# Is It Easier to Count Communities Than Find Them? 

Cynthia Rush $\square$ (<br>Department of Statistics, Columbia University, New York, NY,USA<br>Fiona Skerman $\square$ (0)<br>Department of Mathematics, Uppsala University, Sweden

Alexander S. Wein $\square$ (c)<br>Department of Mathematics, University of California, Davis, CA, USA

Dana Yang $\square$ (
Department of Statistics and Data Science, Cornell University, Ithaca, NY, USA


#### Abstract

Random graph models with community structure have been studied extensively in the literature. For both the problems of detecting and recovering community structure, an interesting landscape of statistical and computational phase transitions has emerged. A natural unanswered question is: might it be possible to infer properties of the community structure (for instance, the number and sizes of communities) even in situations where actually finding those communities is believed to be computationally hard? We show the answer is no. In particular, we consider certain hypothesis testing problems between models with different community structures, and we show (in the low-degree polynomial framework) that testing between two options is as hard as finding the communities.

In addition, our methods give the first computational lower bounds for testing between two different "planted" distributions, whereas previous results have considered testing between a planted distribution and an i.i.d. "null" distribution.


2012 ACM Subject Classification Theory of computation $\rightarrow$ Random network models; Theory of computation $\rightarrow$ Computational complexity and cryptography

Keywords and phrases Community detection, Hypothesis testing, Low-degree polynomials

Digital Object Identifier 10.4230/LIPIcs.ITCS.2023.94

Funding Cynthia Rush: Part of this work was supported by NSF CCF-1849883 and part of the work was done while visiting the Simons Institute for the Theory of Computing, supported by a Google Research Fellowship.
Fiona Skerman: Partially supported by the Wallenberg AI, Autonomous Systems and Software Program WASP and the project AI4Research at Uppsala University. Part of this work was done while visiting the Simons Institute for the Theory of Computing, supported by a Simons-Berkeley Research Fellowship.
Alexander S. Wein: Part of this work was done at Georgia Tech, supported by NSF grants CCF2007443 and CCF-2106444. Part of this work was done while visiting the Simons Institute for the Theory of Computing, supported by a Simons-Berkeley Research Fellowship.
Dana Yang: Part of this work was done while visiting the Simons Institute for the Theory of Computing, supported by a Simons-Berkeley Research Fellowship.

Acknowledgements This work began when the authors were visiting the Simons Institute for the Theory of Computing during the program on Computational Complexity of Statistical Inference in Fall 2021. We are grateful to Guy Bresler for helpful discussions.

## 1 Introduction

The problem of detecting and recovering community structure in random graph models has been studied extensively in the literature. Popular models include the planted dense subgraph model [2, 12], where an Erdős-Rényi base graph is augmented by adding one or more "communities" - subsets of vertices with a higher-than-average connection probability between them - and the stochastic block model (see [1, 18] for a survey). There are by now a multitude of results identifying sharp conditions based on the problem parameters, e.g. edge probabilities and number/sizes of communities, under which it is possible (or impossible) to recover (exactly or approximately) the hidden partition of vertices, given a realization of the graph as input. Notably, many settings are believed to exhibit a statisticalcomputational gap; that is, there exists a "possible but hard" regime of parameters where it is statistically possible to recover the communities (typically by brute-force search) but there is no known computationally efficient, meaning polynomial-time, algorithm for doing so. It may be that this hardness is inherent, meaning no poly-time algorithm exists, which is suggested by a growing body of "rigorous evidence" including reductions from the planted clique problem [7, 12] and limitations of known classes of algorithms [4, 9, 15, 19].

Despite all this progress, one question that remains relatively unexplored is the following: in the aforementioned "hard" regime, even though it seems hard to recover the communities, might it still be possible to learn something about the community structure (e.g., the number or sizes of communities)? After all, in some models it has already been established that detecting the presence of a dense subgraph (i.e., distinguishing the planted subgraph model from an appropriate Erdős-Rényi "null" model) appears to be strictly easier than actually recovering which vertices belong to it [7, 8, 12, 19]. Existing detection-recovery gaps of this nature often occur due to a "trivial" test for detection (e.g., the total edge count), and the motivation for our work is to understand more precisely which properties of the community structure can be inferred in the hard regime, and which ones cannot.

## A simple testing problem

One of the simplest inference tasks on the community structure is to detect the number of communities. Let us consider a toy problem of testing between two graph models: under $\mathbb{P}$ the graph contains one community of expected size $k$, while under $\mathbb{Q}$ the graph contains two communities each of expected size $k / 2$. The community membership of each vertex is independent in both models $(k / n$ under $\mathbb{P}$ and $k /(2 n), k /(2 n)$ under $\mathbb{Q})$ and vertices cannot be members of more than one community. Suppose any pair of vertices from the same community are connected independently with probability $2 q$ and $3 q$ under $\mathbb{P}$ and $\mathbb{Q}$, respectively, and all the other pairs of vertices are connected independently with probability $q$ under both models. Such a parameterization matches the expected degrees of the nodes under the two distributions, so that a simple test based on the total edge count fails to distinguish between $\mathbb{P}$ and $\mathbb{Q}$. One natural test is to threshold the number of triangles. It is easy to derive that the expected number of triangles under $\mathbb{P}$ and $\mathbb{Q}$ scale as different constant multiples of $q^{3} k^{3}$, and the variance of the number of triangles is of order $\Theta\left(n^{3} q^{3}\right)$ under both models. Thus, the simple triangle counting algorithm consistently distinguishes $\mathbb{P}$ and $\mathbb{Q}$ if $q^{3} k^{3} \gg \sqrt{n^{3} q^{3}}$, i.e. $q k^{2} / n \gg 1$.

It is intriguing that the condition for the triangle counting algorithm to succeed coincides with the conjectured computational barrier for the more difficult task of finding all members of the community under the model $\mathbb{P}[19]$. In other words, in the entire "hard" regime where one cannot efficiently locate the planted community, the triangle counting algorithm fails to
even tell whether the graph contains one or two communities. In this paper, we show that this statement extends beyond the simple triangle counting algorithm to all low-degree tests. Our main result is given in the following (informal) theorem statement.

- Theorem 1.1 (Informal). If $q\left(k^{2} / n \vee 1\right) \leqslant 1 / \operatorname{polylog}(n)$, then no low-degree test consistently tests between the graph models with one and two planted communities.

Moreover, the informal result of Theorem 1.1 extends to a much wider class of testing problems than those for which it is stated. We find that, whenever recovery is computationally hard, all low-degree tests fail to distinguish models with different numbers of planted communities of possibly different sizes. In other words, inferring the community structure is just as hard as finding members of the planted communities themselves. We show a similar phenomenon for graphs with Gaussian weights. See Theorems 2.4 and 2.5 for the formal statements. It is important to note that our results apply even in regimes where it is easy to distinguish $\mathbb{P}($ or $\mathbb{Q})$ from an Erdős-Rényi graph; that is, one cannot recover our results simply by arguing that both $\mathbb{P}$ and $\mathbb{Q}$ are hard to distinguish from Erdős-Rényi.

## The low-degree testing framework

Unfortunately, it seems to be beyond the current reach of computational complexity theory to prove that no polynomial-time algorithm can distinguish two random graph models, even under an assumption like $\mathrm{P} \neq \mathrm{NP}$. Nonetheless, a popular heuristic - the low-degree testing framework [5, 13, 14, 15] (see [17] for a survey) - gives us a rigorous basis on which to form conjectures about hardness of such problems. Specifically, we will study the power of low-degree tests, a class of methods that includes tests based on edge counts, triangle counts, and other small subgraph counts. Strikingly, low-degree tests tend to be as powerful as all known polynomial-time algorithms for testing problems that are (informally speaking) of the flavor that we consider in this paper; see $[13,17]$ for discussion. In this paper, we will prove low-degree hardness, meaning failure of all low-degree tests (to be defined formally in Section 2.1), for certain testing problems; this can be viewed as an apparent barrier to fast algorithms that we believe is unlikely to be overcome by known techniques, and perhaps indicates fundamental computational hardness.

## Planted-versus-planted testing

We emphasize that there is a key difference between our work and existing hardness results for high-dimensional testing. The testing problems we consider are between two different "planted" distributions, each with a different type of planted structure. In contrast, previous low-degree hardness results for testing (e.g., $[13,14,15,17]$ and many others) have always considered testing between "planted" and "null," where the null distribution has i.i.d. or at least independent entries. On a technical level, planted-versus-null problems are more tractable to analyze because we can explicitly construct a basis of orthogonal polynomials for the null distribution, but this strategy seems more difficult to implement for planted-versus-planted problems.

The idea of planted-versus-null testing goes beyond the low-degree framework. Other forms of average-case lower bounds typically also, either explicitly or implicitly, leverage a hard planted-versus-null testing problem; this includes reductions from planted clique (e.g., $[6,7]$ ), sum-of-squares lower bounds (e.g., $[5,16]$ ), and statistical query lower bounds (e.g., $[10,11]$ ). In fact, these frameworks seem to struggle in settings where there is not a hard planted-versus-null testing problem available.

Our work overcomes this barrier that has limited the use of the above methods: we demonstrate for the first time that low-degree hardness results can be proven for planted-versus-planted problems. We give some general-purpose formulas (Propositions 2.7 and 2.8) that can be used to analyze a wide variety of such problems in random graphs or random matrices, not limited to just the specific models studied in this paper. The proof techniques are inspired by [19], which studies estimation problems rather than testing. On a technical level, the core challenge in our analysis is to bound certain recursively-defined quantities called $r_{\alpha}$ (defined in (1)). These are analogous to the cumulants that appear in [19], and while the $r_{\alpha}$ are not cumulants, they enjoy a number of similar convenient properties (see Section 3) that are important for the analysis.

## Alternative proof strategy for hardness of recovery

As a byproduct, our results corroborate the computational barrier for planted dense subgraph recovery established in [19]. Indeed, if there were an algorithm that successfully recovers a planted community, one could turn this into an algorithm for testing one community versus two. Therefore the "hard" regime for recovery contains the "hard" regime for testing community structure.

This provides an alternative method for establishing detection-recovery gaps. For problems where recovery of the planted structure is strictly harder than detecting its presence, it is not viable to deduce optimal hardness of recovery from a planted-versus-null testing problem. However, our work demonstrates that it is possible to attain the sharp recovery threshold via reduction from a planted-versus-planted problem, as long as the two planted distributions are appropriately chosen.

## Open problems

A natural next step is to investigate whether our method yields sharp computational thresholds for other problems that exhibit detection-recovery gaps. For example, the problem of parameter estimation in sparse high-dimensional linear regression likely has a detectionrecovery gap (see [3]) and can potentially be related to a testing problem between two planted models, e.g. between a sparse linear regression and a mixture of two sparse linear regressions.

Another open question is whether our computational hardness result can be shown in ways beyond the low-degree testing framework, such as by using the sum-of-squares framework, statistical query framework, or reduction from the planted clique problem. In particular, if the problem of testing community structure can be reduced from planted clique, this would yield a reduction from planted clique to planted dense subgraph recovery, which is an open problem (see [7]).

## 2 Main results

### 2.1 Low-degree testing

We begin by explaining what it means for a low-degree test to distinguish two high-dimensional distributions.

- Definition 2.1. Suppose $\mathbb{P}_{n}$ and $\mathbb{Q}_{n}$ are distributions on $\mathbb{R}^{N}$ for some $N=N_{n}$. $A$ degree- $D$ test is a multivariate polynomial $f_{n}: \mathbb{R}^{N} \rightarrow \mathbb{R}$ of degree at most $D$ (really, a sequence of polynomials, one for each problem size $n$ ). Such a test $f$ is said to strongly separate $\mathbb{P}$ and $\mathbb{Q}$ if, in the limit $n \rightarrow \infty$,

$$
\sqrt{\max \left\{\operatorname{Var}_{\mathbb{Q}}[f], \operatorname{Var}_{\mathbb{P}}[f]\right\}}=o\left(\left|\mathbb{E}_{\mathbb{P}}[f]-\mathbb{E}_{\mathbb{Q}}[f]\right|\right)
$$

and weakly separate $\mathbb{P}$ and $\mathbb{Q}$ if

$$
\sqrt{\max \left\{\operatorname{Var}[f], \operatorname{Var}_{\mathbb{P}}[f]\right\}}=O\left(\left|\mathbb{E}_{\mathbb{P}}[f]-\mathbb{E}_{\mathbb{Q}}[f]\right|\right) .
$$

Strong separation is a natural sufficient condition for success of a polynomial-based test because it implies (by Chebyshev's inequality) that $\mathbb{P}$ and $\mathbb{Q}$ can be distinguished by thresholding $f$ 's output, with both type I and II errors $o(1)$. Weak separation also implies non-trivial testing, i.e. better than a random guess; see [3, Prop. 6.1]. In this paper, we characterize the limits of low-degree tests. For upper bounds, in the "easy" regime, we show that a constant-degree test achieves strong separation, implying a poly-time algorithm for testing with $o(1)$ error probability. For lower bounds, in the "hard" regime, we show that for some $D=\omega(\log n)$, no degree- $D$ test can achieve even weak separation. Because many known algorithms can be implemented as degree- $O(\log n)$ polynomials (e.g., spectral methods; see Section 4.2.3 of [17]), we treat this as "evidence" that no polynomial-time algorithm achieves non-trivial testing power, i.e. better than a random guess. Our results, in fact, often rule out much higher degree tests (e.g., $\left.D=n^{\Omega(1)}\right)$, depending on how far the parameters lie from the critical threshold.

### 2.2 Model formulation

We consider the problem of testing between two random graph models, both of which contain planted communities but with different community structures. We focus on testing between two additive Gaussian models where the edge weights are Gaussian, and between two binary observation models where the edges are unweighted and the diagonal is set to zero to ensure no self-loops in the graph.

Definition 2.2 (Additive Gaussian model). Given the number of vertices $n$, total community size $k$, signal strength $\lambda>0$, number of communities $M$, and vector of community proportions $x \in[0,1]^{M}$ with $\sum_{\ell=1}^{M} x_{\ell}=1$, define the additive Gaussian model $\mathbb{P}=\mathbb{P}_{\text {Gaussian }}(n, k, \lambda, M, x)$ as follows. Under $\mathbb{P}$, independently for each $i \in[n]:=\{1,2, \ldots, n\}$, the community label $\sigma_{i}$ is sampled such that $\sigma_{i}=\ell$ with probability $x_{\ell} k / n$ for each $\ell \in[M]$ and $\sigma_{i}=\star$ (a symbol indicating membership in none of the communities) with probability $1-k / n$. For each pair of vertices $i, j \in[n]$ with $i \leqslant j$, the edge weight $Y_{i j}$ is sampled from

$$
Y_{i j} \sim \begin{cases}\mathcal{N}\left(\frac{\lambda}{x_{\ell}}, 1\right), & \sigma_{i}=\sigma_{j}=\ell \text { for some } \ell \in[M] \\ \mathcal{N}(0,1), & \text { otherwise } .\end{cases}
$$

For $i>j$, the edge weight $Y_{i j}$ is defined to be $Y_{j i}$.
Notice that with the above definition, each community $\ell \in\{1,2, \ldots, M\}$ is expected to be of size $x_{\ell} k$ and the expected number of vertices which do not belong to any community is $n-k$. The choice of mean $\lambda / x_{\ell}$ ensures that on average, the vertices in one community have the same weighted degree (row sum of $Y$ ) as the vertices in any other community.

- Definition 2.3 (Binary observation model). Given the number of vertices n, total community size $k$, edge probability parameters $q, s \geqslant 0$, number of communities $M$, and vector of community proportions $x \in \mathbb{R}^{M}$ with $\sum_{\ell=1}^{M} x_{\ell}=1$, define the Binary observation model $\mathbb{P}=\mathbb{P}_{\text {Binary }}(n, k, q, s, M, x)$ as follows. The community labels $\left\{\sigma_{i}\right\}_{i \in[n]}$ are sampled the same way as in the additive Gaussian model. Given the community labels, for each pair of vertices $i, j \in[n]$ with $i<j$, the edge weight $Y_{i j}$ is sampled from

$$
Y_{i j} \sim \begin{cases}\operatorname{Bernoulli}\left(q+\frac{s}{x_{\ell}}\right), & \sigma_{i}=\sigma_{j}=\ell \text { for some } \ell \in[M] \\ \operatorname{Bernoulli}(q), & \text { otherwise } .\end{cases}
$$

For $i>j$, the edge weight $Y_{i j}$ is defined to be $Y_{j i}$ and the diagonal entries set to zero $Y_{i i}=0$.
For example, if we want to model two communities of equal sizes, we can choose $M=2$ and $x_{1}=x_{2}=\frac{1}{2}$. The communities are then both expected to be of size $k / 2$. If we also set $s=q$ we have an in-community connection probability of $3 q$ and every other pair of nodes is connected with probability $q$ as in the toy model discussed in the Introduction.

The two models introduced in Definitions 2.2 and 2.3 only differ in the edge weight distributions, as the community labels follow the same distribution under both models. Alternatively, we can write $S_{\ell}$ for the set of vertices in community $\ell$, so that $\sigma_{i}=\ell$ if and only if $i \in S_{\ell}$. Note that by definition, each vertex $i$ can belong to at most one community. In other words, the communities $\left\{S_{\ell}\right\}_{\ell \in[M]}$ are disjoint.

With the other parameters fixed, we consider testing between model $\mathbb{P}$ with $M$ planted communities and community proportions $x \in[0,1]^{M}$, and the model $\mathbb{Q}$ with $M^{\prime}$ planted communities and community proportions $x^{\prime} \in[0,1]^{M^{\prime}}$ for some $M^{\prime} \neq M$. In short, for both Gaussian and Bernoulli edge weight models, we establish a "hard" regime where the distributions $\mathbb{P}$ and $\mathbb{Q}$ cannot be weakly separated by low-degree tests. We consider the regime $n \rightarrow \infty$ and allow all the parameters $k, \lambda, M, x$ to depend on $n$; thus, our results can apply to a growing number of communities, although our main focus is on the case where $M, M^{\prime}$ are fixed so that our upper and lower bounds match.

- Theorem 2.4 (Additive Gaussian model). Given parameters $n, k, \lambda, M, M^{\prime}, x, x^{\prime}$, define distributions $\mathbb{P}=\mathbb{P}_{\text {Gaussian }}(n, k, \lambda, M, x)$ and $\mathbb{Q}=\mathbb{P}_{\text {Gaussian }}\left(n, k, \lambda, M^{\prime}, x^{\prime}\right)$. Assume that $M \min _{\ell} x_{\ell} \geqslant C$ and $M^{\prime} \min _{\ell} x_{\ell}^{\prime} \geqslant C$ for some constant $C>0$. Write $\widetilde{M}=\left|M-M^{\prime}\right|$ and $\widehat{M}=\max \left\{M, M^{\prime}\right\}$. We have:
- If $D^{5} \widehat{M}^{2} \lambda^{2}\left(k^{2} / n \vee 1\right)=o(1)$, then no degree- $D$ test weakly separates $\mathbb{P}$ and $\mathbb{Q}$.
- If $\widetilde{M}^{2} \lambda^{2} k^{2} / n=\omega(1)$ and $\widetilde{M}^{2} k / \widehat{M}^{2}=\omega(1)$, then there exists a degree-1 test that strongly separates $\mathbb{P}$ and $\mathbb{Q}$.
In the regime $k^{2} \geqslant n, \widehat{M}=O(1)$, and $D \leqslant \operatorname{polylog}(n)$, Theorem 2.4 precisely characterizes (up to logarithmic factors) the computational threshold for low-degree testing. This threshold coincides with the conjectured computational threshold for recovering a single planted community, which has been established in the low-degree polynomial framework [19, Theorem 2.5]. We focus on the $k^{2} \geqslant n$ regime in this paper, as this is where there is a conjectured detection-recovery gap, but we suspect that when $\widehat{M}$ is constant, $\lambda^{2}\left(k^{2} / n \vee 1\right) \sim 1$ is the computational threshold across the entire parameter regime. The optimal test when $k^{2}<n$ should be based on the maximum diagonal entry, and while this is not a polynomial, it should be possible to approximate it by one (similar to Section 4.1.1 of [19]).
- Theorem 2.5 (Binary observation model). Given parameters $n, k, q, s, M, M^{\prime}, x, x^{\prime}$, define distributions $\mathbb{P}=\mathbb{P}_{\text {Binary }}(n, k, q, s, M, x)$ and $\mathbb{Q}=\mathbb{P}_{\text {Binary }}\left(n, k, q, s, M^{\prime}, x^{\prime}\right)$. Assume that $M \min _{\ell} x_{\ell} \geqslant C$ and $M^{\prime} \min _{\ell} x_{\ell}^{\prime} \geqslant C$ for some constant $C>0$ and that $q+s /\left(\min _{\ell} x_{\ell}\right) \leqslant \tau_{1}$ for some constant $\tau_{1}<1$. Write $\widetilde{M}=\left|M-M^{\prime}\right|$ and $\widehat{M}=\max \left\{M, M^{\prime}\right\}$. We have:
- If $D^{5} \widehat{M}^{2}\left(s^{2} / q\right)\left(k^{2} / n \vee 1\right)=o(1)$, then no degree- $D$ test weakly separates $\mathbb{P}$ and $\mathbb{Q}$.
- If $\widetilde{M}^{2 / 3}\left(s^{2} / q\right) k^{2} / n=\omega(1), \widehat{M}^{-1 / 3} s k=\omega(1)$ and $\widetilde{M}^{2} k / \widehat{M}^{2}=\omega(1)$ then there exists a degree-3 test that strongly separates $\mathbb{P}$ and $\mathbb{Q}$.

The upper and lower bounds match (up to log factors) provided $k^{2} \geqslant n, \widehat{M}=O(1)$, $D \leqslant \operatorname{polylog}(n)$, and $q \geqslant 1 / n$. The condition $q \geqslant 1 / n$ is natural since without it there will be isolated vertices. The regime $k^{2}<n$ is more complicated, and some open questions remain here even for simpler testing and recovery problems than those we study here; see Section 2.4.1 of [19] for discussion.

### 2.3 Proof overview

## Main quantity to bound: advantage

In order to rule out weak separation between distributions $\mathbb{P}=\mathbb{P}_{n}$ and $\mathbb{Q}=\mathbb{Q}_{n}$ on $\mathbb{R}^{N_{n}}$, it will suffice to bound the degree- $D$ "advantage," named as such to emphasize that it measures the ability of low-degree polynomials to outperform random guessing and defined as

$$
\operatorname{Adv}_{\leqslant D}(\mathbb{P}, \mathbb{Q}):=\sup _{f \operatorname{deg} D} \frac{\mathbb{E}_{\mathbb{P}}[f]}{\sqrt{\mathbb{E}_{\mathbb{Q}}\left[f^{2}\right]}}
$$

where $f$ ranges over polynomials $\mathbb{R}^{N} \rightarrow \mathbb{R}$ of degree at most $D$. The quantity $\operatorname{Adv}_{\leqslant D}$ is also the norm of the degree- $D$ likelihood ratio (see $[13,17]$ ), but we will not use this interpretation here as the likelihood ratio is difficult to work with in our setting. We note that while the notion of separation is symmetric between $\mathbb{P}$ and $\mathbb{Q}$, the notion of advantage is not; for our purposes, we could just as easily work with $\operatorname{Adv} \leqslant D(\mathbb{Q}, \mathbb{P})$ instead of $\operatorname{Adv} \leqslant D(\mathbb{P}, \mathbb{Q})$. The following basic fact connects $A d v_{\leqslant D}$ with strong/weak separation.

- Lemma 2.6. Fix a sequence $D=D_{n}$.
- If $\operatorname{Adv}_{\leqslant D}(\mathbb{P}, \mathbb{Q})=O(1)$ then no degree- $D$ test strongly separates $\mathbb{P}$ and $\mathbb{Q}$.
- If $\operatorname{Adv}_{\leqslant D}(\mathbb{P}, \mathbb{Q})=1+o(1)$ then no degree-D test weakly separates $\mathbb{P}$ and $\mathbb{Q}$.

The proof of Lemma 2.6, along with the proofs of all facts in this section, can be found in Section 5. In light of Lemma 2.6, it remains to bound $\operatorname{Adv}_{\leqslant D}$. We will provide a few general-purpose bounds, one for Gaussian problems and one for binary-valued problems. Both will involve the following recursively-defined quantities $r_{\alpha}$ introduced in what follows.

## Recursive definition for the $r$-values

Suppose $X$ is a random variable taking values in $\mathbb{R}^{N}$, which may have a different distribution under $\mathbb{P}$ and $\mathbb{Q}$. For $\alpha, \beta \in \mathbb{N}^{N}$ where $\mathbb{N}=\{0,1,2, \ldots\}$, define

$$
|\alpha|:=\sum_{i} \alpha_{i}, \quad \alpha!:=\prod_{i} \alpha_{i}!, \quad\binom{\alpha}{\beta}:=\prod_{i}\binom{\alpha_{i}}{\beta_{i}}, \quad \text { and } \quad X^{\alpha}:=\prod_{i} X_{i}^{\alpha_{i}} .
$$

Also define $\beta \leqslant \alpha$ to mean " $\beta_{i} \leqslant \alpha_{i}$ for all $i$ " and define $\beta \lessgtr \alpha$ to mean " $\beta_{i} \leqslant \alpha_{i}$ for all $i$ and for some $i$ the inequality is strict: $\beta_{i}<\alpha_{i}$." With this notation in hand, define $r_{\alpha}=r_{\alpha}(X) \in \mathbb{R}$ for $\alpha \in \mathbb{N}^{N}$ recursively by

$$
\begin{equation*}
r_{\alpha}=\mathbb{E}_{\mathbb{P}}\left[X^{\alpha}\right]-\sum_{0 \leqslant \beta \leqslant \alpha} r_{\beta}\binom{\alpha}{\beta} \mathbb{E}_{\mathbb{Q}}\left[X^{\alpha-\beta}\right] . \tag{1}
\end{equation*}
$$

## Bounds on advantage

We have the following general-purpose bounds on $\operatorname{Adv}_{\leqslant D}$ in terms of $r_{\alpha}$ defined in (1). The proofs are inspired by [19] and can be found in Section 5.

- Proposition 2.7 (General additive Gaussian model). Suppose $\mathbb{P}$ and $\mathbb{Q}$ take the following form: to sample $Y \sim \mathbb{P}$ (or $Y \sim \mathbb{Q}$, respectively), first sample $X \in \mathbb{R}^{N}$ from an arbitrary prior $\mathbb{P}_{X}$ (or $\mathbb{Q}_{X}$, resp.), then sample $Z \sim \mathcal{N}\left(0, I_{N}\right)$, and set $Y=X+Z$. Define $r_{\alpha}$ as in (1). Then

$$
\operatorname{Adv}_{\leqslant D}(\mathbb{P}, \mathbb{Q}) \leqslant \sqrt{\sum_{\alpha \in \mathbb{N}^{N},|\alpha| \leqslant D} \frac{r_{\alpha}^{2}}{\alpha!}}
$$

- Proposition 2.8 (General binary observation model). Suppose $\mathbb{P}$ and $\mathbb{Q}$ each take the following form. To sample $Y \sim \mathbb{P}$ (or $Y \sim \mathbb{Q}$, respectively), first sample $X \in \mathbb{R}^{N}$ from an arbitrary prior $\mathbb{P}_{X}$ (or $\mathbb{Q}_{X}$, resp.) supported on $X \in\left[\tau_{0}, \tau_{1}\right]^{N}$ with $0<\tau_{0} \leqslant \tau_{1}<1$, then sample $Y \in\{0,1\}^{N}$ with entries conditionally independent given $X$ and $\mathbb{E}\left[Y_{i} \mid X\right]=X_{i}$. Define $r_{\alpha}$ as in (1). Then

$$
\operatorname{Adv}_{\leqslant D}(\mathbb{P}, \mathbb{Q}) \leqslant \sqrt{\sum_{\alpha \in\{0,1\}^{N},|\alpha| \leqslant D} \frac{r_{\alpha}^{2}}{\left(\tau_{0}\left(1-\tau_{1}\right)\right)^{|\alpha|}}}
$$

## Combinatorial properties of the $r_{\alpha}$

The upshot of the two propositions above is that to show hardness of distinguishing $\mathbb{P}$ versus $\mathbb{Q}$, it suffices to bound the recursively defined $r_{\alpha}$. This task is made easier by indentifying combinatorial properties the $r_{\alpha}$ enjoy. In Section 3, we show general results for how properties of the probability spaces transfer to behaviour of the $r_{\alpha}$. We may consider $\alpha \in \mathbb{N}^{N}$ as a multigraph, see Section 3.1, and we word the results in this language. Loosely speaking the results we present are as follows:

- If $\mathbb{P}$ and $\mathbb{Q}$ are multiplicative for disjoint graphs $\alpha$ and $\beta$ then $r_{\alpha \cup \beta}=r_{\alpha} r_{\beta}$ (Lemma 3.1).
- If $\mathbb{E}_{\mathbb{P}}\left[X^{\tau}\right]=\mathbb{E}_{\mathbb{Q}}\left[X^{\tau}\right]$ for all trees $\tau$, then the $r$ value is zero on trees (Lemma 3.2).
- The $r$-values are indifferent to constant shifts to $X$ (Lemma 3.3).
- If we scale $X$ by a constant factor $c$ to construct $\widetilde{r}$, then $\tilde{r}_{\alpha}=c^{|\alpha|} r_{\alpha}$ (Lemma 3.4).


## Putting it all together

In Section 4 we pivot back to considering our particular probability spaces $\mathbb{P}$ and $\mathbb{Q}$ and calculate the expected value of $X^{\alpha}$ as a function of properties of the graph $\alpha$ (see Lemma 4.1). This, together with the multiplicative and tree results for the $r_{\alpha}$, allow us to bound Adv in the Gaussian case. The scaling and shifting properties of the $r_{\alpha}$ are used to show we can deduce the graph case from the Gaussian case.

## 3 The recursive algebra of planted vs planted

The recursively defined $r_{\alpha}$ play a central role in our proof. By Proposition 2.7, the "advantage" Adv is bounded above by a sum of squares of the $r_{\alpha}$; therefore, to show low-degree hardness for a distinguishing problem, it is enough to control the size of this sum of squares. In this section, we explore the combinatorial behaviour of these $r_{\alpha}$ and show that they exhibit very nice properties under only mild assumptions on the probability spaces $P$ and $Q$. (We will
write $P$ and $Q$ for the probability spaces in this section both to emphasise that these results hold for any probability spaces and to ease the notational burden.) We assume throughout that both $P$ and $Q$ are symmetric, i.e. they are supported on $X$ for which $X_{i j}=X_{j i}$.

### 3.1 The graph interpretation

As in [19], it will be convenient to think of $\alpha \in \mathbb{N}^{N}$ as a multigraph, possibly with self-loops, on the vertex set $[n]$ where $N=n(n+1) / 2$ and we take $\alpha_{i j}$, for each $i \leqslant j$, to be the number of edges between vertices $i$ and $j$. For example, for $n=3, N=6$ and if we fix the order to be $\alpha=\left(\alpha_{11}, \alpha_{12}, \alpha_{22}, \alpha_{13}, \alpha_{23}, \alpha_{33}\right)$ then $(0,2,0,1,1,0)$ is the graph $\therefore$ and, for $n=2, N=3$, $(1,1,0)$ is the graph $\quad$.- a single edge with a loop at one vertex. For graphs $\alpha$ and $\beta$ we consider $\beta$ to be a subgraph of $\alpha$, denoted $\beta \subseteq \alpha$, if the labelled edge set of $\beta$ is a subset of the labelled edge set of $\alpha$. For example, for the graph $\alpha=\therefore$, the graphs $\beta=\therefore$ and $\beta^{\prime}=\therefore$ are distinct subgraphs. For graph $\alpha$ and subgraph $\beta \subseteq \alpha$ define $\alpha \backslash \beta$ to be the graph obtained from $\alpha$ by first removing the labelled edges in $\beta$ and then removing isolated vertices - e.g. $\therefore(\therefore=\cdots($ not $\bullet \cdot)$. Similarly, let $\alpha \cap \beta$ denote the graph obtained by first taking the intersection of both graphs and then deleting any isolated vertices.

The usefulness of considering graphs with labelled edge sets is that it simplifies the expression for the recursion in the definition of $r_{\alpha}$. To avoid confusion, write $v_{\alpha}$ for the vector that maps to the graph $\alpha$. Note first that if $v_{\beta} \leqslant v_{\alpha}$ then $\beta \subseteq \alpha$ and vice-versa. However the counts are different. For fixed $\alpha$ and $\beta$ with $v_{\beta} \leqslant v_{\alpha}$ there are $\binom{v_{\alpha}}{v_{\beta}}$ many distinct edge-labelled graphs $\beta^{\prime}$ such that $\beta^{\prime} \subseteq \alpha$ and $v_{\beta^{\prime}}=v_{\beta}$. Hence, for edge-labelled graphs the equivalent recursive definition to (1) is as follows, where the sum is over edge-labelled subgraphs.

For graph $\alpha$, the term $r_{\alpha}$ is defined recursively by

$$
\begin{equation*}
r_{\alpha}=\mathbb{E}_{P}\left[X^{\alpha}\right]-\sum_{\varnothing \subseteq \beta \subsetneq \alpha} r_{\beta} \mathbb{E}_{Q}\left[X^{\alpha \backslash \beta}\right] \tag{2}
\end{equation*}
$$

starting from the base case of the empty graph $r_{\varnothing}=1$. For example, if the probability spaces are exchangeable (i.e. $\beta=\therefore$ and $\beta^{\prime}=\therefore$ etc. have the same expectations under both $P$ and $Q$ ) then

$$
r_{\therefore}=\mathbb{E}_{P}\left[X^{\bullet \bullet}\right]-\mathbb{E}_{Q}\left[X^{\bullet \bullet}\right]-3 r_{\bullet} \mathbb{E}_{Q}\left[X^{\bullet \bullet}\right]-3 r_{\bullet} \mathbb{E}_{Q}\left[X^{\bullet}\right] .
$$

We will use the notion of edge-labelled subgraphs, denoted $\subseteq$, to aid the proofs but for the rest of the paper we consider $\alpha \in \mathbb{N}^{N}$, or equivalently $\alpha$ a graph without edge labels, and denote by $\leqslant$ the non-labelled subset or subgraph relation.

### 3.2 Combinatorial properties of the $r$-values

We will be interested in how properties of the probability spaces transfer to the behaviour of $r_{\alpha}$. We will see that the $r_{\alpha}$ behave multiplicatively over taking disjoint unions if the following property holds for $P$ and $Q$. Let $\alpha \cup \beta$ denote the disjoint union of $\alpha$ and $\beta$. We say the probability space $A$ is multiplicative over disjoint unions if (3) holds:

$$
\begin{equation*}
\mathbb{E}_{A}\left[X^{\alpha \cup \beta}\right]=\mathbb{E}_{A}\left[X^{\alpha}\right] \mathbb{E}_{A}\left[X^{\beta}\right] \text { for any graphs } \alpha \text { and } \beta . \tag{3}
\end{equation*}
$$

- Lemma 3.1. Suppose $P$ and $Q$ are symmetric and multiplicative over disjoint unions, i.e. they satisfy (3), then for any $\alpha$ and $\beta$, we have $r_{\alpha \cup \beta}=r_{\alpha} r_{\beta}$.

Proof. We proceed by induction on the number of edges.

Base case. Suppose $\alpha$ consists of two disjoint edges, denoted by $\mathbf{\bullet}$ and $\dot{\vdots}$. Then from (2),

$$
r_{\bullet!}=\mathbb{E}_{P}\left[X^{\bullet}\right] \mathbb{E}_{P}\left[X^{\bullet}\right]-r_{\varnothing} \mathbb{E}_{Q}\left[X^{\bullet}\right] \mathbb{E}_{Q}\left[X^{\bullet}\right]-r_{\bullet} \mathbb{E}_{Q}\left[X^{\bullet}\right]-r_{\bullet} \mathbb{E}_{Q}\left[X^{\bullet}\right],
$$

where we used the multiplicative property of (3) to deduce $\mathbb{E}_{P}[X \bullet \bullet \bullet]=\mathbb{E}_{P}\left[X X^{\bullet}\right] \mathbb{E}_{P}\left[X^{\bullet} \dot{\mathbf{\bullet}}\right]$. Now substituting $r_{\varnothing}=1$ along with $r_{!}=\mathbb{E}_{P}\left[X^{\bullet}\right]-\mathbb{E}_{Q}\left[X^{\bullet}\right]$ and the corresponding expression for $r_{\bullet}$, we get

$$
r_{\bullet!}=\mathbb{E}_{P}\left[X^{\bullet}\right] \mathbb{E}_{P}\left[X^{\grave{!}}\right]-\mathbb{E}_{P}\left[X^{\bullet}\right] \mathbb{E}_{Q}\left[X^{\grave{\mathbf{i}}}\right]-\mathbb{E}_{P}\left[X^{\bullet}\right] \mathbb{E}_{Q}\left[X^{!}\right]+\mathbb{E}_{Q}\left[X^{\bullet}\right] \mathbb{E}_{Q}\left[X^{!}\right]=r_{!} r_{\bullet}
$$

Inductive step. Fix $\tau=\alpha \cup \beta$ and assume the factorization of $r$ holds for graphs with fewer than $|\tau|=|\alpha|+|\beta|$ edges. For any graph $\gamma$ define $z_{\gamma}$ by $z_{\gamma}:=\mathbb{E}_{P}\left[X^{\gamma}\right]-r_{\gamma}$. Then, first note

$$
z_{\alpha} z_{\beta}=\mathbb{E}_{P}\left[X^{\alpha}\right] \mathbb{E}_{P}\left[X^{\beta}\right]-z_{\alpha} \mathbb{E}_{P}\left[X^{\beta}\right]-z_{\beta} \mathbb{E}_{P}\left[X^{\alpha}\right]+r_{\alpha} r_{\beta}
$$

and that because $\alpha$ and $\beta$ are disjoint and $P$ satisfies (3), we have $\mathbb{E}_{P}\left[X^{\alpha}\right] \mathbb{E}_{P}\left[X^{\beta}\right]=$ $\mathbb{E}_{P}\left[X^{\alpha \cup \beta}\right]$. Hence,

$$
z_{\alpha} z_{\beta}=\mathbb{E}_{P}\left[X^{\alpha \cup \beta}\right]-z_{\alpha} \mathbb{E}_{P}\left[X^{\beta}\right]-z_{\beta} \mathbb{E}_{P}\left[X^{\alpha}\right]+r_{\alpha} r_{\beta}
$$

and now (back) substituting $\mathbb{E}_{P}\left[X^{\alpha}\right]=r_{\alpha}+z_{\alpha}$ and $\mathbb{E}_{P}\left[X^{\beta}\right]=r_{\beta}+z_{\beta}$ we find

$$
r_{\alpha} r_{\beta}=\mathbb{E}_{P}\left[X^{\alpha \cup \beta}\right]-r_{\alpha} z_{\beta}-r_{\beta} z_{\alpha}-z_{\alpha} z_{\beta}
$$

By definition, $r_{\alpha \cup \beta}=\mathbb{E}_{P}\left[X^{\alpha \cup \beta}\right]-z_{\alpha \cup \beta}$; therefore, to complete the proof, it suffices to show the identity

$$
\begin{equation*}
z_{\alpha \cup \beta}=z_{\beta} r_{\alpha}+z_{\alpha} r_{\beta}+z_{\alpha} z_{\beta} \tag{4}
\end{equation*}
$$

Again, write $\tau=\alpha \cup \beta$ and note that by the definitions of $r_{\tau}$ and $z_{\tau}$, we have

$$
\begin{equation*}
z_{\tau}=\mathbb{E}_{P}\left[X^{\tau}\right]-r_{\tau}=-\sum_{\gamma \subsetneq \tau} r_{\gamma} \mathbb{E}_{Q}\left[X^{\tau \backslash \gamma}\right] . \tag{5}
\end{equation*}
$$

Now observe that for any $\gamma \subsetneq \tau$ since $\tau=\alpha \cup \beta$ we have $\gamma=\gamma_{\alpha} \cup \gamma_{\beta}$ where $\gamma_{\alpha}=\gamma \cap \alpha$ and $\gamma_{\beta}=\gamma \cap \beta$. Thus $\gamma$ is a disjoint union of $\gamma_{\alpha}$ and $\gamma_{\beta}$ with strictly fewer total edges than $\alpha \cup \beta$ and so by the inductive hypothesis $r_{\gamma}=r_{\gamma_{\alpha}} r_{\gamma_{\beta}}$. Hence, for any fixed $\gamma \subsetneq \alpha \cup \beta$,

$$
\begin{equation*}
r_{\gamma} \mathbb{E}_{Q}\left[X^{(\alpha \cup \beta) \backslash \gamma}\right]=r_{\gamma_{\alpha}} \mathbb{E}_{Q}\left[X^{\alpha \backslash \gamma_{\alpha}}\right] r_{\gamma_{\beta}} \mathbb{E}_{Q}\left[X^{\beta \backslash \gamma_{\beta}}\right] \tag{6}
\end{equation*}
$$

There are two special cases for (6). If $\gamma_{\alpha}=\alpha$, then

$$
r_{\gamma} \mathbb{E}_{Q}\left[X^{(\alpha \cup \beta) \backslash \gamma}\right]=r_{\alpha} r_{\gamma_{\beta}} \mathbb{E}_{Q}\left[X^{\beta \backslash \gamma_{\beta}}\right]
$$

and symmetrically for the case $\gamma_{\beta}=\gamma$. Note that because $\gamma$ is a strict subgraph of $\alpha \cup \beta$ either of $\gamma_{\alpha}=\gamma$ or $\gamma_{\beta}=\beta$ may hold but not both.

In the expression for $z_{\alpha \cup \beta}$ in (5) we take the sum over $\{\gamma: \gamma \subsetneq \alpha \cup \beta\}$ and partition it into sums over the sets $S_{1}=\left\{\gamma: \gamma_{\alpha}=\alpha, \gamma_{\beta} \subsetneq \beta\right\}, S_{2}=\left\{\gamma: \gamma_{\alpha} \subsetneq \alpha, \gamma_{\beta}=\beta\right\}$ and $S_{3}=\left\{\gamma: \gamma_{\alpha} \subsetneq \alpha, \gamma_{\beta} \subsetneq \beta\right\}$. We begin with $S_{1}$ : by (6),

$$
-\sum_{\gamma \in S_{1}} r_{\gamma} \mathbb{E}_{Q}\left[X^{(\alpha \cup \beta) \backslash \gamma}\right]=-\sum_{\gamma_{\beta} \subsetneq \beta} r_{\alpha} r_{\gamma_{\beta}} \mathbb{E}_{Q}\left[X^{\beta \backslash \gamma_{\beta}}\right]=r_{\alpha} z_{\beta}
$$

Similarly taking the sum over $S_{2}$ yields $r_{\beta} z_{\alpha}$. Lastly, the sum over $S_{3}$ is given by

$$
-\sum_{\gamma \in S_{3}} r_{\gamma} \mathbb{E}_{Q}\left[X^{(\alpha \cup \beta) \backslash \gamma}\right]=-\sum_{\gamma_{\alpha} \subsetneq \alpha, \gamma_{\beta} \subsetneq \beta} r_{\gamma_{\alpha}} \mathbb{E}_{Q}\left[X^{\alpha \backslash \gamma_{\alpha}}\right] r_{\gamma_{\beta}} \mathbb{E}_{Q}\left[X^{\beta \backslash \gamma_{\beta}}\right]=z_{\alpha} z_{\beta} .
$$

By (5), $z_{\alpha \cup \beta}$ can be obtained as a sum of $f(\gamma, \alpha \cup \beta)$ over $\gamma \subsetneq \alpha \cup \beta$ for some function $f$. However, when we sum the same function $f$ over $\gamma$ in $S_{1}, S_{2}$ and $S_{3}$ it gives the three terms on the right hand side of (4), thus confirming the identity as required.

- Lemma 3.2. For all $\tau$ where $\tau$ is a forest, meaning a graph with no cycles, suppose that $P$ and $Q$ satisfy $\mathbb{E}_{P}\left[X^{\tau}\right]=\mathbb{E}_{Q}\left[X^{\tau}\right]$. Then, $r_{\alpha}=0$ for any forest graph $\alpha$.
Proof. The proof is almost immediate by induction on the number of edges. For the base case we note $r_{\bullet}=\mathbb{E}_{P}\left[X^{\bullet}\right]-\mathbb{E}_{Q}\left[X_{\bullet}^{\bullet}\right]=0$. For any fixed forest $\alpha$ and $\beta \subsetneq \alpha$, the graph $\beta$ is a forest on strictly fewer edges and so by induction $r_{\beta}=0$, but then $r_{\alpha}=\mathbb{E}_{P}\left[X^{\alpha}\right]-\mathbb{E}_{Q}\left[X^{\alpha}\right]=0$.

We also show that one can add a constant shift to the distribution without changing the values of the $r_{\alpha}$. The proof is somewhat technical, so we relegate it to Section 5 .

- Lemma 3.3. Let $\tilde{X}$ be defined by $\tilde{X}_{i j}=X_{i j}+y_{i j}$ where $y_{i j} \in \mathbb{R}$ is non-random for each pair $i, j$. Then, for any probability spaces $P$ and $Q$, for $r_{\alpha}=r_{\alpha}(P, Q, X)$ and $\widetilde{r}_{\beta}=\widetilde{r}_{\beta}(P, Q, \widetilde{X})$, and for all $\gamma$, we have that $r_{\gamma}=\tilde{r}_{\gamma}$.
The following lemma concerns the effect on $r$ of scaling.
- Lemma 3.4. Fix $a \in \mathbb{R}$ and $a \neq 0$. Let $\tilde{X}$ be defined by $\widetilde{X}_{i j}=a X_{i j}$. Then for any probability spaces $P$ and $Q$, for $r_{\alpha}=r_{\alpha}(P, Q, X)$ and $\widetilde{r}_{\beta}=\widetilde{r}_{\beta}(P, Q, \widetilde{X})$, and for all $\gamma$, we have that $\widetilde{r}_{\gamma}=a^{|\gamma|} r_{\gamma}$, where $|\gamma|$ equals the number of edges in the graph $\gamma$, i.e. $|\gamma|=|E(\gamma)|$.

Proof. This proof is a simple induction on $|\alpha|$. The base case is easy as $\widetilde{r}_{\varnothing}=r_{\varnothing}=1$ as required. Now, fix $\alpha$ for some $|\alpha|>1$, and assume we have proven the result for $|\beta|<|\alpha|$. However,

$$
\tilde{r}_{\alpha}=\mathbb{E}_{P}\left[\tilde{X}^{\alpha}\right]-\sum_{\varnothing \subseteq \beta \subsetneq \alpha} \tilde{r}_{\alpha \backslash \beta} \mathbb{E}_{Q}\left[\tilde{X}^{\beta}\right]=a^{|\alpha|} \mathbb{E}_{P}\left[X^{\alpha}\right]-\sum_{\varnothing \subseteq \beta \subsetneq \alpha} \tilde{r}_{\alpha \backslash \beta} a^{|\beta|} \mathbb{E}_{Q}\left[X^{\beta}\right] .
$$

By the inductive hypothesis, $\widetilde{r}_{\alpha \backslash \beta}=a^{|\alpha \backslash \beta|} r_{\alpha \backslash \beta}$ and so by the equation above we are done as $a^{|\beta|} a^{|\alpha \backslash \beta|}=a^{|\alpha|}$.

## 4 Proof

In this section we give the full proofs of the main results, Theorems 2.4 and 2.5.
Proof of Theorem 2.4. Hard regime. We start by proving the computational lower bound. By definition of the Additive Gaussian model, we can write the observed edge weights $Y=\left\{Y_{i j}\right\}_{i \leqslant j}$ as $Y=X+Z$, where $Z$ consists of i.i.d. $\mathcal{N}(0,1)$ entries, and

$$
X_{i j}= \begin{cases}\lambda / x_{\ell} & \sigma_{i}=\sigma_{j}=\ell \text { for some } \ell \in[M]  \tag{7}\\ 0 & \text { otherwise }\end{cases}
$$

Recall the sequence $r_{\alpha}$, defined recursively via

$$
r_{\alpha}=\mathbb{E}_{\mathbb{P}}\left[X^{\alpha}\right]-\sum_{0 \leqslant \beta \leq \alpha} r_{\beta}\binom{\alpha}{\beta} \mathbb{E}_{\mathbb{Q}}\left[X^{\alpha-\beta}\right] .
$$

By Lemma 2.6 and Proposition 2.7, we have that if

$$
\begin{equation*}
\sum_{\alpha:|\alpha| \leqslant D} \frac{r_{\alpha}^{2}}{\alpha!}=1+o(1) \tag{8}
\end{equation*}
$$

then no degree- $D$ test can weakly separate $\mathbb{P}$ and $\mathbb{Q}$. Thus, to prove the computational lower bound, it suffices to show that (8) holds for $D^{5} \lambda^{2} M^{2}\left(k^{2} / n \vee 1\right)=o(1)$.

We will demonstrate (8) by proving the following three facts. (We consider the sets $\alpha$ as graphs and write $V(\alpha)$ for the vertex set and $C(\alpha)$ for the set of connected components, see Section 3.1 for details.)
(i) For all $\alpha$, the term $r_{\alpha}$ factorizes over the connected components of $\alpha$. That is,

$$
r_{\alpha}=\prod_{\beta \in \mathcal{C}(\alpha)} r_{\beta} .
$$

(ii) If at least one connected component of $\alpha$ is a tree, then $r_{\alpha}=0$.
(iii) For all $\alpha$, where $|\alpha|=|E(\alpha)|$ counts the edges in the graph $\alpha$,

$$
\left|r_{\alpha}\right| \leqslant(|\alpha|+1)^{|\alpha|}\left(\frac{\widehat{M} \lambda}{C}\right)^{|\alpha|}\left(\frac{k}{n}\right)^{|V(\alpha)|}
$$

Fact (i) follows directly from Lemma 3.1. To see Fact (ii), we note that by Lemma 3.2 it suffices to show that for any $\tau$ a tree, we have $\mathbb{E}_{\mathbb{P}}\left[X^{\tau}\right]=\mathbb{E}_{\mathbb{Q}}\left[X^{\tau}\right]$. But recall that for a tree, the number of edges is one less than the number of vertices, i.e. $|\tau|=|V(\tau)|-1$ and $\tau$ consists of one connected component so that $|C(\tau)|=1$. Thus, by Lemma 4.1 we are done. Fact (iii) follows from Lemma 4.2. We will state and prove Lemmas 4.1 and 4.2 at the end of this section.

Next, we argue that the three facts combined yield (8). From fact (iii), we have for each $\alpha$,

$$
\begin{aligned}
r_{\alpha}^{2} & \leqslant(|\alpha|+1)^{2|\alpha|}\left(\frac{\widehat{M} \lambda}{C}\right)^{2|\alpha|}\left(\frac{k}{n}\right)^{2|V(\alpha)|} \\
& =(|\alpha|+1)^{2|\alpha|}\left(\frac{\widehat{M}^{2} \lambda^{2} k^{2}}{C^{2} n}\right)^{|E(\alpha)|}\left(\frac{k^{2}}{n}\right)^{|V(\alpha)|-|E(\alpha)|} n^{-|V(\alpha)|}
\end{aligned}
$$

From (ii), we know that $r_{\alpha}$ is nonzero only when all connected components of $\alpha$ contain at least one cycle. Denote

$$
\mathcal{G}_{d, v}=\{\alpha:|E(\alpha)|=d ;|V(\alpha)|=v ; \text { for all } \beta \in \mathcal{C}(\alpha), \beta \text { is not a tree }\} .
$$

Note that for all $d, v$ such that $v>d$, we have that $\mathcal{G}_{d, v}=\varnothing$ because if all connected components of $\alpha$ contains at least one cycle, we must have $|\alpha| \geqslant|V(\alpha)|$. Thus for $k^{2} \geqslant n$, we have shown that for all $d, v$ with $\alpha \in \mathcal{G}_{d, v}$,

$$
r_{\alpha}^{2} \leqslant(d+1)^{2 d}\left(\frac{\widehat{M}^{2} \lambda^{2} k^{2}}{C^{2} n}\right)^{d} n^{-v}
$$

On the other hand, for $k^{2}<n$, we have

$$
r_{\alpha}^{2} \leqslant(d+1)^{2 d}\left(\frac{\widehat{M} \lambda}{C}\right)^{2 d}\left(\frac{k}{n}\right)^{2 v} \leqslant(d+1)^{2 d}\left(\frac{\widehat{M} \lambda}{C}\right)^{2 d} n^{-v}
$$

Combined with the bound on $r_{\alpha}^{2}$ for $k^{2} \geqslant n$, we have shown that

$$
r_{\alpha}^{2} \leqslant(d+1)^{2 d}\left(\left(\frac{\widehat{M} \lambda}{C}\right)^{2}\left(\frac{k^{2}}{n} \vee 1\right)\right)^{d} n^{-v} .
$$

Next, we bound the size of $\mathcal{G}_{d, v}$ by counting the number of graphs with exactly $d$ edges and $v$ vertices:

$$
\begin{equation*}
\left|\mathcal{G}_{d, v}\right| \leqslant\binom{ n}{v}\binom{v}{2}^{d} \leqslant n^{v} v^{2 d} . \tag{9}
\end{equation*}
$$

where the factor $\binom{n}{v}$ enumerates the possibilities for the vertex set in $\alpha$; the $\binom{v}{2}$ dactor counts the allocation of the $d$ edges, allowing for edge multiplicity. Combining (12) (see Lemma 4.2 below) and (9) yields

$$
\begin{aligned}
\sum_{\alpha:|\alpha| \leqslant D} \frac{r_{\alpha}^{2}}{\alpha!} & \leqslant r_{0}^{2}+\sum_{d=1}^{D} \sum_{v=1}^{d} \sum_{\alpha \in \mathcal{G}_{d, v}} \frac{r_{\alpha}^{2}}{\alpha!} \\
& \leqslant 1+\sum_{d=1}^{D} \sum_{v=1}^{d}\left|\mathcal{G}_{d, v}\right| \cdot(d+1)^{2 d}\left(\left(\frac{\widehat{M} \lambda}{C}\right)^{2}\left(\frac{k^{2}}{n} \vee 1\right)\right)^{d} n^{-v} \\
& \leqslant 1+\sum_{d=1}^{D} \sum_{v=1}^{d} n^{v} v^{2 d}(d+1)^{2 d}\left(\left(\frac{\widehat{M} \lambda}{C}\right)^{2}\left(\frac{k^{2}}{n} \vee 1\right)\right)^{d} n^{-v} \\
& =1+\sum_{d=1}^{D}\left((d+1)^{2}\left(\frac{\widehat{M} \lambda}{C}\right)^{2}\left(\frac{k^{2}}{n} \vee 1\right)\right)^{d} \sum_{v=1}^{d} v^{2 d} \\
& \leqslant 1+D \sum_{d=1}^{D}\left((D+1)^{2} D^{2}\left(\frac{\widehat{M} \lambda}{C}\right)^{2}\left(\frac{k^{2}}{n} \vee 1\right)\right)^{d} \\
& \leqslant 1+D \sum_{d=1}^{D}\left(\left(2 D^{2} \frac{\widehat{M} \lambda}{C}\right)^{2}\left(\frac{k^{2}}{n} \vee 1\right)\right)^{d} \\
& =1+(1+o(1)) 4 D^{5}\left(\frac{\widehat{M} \lambda}{C}\right)^{2}\left(\frac{k^{2}}{n} \vee 1\right)=1+o(1)
\end{aligned}
$$

where the last two equalities follow by the condition $D^{5}(\widehat{M} \lambda)^{2}\left(k^{2} / n \vee 1\right)=o(1)$, under which the summation over $d$ is a geometrically decreasing sequence, dominated by the first term.

Easy regime. Next, we show that in the "easy" regime $\lambda^{2} \widetilde{M}^{2}\left(k^{2} / n \vee 1\right)=\omega(1)$ and $\widetilde{M}^{2} k=$ $\omega\left(\widehat{M}^{2}\right)$, there is a low-degree test that strongly separates $\mathbb{P}$ and $\mathbb{Q}$. When $\lambda^{2} \widehat{M}^{2} k^{2} / n=\omega(1)$, consider the algorithm that uses $\widehat{T}=\sum_{i} Y_{i i}$, the sum of the diagonal elements, as the test statistic. We can compute the first and second moments of $\widehat{T}$ under the two models using
(7) to note that under $\mathbb{P}$, we have $Y_{i i}=\frac{\lambda}{x_{\ell}}+\mathcal{N}(0,1)$ if $\sigma_{i}=\sigma_{j}=\ell$ for some $\ell \in[M]$ and $Y_{i i}=\mathcal{N}(0,1)$ otherwise, where each community label $\ell$ is selected with probability $\frac{x_{\ell} k}{n}$ and no label is selected with probability $1-\frac{k}{n}$. Under $\mathbb{Q}$, we replace $x$ and $M$ with $x^{\prime}$ and $M^{\prime}$.

$$
\begin{aligned}
& \mathbb{E}_{\mathbb{P}}[\hat{T}]=n \mathbb{E}_{\mathbb{P}}\left[Y_{11}\right]=n\left[\sum_{\ell \in[M]} \frac{\lambda}{x_{\ell}} \cdot \mathbb{P}\left\{\sigma_{1}=\ell\right\}+0 \cdot \mathbb{P}\left\{\sigma_{1}=\star\right\}\right]=n \sum_{\ell \in[M]} \frac{k \lambda}{n}=M k \lambda \\
& \mathbb{E}_{\mathbb{Q}}[\widehat{T}]=n \mathbb{E}_{\mathbb{Q}}\left[Y_{11}\right]=M^{\prime} k \lambda, \\
& \operatorname{Var}_{\mathbb{P}}[\widehat{T}] \leqslant n \mathbb{E}_{\mathbb{P}}\left[Y_{11}^{2}\right]=n\left[\sum_{\ell \in[M]}\left(\frac{\lambda^{2}}{x_{\ell}^{2}}+1\right) \cdot \mathbb{P}\left\{\sigma_{1}=\ell\right\}+1 \cdot \mathbb{P}\left\{\sigma_{1}=\star\right\}\right]=n+\sum_{\ell \in[M]} \frac{k \lambda^{2}}{x_{\ell}}, \\
& \operatorname{Var}[\widehat{T}] \leqslant n \mathbb{E}_{\mathbb{Q}}\left[Y_{11}^{2}\right]=n+\sum_{\ell \in\left[M^{\prime}\right]} \frac{k \lambda^{2}}{x_{\ell}^{\prime}} .
\end{aligned}
$$

Note also that $M \min _{\ell} x_{\ell} \geqslant C$ implies $\max _{\ell} 1 / x_{\ell}<M / C$; thus, $\sum_{\ell \leqslant M} \frac{1}{x_{\ell}} \leqslant M^{2} / C$. Hence, when $\widetilde{M}^{2} k / \widehat{M}^{2}=\omega(1)$ and $\widetilde{M}^{2} \lambda^{2} k^{2} / n=\omega(1)$,

$$
\sqrt{\max \{\operatorname{Var}[\widehat{T}], \operatorname{Var}} \underset{\mathbb{P}}{ }[\widehat{T}]\}=o\left(\left|\mathbb{E}_{\mathbb{P}}[\widehat{T}]-\mathbb{E}_{\mathbb{Q}}[\widehat{T}]\right|\right)
$$

Thus, thresholding $\widehat{T}$ strongly separates $\mathbb{P}$ and $\mathbb{Q}$.

## Proof of Theorem 2.5.

Hard regime. The proof proceeds by comparison to a corresponding Gaussian model, so that we can reuse the calculations in the proof of Theorem 2.4. Our starting point is Proposition 2.8. Define $X=X^{(q, s)}$ appropriately for our binary testing problem, i.e., $X_{i j}^{(q, s)}=q+s / x_{\ell}$ if $\sigma_{i}=\sigma_{j}=\ell$, and $X_{i j}^{(q, s)}=q$ otherwise. Let $\tau_{0}=q$, and recall that we have a valid constant $\tau_{1}<1$ by assumption. Consider the additive Gaussian testing problem (as in Theorem 2.4) with the same parameters $n, k, M, x$ as our binary model, and with $\lambda:=s / \sqrt{q\left(1-\tau_{1}\right)}$. Let $X^{(\lambda)}$ denote the corresponding $X$ as per Proposition 2.7, i.e., $X_{i j}^{(\lambda)}=\lambda / x_{\ell}$ if $\sigma_{i}=\sigma_{j}=\ell$, and $X_{i j}^{(\lambda)}=0$ otherwise. Note $X_{i j}^{(q, s)}=(s / \lambda) X_{i j}^{(\lambda)}+q$ and so by Lemmas 3.3 and 3.4 we have, $r_{\alpha}\left(X^{(q, s)}\right)=(s / \lambda)^{|\alpha|} r_{\alpha}\left(X^{(\lambda)}\right)$. By Proposition 2.8,

$$
\begin{aligned}
\operatorname{Adv}_{\leqslant D}(\mathbb{P}, \mathbb{Q}) & \leqslant \sqrt{\sum_{\alpha \in\{0,1\}^{N},|\alpha| \leqslant D} \frac{r_{\alpha}\left(X^{(q, s)}\right)^{2}}{\left(q\left(1-\tau_{1}\right)\right)^{|\alpha|}}}=\sqrt{\sum_{\alpha \in\{0,1\}^{N},|\alpha| \leqslant D} r_{\alpha}\left(X^{(\lambda)}\right)^{2}} \\
& \leqslant \sqrt{\sum_{\alpha \in \mathbb{N}^{N},|\alpha| \leqslant D} \frac{r_{\alpha}\left(X^{(\lambda))^{2}}\right.}{\alpha!}}
\end{aligned}
$$

In other words, we have related the conclusion of Proposition 2.8 to the conclusion of Proposition 2.7 but with $s / \sqrt{q\left(1-\tau_{1}\right)}$ in place of $\lambda$. The result now follows by the proof of Theorem 2.4.

Easy regime. We now consider a signed triangle count $\widehat{R}$ as our test statistic. Let

$$
\begin{equation*}
\widehat{R}=\sum_{i<j<k} R_{i j} R_{i k} R_{j k} \quad \text { where } R_{i j}=Y_{i j}-q \tag{10}
\end{equation*}
$$

Expectation and variance calculations for $\widehat{R}$ are computed in Lemma 5.1 of Section 5.5. Denote by $\widehat{M}$ the maximum of $M$ and $M^{\prime}$. Then,

$$
\left|\mathbb{E}_{\mathbb{P}}[\hat{R}]-\mathbb{E}_{\mathbb{Q}}[\hat{R}]\right|=\frac{1}{3}\left|M-M^{\prime}\right| s^{3} k^{3}\left(1+O\left(n^{-1}\right)\right)
$$

and

$$
\begin{align*}
& \max \left\{\operatorname{Var}_{\mathbb{P}}[\hat{R}], \operatorname{Var}[\hat{\mathbb{Q}}]\right\} \\
& \leqslant \frac{1}{C} \widehat{M}^{2} k^{5} s^{6}+\widehat{M} k^{4} s^{4} q+\frac{1}{C} \widehat{M}^{2} k^{4} s^{5}+\frac{1}{3} n^{3} q^{3}+n k^{2} s q^{2}+k^{3} q^{2} s+k^{3} q s^{2}+\frac{1}{3} \widehat{M} k^{3} s^{3} \tag{11}
\end{align*}
$$

where $C$ is the constant from the assumption that $M \min _{\ell} x_{\ell}, M^{\prime} \min _{\ell} x_{\ell}^{\prime}>C$. Writing $\widetilde{M}=\left|M-M^{\prime}\right|$, notice that to prove strong separation it suffices to show that each term in (11) is $o\left(\widetilde{M}^{2} s^{6} k^{6}\right)$. For the fourth term to be $o\left(\widetilde{M}^{2} s^{6} k^{6}\right)$ is equivalent to $\widetilde{M}^{2 / 3} s^{2} k^{2} /(n q)=\omega(1)$, one of our assumptions. Similarly for the first term to be $o\left(\widetilde{M}^{2} s^{6} k^{6}\right)$ is equivalent to $\widetilde{M}^{2} k \widehat{M}^{2}=\omega(1)$ another of our assumptions. For the last term to be $o\left(\widetilde{M}^{2} s^{6} k^{6}\right)$ is equivalent to $\widetilde{M}^{2 / 3} \widehat{M}^{-1 / 3} s k=\omega(1)$, which is implied by our assumption $\widehat{M}^{-1 / 3} s k=\omega(1)$. All other terms follow also because of these assumptions.

- Lemma 4.1. For each $\alpha \in \mathbb{N}^{N}$, and for each $x=\left(x_{1}, \ldots, x_{c}\right)$ with $\sum_{\ell} x_{\ell}=1$,

$$
\mathbb{E}_{\mathbb{P}}\left[X^{\alpha}\right]=\lambda^{|\alpha|}\left(\frac{k}{n}\right)^{|V(\alpha)|} \prod_{\beta \in C(\alpha)} \sum_{\ell=1}^{c} x_{\ell}^{|V(\beta)|-|\beta|}
$$

Proof. First consider $\beta$ a connected graph. Note that for $(i, j) \in \beta$, if it is not the case that $i, j \in S_{\ell}$ for some $\ell$ then $X^{(i, j)} \sim \mathcal{N}(0,1)$ and so $\mathbb{E}_{\mathbb{P}}\left[X^{(i, j)}\right]=0$ (here, we have used that our $S_{\ell}$ 's do not overlap). Hence, for $\beta$ connected,

$$
\mathbb{E}_{\mathbb{P}}\left[X^{\beta}\right]=\sum_{\ell=1}^{c} \mathbb{P}\left(V(\beta) \in S_{\ell}\right)\left(\frac{\lambda}{x_{\ell}}\right)^{|\beta|}=\sum_{\ell=1}^{c}\left(\frac{x_{\ell} k}{n}\right)^{|V(\beta)|}\left(\frac{\lambda}{x_{\ell}}\right)^{|\beta|}
$$

Notice, it is now enough to show that the $X^{\beta}$ 's are independent for $\beta$ 's connected components of $\alpha$, as this would imply that $\mathbb{E}_{\mathbb{P}}\left[X^{\alpha}\right]=\prod_{\beta \in C(\alpha)} \mathbb{E}_{\mathbb{P}}\left[X^{\beta}\right]$ and we have the result.

This independence follows because $X^{(i, j)}$ depends only on the events $\left[i \in S_{\ell}\right],\left[j \in S_{\ell^{\prime}}\right]$ for each $\ell, \ell^{\prime}$; thus, $X^{\beta}$ and $X^{\beta^{\prime}}$ are independent as long as their vertex sets $V(\beta)$ and $V\left(\beta^{\prime}\right)$ do not overlap. As the vertex sets of connected components are mutually non-overlapping, we have finished the proof.

- Lemma 4.2. Suppose $M x_{(1)} \geqslant C$ and $M^{\prime} x_{(1)}^{\prime} \geqslant C$ where $x_{(1)}:=\min _{\ell} x_{\ell}$ for some constant $C>0$. Then there exists editn ${ }_{0} \in \mathbb{N}$ such that for $n>n_{0}$, for all $\alpha$, we have that $r_{\alpha}$ satisfies

$$
\begin{equation*}
\left|r_{\alpha}\right| \leqslant(|\alpha+1|)^{|\alpha|}\left(\frac{\widehat{M} \lambda}{C}\right)^{|\alpha|}\left(\frac{k}{n}\right)^{|V(\alpha)|} \tag{12}
\end{equation*}
$$

Proof. We will argue by induction on $|\alpha|$. A graph $\alpha$ with $|\alpha|=1$ is either a tree with two vertices and one edge, or a self-loop with one vertex and one edge. If $\alpha$ is a tree, then $r_{\alpha}=0$ and (12) trivially holds. If $\alpha$ is a self-loop, we have by Lemma 4.1,

$$
r_{\alpha}=\mathbb{E}_{\mathbb{P}}\left[X^{\alpha}\right]-\mathbb{E}_{\mathbb{Q}}\left[X^{\alpha}\right]=M \lambda\left(\frac{k}{n}\right)-M^{\prime} \lambda\left(\frac{k}{n}\right) \leqslant(|\alpha|+1)^{|\alpha|}\left(\frac{\widehat{M} \lambda}{C}\right)^{|\alpha|}\left(\frac{k}{n}\right)^{|V(\alpha)|}
$$

where the last inequality is because $C \leqslant M x_{(1)} \leqslant 1$. We have shown (12) for $|\alpha|=1$. Suppose (12) holds for all $\alpha$ with $|\alpha| \leqslant d-1$; next we show it also holds for $|\alpha|=d$.

If $\alpha$ is not connected, then each connected component $\beta \in \mathcal{C}(\alpha)$ has $|\beta|<d$. Thus from the factorization lemma and the induction hypothesis, we have

$$
\left|r_{\alpha}\right|=\prod_{\beta \in \mathcal{C}(\alpha)}\left|r_{\beta}\right| \leqslant \prod_{\beta \in \mathcal{C}(\alpha)}(|\beta|+1)^{|\beta|}\left(\frac{\lambda \widehat{M}}{C}\right)^{|\beta|}\left(\frac{k}{n}\right)^{|V(\beta)|} \leqslant(|\alpha|+1)^{|\alpha|}\left(\frac{\lambda \widehat{M}}{C}\right)^{|\alpha|}\left(\frac{k}{n}\right)^{|V(\alpha)|}
$$

Thus (12) holds. Next we show (12) for $\alpha$ connected. If $\alpha$ is a tree, then by Fact (ii) we have $r_{\alpha}=0$ and (12) holds. Therefore it suffices to consider $\alpha$ that is not a tree. Recall that

$$
\begin{equation*}
r_{\alpha}=\mathbb{E}_{\mathbb{P}}\left[X^{\alpha}\right]-\mathbb{E}_{\mathbb{Q}}\left[X^{\alpha}\right]-\sum_{0<\beta \nless \alpha} r_{\beta}\binom{\alpha}{\beta} \mathbb{E}_{\mathbb{Q}}\left[X^{\alpha \backslash \beta}\right] \tag{13}
\end{equation*}
$$

For the first term in (13), we can apply Lemma 4.1 for connected $\alpha$ :

$$
\begin{aligned}
\mathbb{E}_{\mathbb{P}}\left[X^{\alpha}\right] & =\lambda^{|\alpha|}\left(\frac{k}{n}\right)^{|V(\alpha)|} \sum_{\ell \in[M]} x_{\ell}^{|V(\alpha)|-|\alpha|} \leqslant \lambda^{|\alpha|}\left(\frac{k}{n}\right)^{|V(\alpha)|}\left[M x_{(1)}\right]^{|V(\alpha)|-|\alpha|} \\
& =\left[M x_{(1)}\right]^{|V(\alpha)|-|\alpha|} M^{1-|V(\alpha)|}(M \lambda)^{|\alpha|}\left(\frac{k}{n}\right)^{|V(\alpha)|} \\
& \leqslant\left(\frac{M \lambda}{C}\right)^{|\alpha|}\left(\frac{k}{n}\right)^{|V(\alpha)|}
\end{aligned}
$$

for large enough $n$. The last inequality is because we assumed that $\alpha$ is not a tree. Thus $|V(\alpha)| \leqslant|\alpha|$, and $\left(M x_{(1)}\right)^{|V(\alpha)|-|\alpha|} \leqslant C^{|V(\alpha)|-|\alpha|} \leqslant C^{|\alpha|}$.

Next we bound the third term in (13). For each $\beta \lessgtr \alpha$ that is nonempty, $|\beta|<|\alpha|=d$. From the induction hypothesis we have

$$
\left|r_{\beta}\right| \leqslant(|\beta|+1)^{|\beta|}\left(\frac{\widehat{M} \lambda}{C}\right)^{|\beta|}\left(\frac{k}{n}\right)^{|V(\beta)|}
$$

Thus

$$
\begin{aligned}
& \left|r_{\beta} \mathbb{E}_{\mathbb{Q}} X^{\alpha \backslash \beta}\right| \\
\leqslant & (|\beta|+1)^{|\beta|}\left(\frac{\widehat{M} \lambda}{C}\right)^{|\beta|}\left(\frac{k}{n}\right)^{|V(\beta)|} \cdot \lambda^{|\alpha \backslash \beta|}\left(\frac{k}{n}\right)^{|V(\alpha \backslash \beta)|} \prod_{\gamma \in \mathcal{C}(\alpha \backslash \beta)} \sum_{\ell \in\left[M^{\prime}\right]}\left(x_{\ell}^{\prime}\right)^{|V(\gamma)|-|\gamma|} \\
= & (|\beta|+1)^{|\beta|}\left(\frac{\widehat{M} \lambda}{C}\right)^{|\alpha|}\left(\frac{k}{n}\right)^{|V(\alpha)|}\left(\frac{\widehat{M}}{C}\right)^{-|\alpha \backslash \beta|}\left(\frac{k}{n}\right)^{-|V(\beta) \cap V(\alpha \backslash \beta)|} \prod_{\gamma \in \mathcal{C}(\alpha \backslash \beta)} \sum_{\ell \in\left[M^{\prime}\right]}\left(x_{\ell}^{\prime}\right)^{|V(\gamma)|-|\gamma|} \\
\leqslant & (|\beta|+1)^{|\beta|}\left(\frac{\widehat{M} \lambda}{C}\right)^{|\alpha|}\left(\frac{k}{n}\right)^{|V(\alpha)|} \prod_{\gamma \in \mathcal{C}(\alpha \backslash \beta)}\left(\frac{\widehat{M}}{C}\right)^{-|\gamma|} \sum_{\ell \in\left[M^{\prime}\right]}\left(x_{\ell}^{\prime}\right)^{|V(\gamma)|-|\gamma|}
\end{aligned}
$$

Next we show that for all $\gamma \in \mathcal{C}(\alpha \backslash \beta)$, we have that $(\widehat{M} / C)^{-|\gamma|} \sum_{\ell \in\left[M^{\prime}\right]}\left(x_{\ell}^{\prime}\right)^{|V(\gamma)|-|\gamma|} \leqslant 1$. Note that $|V(\gamma)| \leqslant|\gamma|+1$. We discuss the cases $|V(\gamma)|=|\gamma|+1$ and $|V(\gamma)| \leqslant|\gamma|$ separately. If $|V(\gamma)|=|\gamma|+1$, then

$$
\left(\frac{\widehat{M}}{C}\right)^{-|\gamma|} \sum_{\ell \in\left[M^{\prime}\right]}\left(x_{\ell}^{\prime}\right)^{|V(\gamma)|-|\gamma|}=\left(\frac{\widehat{M}}{C}\right)^{-|\gamma|} \leqslant 1
$$

If $|V(\gamma)| \leqslant|\gamma|$, then we have

$$
\begin{aligned}
\left(\frac{\widehat{M}}{C}\right)^{-|\gamma|} \sum_{\ell \in\left[M^{\prime}\right]}\left(x_{\ell}^{\prime}\right)^{|V(\gamma)|-|\gamma|} & \leqslant\left(\frac{M}{C}\right)^{-|\gamma|} M^{\prime}\left(x_{(1)}^{\prime}\right)^{|V(\gamma)|-|\gamma|} \\
& \stackrel{(a)}{\leqslant}\left(\widehat{M} x_{(1)}^{\prime}\right)^{|V(\gamma)|-|\gamma|} \widehat{M}^{1-|V(\gamma)|} C^{|\gamma|} \\
& \stackrel{(b)}{\leqslant} C^{|V(\gamma)|} \widehat{M}^{1-|V(|\gamma|)|} \stackrel{(c)}{\leqslant} 1,
\end{aligned}
$$

where (a) is from $M^{\prime} \leqslant M ;(\mathrm{b})$ is from $M^{\prime} x_{(1)}^{\prime} \geqslant C$ and $|V(\gamma)| \leqslant|\gamma| ;(\mathrm{c})$ is from $C \leqslant 1$, $\widehat{M} \geqslant 1$, and $|V(\gamma)| \geqslant 1$ for all $\gamma \in \mathcal{C}(\alpha \backslash \beta)$. We have shown that

$$
\left|r_{\beta} \mathbb{E}_{\mathbb{Q}} X^{\alpha \backslash \beta}\right| \leqslant(|\beta|+1)^{|\beta|}\left(\frac{\widehat{M} \lambda}{C}\right)^{|\alpha|}\left(\frac{k}{n}\right)^{|V(\alpha)|}
$$

Plug in the values of $\mathbb{E}_{\mathbb{P}}\left[X^{\alpha}\right]$ and $\mathbb{E}_{\mathbb{Q}}\left[X^{\alpha}\right]$ to (13) to obtain

$$
\begin{aligned}
\left|r_{\alpha}\right| & \leqslant\left(\frac{\widehat{M} \lambda}{C}\right)^{|\alpha|}\left(\frac{k}{n}\right)^{|V(\alpha)|}+\lambda^{|\alpha|}\left(\frac{k}{n}\right)^{|V(\alpha)|}+\sum_{0<\beta \notinfty \alpha}\binom{\alpha}{\beta}(|\beta|+1)^{|\beta|}\left(\frac{\widehat{M} \lambda}{C}\right)^{|\alpha|}\left(\frac{k}{n}\right)^{|V(\alpha)|} \\
& \leqslant\left[1+1+\sum_{0<\beta \leq \alpha}(|\beta|+1)^{|\beta|}\right]\left(\frac{\widehat{M} \lambda}{C}\right)^{|\alpha|}\left(\frac{k}{n}\right)^{|V(\alpha)|} \\
& \leqslant(|\alpha|+1)^{|\alpha|}\left(\frac{\widehat{M} \lambda}{C}\right)^{|\alpha|}\left(\frac{k}{n}\right)^{|V(\alpha)|}
\end{aligned}
$$

where the last inequality is because

$$
2+\sum_{0<\beta \leq \alpha}\binom{\alpha}{\beta}(|\beta|+1)^{|\beta|}=2+\sum_{0<\ell<|\alpha|}\binom{|\alpha|}{\ell}(\ell+1)^{\ell} \leqslant(|\alpha|+1)^{|\alpha|}
$$

We have shown that (12) holds for all $\alpha$.

## 5 Additional proofs

### 5.1 Proof of Lemma 2.6

First we prove the statement for weak separation. Assume, for the sake of contradiction, that some degree- $D$ test $g: \mathbb{R}^{N} \rightarrow \mathbb{R}$ weakly separates $\mathbb{P}$ and $\mathbb{Q}$. Without loss of generality, we can shift and scale $g$ so that $\mathbb{E}_{\mathbb{Q}}[g]=0$ and $\mathbb{E}_{\mathbb{P}}[g]=1$. Weak separation guarantees that for sufficiently large $n, \operatorname{Var}_{\mathbb{Q}}[g]=\mathbb{E}_{\mathbb{Q}}\left[g^{2}\right] \leqslant C$ for some positive constant $C>0$. Defining $f=g+C$, we have

$$
\operatorname{Adv}_{\leqslant D} \geqslant \frac{\mathbb{E}_{\mathbb{P}}[f]}{\sqrt{\mathbb{E}_{\mathbb{Q}}\left[f^{2}\right]}}=\frac{1+C}{\sqrt{\mathbb{E}_{\mathbb{Q}}\left[g^{2}\right]+C^{2}}} \geqslant \frac{1+C}{\sqrt{C+C^{2}}}=\sqrt{\frac{1+C}{C}}
$$

which is a constant strictly greater than 1 , contradicting $\operatorname{Adv}_{\leqslant D}=1+o(1)$. The proof for strong separation is identical, except now $C=o(1)$.

### 5.2 Proof of Proposition 2.7

The proof is similar to the proof of Theorem 2.2 in [19], so we only explain the differences. Our distribution $\mathbb{Q}$ plays the role of the single "planted" distribution in [19]. The only difference is that the quantity $\mathbb{E}[f(Y) x]$ from [19] needs to be replaced by our $\mathbb{E}_{\mathbb{P}}[f(Y)]$, which means (in the notation of $[19]$ ) the vector $c$ needs to be redefined as $c_{\alpha}=\mathbb{E}_{\mathbb{P}}\left[h_{\alpha}(Y)\right]=\mathbb{E}_{\mathbb{P}}\left[X^{\alpha}\right] / \sqrt{\alpha!}$.

### 5.3 Proof of Proposition 2.8

Follow the proof of Theorem 2.7 in [19], but redefine $c=\left(c_{\alpha}\right)_{\alpha \in\{0,1\}^{N}}$ by $c_{\alpha}=\mathbb{E}_{\mathbb{P}}\left[\tilde{X}^{\alpha}\right]$ where $\tilde{X}_{i}=(\mu+1 / \mu) X_{i}-1 / \mu$ and $\mu=\sqrt{\frac{1-\tau_{1}}{\tau_{0}}}$. This gives the bound

$$
\operatorname{Adv}_{\leqslant D}(\mathbb{P}, \mathbb{Q}) \leqslant \sqrt{\sum_{\alpha \in\{0,1\}^{N},|\alpha| \leqslant D} \frac{r_{\alpha}(\tilde{X})^{2}}{\left(1+\tau_{0}-\tau_{1}\right)^{2|\alpha|}}}
$$

where $r_{\alpha}(\tilde{X})$ is defined in (1). Using Lemmas 3.3 and 3.4, we have $r_{\alpha}(\tilde{X})=(\mu+1 / \mu)^{|\alpha|} r_{\alpha}(X)$, so the above simplifies to give the result.

### 5.4 Proof of Lemma 3.3

Base case(s). Note that by definition $\widetilde{r}_{\varnothing}=r_{\varnothing}=1$. Let $|\alpha|=1$, i.e. $\alpha=\{i j\}$ for some $1 \leqslant i \leqslant j \leqslant n$. Then the base step follows directly from the definition

$$
\tilde{r}_{\alpha}=\mathbb{E}_{P}\left[\tilde{X}^{i j}\right]-\mathbb{E}_{Q}\left[\tilde{X}^{i j}\right]=\mathbb{E}_{P}\left[X^{i j}\right]+y_{i j}-\mathbb{E}_{Q}\left[X^{i j}\right]-y_{i j}=r_{\alpha}
$$

Inductive step. Fix $\alpha$ with $|\alpha|>1$ and assume $\widetilde{r}_{\beta}=r_{\beta}$ for all $\beta \subsetneq \alpha$. Directly from the definition of $r$ and the inductive hypothesis,

$$
\begin{aligned}
\tilde{r}_{\alpha} & =\mathbb{E}_{P}\left[\tilde{X}^{\alpha}\right]-\mathbb{E}_{Q}\left[\tilde{X}^{\alpha}\right]-\sum_{\varnothing \subsetneq \beta \subsetneq \alpha} \tilde{r}_{\alpha \backslash \beta} \mathbb{E}_{Q}\left[\tilde{X}^{\beta}\right] \\
& =\mathbb{E}_{P}\left[\tilde{X}^{\alpha}\right]-\mathbb{E}_{Q}\left[\tilde{X}^{\alpha}\right]-\sum_{\varnothing \subsetneq \beta \subsetneq \alpha} r_{\alpha \backslash \beta} \mathbb{E}_{Q}\left[\tilde{X}^{\beta}\right] .
\end{aligned}
$$

We consider the third term, call it $*$. Writing $y^{\eta}$ to indicate $\prod_{i j \in \eta} y_{i j}$, first notice that

$$
\mathbb{E}_{Q}\left[\tilde{X}^{\beta}\right]=\mathbb{E}_{Q}\left[\prod_{i j \in \beta}\left(X_{i j}+y_{i j}\right)\right]=\mathbb{E}_{Q}\left[X^{\beta}\right]+\sum_{\varnothing \subsetneq \eta \subseteq \beta} y^{\eta} \mathbb{E}_{Q}\left[X^{\beta \backslash \eta}\right]
$$

hence,

$$
*=\sum_{\varnothing \subsetneq \beta \subsetneq \alpha} r_{\alpha \backslash \beta} \mathbb{E}_{Q}\left[X^{\beta}\right]+\sum_{\varnothing \subsetneq \beta \subsetneq \alpha} r_{\alpha \backslash \beta} \sum_{\varnothing \subsetneq \eta \subseteq \beta} y^{\eta} \mathbb{E}_{Q}\left[X^{\beta \backslash \eta}\right] .
$$

If we let $\beta^{\prime}=\beta \backslash \eta$, instead of summing over $0 \subsetneq \beta \subsetneq \alpha$ and then $\varnothing \subsetneq \eta \subseteq \beta$, we may sum over $\varnothing \subsetneq \eta \subsetneq \alpha$ then $\varnothing \subseteq \beta^{\prime} \subsetneq \alpha \backslash \eta$. Thus, noting also that $\alpha \backslash \beta=(\alpha \backslash \eta) \backslash \beta^{\prime}$,

$$
*=\sum_{\varnothing \subsetneq \beta \subsetneq \alpha} r_{\alpha \backslash \beta} \mathbb{E}_{Q}\left[X^{\beta}\right]+\sum_{\varnothing \subsetneq \eta \subseteq \alpha} y^{\eta} \sum_{\varnothing \subseteq \beta^{\prime} \subsetneq \alpha \backslash \eta} r_{(\alpha \backslash \eta) \backslash \beta^{\prime}} \mathbb{E}_{Q}\left[X^{\beta^{\prime}}\right] .
$$

But, by the definition of $r_{\alpha \backslash \eta}$,

$$
\begin{aligned}
\sum_{\varnothing \subseteq \beta^{\prime} \subsetneq \alpha \backslash \eta} r_{(\alpha \backslash \eta) \backslash \beta^{\prime}} \mathbb{E}_{Q}\left[X^{\beta^{\prime}}\right] & =r_{\alpha \backslash \eta}+\sum_{\varnothing \subsetneq \beta^{\prime} \subsetneq \alpha \backslash \eta} r_{(\alpha \backslash \eta) \backslash \beta^{\prime}} \mathbb{E}_{Q}\left[X^{\beta^{\prime}}\right] \\
& =\mathbb{E}_{P}\left[X^{\alpha \backslash \eta}\right]-\mathbb{E}_{Q}\left[X^{\alpha \backslash \eta}\right]
\end{aligned}
$$

which gives the following expression for $*$ where we no longer have the sum over $\beta^{\prime}$ :

$$
*=\sum_{\varnothing \subsetneq \beta \subsetneq \alpha} r_{\alpha \backslash \beta} \mathbb{E}_{Q}\left[X^{\beta}\right]+\sum_{\varnothing \subsetneq \eta \subseteq \alpha} y^{\eta}\left(\mathbb{E}_{P}\left[X^{\alpha \backslash \eta}\right]-\mathbb{E}_{Q}\left[X^{\alpha \backslash \eta}\right]\right) .
$$

Substituting this expression for $*$ into our original expression for $\widetilde{r}_{\alpha}$ we have

$$
\tilde{r}_{\alpha}=\mathbb{E}_{P}\left[\tilde{X}^{\alpha}\right]-\mathbb{E}_{Q}\left[\tilde{X}^{\alpha}\right]-\sum_{\varnothing \subsetneq \beta \subsetneq \alpha} r_{\alpha \backslash \beta} \mathbb{E}_{Q}\left[X^{\beta}\right]-\sum_{\varnothing \subsetneq \eta \subseteq \alpha} y^{\eta}\left(\mathbb{E}_{P}\left[X^{\alpha \backslash \eta}\right]-\mathbb{E}_{Q}\left[X^{\alpha \backslash \eta}\right]\right) .
$$

However, this last term is precisely what we need to cancel with the difference between $\mathbb{E}_{P}\left[\tilde{X}^{\alpha}\right]$ and $\mathbb{E}_{P}\left[X^{\alpha}\right]$ and the difference between $\mathbb{E}_{Q}\left[\tilde{X}^{\alpha}\right]$ and $\mathbb{E}_{Q}\left[X^{\alpha}\right]$. Therefore,

$$
\tilde{r}_{\alpha}=\mathbb{E}_{P}\left[X^{\alpha}\right]-\mathbb{E}_{Q}\left[X^{\alpha}\right]-\sum_{\varnothing \subsetneq \beta \subsetneq \alpha} r_{\alpha \backslash \beta} \mathbb{E}_{Q}\left[X^{\beta}\right]=r_{\alpha},
$$

and we have proven the inductive step.

### 5.5 Calculations for signed triangle counts

In this section we analyse the degree 3 signed triangle count test statistic $\widehat{R}$, defined in (10), and show bounds on the expectation and variance of $\widehat{R}$, which will prove it strongly separates $\mathbb{P}$ and $\mathbb{Q}$ in the easy regime. Recall,

$$
\widehat{R}=\sum_{i<j<k} R_{i j} R_{i k} R_{j k} \quad \text { where } R_{i j}=Y_{i j}-q
$$

- Lemma 5.1. Given parameters $n, k, q, s, M$ and $x \in \mathbb{R}^{M}$ with $\sum_{\ell \in[M]} x_{\ell}=1$, we let $\mathbb{P}=\mathbb{P}_{\text {Binary }}(n, k, q, s, M, x)$. Assume that $M \min _{\ell} x_{\ell} \geqslant C$. Then,

$$
\begin{aligned}
\mathbb{E}_{\mathbb{P}}[\hat{R}] & =\frac{1}{3} M s^{3} k^{3}\left(1+O\left(n^{-1}\right)\right), \\
\begin{aligned}
\operatorname{Var}
\end{aligned} & \\
& =\hat{R}] \leqslant \frac{1}{C} M^{2} k^{5} s^{6}+M k^{4} s^{4} q+\frac{1}{C} M^{2} k^{4} s^{5}+\frac{1}{3} n^{3} q^{3}+n k^{2} s q^{2} \\
& +k^{3} q^{2} s+k^{3} q s^{2}+\frac{1}{3} M k^{3} s^{3}
\end{aligned}
$$

Proof. Recall that in our model, the binary random variable $Y_{i j}$ takes value 1 with probability $q+s / x_{c}$ if $\sigma_{i}=\sigma_{j}=c$ for some $c \in[M]$ and takes value 1 with probability $q$ otherwise. Thus, we may calculate the expected values of $R_{i j}$ conditioned on the community assignments of $i$ and $j$ :

$$
\mathbb{E}_{\mathbb{P}}\left[R_{i j} \mid \sigma_{i}=c_{i}, \sigma_{j}=c_{j}\right]= \begin{cases}\frac{s}{x_{c}} & \text { if } c_{i}=c_{j}=c \text { for some } c \in[M]  \tag{14}\\ 0 & \text { otherwise }\end{cases}
$$

We now split the proof into expectation and variance calculations. All probabilities, expectations and variances will be with respect to $\mathbb{P}$, but we drop the subscript.

Expectation. Let

$$
N^{\operatorname{tri}}=\{\{i j, i k, j k\}: i, j, k \in[n], i<j<k\}
$$

and then we may express the signed triangle count $\widehat{R}$ by $\hat{R}=\sum_{S \in N^{\text {tri }}} R_{S}$. Fix a set of edges in $N^{\text {tri }}$, w.l.o.g. $S=\{12,13,23\}$. Then, writing $[M]_{\star}$ for the set $\{\star, 1, \ldots, M\}$ (recall $\star$ denotes no community membership),

$$
\begin{aligned}
\mathbb{E}\left[R_{S}\right] & =\sum_{c_{1}, c_{2}, c_{3} \in[M]_{\star}} \mathbb{E}\left[R_{12} R_{13} R_{23} \mid \sigma_{1}=c_{1}, \ldots, \sigma_{3}=c_{3}\right] P\left(\sigma_{1}=c_{1}, \ldots, \sigma_{3}=c_{3}\right) \\
& =\sum_{c_{1}, c_{2}, c_{3} \in[M]_{\star}} \prod_{i j \in\{12,13,23\}} \mathbb{E}\left[R_{i j} \mid \sigma_{1}=c_{1}, \ldots, \sigma_{3}=c_{3}\right] \prod_{i=1}^{3} P\left(\sigma_{i}=c_{i}\right)
\end{aligned}
$$

as the expected values of $R_{i j}$ and $R_{i k}$ are independent conditional on the community assignments of $i, j, k$. Note by (14), $\mathbb{E}\left[R_{i j} \mid \sigma_{i}=c_{i}, \sigma_{j}=c_{j}\right]$ is equal to zero unless $c_{i}=c_{j}=c$ for some $c \in[M]$. Therefore the only non-zero terms in the sum above are those for which $c_{1}=c_{2}=c_{3}=c$ for some $c \in[M]$. Let $C_{c}$ be the event that $\sigma_{1}=\sigma_{2}=\sigma_{3}=c$, then

$$
\mathbb{E}\left[R_{S}\right]=\sum_{c=1}^{M} \prod_{i j \in S} \mathbb{E}\left[R_{i j} \mid C_{c}\right] \prod_{i=1}^{3} P\left(\sigma_{i}=c\right)=\sum_{c=1}^{M} \frac{s^{3}}{x_{c}^{3}}\left(\frac{k x_{c}}{n}\right)^{3}=M k^{3} s^{3} n^{-3} .
$$

Because $\left|N^{\text {tri }}\right|=\binom{n}{3}=\frac{1}{3} n^{3}\left(1+O\left(\frac{1}{n}\right)\right)$, the expectation of $\widehat{R}$ is as claimed.
Variance. Recall $\widehat{R}=\sum_{S \in N^{\text {tri }}} R_{S}$ and so the variance is

$$
\operatorname{Var}[\hat{R}]=\sum_{S, T \in N^{\mathrm{tri}}} \mathbb{E}\left[R_{S} R_{T}\right]-\mathbb{E}\left[R_{S}\right] \mathbb{E}\left[R_{T}\right]
$$

Note that if $V(S) \cap V(T)=\varnothing$, i.e. the sets of pairs have no vertices in common, then $R_{S}$ and $R_{T}$ are independent and these terms cancel in the expression above. Hence we need only sum over $S, T$ with one overlapping vertex, with two overlapping vertices or equivalently one overlapping edge and lastly with all three vertices overlapping or equivalently $S=T$. Thus

$$
\begin{equation*}
\operatorname{Var}[\hat{R}] \leqslant \sum_{\substack{S, T \in N^{\mathrm{tri}} \\|V(S) \cap V(T)|=1}} \mathbb{E}\left[R_{S} R_{T}\right]+\sum_{\substack{S, T \in N^{\operatorname{tri}} \\|S \cap T|=1}} \mathbb{E}\left[R_{S} R_{T}\right]+\sum_{S \in N^{\mathrm{tri}}} \mathbb{E}\left[R_{S}^{2}\right] \tag{15}
\end{equation*}
$$

The terms above correspond to the sets of pairs overlapping as $\bullet \bullet \bullet \bullet$ and $\bullet$ respectively where the gray edges denote pairs in $S$ and the pink edges denote pairs in $T$.

We begin by bounding the first term in (15), i.e. that corresponding to $\therefore \cdot{ }^{\circ}$. Fix some pair of sets which overlap on one vertex, w.l.o.g. $S_{1}=\{12,13,23\}$ and $T_{1}=\{14,15,45\}$. Then, similarly to the expectation, again writing $[M]_{\star}$ for the set $\{\star, 1, \ldots, M\}$,

$$
\mathbb{E}\left[R_{S_{1}} R_{T_{1}}\right]=\sum_{c_{1}, \ldots, c_{5} \in[M]_{\star}} \prod_{i j \in S_{1} \cup T_{1}} \mathbb{E}\left[R_{i j} \mid \sigma_{1}=c_{1}, \ldots \sigma_{5}=c_{5}\right] \prod_{i=1}^{5} P\left(\sigma_{i}=c_{i}\right)
$$

as the expected values of $R_{i j}$ and $R_{i k}$ are independent conditional on the community assignments of $i, j, k$. Note that $\mathbb{E}\left[R_{i j} \mid \sigma_{i}=c_{i}, \sigma_{j}=c_{j}\right]$ is equal to zero unless $c_{i}=c_{j}=c$ for some $c \in[M]$. Therefore the only non-zero terms in the sum above are those for which $c_{1}=\ldots=c_{5}=c$ for some $c \in[M]$. Let $C_{c}$ be the event that $\sigma_{1}=\ldots=\sigma_{5}=c$, then

$$
\mathbb{E}\left[R_{S_{1}} R_{T_{1}}\right]=\sum_{c=1}^{M} \prod_{i j \in S_{1} \cup T_{1}} \mathbb{E}\left[R_{i j} \mid C_{c}\right] \prod_{i=1}^{5} P\left(\sigma_{i}=c\right)=\sum_{c=1}^{M} \frac{s^{6}}{x_{c}^{6}}\left(\frac{k x_{c}}{n}\right)^{5}=k^{5} s^{6} n^{-5} \sum_{c=1}^{M} \frac{1}{x_{c}} .
$$

Since there are at most $n^{5}$ ways we may pick $S, T \in N^{\text {tri }}$ with $|V(S) \cap V(T)|=1$, we may conclude that the first term of (15) is at most $k^{5} s^{6} \sum_{c=1}^{M} \frac{1}{x_{c}}$.

We next bound the second term in (15), i.e. that corresponding to $\bullet \bullet$. Similarly to above, fix some pair of sets which overlap on one edge, w.l.o.g. $S_{2}=\{12,13,23\}$ and $T_{2}=\{12,14,24\}$.

$$
\begin{align*}
\mathbb{E}\left[R_{S_{2}} R_{T_{2}}\right] & =\sum_{\underline{c} \in[M]_{\star}^{4}} \mathbb{E}\left[R_{12}^{2} R_{13} R_{23} R_{14} R_{24} \mid \sigma_{1}=c_{1}, \ldots, \sigma_{4}=c_{4}\right] \prod_{i=1}^{4} P\left(\sigma_{i}=c_{i}\right) \\
& =\sum_{\underline{c} \in[M]_{\star}^{4}} \mathbb{E}\left[R_{12}^{2} \mid \underline{\sigma}=\underline{c}\right] \prod_{i j \in\{13,23,14,24\}} \mathbb{E}\left[R_{i j} \mid \underline{\sigma}=\underline{c}\right] \prod_{i=1}^{4} P\left(\sigma_{i}=c_{i}\right) \tag{16}
\end{align*}
$$

since, as before, $R_{i j}$ and $R_{i k}$ are independent when we have conditioned on the community assignments of $i, j, k$. Again, recall $\mathbb{E}\left[R_{i j} \mid \sigma_{i}=c_{i}, \sigma_{j}=c_{j}\right]$ is equal to zero unless $c_{i}=c_{j}=c$ for some $c \in[M]$. Thus for the product over $i j \in\{13,23,14,24\}$ in (16) to be non-zero all vertices must have the same community assignment to some $c \in[M]$. Hence,

$$
\mathbb{E}\left[Y_{S_{2}} Y_{T_{2}}\right]=\sum_{c=1}^{M} \mathbb{E}\left[R_{12}^{2} \mid C_{c}\right] \prod_{i j \in\{13,23,14,24\}} \mathbb{E}\left[R_{i j} \mid C_{c}\right] \prod_{i=1}^{4} P\left(\sigma_{i}=c\right) .
$$

Calculate the conditional expectation of the square.

$$
\mathbb{E}\left[R_{i j}^{2} \mid \sigma_{i}=c_{i}, \sigma_{j}=c_{j}\right]= \begin{cases}q(1-q)+\frac{s}{x_{c}}(1-2 q) & \text { if } c_{i}=c_{j}=c \text { for some } c \in[M]  \tag{17}\\ q(1-q) & \text { otherwise }\end{cases}
$$

and thus,

$$
\begin{aligned}
\mathbb{E}\left[R_{S_{2}} R_{T_{2}}\right] & =\sum_{c=1}^{M}\left(q(1-q)+\frac{s}{x_{c}}(1-2 q)\right)\left(\frac{s}{x_{c}}\right)^{4}\left(\frac{k x_{c}}{n}\right)^{4} \\
& =M\left(\frac{k s}{n}\right)^{4} q(1-q)+\left(\frac{k s}{n}\right)^{4} s(1-2 q) \sum_{c=1}^{M} \frac{1}{x_{c}}
\end{aligned}
$$

Since there are at most $n^{4}$ ways we may pick $S, T \in N^{\text {tri }}$ with $|S \cap T|=1$, we may conclude that the second term of (15) is at most $M k^{4} s^{4} q+k^{4} s^{5} \sum_{c=1}^{M} \frac{1}{x_{c}}$.

Lastly we bound the third (and last) term in (15), i.e. that corresponding to $\bullet^{\bullet}$. Similarly to above, fix a set $S$ (and $T$ which entirely overlaps with it), w.l.o.g. $S_{3}=\{12,13,23\}$. Calculate

$$
\begin{aligned}
\mathbb{E}\left[R_{S_{3}}^{2}\right] & =P\left(D_{0}\right)(q(1-q))^{3}+\sum_{i=1}^{3} \sum_{c=1}^{M} P\left[D_{i, c}\right]\left(q(1-q)+\frac{s}{x_{c}}(1-2 q)\right)^{i}(q(1-q))^{3-i} \\
& \leqslant P\left(D_{0}\right) q^{3}+\sum_{i=1}^{3} \sum_{c=1}^{M} P\left[D_{i, c}\right]\left(q+\frac{s}{x_{c}}\right)^{i} q^{3-i}
\end{aligned}
$$

where $D_{i, c}$ denotes the set of community assignments such that $i$ of $R_{12}, R_{13}, R_{23}$ has distribution $\operatorname{Ber}\left(q+s / x_{c}\right.$ ) (while the others have distribution $\operatorname{Ber}(q)$ ), and $D_{0}$ denotes the set of community assignments where all three have distribution $\operatorname{Ber}(q)$. Observe $D_{1, c}$ is the set of assignments such that two vertices have label $c \in[M]$ and the other vertex has label in $\{\star, 1, \ldots, M\} \backslash\{c\}$ and thus $P\left(D_{1, c}\right) \leqslant 3\left(x_{c} k / n\right)^{2}$. Note $D_{2, c}=\varnothing$. Lastly $P\left(D_{3, c}\right)=\sum_{c \in M}\left(x_{c} k / n\right)^{3}$ as $D_{3, c}$ is the community assignment where each of the three vertices has label $c$. Then $P\left(D_{0}\right)=1-\sum_{c} P\left(D_{1, c}\right)-\sum_{c} P\left(D_{3, c}\right)$. Substituting these bounds for $D_{0}$ and $D_{i, c}$ for $i=1,2,3$ and writing $\rho_{c}=k x_{c} / n$ we get

$$
\begin{aligned}
\mathbb{E}\left[R_{S_{3}}^{2}\right] & \leqslant q^{3}\left(1-3 \rho_{c}^{2}-\rho_{c}^{3}\right)+3 \sum_{c=1}^{M} \rho_{c}^{2}\left(q+\frac{s}{x_{c}}\right) q^{2}+\sum_{c=1}^{M} \rho_{c}^{3}\left(q+\frac{s}{x_{c}}\right)^{3} \\
& =q^{3}+3 n^{-2} k^{2} s q^{2}+n^{-3} k^{3}\left(3 q^{2} s \sum_{c=1}^{M} x_{c}^{2}+3 q s^{2}+M s^{3}\right)
\end{aligned}
$$

Since there are $\binom{n}{3}$ ways to pick $S \in N^{\text {tri }}$ the third term of (15) is at most $\frac{1}{3} n^{3} E\left[R_{S_{3}}^{2}\right]$,

$$
\frac{1}{3} n^{3} E\left[R_{S_{3}}^{2}\right] \leqslant \frac{1}{3} n^{3} q^{3}+n k^{2} s q^{2}+k^{3} q^{2} s+k^{3} q s^{2}+\frac{1}{3} M k^{3} s^{3}
$$

where we substituted $\sum_{c \in M} x_{c}^{2}, \sum_{c \in M} x_{c}^{3} \leqslant 1$. To finish, recall we assumed $M \min _{c} x_{c}>C$ for some constant $C$, and note this implies $\max _{c} 1 / x_{c}<M / C$ and thus $\sum_{c} 1 / x_{c}^{2}<M^{2} / C$. Apply this to the bounds from the first and second terms of (15) and we are done.

## References

1 Emmanuel Abbe. Community detection and stochastic block models: recent developments. The Journal of Machine Learning Research, 18(1):6446-6531, 2017.
2 Ery Arias-Castro and Nicolas Verzelen. Community detection in random networks. arXiv preprint, 2013. arXiv:1302.7099.
3 Afonso S Bandeira, Ahmed El Alaoui, Samuel B Hopkins, Tselil Schramm, Alexander S Wein, and Ilias Zadik. The Franz-Parisi criterion and computational trade-offs in high dimensional statistics. arXiv preprint, 2022. arXiv:2205.09727.
4 Jess Banks, Sidhanth Mohanty, and Prasad Raghavendra. Local statistics, semidefinite programming, and community detection. In Proceedings of the 2021 ACM-SIAM Symposium on Discrete Algorithms (SODA), pages 1298-1316. SIAM, 2021.
5 Boaz Barak, Samuel Hopkins, Jonathan Kelner, Pravesh K Kothari, Ankur Moitra, and Aaron Potechin. A nearly tight sum-of-squares lower bound for the planted clique problem. SIAM Journal on Computing, 48(2):687-735, 2019.
6 Quentin Berthet and Philippe Rigollet. Complexity theoretic lower bounds for sparse principal component detection. In Conference on learning theory, pages 1046-1066. PMLR, 2013.
7 Matthew Brennan, Guy Bresler, and Wasim Huleihel. Reducibility and computational lower bounds for problems with planted sparse structure. In Conference On Learning Theory, pages 48-166. PMLR, 2018.
8 Yudong Chen and Jiaming Xu. Statistical-computational tradeoffs in planted problems and submatrix localization with a growing number of clusters and submatrices. The Journal of Machine Learning Research, 17(1):882-938, 2016.
9 Aurelien Decelle, Florent Krzakala, Cristopher Moore, and Lenka Zdeborová. Asymptotic analysis of the stochastic block model for modular networks and its algorithmic applications. Physical Review E, 84(6):066106, 2011.
10 Ilias Diakonikolas, Daniel M Kane, and Alistair Stewart. Statistical query lower bounds for robust estimation of high-dimensional gaussians and gaussian mixtures. In 58th Annual Symposium on Foundations of Computer Science (FOCS), pages 73-84. IEEE, 2017.
11 Vitaly Feldman, Elena Grigorescu, Lev Reyzin, Santosh S Vempala, and Ying Xiao. Statistical algorithms and a lower bound for detecting planted cliques. Journal of the ACM (JACM), 64(2):1-37, 2017.
12 Bruce Hajek, Yihong Wu, and Jiaming Xu. Computational lower bounds for community detection on random graphs. In Conference on Learning Theory, pages 899-928. PMLR, 2015.
13 Samuel Hopkins. Statistical Inference and the Sum of Squares Method. PhD thesis, Cornell University, 2018.

14 Samuel B Hopkins, Pravesh K Kothari, Aaron Potechin, Prasad Raghavendra, Tselil Schramm, and David Steurer. The power of sum-of-squares for detecting hidden structures. In $58 t h$ Annual Symposium on Foundations of Computer Science (FOCS), pages 720-731. IEEE, 2017.
15 Samuel B Hopkins and David Steurer. Efficient bayesian estimation from few samples: community detection and related problems. In 58th Annual Symposium on Foundations of Computer Science (FOCS), pages 379-390. IEEE, 2017.
16 Pravesh K Kothari, Ryuhei Mori, Ryan O'Donnell, and David Witmer. Sum of squares lower bounds for refuting any CSP. In Proceedings of the 49th Annual ACM SIGACT Symposium on Theory of Computing, pages 132-145, 2017.
17 Dmitriy Kunisky, Alexander S Wein, and Afonso S Bandeira. Notes on computational hardness of hypothesis testing: Predictions using the low-degree likelihood ratio. In ISAAC Congress (International Society for Analysis, its Applications and Computation), pages 1-50. Springer, 2022.

18 Cristopher Moore. The computer science and physics of community detection: Landscapes, phase transitions, and hardness. Bulletin of EATCS, 1(121), 2017.
19 Tselil Schramm and Alexander S Wein. Computational barriers to estimation from low-degree polynomials. The Annals of Statistics, 50(3):1833-1858, 2022.

