition 6 ( $\alpha$-equivalence). We define $\alpha$-equivalence (denoted $\equiv_{\alpha}$ ) for variables only (not aliases which are fixed "addresses") as the least congruence (a reflexive, transitive, and symmetric relation preserved in all contexts) such that, whenever $z \# \nu x . P$, we have $\nu x \cdot P \equiv{ }_{\alpha} \nu z \cdot(P\{z / x\})$ and $M(x) . P \equiv_{\alpha} M(z) \cdot(P\{z / x\})$. Similarly, for extended processes, we have the least congruence such that, whenever $z \# \nu x . A$, we have $\nu x . A \equiv_{\alpha} \nu z .\left(A\left\{{ }^{z} / x\right\}\right)$.
- Definition 7 (capture-avoiding substitutions). Restriction is such that $\theta \upharpoonright_{\vec{\alpha}}(x)=\theta(x)$ if $x \in \vec{\alpha}$ and $x$ otherwise. Capture-avoiding substitutions are defined for processes such that for any $z \# \operatorname{dom}(\sigma), \operatorname{ran}(\sigma), \nu x . P$, we have $(M(x) \cdot P) \sigma \equiv{ }_{\alpha} M \sigma(z) \cdot P\{z / x\} \sigma$ and $(\nu x . P) \sigma \equiv{ }_{\alpha}$ $\nu z . P\left\{z^{z} / x\right\} \sigma$. For extended processes, it is defined such that $(\nu x . A) \rho \equiv_{\alpha} \nu z .(A(\{z / x\} \circ \rho))$ and $(\sigma \mid P) \rho=\left(\sigma \circ \rho \upharpoonright_{\operatorname{dom}(\sigma)} \mid P \rho\right)$, for $z \# \operatorname{dom}(\rho), \operatorname{ran}(\rho), \nu x . A$.
- Definition 8 (structural congruence). Our minimal structural congruence (denoted $\equiv$ ) is the least equivalence relation on extended processes extending $\alpha$-equivalence such that whenever $\sigma=\theta$ (i.e., the substitutions denote the same function), $P \equiv{ }_{\alpha} Q$ and $A \equiv B$, we have:

$$
\sigma|P \equiv \theta| Q \quad \quad \nu x . A \equiv \nu x . B \quad \quad \nu x . \nu z . A \equiv \nu z . \nu x . A
$$

Notice that we did not include equations such as $P|Q \equiv Q| P,(P \mid Q)|R \equiv P|(Q \mid R)$ or $P \mid 0 \equiv P$, for reasons that will become clear in Sect. 4.2. Many similar systems (sometimes called proved transition systems) miss a structural congruence altogether [15, 24, 26], or miss the associativity and commutativity of the parallel composition [25, p. 242], since they can alter the label of the transition and complicate tracking the source of an action, yet can be recovered by a suitable observational equivalence (e.g., a non-interleaving bisimilarity).

## 4 The Design of a Non-interleaving Structural Operational Semantics

The located structural operational semantic rules introduced in Figs. 2 and 3 adapt the recent semantics developed for the applied $\pi$-calculus in [31, 32], which can be obtained from the one here by simply ignoring the information in red and any other information beneath the arrow in labelled transitions. To obtain a structural operational semantics for

$$
\frac{G \underset{[t]}{\stackrel{\pi}{4}} A}{G+H \underset{[0 t]}{\pi}} \text { SUM-L } \quad \frac{H \underset{[t]}{\underset{~}{\pi}} A}{G+H \underset{[1 t]}{\xrightarrow{\pi}} A} \text { SUM-R } \quad \frac{P \mid!P \underset{u}{\vec{u}} A}{!P \underset{u}{\rightarrow} A} \text { BANG }
$$

$$
\frac{P \stackrel{\pi}{u} A \quad M=_{E} N}{[M=N] P \underset{u}{\vec{~}} A} \text { MAT }
$$

$$
\frac{P \stackrel{\pi}{\vec{u}} A \quad M \not \mathcal{E}_{E} N}{[M \neq N] P \underset{u}{\vec{m}} A} \text { Mismat }
$$

Figure 2 An early located non-interleaving structural operational semantics.
the $\pi$-calculus in this style, simply assume that all messages $M, N$, etc., are variables, and that two variables are equal only if they are the same variable. After briefly introducing our structural operational semantics, we explain our design choices in the subsections that follow.

Action labels range over $\pi$. A free input action label $M N$ indicates the input of message $N$ on channel $M$. A bound output action label $\bar{M}(\alpha)$ indicates the output of something on channel $M$ where the message we output is assigned the alias $\alpha$, which can be used to refer to that message in the future by the observer, or a direct communication $\tau$ that the observer does not intercept. This is the reason why the substitution is applied to the continuation in the InP rule, but "stored" in the substitution in the Out rule. The label $\tau$ denotes an internal communication, and is used in the synchronisation rules presented in Fig. 3.

The functions for free variables and free aliases extend to labels as follows.

$$
\mathrm{fv}(\pi)=\left\{\begin{array}{ll}
\mathrm{fv}(M) \cup \mathrm{fv}(N) & \text { if } \pi=M N \\
\mathrm{fv}(M) & \text { if } \pi=\bar{M}(\alpha) \\
\emptyset & \text { if } \pi=\tau
\end{array} \quad \mathrm{fa}(\pi)= \begin{cases}\mathrm{fa}(M) \cup \mathrm{fa}(N) & \text { if } \pi=M N \\
\mathrm{fa}(M) & \text { if } \pi=\bar{M}(\alpha) \\
\emptyset & \text { if } \pi=\tau\end{cases}\right.
$$

Readers familiar with labelled transition systems will immediately notice the additional annotation below transitions, that uses prefixes composed of 0 s and 1s. This indicates the location of the parallel sub-process (a.k.a. component or thread) performing the action:

$$
\begin{aligned}
& \frac{M={ }_{E} K}{K(x) \cdot P \xrightarrow[{[ }]]{M N} \operatorname{id} \mid P\left\{{ }^{N} / x\right\}} \text { InP } \\
& \frac{P \xrightarrow[u]{\pi} \nu \vec{x} .(\sigma \mid R) \quad \vec{x} \# Q}{P \mid Q \xrightarrow[0 u]{\vec{~}} \nu \vec{x} \cdot(\sigma|R| Q)} \text { PAR-L } \\
& \frac{M={ }_{E} K}{\bar{K}\langle N\rangle . P \xrightarrow[{[ }]]{\bar{M}(\lambda)}\left\{{ }^{N} / \lambda\right\} \mid P} \text { OuT } \\
& \frac{Q \underset{u}{\vec{u}} \nu \vec{x} .(\sigma \mid R) \quad \vec{x} \# P}{P \mid Q \xrightarrow[1 u]{\rightarrow} \nu \vec{x} \cdot(\sigma|P| R)} \text { PAR-R } \\
& \frac{P \underset{u}{\underset{\sim}{\pi}} A \quad x \# \mathrm{fv}(\pi)}{\nu x . P \underset{u}{\vec{~}} \nu x . A} \text { Extrude } \\
& \xrightarrow{P \xrightarrow[{s\left[s^{\prime}\right.}]]{\overline{M \sigma}(\lambda)}} \nu \vec{x} \cdot\left(\left\{{ }^{N} / \lambda\right\} \mid Q\right) \quad \vec{x} \# \operatorname{ran}(\sigma) \quad \mathrm{fa}(M) \subseteq \operatorname{dom}(\sigma) \quad s \lambda \# \operatorname{dom}(\sigma) \quad \text { Alias-out } \\
& \sigma \mid P \xrightarrow[{s\left[s^{\prime}\right.}]]{\bar{M}(s \lambda)} \nu \vec{x} .\left(\sigma \circ\left\{{ }^{N} / s \lambda\right\} \mid Q\right) \\
& \frac{P \xrightarrow[u]{\pi \sigma} \nu \vec{x} .(\mathrm{id} \mid Q) \quad \vec{x} \# \operatorname{ran}(\sigma) \quad \mathrm{fa}(\pi) \subseteq \operatorname{dom}(\sigma)}{\sigma \mid P \xrightarrow[u]{\vec{~}} \nu \vec{x} \cdot(\sigma \mid Q)} \text { ALIAS-FREE }
\end{aligned}
$$

$$
\begin{gathered}
\xrightarrow[\ell_{0}]{P \stackrel{\bar{M}(\lambda)}{\longrightarrow}} \nu \vec{y} \cdot\left(\left\{{ }^{N} / \lambda\right\} \mid P^{\prime}\right) \quad Q \xrightarrow[\ell_{1}]{M N} \nu \vec{w} .\left(\mathrm{id} \mid Q^{\prime}\right) \quad \vec{y} \# Q \quad \vec{w} \# P, \vec{y} \\
P \mid Q \underset{\left(0 \ell_{0}, 1 \ell_{1}\right)}{\longrightarrow} \nu \vec{y}, \vec{w} \cdot\left(\mathrm{id}\left|P^{\prime}\right| Q^{\prime}\right) \\
\xrightarrow{P \xrightarrow[\ell_{0}]{M N}} \nu \vec{y} .\left(\mathrm{id} \mid P^{\prime}\right) \quad Q \underset{\left(0 \ell_{0}, 1 \ell_{1}\right)}{\ell_{1}} \nu \vec{w} \cdot\left(\left\{{ }^{N} / \lambda\right\} \mid Q^{\prime}\right) \quad \vec{y} \# P \quad \vec{y}, \vec{w} .\left(\mathrm{id}\left|P^{\prime}\right| Q^{\prime}\right)
\end{gathered}
$$

Figure 3 Rules for communication.

- Definition 9 (locations). $A$ location $\ell$ is of the form $s[t]$, where $s \in\{0,1\}^{*}$ and $t \in\{0,1\}^{*}$. If $s$ or $t$ is empty, we omit it (hence, we write $\epsilon[\epsilon]$ as []).

The colour coding above is to emphasise everywhere, what we call, the location prefix used to indicate the parallel component from which a transition originates, and the " $t$ part" of a location serves to identify which operand of the sum triggered the transition, as indicated in the Sum-L and Sum-R rules in Fig. 2.

To handle $\tau$-transitions that originate from a synchronisation between an input and an output in two different locations, location labels, used to annotate transitions with events, may be pairs of locations, as employed in Fig. 3.

- Definition 10 (location labels). A location label $u$ is either a location $\ell$ or a pair of locations $\left(\ell_{0}, \ell_{1}\right)$, and we let $c\left(\ell_{0}, \ell_{1}\right)=\left(c \ell_{0}, c \ell_{1}\right)$ for $c \in\{0,1\}$.

Events are pairs of action labels and location labels, as they appear above and below labelled transitions in Fig. 2 and 3. The role of the aliases and the usefulness of their prefix location is justified in Sec. 4.1 and 4.2. The rules Sum-L and Sum-R, and Bang rules have also been carefully designed, as explained in Sec. 4.3, 4.4 and 4.5. We will return, in those sections, to these rules to provide more detailed insight.

The only significant modification that we make to the standard syntax of applied $\pi$ calculus is that aliases have more structure than variables. Aliases, ranging over $\alpha, \beta, \gamma$, are variables, extended with a, possibly empty, prefix of 0 s and 1 s representing the location of the process producing them. For convenience, we use $\lambda, \lambda^{\prime}, \ldots$ to range over variables used as aliases where the prefix is empty, and assume they are of a separate syntactic category from variables used for names and input binders, allowing us to drop some side conditions in rules.

We illustrate throughout the article how some transitions are derived. We sometimes apply the Extrude or Res rules "in batch", omit the id substitution, and list some hypothesis below the derivation. The derivation presented in Fig. 4 illustrates those conventions, but it also explicitly lists the occurrences of $\epsilon$ to help with readability. Indeed, this instance of Alias-out is trivial, since it turns the process on the left into an extended process with the identity substitution that records that nothing has yet been output.

Letting $P_{\mathrm{ok}}=\nu m, n \cdot(\bar{a}\langle\langle m, n\rangle\rangle \mid m(x) \cdot[x=n] \overline{\mathrm{ok}}\langle\mathrm{ok}\rangle)$, we leave to the reader to convince themselves that the following transition is similarly derivable, using the Par-L rule:
id $\mid P_{\mathrm{ok}} \xrightarrow[{{ }_{0[]}}]{\bar{a}(0 \lambda)} \nu m, n \cdot(\{\langle m, n\rangle / 0 \lambda\}|0| m(x) \cdot[x=n] \overline{o k}\langle\mathrm{ok}\rangle)$.

$$
\begin{align*}
& \overline{\bar{c}\langle\langle m, n\rangle\rangle \underset{\epsilon[\epsilon]}{\bar{c}(\lambda)}\{\langle m, n\rangle / \lambda\} \mid 0 \text { OUT } n, m \# \operatorname{fv}(\bar{c}(\lambda)) .} \\
& \xrightarrow{\text { עm. } \nu n . \bar{c}\langle\langle m, n\rangle\rangle \xrightarrow[{\epsilon[\epsilon}]]{\bar{c}(\lambda)}} \nu m . \nu n .(\{\langle m, n\rangle / \lambda\} \mid 0) \\
& \text { Extrude ( } \times 2 \text { ) } \\
& \text { Alias-out } \\
& m, n \# \operatorname{ran}(\mathrm{id})=\emptyset \quad \mathrm{fa}(c)=\emptyset \subseteq \operatorname{dom}(\mathrm{id})=\emptyset \quad \epsilon \lambda \# \operatorname{dom}(\mathrm{id})=\emptyset
\end{align*}
$$

Figure 4 First, simple example of derivation.

We discuss the next transition of $P_{\mathrm{ok}}$ in Sect. 4.1, and the dependence of the two events in Sect. 5. Another interesting example is given by the $\tau$-transitions of the following process.

$$
P_{\tau}=\nu z \cdot\left((\nu x \cdot \bar{a}\langle\langle x, z\rangle\rangle \mid \nu y \cdot \bar{b}\langle\langle y, z\rangle\rangle) \mid\left(a\left(x_{1}\right) \cdot P \mid b\left(x_{2}\right) \cdot Q\right)\right)
$$

This process can perform two different (and, as we will discuss in Sect. 5, independent) synchronizations whose location labels are (00[], 10[]) and (01[], 11[]). The following execution sequences illustrates how our semantics gracefully handles the two (parallel) sources of extrusions of the name $z$ without any additional machinery.

$$
\begin{aligned}
\text { id } \left.\mid P_{\tau} \xrightarrow[{(00[], 10[]})\right]{\tau} & \nu z . \nu x .\left(\mathrm{id}|(0 \mid \nu y . \bar{b}\langle\langle y, z\rangle\rangle)|\left(P\left\{\langle x, z\rangle / x_{1}\right\} \mid b\left(x_{2}\right) \cdot Q\right)\right. \\
& \xrightarrow[{(01[], 11]})]{\tau} \nu z . \nu x . \nu y .\left(\mathrm{id}|(0 \mid 0)|\left(P\left\{\langle x, z\rangle / x_{1}\right\} \mid Q\left\{\langle y, z\rangle / x_{2}\right\}\right)\right)
\end{aligned}
$$

The full derivation trees for the above transitions are presented in Appendix A, Fig. 6. The derivation trees for the alternative sequence of transitions below are similar.

$$
\begin{aligned}
\left.\operatorname{id} \mid P_{\tau} \xrightarrow[{(01[], 11]})\right]{\tau} & \nu z . \nu y .\left(\mathrm{id}|(\nu x \cdot \bar{a}\langle\langle x, z\rangle\rangle \mid 0)|\left(a\left(x_{1}\right) \cdot P \mid Q\left\{\langle y, z\rangle / x_{2}\right\}\right)\right) \\
& \xrightarrow[{(00[], 10[]})]{\tau} \nu z . \nu y . \nu x .\left(\mathrm{id}|(0 \mid 0)|\left(P\left\{\langle x, z\rangle / x_{1}\right\} \mid Q\left\{\langle y, z\rangle / x_{2}\right\}\right)\right)
\end{aligned}
$$

We reuse this process $P_{\tau}$ in Sect. 4.3 to illustrate the need for equivariance.

### 4.1 The Modern Applied $\pi$-Calculus Avoids Disjunctive Causality

The input and output prefixes $M(x) . P$ and $\bar{M}\langle N\rangle . P$, respectively, indicate the channel as a message $M$, which is the modern approach to the applied $\pi$-calculus handling extruded messages [1]. Looking back at id $\left.\mid P_{\mathrm{ok}} \xrightarrow[{[ }]\right]{\bar{a}(0 \lambda)} \nu m, n .\left(\left\{{ }^{\langle m, n\rangle} / 0 \lambda\right\}|0| m(x) \cdot[x=n] \overline{\mathrm{ok}}\langle\mathrm{ok}\rangle\right)$, note that the active substitution $\{\langle m, n\rangle / 0 \lambda\}$ can be used in subsequent events. For example, we may refer to the private name $m$ by using the message $f s t(0 \lambda)$, which is then instantiated with the above active substitution, as illustrated by the following derivation of a transition (assuming a message theory featuring equation $\operatorname{fst}(\langle m, n\rangle)={ }_{E} m$ ):

Referring to channels that were extruded inside messages was not possible in early versions of the applied $\pi$-calculus [2]. This approach to extrusion is important to emphasise since adopting this modern approach significantly simplifies our labelled asynchronous transition system, as we explain next.

The key problem is to define a "stable" semantic in the presence of "link causality". This means that, if multiple output events extrude the same name, we must record which output was used when that name appears in future events. An established approach to dealing with


```
Letting \(\sigma=\{\langle m, n\rangle / 0 \lambda\}\), since fst \((0 \lambda) \operatorname{snd}(0 \lambda) \sigma=\mathrm{fst}(\langle m, n\rangle) \operatorname{snd}(\langle m, n\rangle)\),
    \(\epsilon \# \operatorname{ran}(\sigma)=\{m, n\} \quad\) fa \((\mathrm{fst}(0 \lambda) \operatorname{snd}(0 \lambda))=\{0 \lambda\} \subseteq \operatorname{dom}(\sigma)=\{0 \lambda\} \quad(\star)\)
    \(n, m \# \mathrm{fv}(\mathrm{fst}(0 \lambda) \operatorname{snd}(0 \lambda))=\emptyset \quad \quad(\star \star)\)
```

this "disjunctive dependency" is to extend the labels of transitions to record explicitly the set of output events each input depends on (by recording the source and target processes of the transition) [30, Def. 2.18]. Another established approach is to represent the disjunctive link causality in an "inclusive way" [20, p. 227], that "ensures that whenever an action with a bound subject is executed, at least one extrusion of that bound name must have been already executed", but without recording which output was the real extruder that influenced another event. These additional mechanisms, used in related work, are used to acknowledge the difference between two extrusion events and recognise them as separate events.

The use of aliases avoids the disjunctive dependency problem entirely. Consider the process $\nu n .(\bar{a}\langle n\rangle \mid(\bar{a}\langle n\rangle \mid n(x) . P))$ for example. This process can trigger both the output events $(\bar{a}(0 \lambda), 0[])$ and $(\bar{a}(10 \lambda), 10[])$ :

$$
\begin{aligned}
\text { id } \mid \nu n .(\bar{a}\langle n\rangle \mid(\bar{a}\langle n\rangle \mid n(x) \cdot P)) \xrightarrow[{0[ }]]{\bar{a}(0 \lambda)} & \nu n .\left(\left\{{ }^{n} / 0 \lambda\right\}|0|(\bar{a}\langle n\rangle \mid n(x) \cdot P)\right) \\
& \xrightarrow[{10[ }]]{ } \nu n \cdot\left(\left\{{ }^{n} / 0 \lambda\right\} \circ\left\{{ }^{n} / 10 \lambda\right\}|0|(0 \mid n(x) \cdot P)\right)
\end{aligned}
$$

and, afterwards, only one of the input events $(0 \lambda M, 11[])$ or ( $10 \lambda M, 11[]$ ) (letting $M^{\prime}=$ $M\{n / 0 \lambda\} \circ\{n / 10 \lambda\})$ :

$$
\nu n \cdot\left(\{ n / 0 \lambda \} \circ \{ n / 1 0 \lambda \} | 0 | ( 0 | n ( x ) \cdot P ) \left\{\begin{array}{l}
\left.\begin{array}{l}
\frac{0 \lambda M}{11]} \nu n \cdot\left(\{ n / 0 \lambda \} \circ \{ n / 1 0 \lambda \} | 0 | \left(0 \mid P\left\{M^{\prime} / x\right\}\right.\right.
\end{array}\right) \\
\xrightarrow[11]]{\frac{10 \lambda M}{}} \nu n \cdot\left(\{n / 0 \lambda\} \circ\{n / 10 \lambda\}|0|\left(0 \mid P\left\{M^{\prime} / x\right\}\right)\right.
\end{array}\right.\right.
$$

It is clear that input $0 \lambda M$ is dependent on the output originating from the first thread in location 0 , while the input with alias $10 \lambda M$ is dependent on the output in location 10. Thus there is no need to perform event splitting, since there is no ambiguity about the source of the extrusion used to refer to channel $n$. The derivations of the transitions producing these events are presented in Appendix A.

### 4.2 Applied $\pi$-Calculus With Located Aliases

Recall that located aliases are variables prefixed with a string indicating the location in which the corresponding output occurred. The idea of prefixing aliases with a string representing a location is a novelty, which is necessary for the development of our LATS, as explained here. The strings themselves are, however, inherited from earlier work on LATS for CCS [39], where such strings are used to annotate labelled transitions and are used to determine whether actions are independent.

This modification to the syntax of the applied $\pi$-calculus serves two purposes: it enables us to define the independence relation only based on information from the events that label the transitions (Def. 12), and provides each location with a separate pool of aliases. Let us illustrate this latter purpose by picturing two execution sequences, with the locations omitted for now:


The challenge stems from needing to satisfy diamond property 1 , as the two transitions are clearly independent: in the initial process $\nu m, n .(\bar{a}\langle m\rangle \mid \bar{a}\langle n\rangle)$, traditional semantics of the applied $\pi$-calculus allow us to use alias $\alpha$ for both initial transitions, whether the up or down transition is triggered. This freedom, unfortunately, violates diamond property 1 , since taking the top or bottom transitions yields distinct substitutions, represented by ?. Of course, this difference in aliasing is irrelevant provided $\alpha$ and $\beta$ are both fresh in every process involved, hence we "localise" the generation of fresh aliases.

To "localise" the generation of fresh aliases, we add a prefix to aliases, similarly to location labels, i.e., a (possibly empty) string of 1 s and 0 s , representing where an alias originates from within the binary tree of parallel locations. Those locations become genuine parts of the aliases, so that, e.g., $10 \lambda$ and $11 \lambda$ are distinct aliases (and of course $10 \lambda$ and $10 \lambda^{\prime}$ are also distinct aliases, so there is an infinite supply of aliases for each location). Since our structural operational semantics does not assume that the parallel operator is commutative or associative, the bracketing of processes composed in parallel remains stable throughout an execution; and locations do not disappear as they would if we had included $P \mid 0 \equiv P$.

Going back to our example (rough diamond), this modification allows us to satisfy diamond property 1 (ignoring the location label from under the arrows):

(smooth diamond)

### 4.3 The Need for Equivariance

The order in which threads can be triggered can have an effect on the order of fresh name binders. Therefore, we consider states up to equivariance, that is, our structural congruence (Def. 8) extends $\alpha$-equivalence such that $\nu x . \nu y . A \equiv \nu y . \nu x . A$. To see why we require equivariance, consider the following diamond of output transitions:

(Diamond upto equivariance)
Without taking the quotient, both transitions would reach different states, and any independence relation making the consecutive events $\bar{a}(0 \lambda)$ and $\bar{a}(1 \lambda)$ independent could not satisfy diamond property 2. This is also because the substitutions are the same function, hence the order in which composition is applied does not distinguish the extended processes.

Equivariance is also essential for identifying states that are the same after independent synchronisations. For example, the two execution sequences of id $\mid P_{\tau}$ discussed earlier would not reach equivalent states without equivariance. More explicitly, after two $\tau$ transitions id $\mid P_{\tau}$ can either reach the state $\nu z . \nu y . \nu x$.(id $|(0 \mid 0)|\left(P\left\{{ }^{\left.\langle x, z\rangle / x_{1}\right\}} \mid Q\left\{{ }^{\langle y, z\rangle} / x_{2}\right\}\right)\right)$ or the state $\nu z . \nu x . \nu y$.(id $|(0 \mid 0)|\left(P\left\{{ }^{\langle x, z\rangle} / x_{1}\right\} \mid Q\left\{{ }^{\left.\langle y, z\rangle / x_{2}\right\}}\right)\right)$ depending on which synchronisation is applied first. Observe how these extended processes only differ in that the binders for $x$ and $y$ are swapped, and hence are the same state up to equivariance.

### 4.4 Distinguishing Events in Conflict

The event determinism property of LATS requires more care in defining the semantics for the choice operator. Since event determinism is more fine-grained than the concept of "action determinism" in works on POR [5, Definition 4.1], our work is useful there too.

Our mechanism giving a located semantics to choice is similar to proved transtions [12] in the sense that our locations $s[t]$ contain information not only about the parallel structure (given by $s$ ), but also about the structure of choices (given by $t$ ). For instance, in transition

$$
\text { id } \left.\left|\left(\left(\left(P_{1}+a(x) \cdot P\right)+P_{2}\right) \mid\left(P_{3}+\bar{a}\langle n\rangle\right)\right)\right| P_{4} \xrightarrow[{0(0[01], 1[1]})\right]{\tau} \mathrm{id}\left|\left(P\left\{{ }^{n} / x\right\} \mid 0\right)\right| P_{4},
$$

(derived in Fig. 5) the first choice label [01] indicates that $a(x) . P$ was responsible for the input action in $\left(P_{1}+a(x) . P\right)+P_{2}$. Our choice labels diverge, however, from [39] where each location contains the source and target processes involved in that transition. We found that this established approach for CCS does not appear to work for applied $\pi$-calculus extended processes, such as $\nu m, n .\left(\left\{{ }^{m} / \lambda_{0}\right\} \mid \bar{c}\langle\langle m, n\rangle\rangle+\bar{c}\langle\langle n, m\rangle\rangle\right)$, for which transitions $\left.\xrightarrow[{[\bar{c}\langle\langle m, n\rangle\rangle][0}]\right]{\bar{c}\left(\lambda_{1}\right)}$ and $\xrightarrow[{[\bar{c}\langle\langle n, m\rangle\rangle][0}]]{\bar{c}\left(\lambda_{1}\right)}$ could be made by either branch of the choice upto equivariance, unless we add information that would break diamond properties.

Besides providing a more concise notation, our location labels unambiguously indicate which output in the non-deterministic choice was triggered in the following two co-initial transitions:

$$
\nu m, n .\left(\left\{{ }^{m} / \lambda_{0}\right\} \mid \bar{c}\langle\langle m, n\rangle\rangle+\bar{c}\langle\langle n, m\rangle\rangle\right)\left\{\begin{array}{l}
\left.\begin{array}{l}
\stackrel{\bar{c}\left(\lambda_{1}\right)}{[1]} \\
\\
\end{array}\right], n \cdot\left(\left\{m / \lambda_{0}\right\} \circ\left\{\langle n, m\rangle / \lambda_{1}\right\} \mid 0\right) \\
\xrightarrow[{[0}]]{\bar{c}\left(\lambda_{1}\right)} \nu m, n \cdot\left(\left\{m / \lambda_{0}\right\} \circ\left\{\langle m, n\rangle / \lambda_{1}\right\} \mid 0\right)
\end{array}\right.
$$

Figure 5 Derivation example involving sum and synchronisation.

Moreover, identifying the events would violate event determinism, as the resulting extended processes are different. Notice that we do not record name binders in the events, since, unlike CSS, names move around in a way that would violate diamonds. Instead, name binders are handled by mechanisms used inside the proofs of diamond properties.

### 4.5 Addressing the Location of Replicated Processes

As usual, the replication operator ! is used to represent an unbounded number of sessions. Recording more structure than the labels when defining events prevents the rule BANG from creating image-finiteness problems that the same rule creates for an action-based LTS. Indeed, since we have event determinism, the image of any extended process and event is a singleton upto structural congruence. This design decision gives to every replicated process an infinite pool of explicit location names, and allows each of these locations to be triggered in any order. This is important to satisfy diamond property 2.

To explain this, consider the following example that use the process $\bar{a}\langle y\rangle \cdot \bar{b}\langle z\rangle \cdot Q=P_{b}$, which can perform the following transitions:

$$
\text { id } \left.\left.\mid!P_{b} \xrightarrow[{0[ }]\right]{\bar{a}(0 \lambda)}\{y / 0 \lambda\}|\bar{b}\langle z\rangle \cdot Q|!P_{b} \xrightarrow[{0[ }]\right]{\bar{b}\left(0 \lambda^{\prime}\right)}\{y / 0 \lambda\} \circ\left\{z / 0 \lambda^{\prime}\right\}|Q|!P_{b}
$$

Our definition of independence relation (Def. 11) - and, we believe, any reasonable locationbased definition of independence - would ensure that the two events $(\bar{a}(0 \lambda), 0[])$ and ( $\left.\bar{b}\left(0 \lambda^{\prime}\right), 0[]\right)$ are not independent - they are treated as coming from the same location, even if that location "did not exist" when $P_{b}$ started its execution. Hence diamond property 2 cannot apply and these events cannot permute, as expected. This mechanism echoes e.g., the dependency relation that can be developed to accommodate replication for CCS [23].

In contrast, consider the following transitions, also originating from the same process $!P_{b}$ :

(Diamond with a bang)

The events on the left-hand side of the diamond above are expected to be independent. Fortunately, by triggering BANG twice, we can permute these transitions as required by diamond property 2. That is, the right side of the above diamond exists.

An alternative solution could be to use explicit names to label locations, and partially ordering those labels to reflect the hierarchy of locations, and then minting fresh names for each transition of a replication [13, 44]. Using opaque names as locations, however, would have forced us to record them in the syntax of processes, that would have become e.g., of the form $\ell_{1}:: \bar{b}\langle z\rangle . Q \mid\left(\ell_{2}:: \bar{b}\langle z\rangle . Q \mid!P\right)[12]$. The intent is however the same.

## 5 The Independence Relation and the Main Result

In this section, we define what it means for two events to be independent. To do this, firstly, we define structural independence, which ensures that two events occur in different locations by checking that it is not the case that one location prefix is a prefix (as a string) of the other event's location prefix.

- Definition 11 (structural independence). Define $\mathcal{L}$ oc on location labels such that $\mathcal{L} o c(\ell)=\{\ell\}$ and $\mathcal{L o c}\left(\ell_{0}, \ell_{1}\right)=\left\{\ell_{0}, \ell_{1}\right\}$. The structural independence relation $I_{\ell}$ on location labels is the least relation defined by $u_{0} I_{\ell} u_{1}$ whenever for all locations $\ell_{0} \in \mathcal{L}$ oc $\left(u_{0}\right)$ and $\ell_{1} \in \mathcal{L} o c\left(u_{1}\right)$, there exist a string $s \in\{0,1\}^{*}$ and locations $\ell_{0}^{\prime}, \ell_{1}^{\prime}$, such that either: $\ell_{0}=s 0 \ell_{0}^{\prime}$ and $\ell_{1}=s 1 \ell_{1}^{\prime}$; or $\ell_{0}=s 1 \ell_{0}^{\prime}$ and $\ell_{1}=s 0 \ell_{1}^{\prime}$.

For example, consider the locations of the four output events in $\bar{a}\langle a\rangle \mid \bar{b}\langle b\rangle .(\bar{c}\langle c\rangle \mid \bar{d}\langle d\rangle)$. The output on channel $a$ (location prefix 0 ) is structurally independent from all other outputs. The output on channel $b$ (location prefix 1 ) is not structurally independent with respect to the outputs on channels $c$ or $d$; which will have location prefixes 10 and 11 respectively, both with 1 as a common prefix. However, the outputs on channel $c$ and $d$ are independent, since neither 10 nor 11 are prefixes of each other.

Independence on events in addition detects whether an output influences another action. That is, in addition to structural independence, we have link independence.

- Definition 12 (independence of events). Events $e=(\pi, u)$ are pairs of labels $\pi$ and location labels $u$. The independence relation $I$ on events is the least symmetric relation such that $\left(\pi_{0}, u_{0}\right) I\left(\pi_{1}, u_{1}\right)$ whenever $u_{0} I_{\ell} u_{1}$ and if $\pi_{0}=\bar{M}(\alpha)$, then $\alpha \# \pi_{1}$.

Remember that $P_{\mathrm{ok}}$ from Sect. 4 and 4.1 can trigger the event $(\bar{a}(0 \lambda), 0)$ followed by (fst $(0 \lambda) \operatorname{snd}(0 \lambda), 1)$. Even if the locations are independent (as $0 I_{\ell} 1$ ), the two events are not independent, since $0 \lambda$ is not fresh in (fst $(0 \lambda) \operatorname{snd}(0 \lambda))$.

- Theorem 13. The structural operational semantics in Fig. 2 and 3 generates a labelled asynchronous transition system with respect to the independence relation I from Def. 12, i.e., it respects Def. $1-3$, where events are the pairs of action and location labels $(\pi, u)$, as they appear on the labels of transitions, and states are extended processes modulo the structural congruence from Def. 8. [see proof in Appendix B]

Link independence is only required to permute an output event followed by an independent event, when establishing diamond property 2. The main intricacy compared to CCS is to ensure that the name restrictions occurring along any common prefix of two independent transitions are handled correctly - this is how the parallel extrusion problem in related theories manifests itself in this theory. We handle this problem entirely within the proof, via variables accumulated in a function that picks out the component of a process corresponding to a location prefix, rather than within the semantics as in related work [30, 50].

## 6 Related Work

The earliest papers on partial-order reduction for security are not working with the applied $\pi$-calculus, but rely on constructing execution DAGs (or Mazurkiewicz traces) recording all input-output dependencies; as a result, the protocols considered in [18, 21, 27, 38] are essentially threads of inputs and outputs, disregarding channels.

Our paper is closer to more recent approaches to POR for the applied $\pi$-calculus $[6,7,8]$. However, one limitation of these works is that they require processes to be of a particular form. In that related line of work, structural independence is based on the channel of an input and output action, thus considering events structurally independent only when they employ distinct channels. Thus, their scope is restricted to processes in which every location is a single thread of sequential actions (e.g., cannot spawn parallel threads in a location) and if-then-else branches that employ a unique channel. While many finite protocol problems can be formulated with a fixed number of threads, each employing separate channels, this is still a significant restriction. In contrast, we base the structural independence on the components' addresses, which allows us to consider the "full" applied $\pi$-calculus.

For modelling infinite protocols (or protocols where the same, or multiple, actors can engage in multiple parallel sessions) one normally uses replication, and thus parallel extrusion appears naturally. Some of the above related works [7] approximate replication by creating fresh channels manufactured every time a parallel component is created. However, since these works do not have mechanisms for dealing with disjunctive causality (which in these settings is required because of the use of a different mechanism for extrusion, similar to the standard $\pi$-calculus), channel extrusion is only supported for processes where parallel extrusion of channels never occurs. In contrast, our approach, where channels are extruded like any other message and aliases resolve the aforementioned disjunctive causality problem, supports all forms of processes including replication and parallel extrusion.

A further difference compared to the above work concerns $\tau$ transitions. In the related work we are discussing, there is not enough information to determine whether two $\tau$ transitions are independent, and hence such parts of a protocol's behaviour cannot be considered for POR optimisation. In our semantics, we resolve this problem using our structural independence relation based on the recorded locations responsible for the input and output actions involved in a $\tau$ transition. Our solution simply lifts classic work on CCS [39] to this security setting, while taking care to handle parallel extrusion correctly (recall the $P_{\tau}$ example from Sect. 4).

All the above work does not follow the non-interleaving tradition in the sense that they do not feature diamond property 1. It is possible in the semantics of $[6,8,17]$ that two transitions that we deem independent and are enabled from some process will disable each other, since their executions change the substitution on which the other depends. This is the key problem our located aliases address. The only diamond property that related approaches obtain (and for a limited subset of processes, as explained above) is the "reordering of sequential independent transitions", which is our diamond property 2. However, this property alone can be achieved without located aliases since, anyway, two sequential outputs would be named differently by the regular constraints of the applied $\pi$-calculus, which simply ensure that an extruded alias is globally fresh.

Event determinism can be achieved in works such as [7, 8] only for choice of the type if-then-else. By borrowing from proved transitions [12], our events record the precise branch of a general non-deterministic choice from which they originate, thereby achieving event-determinism for all types of processes. This problem has been acknowledged [6], and an
alternative approach to POR using sleep sets has been proposed. This approach essentially defines independence in terms of events satisfying our diamond property 1 , but since the semantics they employ allows two concurrently enabled outputs on the same channel to use the same label, such events would incorrectly be considered not independent.

We see a good opportunity in adopting (concepts from) our semantics in the settings and tools of the above papers. This possibility has been one of our goals all along, and guided our decisions to consider a syntax very close to the standard applied $\pi$-calculus and to define a structural operational semantics that just extends previous semantics for applied $\pi$ [32]. Even the choice of LATS was guided by our wish to stay within the realm of transition systems, yet to go over from interleaving to non-interleaving semantics. Hence, we expect it to be possible to upgrade tools from the above mentioned papers, so that they may fully support POR for all processes.

## 7 Conclusion

The work we build on incorporates elements of the modern applied $\pi$-calculus [1] - aliases for extrusion of channels as messages - into a structural operational semantics [31, 32]. Our semantics in Fig. 2 and 3 transforms this established semantics into a non-interleaving structural operational semantics by recording on transitions also the location from which an event originates as well as the location from where an alias representing an output originates. The former is a standard device, coming from non-interleaving semantics for CCS [12, 39] and $\pi$-calculus [30], while the latter "located alias" is the key technical innovation required to ensure that our structural operational semantics defines a LATS (Theorem 13). In this way we obtain a genuine operational semantics, with a remarkably simple independence relation (Def. 12) for such a powerful calculus. Moreover, this paper can also be seen as proposing LATS as the semantic objects for applied $\pi$-calculi, instead of transition systems, so as to bridge other non-interleaving models to which LATS have been related in the literature.

Because LATS have been shown [28] to be exactly the higher-dimensional automata of dimension 2, we can reuse the definitions for higher-dimensional automata of the classical concurrency bisimulations (i.e., of ST-, history preserving-, and hereditary history preservingbisimulations) for LATS [47]. Moreover, through relations of LATS with configuration structures [49] and event structures [51] we can reuse also other concurrency bisimulations [48]. In related work, partial-order semantics have been employed in tools for optimising verification of equivalence properties [17]. Making precise the connection between the equivalences employed in such tools and the above non-interleaving equivalences for LATS is future work.

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## A Derivations for selected example transitions

We present the derivations of the transitions used to illustrate stability in Sect. 4.1. We are explicit, in the input transitions, about the source of the extruded name.

$\overline{\bar{a}\langle\langle x, z\rangle\rangle \xrightarrow{\bar{a}(\lambda)}\{\langle x, z\rangle / \lambda\} \mid 0}$ OUT

Figure 6 Derivation of the first execution sequence for $P_{\tau}$.

## B Proof outline: event determinism, decomposition, \& composition

We prove each condition event determinism, diamond property 1 and diamond property 2 separately. For event determinism, we first establish a slightly stronger lemma for processes only (Lemma 14), before covering extended processes. The two diamond properties are more involved. For both, we make use of a function (Def. 16) that, for each location prefix, "localises" in a process the corresponding "component". This is used to pick out components of a process that are active or inactive in a transition. The function also calculates the variables that are to be extruded along the path to the component to be picked out. The decomposition lemmas (Lemmas 18 and 20) use the above function, to pull apart the derivation tree of transitions to get to the exact part of the tree that concerns the component(s) independent from the component(s) of another transition. In both diamond properties, we have two independent transitions, and hence by decomposition, we can identify the common parts of the derivation of both transitions, and the parts of the derivation where the transitions differ. We then appeal to composition lemmas (Lemmas 22 and 23), that construct transitions where we swap the beginning and end of derivations, thereby completing the missing face of each diamond, modulo some permutations of name binders (enabled by equivariance, Sect. 4.3) and substitutions.

We first establish event determinism for processes only, below. The permutation on variables is used to cope with the Extrude rules that possibly applies $\alpha$-equivalence to rename bound variables.

- Lemma 14 (determinism for processes). Assuming $\rho$ is a permutation (bijective operator) on variables such that $\operatorname{dom}(\rho) \# \pi$ we have, if $P \equiv{ }_{\alpha} Q \rho$ and $P \xrightarrow[u]{\vec{\rightarrow}} B$ and $Q \xrightarrow[u]{\pi^{\prime}} C$ then:
- if $\pi=\bar{M}(\lambda)$, then $\pi^{\prime}=\bar{K}\left(\lambda^{\prime}\right)$ and $M={ }_{E} K$ and, furthermore, given that we have $C=\nu \vec{y} \cdot\left(\left\{{ }^{N} / \lambda^{\prime}\right\} \mid Q^{\prime}\right)$ we have also that $B \equiv_{\alpha}\left(\nu \vec{y} \cdot\left(\left\{{ }^{N} / \lambda\right\} \mid Q^{\prime}\right)\right) \rho ;{ }^{1}$
- if $\pi=\pi^{\prime}$, we have $B \equiv{ }_{\alpha} C \rho$.

Then we extend the above lemma to extended processes, from which event determinism follows by taking the permutation to be the identity.

- Lemma 15 (determinism for extend processes). Assuming $\rho$ is a permutation on variables such that $\operatorname{dom}(\rho) \# \pi$, we have, if $A_{0} \equiv A_{1} \rho$ and $A_{0} \xrightarrow[\vec{u}]{\vec{\pi}} B_{0}$ and $A_{1} \underset{\vec{u}}{\vec{\pi}} B_{1}$ then $B_{0} \equiv B_{1} \rho$.

The proofs of the diamond properties rely on the following function selecting the component of a process corresponding to a location prefix.

- Definition 16 (components). Writing Proc the set of processes and Vars the set of variables, we define inductively a partial function Comp : $\{0,1\}^{*} \rightarrow$ (Vars* $\times$ Proc) $\rightarrow$ (Vars* $\left.{ }^{*} \mathbf{P r o c}\right)$ such that $\operatorname{Comp}(\epsilon)(\vec{y}, P)=(\vec{y}, P)$ and if $s \neq \epsilon$ then it is defined as follows:

$$
\begin{array}{lr}
\operatorname{Comp}(0 s)\left(\vec{y}, P_{0} \mid P_{1}\right)=\operatorname{Comp}(s)\left(\vec{y}, P_{0}\right) & \operatorname{Comp}(s)(\vec{y}, \nu x . P)=\operatorname{Comp}(s)(\vec{y} x, P) \\
\operatorname{Comp}(1 s)\left(\vec{y}, P_{0} \mid P_{1}\right)=\operatorname{Comp}(s)\left(\vec{y}, P_{1}\right) & \operatorname{Comp}(s)(\vec{y},!P)=\operatorname{Comp}(s)(\vec{y}, P \mid!P)
\end{array}
$$

[^0]The decomposition lemmas below select the part of a derivation tree that concerns a single component. We first establish decomposition for simple prefixes consisting of 0 or 1 . In what follows, we write $\neg:\{0,1\} \rightarrow\{0,1\}$ for Boolean negation.

- Lemma 17 (decomposing prefixed transitions). For all $c \in\{0,1\}$, if $P \xrightarrow[c u]{\pi} \nu \vec{z} \cdot(\theta \mid Q)$, then:
- $\operatorname{Comp}(c)(\epsilon, P)=\left(\vec{y}, P^{\prime}\right)$ and $\vec{z}=\vec{y}, \vec{x}$ and $P^{\prime} \xrightarrow[u]{\pi} \nu \vec{x} .\left(\theta \mid Q^{\prime}\right)$ and $\operatorname{Comp}(c)(\epsilon, Q)=\left(\epsilon, Q^{\prime}\right)$.
- In addition, $\operatorname{Comp}(\neg c)(\epsilon, P)=(\vec{y}, R)$ and $\operatorname{Comp}(\neg c)(\epsilon, Q)=(\epsilon, R)$ and $\vec{x} \# R .{ }^{2}$

We then appeal to the fact that $\operatorname{Comp}(s)\left(\operatorname{Comp}\left(s^{\prime}\right)(h, P)\right)=\operatorname{Comp}\left(s^{\prime} s\right)(h, P)$ and make use of Lemma 17 repeatedly to generalise decomposition to an arbitrary string.

- Lemma 18 (decomposing process transitions). For all $s \in\{0,1\}^{*}$ and $P \underset{s u}{\underset{~}{~}} \nu \vec{z} \cdot(\theta \mid Q)$ then we have the following:
- $\operatorname{Comp}(s)(\epsilon, P)=\left(\vec{y}, P^{\prime}\right)$ and $\vec{z}=\vec{y}, \vec{x}$ and $P^{\prime} \underset{u}{\vec{u}} \nu \vec{x} .\left(\theta \mid Q^{\prime}\right)$ and $\operatorname{Comp}(s)(\epsilon, Q)=\left(\epsilon, Q^{\prime}\right)$;
- for any $s^{\prime}, s^{\prime \prime} \in\{0,1\}^{*}$, and $c \in\{0,1\}$, if $s=s^{\prime} c s^{\prime \prime}$ then $\operatorname{Comp}\left(s^{\prime} \neg c\right)(\epsilon, P)=(\vec{w}, R)$ and $\operatorname{Comp}\left(s^{\prime} \neg c\right)(\epsilon, Q)=(\epsilon, R)$ and $\operatorname{Comp}\left(s^{\prime} c\right)(\epsilon, P)=(\vec{w}, S)$ and $\operatorname{Comp}\left(s^{\prime \prime}\right)(\epsilon, S)=\left(\vec{v}, P^{\prime}\right)$, and also $\vec{v}, \vec{x} \# R$.

A richer decomposition lemma is needed for $\tau$-transitions, so that we can identify the two components - for the input and output transition involved in the communication - that are both structurally independent of another transition.

- Lemma 19 (interaction decomposition). If $P \xrightarrow[\left(0 \ell_{0}, 1 \ell_{1}\right)]{\tau} \nu \vec{z} \cdot(\theta \mid Q)$ then we have $\operatorname{Comp}(0)(\epsilon, P)=\left(\vec{y}, P_{0}\right)$ and $\operatorname{Comp}(1)(\epsilon, P)=\left(\vec{y}, P_{1}\right)$ and $\operatorname{Comp}(0)(\epsilon, Q)=\left(\epsilon, Q_{0}\right)$ and $\operatorname{Comp}(1)(\epsilon, Q)=\left(\epsilon, Q_{1}\right)$ and $\vec{z}=\vec{y}, \vec{x}_{0}, \vec{x}_{1}$ and $\vec{x}_{0} \# Q_{1}$ and $\vec{x}_{1} \# Q_{0}$ and $\vec{x}_{0} \# \vec{x}_{1}$ and one of the following hold:
- $P_{0} \xrightarrow[\ell_{0}]{\bar{M}(\lambda)} \nu \vec{x}_{0} \cdot\left(\left\{{ }^{N} / \lambda\right\} \mid Q_{0}\right)$ and $P_{1} \xrightarrow[\ell_{1}]{M N} \nu \vec{x}_{1} .\left(\mathrm{id} \mid Q_{1}\right)$.
$=P_{0} \xrightarrow[\ell_{0}]{M N} \nu \vec{x}_{0} .\left(\mathrm{id} \mid Q_{0}\right)$ and $P_{1} \xrightarrow[\ell_{1}]{\bar{M}(\lambda)} \nu \vec{x}_{1} \cdot\left(\left\{{ }^{N} / \lambda\right\} \mid Q_{1}\right)$.
Again appealing to that fact that $\operatorname{Comp}(s)\left(\operatorname{Comp}\left(s^{\prime}\right)(h, P)\right)=\operatorname{Comp}\left(s^{\prime} s\right)(h, P)$ we can generalise decomposition of interactions to an arbitrary prefix string.
- Lemma 20 (full decomposition of interactions). For all $s, s_{0}, s_{1} \in\{0,1\}^{*}$ such that we have $P \xrightarrow[s\left(0 s_{0} \ell_{0}, 1 s_{1} \ell_{1}\right)]{\tau} \nu \vec{z} \cdot(\theta \mid Q)$, the following hold:
- we have $\operatorname{Comp}\left(s 0 s_{0}\right)(\epsilon, P)=\left(\vec{y} \vec{z}_{0}, P_{0}\right)$ and $\operatorname{Comp}\left(s 1 s_{1}\right)(\epsilon, P)=\left(\vec{y} \vec{z}_{1}, P_{1}\right)$ and, also we have $\operatorname{Comp}\left(s 0 s_{0}\right)(\epsilon, Q)=\left(\epsilon, Q_{0}\right)$ and $\operatorname{Comp}\left(s 1 s_{1}\right)(\epsilon, Q)=\left(\epsilon, Q_{1}\right)$ and $\vec{z}=\vec{y}, \vec{z}_{0}, \vec{x}_{0}, \vec{z}_{0}, \vec{x}_{1}$ and $\vec{z}_{0}, \vec{x}_{0} \# Q_{1}$ and $\vec{z}_{1}, \vec{x}_{1} \# Q_{0}$ and $\vec{z}_{0}, \vec{x}_{0} \# \vec{z}_{1}, \vec{x}_{1}$ and one of the following hold:
$=P_{0} \xrightarrow[\ell_{0}]{\bar{M}(\lambda)} \nu \vec{x}_{0} \cdot\left(\{N / \lambda\} \mid Q_{0}\right)$ and $P_{1} \xrightarrow[\ell_{1}]{M N} \nu \vec{x}_{1} .\left(\mathrm{id} \mid Q_{1}\right)$,
$=P_{0} \xrightarrow[\ell_{0}]{M N} \nu \vec{x}_{0} .\left(\mathrm{id} \mid Q_{0}\right)$ and $P_{1} \xrightarrow[\ell_{1}]{\bar{M}(\lambda)} \nu \vec{x}_{1} .\left(\{N / \lambda\} \mid Q_{1}\right)$;
- for any $s^{\prime}, s^{\prime \prime} \in\{0,1\}^{*}$, and $c \in\{0,1\}$ and $s^{\prime} \neq s$, we have the following: if $s 0 s_{0}=s^{\prime} c s^{\prime \prime}$ or $s 1 s_{1}=s^{\prime} c s^{\prime \prime}$ then $\operatorname{Comp}\left(s^{\prime} \neg c\right)(\epsilon, P)=(\vec{w}, R)$ and $\operatorname{Comp}\left(s^{\prime} \neg c\right)(\epsilon, Q)=(\epsilon, R)$ and also $\operatorname{Comp}\left(s^{\prime} c\right)(\epsilon, P)=(\vec{w}, S)$ and $\operatorname{Comp}\left(s^{\prime \prime}\right)(\epsilon, S)=\left(\vec{v}, P^{\prime}\right)$, and we have $\vec{v}, \vec{x}_{0}, \vec{x}_{1} \# R$.

[^1]Composition lemmas are required to remember the part of the derivation tree picked out by the decomposition lemmas, when constructing a new transition. As for decomposition, we first establish composition for a single-character prefix: 0 or 1 .

- Lemma 21 (composing in one-step). For any $s \in\{0,1\}$, if $\operatorname{Comp}(s)(P)=\left(\vec{y}, P^{\prime}\right)$ and we have $P^{\prime} \xrightarrow[u]{\pi} \nu \vec{z} \cdot\left(\sigma \mid Q^{\prime}\right)$ and, furthermore, $\operatorname{Comp}(\neg s)(P)=(\vec{y}, R)$ and $\vec{z} \# R$, then, for some $Q$, we have $P \underset{s u}{\underset{s u}{\rightarrow}} \nu \vec{y}, \vec{z} \cdot(\sigma \mid Q)$ and $\operatorname{Comp}(s)(\epsilon, Q)=\left(\epsilon, Q^{\prime}\right)$.

As for decomposition, we extend composition to any prefix.

- Lemma 22 (composing transitions). Assume $s \in\{0,1\}^{*}$, and $\operatorname{Comp}(s)(P)=\left(\vec{y}, P^{\prime}\right)$ and we have $P^{\prime} \xrightarrow[u]{\vec{u}} \nu \vec{z} \cdot\left(\sigma \mid Q^{\prime}\right)$, and, furthermore, for any $s^{\prime}, s^{\prime \prime} \in\{0,1\}^{*}$, and $c \in\{0,1\}$ such that $s=s^{\prime} c s^{\prime \prime}$, we have $\operatorname{Comp}\left(s^{\prime} \neg c\right)(\epsilon, P)=(\vec{w}, R)$ and $\operatorname{Comp}\left(s^{\prime} c\right)(\epsilon, P)=(\vec{w}, S)$ and $\operatorname{Comp}\left(s^{\prime \prime}\right)(\epsilon, S)=\left(\vec{v}, P^{\prime}\right)$, and also $\vec{v}, \vec{x} \# R$. Given these assumptions, we have that, for some $Q$, we have $P \xrightarrow[s u]{\pi} \nu \vec{y}, \vec{z} \cdot(\sigma \mid Q)$ and $\operatorname{Comp}(s)(\epsilon, Q)=\left(\epsilon, Q^{\prime}\right)$.

Interactions can also be composed.

- Lemma 23 (composing interactions). Assume $s, s_{0}, s_{0} \in\{0,1\}$, are such that we have $\operatorname{Comp}(s 0)(\epsilon, P)=\left(\vec{y}, Q_{0}\right)$ and $\operatorname{Comp}(s 1)(\epsilon, P)=\left(\vec{y}, Q_{1}\right)$ and $\operatorname{Comp}\left(s_{0}\right)\left(\epsilon, Q_{0}\right)=\left(\vec{x}_{0}, P_{0}\right)$ and $\operatorname{Comp}\left(s_{1}\right)\left(\epsilon, Q_{1}\right)=\left(\vec{x}_{1}, P_{1}\right)$ and either of the following hold:
- $P_{0} \xrightarrow[\ell_{0}]{\bar{M}(\lambda)} \nu \vec{z} \cdot\left(\{N / \lambda\} \mid P_{0}^{\prime}\right)$ and $P_{1} \xrightarrow[\ell_{1}]{M N} \nu \vec{w} .\left(\mathrm{id} \mid P_{1}^{\prime}\right)$,
- $P_{0} \xrightarrow[\ell_{0}]{M N} \nu \vec{z} .\left(\mathrm{id} \mid P_{0}^{\prime}\right)$ and $P_{1} \xrightarrow[\ell_{1}]{\bar{M}(\lambda)} \nu \vec{w} .\left(\{N / \lambda\} \mid P_{1}^{\prime}\right)$;
and also assume we have, for any $s^{\prime}, s^{\prime \prime} \in\{0,1\}^{*}$, and $c \in\{0,1\}$, such that $s^{\prime} \neq s$ and either $s 0 s_{0}=s^{\prime} c s^{\prime \prime}$ or $s 1 s_{1}=s^{\prime} c s^{\prime \prime}$, we have that $\operatorname{Comp}\left(s^{\prime} \neg c\right)(\epsilon, P)=(\vec{w}, R)$ and also $\operatorname{Comp}\left(s^{\prime} c\right)(\epsilon, P)=(\vec{w}, S)$ and $\operatorname{Comp}\left(s^{\prime \prime}\right)(\epsilon, S)=\left(\vec{v}, P^{\prime}\right)$, and $\vec{v}, \vec{z}, \vec{w} \#$ R. Under those assumptions, for some $P^{\prime}$, we have the transition $P \xrightarrow[\text { su }]{\stackrel{\pi}{\longrightarrow}} \nu \vec{y}, \vec{x}_{0}, \vec{z}, \vec{x}_{1}, \vec{w} \cdot\left(\sigma \mid P^{\prime}\right)$ and also we have $\operatorname{Comp}\left(s 0 s_{0}\right)\left(\epsilon, P^{\prime}\right)=\left(\epsilon, P_{0}^{\prime}\right)$ and $\operatorname{Comp}\left(s 1 s_{1}\right)\left(\epsilon, P^{\prime}\right)=\left(\epsilon, P_{1}^{\prime}\right)$.

Using the decomposition and composition lemmas, we can now construct the transitions required to complete the two diamond properties.

- Lemma 24 (diamond property 1). If $\left(\pi_{0}, u_{0}\right) I\left(\pi_{1}, u_{1}\right), A \xrightarrow[u_{0}]{\stackrel{\pi_{0}}{\longrightarrow}} B_{0}$ and $A \xrightarrow[u_{1}]{\pi_{1}} B_{1}$, then $\exists C_{0}, C_{1}$ s.t. $B_{0} \xrightarrow[u_{1}]{\pi_{1}} C_{0}$ and $B_{1} \xrightarrow[u_{0}]{\pi_{0}} C_{1}$ and $C_{0} \equiv C_{1}$.

In both diamond properties, there are several cases depending on what combination of $\tau$ and output labelled events we are considering to be independent. Below we present the top-level breakdown of the case analysis, which applies to both diamond properties. We also provide the details of one of the most interesting cases, where two independent output transitions occur.
 $\exists B_{1}, C_{1}$ s.t. $A \xrightarrow[u_{1}]{\pi_{1}} B_{1}$ and $B_{1} \xrightarrow[u_{0}]{\pi_{0}} C_{1}$ and $C_{0} \equiv C_{1}$.

Proof. Assume we have $\left(\pi_{0}, u_{0}\right) I\left(\pi_{1}, u_{1}\right)$, and the two transitions $A \xrightarrow[u_{0}]{\pi_{0}} B_{0}$ and $B_{0} \xrightarrow[u_{1}]{\pi_{1}} C$.
For two transitions from the same state we have $\left(\pi_{0}, u_{0}\right) I\left(\pi_{1}, u_{1}\right)$ iff for all $\ell_{0} \in \mathcal{L}$ oc $\left(u_{0}\right)$ and for all $\ell_{1} \in \mathcal{L} \operatorname{Loc}\left(u_{1}\right)$, we have $\ell_{0} I_{\ell} \ell_{1}$ (i.e., there is no structural causality), and, furthermore, if $\pi_{0}=\overline{M_{0}}\left(\alpha_{0}\right)$, then $\alpha_{0} \# \pi_{1}$ (i.e., there is no link causality). The structural independence ensures that, without loss of generality, we have one of the following.

- Both location labels have a largest common prefix $s \in\{0,1\}^{*}$ and hence are of the form $s 0 u_{0}^{\prime}=u_{0}$ and $s 1 u_{1}^{\prime}=u_{1}$.
- At least one transition is labelled with a $\tau$ action (without loss of generality let $\pi_{0}=\tau$ ), and so $u_{0}=s_{0}\left(0 \ell_{0}, 1 \ell_{1}\right)$ and there is a string $s_{1} \in\{0,1\}^{*}$, characters $c, d \in\{0,1\}$ and prefix location $\ell^{\prime}$ such that $s_{0} d s_{1} c u_{1}^{\prime}=u_{1}$ and $s_{1} \neg c \ell^{\prime}=\ell_{d}$. That is, one transition is an interaction, and the other transition is entirely located within one of the locations from which either interacting input or the interacting output emanated.
- Both are $\tau$ transitions with a common prefix $s \in\{0,1\}^{*}$ such that $u_{0}=s\left(0 \ell_{0}^{0}, 1 \ell_{0}^{1}\right)$ and $u_{1}=s\left(0 \ell_{1}^{0}, 1 \ell_{1}^{1}\right)$ and there are strings $s_{1} \in\{0,1\}^{*}$ such that $\ell_{0}^{0}=s_{0} 0 \ell_{0}^{\prime 0}$ and $\ell_{1}^{0}=s_{0} 1 \ell_{1}^{\prime 0}$ and $\ell_{0}^{1}=s_{1} 0 \ell_{0}^{\prime 1}$ and $\ell_{1}^{1}=s_{1} 1 \ell_{1}^{\prime 1}$. That is, we have two interactions, where the interaction occurs in the same location (even though the inputs and outputs involved are independent).

We break down further the first case above, where the two independent transitions have a common prefix. Due to differences between Alias-out or and Alias-free, we should consider separately the cases where the first transition is an output transition or a free transition. We consider only the most interesting case, where we appeal to the absence of link causality, which is only relevant when $\pi_{0}=\overline{M_{0}}\left(\alpha_{0}\right)$ is an output transition. That case itself breaks down into two cases, where $\pi_{1}$ is either another output transition or a free transition. We provide only the case when $\pi_{1}$ is an output transition such that $\pi_{1}=\overline{M_{1}}\left(\alpha_{1}\right)$ below.

Without loss of generality ( 0 and 1 can be reversed without changing the proof), assume there exists $s$ such that $u_{0}=\ell_{0}=s 0 s_{0}\left[t_{0}\right]$ and $u_{1}=\ell_{1}=s 1 s_{1}\left[t_{1}\right]$.

Thus, by the Res rule, repeatedly, we have $A=\nu \vec{x} \cdot(\sigma \mid P)$ and $\alpha_{0}=s 0 s_{0} \lambda_{0}$ and $\vec{x} \# M_{0}$ and $B_{0}=\nu \vec{x}, \vec{y}_{0} \cdot\left(\sigma \circ\left\{N_{0} / s 0 s_{0} \lambda_{0}\right\} \mid Q_{0}\right)$, and, also by the AliAS-OUT rule we have the following.

$$
\begin{gathered}
P \underset{s 0 s_{0}\left[t_{0}\right]}{\overline{M_{0} \sigma}\left(\lambda_{0}\right)} \nu \vec{y}_{0} \cdot\left(\left\{N_{0} / \lambda_{0}\right\} \mid Q_{0}\right) \quad \vec{y} \# \operatorname{ran}(\sigma) \quad \operatorname{fa}\left(M_{0}\right) \subseteq \operatorname{dom}(\sigma) \quad s 0 s_{0} \lambda_{0} \# \operatorname{dom}(\sigma) \\
\\
\frac{\left.\left.\sigma \left\lvert\, P \frac{\overline{M_{0}}\left(s 0 s_{0} \lambda_{0}\right)}{s 0 s_{0}\left[t_{0}\right]} \nu \overrightarrow{y_{0}} \cdot(\sigma \mid P) \frac{\overline{M_{0}}\left(s 0 s_{0} \lambda_{0}\right)}{s 0 s_{0}\left[t_{0}\right]} \nu \vec{x}\right., \vec{y}_{0} / s 0 s_{0} \lambda_{0}\right\} \mid Q_{0}\right)}{\left(\sigma \circ\left\{{ }^{N_{0}} / s 0 s_{0} \lambda_{0}\right\} \mid Q_{0}\right)}
\end{gathered}
$$

Now, since we have $P \xrightarrow[{s 0 s_{0}\left[t_{0}\right.}]]{\overline{M_{0} \sigma}\left(\lambda_{0}\right)} \nu \vec{y}_{0} .\left(\left\{N_{0} / \lambda_{0}\right\} \mid Q_{0}\right)$, by Lemma 18, we have the following:

- $\left.P_{0} \xrightarrow[{s_{0}\left[t_{0}\right.}]\right]{\overline{M_{0}}\left(\lambda_{0}\right)} \nu \vec{z}_{0} \cdot\left(\left\{N_{0} / \lambda_{0}\right\} \mid Q_{0}^{\prime}\right)$ and $\operatorname{Comp}(s 0)(\epsilon, P)=\left(\vec{y}, P_{0}\right)$ and $\vec{y}_{0}=\vec{y}, \vec{z}_{0}$ and $\operatorname{Comp}(s 0)\left(\epsilon, Q_{0}\right)=\left(\vec{y}, Q_{0}^{\prime}\right)$.
- for any $s^{\prime}, s^{\prime \prime} \in\{0,1\}^{*}$, and $c \in\{0,1\}$, if $s 0=s^{\prime} c s^{\prime \prime}$ then $\operatorname{Comp}\left(s^{\prime} \neg c\right)(\epsilon, P)=(\vec{w}, R)$ and $\operatorname{Comp}\left(s^{\prime} \neg c\right)\left(\epsilon, Q_{0}\right)=(\epsilon, R)$ and $\operatorname{Comp}\left(s^{\prime} c\right)(\epsilon, P)=(\vec{w}, S)$ and $\operatorname{Comp}\left(s^{\prime \prime}\right)(\epsilon, S)=\left(\vec{v}, P_{0}\right)$, and also $\vec{v}, \vec{x} \# R$.
Now since $B_{0}=\nu \vec{x}, \vec{y}_{0} \cdot\left(\sigma \circ\left\{N_{0} / s 0 s_{0} \lambda_{0}\right\} \mid Q_{0}\right)$ and $B_{0} \xrightarrow[\ell_{1}]{\pi_{1}} C$, by the RES rule repeatedly and the Alias-out rule, we have the following, where $\vec{x}, \vec{y}_{0} \# M_{1}$ and $\theta_{0}=\sigma \circ\left\{N_{0} / s 0 s_{0} \lambda_{0}\right\}$ and $C_{0}=\nu \vec{x}, \vec{y}_{0}, \vec{z}_{1} \cdot\left(\theta_{0} \circ\left\{{ }^{N_{1} / s 1 s_{1} \lambda_{1}}\right\} \mid R_{0}\right)$.

$$
\begin{aligned}
& \xrightarrow{\left.Q_{0} \xrightarrow[{s 1 s_{1}\left[t_{1}\right.}]\right]{\overline{M_{1} \sigma}\left(\lambda_{1}\right)}} \nu \vec{z}_{1} \cdot\left(\left\{N_{1} / \lambda_{1}\right\} \mid R_{0}\right) \quad \vec{z}_{1} \# \operatorname{ran}\left(\theta_{0}\right) \quad \mathrm{fa}\left(M_{1}\right) \subseteq \operatorname{dom}\left(\theta_{0}\right) \quad s 1 s_{1} \lambda_{1} \# \operatorname{dom}\left(\theta_{0}\right) \\
& \left.\theta_{0} \mid Q_{0} \xrightarrow[{s 1 s_{1}\left[t_{1}\right.}]\right]{\overline{M_{1}}\left(s 1 s_{1} \lambda_{1}\right)} \nu \vec{z}_{1} \cdot\left(\theta_{0} \circ\left\{N_{1} / s 1 s_{1} \lambda_{1}\right\} \mid R_{0}\right) \\
& \left.\nu \vec{x}, \vec{y}_{0} \cdot\left(\theta_{0} \mid Q_{0}\right) \xrightarrow[{s 1 s_{1}\left[t_{1}\right.}]\right]{\overline{M_{1}}\left(s 1 s_{1} \lambda_{1}\right)} \nu \vec{x}, \vec{y}_{0}, \vec{z}_{1} \cdot\left(\theta_{0} \circ\left\{{ }^{N_{1} / s 1 s_{1} \lambda_{1}}\right\} \mid R_{0}\right)
\end{aligned}
$$

Since $\left.Q_{0} \xrightarrow[{s 1 s_{1}\left[t_{1}\right.}]\right]{\overline{M_{1} \sigma}\left(\lambda_{1}\right)} \nu \vec{z}_{1} \cdot\left(\left\{{ }^{M_{1}} / \lambda_{1}\right\} \mid R_{0}\right)$, by Lemma 18 , we have the following:

- $\operatorname{Comp}(s 1)\left(\epsilon, Q_{0}\right)=\left(s 1, Q_{0}^{\prime}\right)$ and $\left.Q_{0}^{\prime} \xrightarrow[{s_{1}\left[t_{1}\right.}]\right]{\overline{M_{1}}\left(\lambda_{1}\right)} \nu \vec{z}_{1} \cdot\left(\left\{M_{1} / \lambda_{1}\right\} \mid R_{0}^{\prime}\right)$ and $\operatorname{Comp}(s 1)\left(\epsilon, R_{0}\right)=$ $\left(\epsilon, R_{0}^{\prime}\right)$.
- for any $s^{\prime}, s^{\prime \prime} \in\{0,1\}^{*}$, and $c \in\{0,1\}$, if $s 1=s^{\prime} c s^{\prime \prime}$ then $\operatorname{Comp}\left(s^{\prime} \neg c\right)\left(\epsilon, Q_{0}\right)=(\vec{w}, R)$ and $\operatorname{Comp}\left(s^{\prime} \neg c\right)\left(\epsilon, R_{0}\right)=(\epsilon, R)$ and $\operatorname{Comp}\left(s^{\prime} c\right)\left(\epsilon, Q_{0}\right)=(\vec{w}, S)$ and $\operatorname{Comp}\left(s^{\prime \prime}\right)(\epsilon, S)=\left(\vec{v}, Q_{0}^{\prime}\right)$, and also $\vec{v}, \vec{x} \# R$.

From the above we have that $\operatorname{Comp}(s 1)(\epsilon, P)=\left(\vec{y}, Q_{0}^{\prime}\right)$ and $\operatorname{Comp}(s 1)\left(\epsilon, Q_{0}\right)=$ $\left(\epsilon, Q_{0}^{\prime}\right)$. We also have that, for any $s^{\prime}, s^{\prime \prime} \in\{0,1\}^{*}$, and $c \in\{0,1\}$, if $s=s^{\prime} c s^{\prime \prime}$ then $\operatorname{Comp}\left(s^{\prime} \neg c\right)\left(\epsilon, P_{0}\right)=(\vec{w}, R)$ and $\operatorname{Comp}\left(s^{\prime} \neg c\right)\left(\epsilon, Q_{0}\right)=(\epsilon, R)$ and $\operatorname{Comp}\left(s^{\prime} \neg c\right)\left(\epsilon, R_{0}\right)=(\epsilon, R)$ and $\operatorname{Comp}\left(s^{\prime} c\right)\left(\epsilon, Q_{0}\right)=(\vec{w}, S)$ and $\operatorname{Comp}\left(s^{\prime \prime}\right)(\epsilon, S)=\left(\vec{v}, Q_{0}^{\prime}\right)$, and also $\vec{v}, \vec{x} \# R$.

We now appeal to the absence of link causality, so we know that $s 0 s_{0} \lambda_{0} \# M_{1}$, and hence $M_{1} \theta_{0}=M_{1} \sigma$, and so $\left.Q_{0}^{\prime} \xrightarrow[{s_{1}\left[t_{1}\right.}]\right]{\overline{M_{1} \sigma}\left(\lambda_{1}\right)} \nu \overrightarrow{z_{1}} \cdot\left(\left\{{ }^{N_{1}} / \lambda_{1}\right\} \mid R_{0}^{\prime}\right)$. Therefore by Lemma 22 , we have $P \xrightarrow[{s 1 s_{1}\left[t_{1}\right.}]]{\overline{M_{1} \sigma}\left(\lambda_{1}\right)} \nu \vec{y}, \vec{z}_{1} \cdot\left(\left\{{ }^{N_{1}} / \lambda_{1}\right\} \mid Q_{1}\right)$ and $\operatorname{Comp}(s 1)\left(\epsilon, Q_{1}\right)=\left(\epsilon, R_{0}^{\prime}\right)$. Since we know fa $\left(M_{1}\right) \subseteq$ $\operatorname{dom}\left(\theta_{0}\right)$ and $s 0 s_{0} \lambda_{0} \# M_{1}$ we know that $\mathrm{fa}\left(M_{1}\right) \subseteq \operatorname{dom}(\sigma)$. Since $s 1 s_{1} \lambda_{1} \# \operatorname{dom}\left(\theta_{0}\right)$ we have $s 1 s_{1} \lambda_{1} \# \operatorname{dom}(\sigma)$. Thus, by Alias-out and Res repeatedly, we have the following.

$$
\begin{aligned}
& P \xrightarrow[{s 1 s_{1}\left[t_{1}\right.}]]{\overline{M_{1} \sigma}\left(\lambda_{1}\right)} \nu \vec{y}, \vec{z}_{1} \cdot\left(\left\{{ }^{N_{1}} / \lambda_{1}\right\} \mid Q_{1}\right) \quad \operatorname{fa}\left(M_{1}\right) \subseteq \operatorname{dom}(\sigma) \quad \vec{y}, \vec{z}_{1} \# \operatorname{ran}(\sigma) \quad s 1 s_{1} \lambda_{1} \# \operatorname{dom}(\sigma) \\
& \sigma \mid P \xrightarrow[{s 1 s_{1}\left[t_{1}\right.}]]{\overline{M_{1} \sigma}\left(s 1 s_{1} \lambda_{1}\right)} \nu \vec{y}, \vec{z}_{1} \cdot\left(\sigma \circ\left\{{ }^{N_{1}} / s 1 s_{1} \lambda_{1}\right\} \mid Q_{1}\right) \\
& \nu \vec{x} .(\sigma \mid P) \xrightarrow[{s 1 s_{1}\left[t_{1}\right.}]]{\overline{M_{1} \sigma}\left(s 1 s_{1}\right)} \nu \vec{x}, \vec{y}, \vec{z}_{1} \cdot\left(\sigma \circ\left\{{ }^{N_{1} / s 1 s_{1} \lambda_{1}}\right\} \mid Q_{1}\right)
\end{aligned}
$$

Recall that $A=\nu \vec{x} \cdot(\sigma \mid P)$, hence we have the first of our desired transitions.
It remains to show that $\nu \vec{x}, \vec{y}, \vec{z}_{1} \cdot\left(\theta_{1} \mid Q_{1}\right) \xrightarrow[u_{0}]{\pi_{0}} C_{1}$, where $\theta_{1}=\sigma \circ\left\{N_{1} / s 1 s_{1} \lambda_{1}\right\}$, and also $C_{0} \equiv C_{1}$. Since fa $\left(M_{0}\right) \subseteq \operatorname{dom}(\sigma) \subseteq \operatorname{dom}\left(\theta_{1}\right)$, we have $M_{0} \sigma=M_{0} \theta_{1}$, thus $\left.P_{0} \xrightarrow[{s_{0}\left[t_{0}\right.}]\right]{\overline{M_{0}} \theta_{1}}\left(\lambda_{0}\right)$ $\nu \vec{z}_{0} .\left(\left\{N_{0} / \lambda_{0}\right\} \mid Q_{1}^{\prime}\right)$. Therefore, since we know (via Lemma 18) that $\operatorname{Comp}(s 0)\left(\epsilon, Q_{1}\right)=\left(\epsilon, P_{0}\right)$, by Lemma 22, $\left.Q_{1} \xrightarrow[{s_{0}\left[t_{0}\right.}]\right]{\overline{M_{0} \theta_{1}}\left(\lambda_{0}\right)} \nu \vec{z}_{0} \cdot\left(\left\{N_{0} / \lambda_{0}\right\} \mid R_{1}\right)$ and $\operatorname{Comp}(s 0)\left(\epsilon, R_{1}\right)=\left(\epsilon, Q_{0}^{\prime}\right)$.

By the RES rule repeatedly and the Alias-out rule, we have that $\vec{x}, \vec{y}, \vec{z}_{1} \# M_{0}$ and we have the following transition, and so $C_{1}=\nu \vec{x}, \vec{y}, \vec{z}_{1}, \vec{z}_{0} .\left(\theta_{1} \circ\left\{{ }^{N_{0} / s 0 s_{0} \lambda_{0}}\right\} \mid R_{1}\right)$.

$$
\begin{aligned}
& \left.\left.Q_{1} \xrightarrow[{s 0 s_{0}\left[t_{0}\right.}]\right]{\overline{M_{0}}\left(\lambda_{0}\right)} \nu \vec{z}_{0} .\left(\left\{{ }^{N_{0} / s 0 s_{0} \lambda_{0}}\right\} \mid R_{1}\right) \quad \operatorname{fa}\left(M_{0}\right) \subseteq \operatorname{dom}\left(\theta_{1}\right) \quad \vec{z}_{0} \# \operatorname{ran}\left(\theta_{1}\right) \quad s 0 s_{0} \lambda_{0}\right) \# \operatorname{dom}\left(\theta_{1}\right) \\
& \left.\theta_{1} \mid Q_{1} \xrightarrow[{s 0 s_{0}\left[t_{0}\right.}]\right]{\overline{M_{0}}\left(s 0 s_{0}\right)} \nu \vec{z}_{0} \cdot\left(\sigma \circ\left\{{ }^{N_{1} / s 1 s_{1} \lambda_{1}}\right\} \circ\left\{{ }^{N_{0} / s 0 s_{0} \lambda_{0}}\right\} \mid R_{1}\right) \\
& \left.\nu \vec{x}, \vec{y}, \vec{z}_{1} \cdot\left(\theta_{1} \mid Q_{1}\right) \xrightarrow[{s 0 s_{0}\left[t_{0}\right.}]\right]{\overline{M_{0}\left(s 0 s_{0} \lambda_{0}\right)}} \nu \vec{x}, \vec{y}, \vec{z}_{1}, \vec{z}_{0} \cdot\left(\sigma \circ\left\{{ }^{N_{1} / s 1 s_{1} \lambda_{1}}\right\} \circ\left\{{ }^{N_{0} / s 0 s_{0} \lambda_{0}}\right\} \mid R_{1}\right)
\end{aligned}
$$

Now since for all $s^{\prime}, s^{\prime \prime} \in\{0,1\}$ and $c, d \in\{0,1\}$ such that $s^{\prime} c s^{\prime \prime}=s d$ we have $\operatorname{Comp}\left(s^{\prime} \neg c\right)\left(\epsilon, R_{0}\right)=\operatorname{Comp}\left(s^{\prime} \neg c\right)\left(\epsilon, R_{1}\right)$ (via Lemma 18 and the above), clearly it is the case that $R_{0}=R_{1}$. Furthermore, we have the following, as required.

$$
\begin{aligned}
& C_{0}=\nu \vec{x}, \vec{y}, \vec{z}_{0}, \vec{z}_{1} \cdot\left(\sigma \circ \left\{\begin{array} { c } 
{ N _ { 0 } / s 0 s _ { 0 } \lambda _ { 0 } \} }
\end{array} \quad \circ \left\{\begin{array}{l}
\left.\left.N_{1} / s 1 s_{1} \lambda_{1}\right\} \mid R_{0}\right)
\end{array}\right.\right.\right. \\
& \quad \equiv \nu \vec{x}, \vec{y}, \vec{z}_{1}, \vec{z}_{0} \cdot\left(\sigma \circ\left\{N_{1} / s 1 s_{1} \lambda_{1}\right\} \circ\left\{N_{0} / s 0 s_{0} \lambda_{0}\right\} \mid R_{1}\right)=C_{1}
\end{aligned}
$$

Other cases follow a similar pattern of applying to decomposition and composition.


[^0]:    1 This means outputs may only differ in the choice of alias ( $\lambda$ v.s. $\lambda^{\prime}$ ) or in that an equivalent recipe ( $M$ v.s. $K$ ) may be used, and, furthermore, we are free to rename the alias. This clause is a trick used to determine whether the CLOSE-L or ClOSE-R rule applied in an interaction, by looking at the output action and without being required to record additional information in the interaction event.

[^1]:    2 This states that the locations independent from $P^{\prime}$ are unchanged by the transition stemming from $P^{\prime}$, except that the common name binders will be extruded. Generalisations of this statement carry through to the other decomposition lemmas.

