



Geometry of Reachability Sets of Vector Addition Systems

Roland Guttenberg  

Technical University of Munich, Germany

Mikhail Raskin  

LaBRI, University of Bordeaux, France

Javier Esparza  

Technical University of Munich, Germany

Abstract

Vector Addition Systems (VAS), aka Petri nets, are a popular model of concurrency. The reachability set of a VAS is the set of configurations reachable from the initial configuration. Leroux has studied the geometric properties of VAS reachability sets, and used them to derive decision procedures for important analysis problems. In this paper we continue the geometric study of reachability sets. We show that every reachability set admits a finite decomposition into disjoint almost hybridlinear sets enjoying nice geometric properties. Further, we prove that the decomposition of the reachability set of a given VAS is effectively computable. As a corollary, we derive a new proof of Hauschildt’s 1990 result showing the decidability of the question whether the reachability set of a given VAS is semilinear. As a second corollary, we prove that the complement of a reachability set, if it is infinite, always contains an infinite linear set.

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1 Introduction

Vector Addition Systems (VAS), also known as Petri nets, are a popular model of concurrent systems. The VAS reachability problem consists of deciding if a target configuration of a VAS is reachable from some initial configuration. It was proved decidable in the 1980s [8, 17], but its complexity (Ackermann-complete) could only be determined recently [2, 3, 14].

The *reachability set* of a VAS is the set of all configurations reachable from the initial configuration. Configurations are tuples of natural numbers, and so the reachability set of a VAS is a subset of \mathbb{N}^n for some n called the *dimension* of the VAS. Results on the geometric properties of reachability sets have led to new algorithms in the past. For example, in [12] it was shown that every configuration outside the reachability set \mathbf{R} of a VAS is separated from \mathbf{R} by a semilinear inductive invariant. This immediately leads to an algorithm for the reachability problem consisting of two semi-algorithms, one enumerating all possible paths to certify reachability, and one enumerating all semilinear sets and checking if they are separating inductive invariants. Another example is [13], where it was shown that semilinear reachability sets are flatable. The result led to an algorithm for deciding whether a semilinear set is included in or equal to the reachability set of a given VAS.



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The separability and flatability results of [12, 13] are proven not only for VAS reachability sets, but for arbitrary semilinear *Petri sets*, a larger class with a geometric definition introduced in [12]. So, in particular, [13] is an investigation into the geometric structure of semilinear Petri sets. In this paper we study the structure of the *non-semilinear* Petri sets. We introduce hybridization, or, equivalently, the class of *almost hybridlinear* sets, a generalization of the hybridlinear sets introduced by Ginsburg and Spanier [4] and further studied by Chistikov and Haase [1]. We prove the following decomposition:

► **Theorem 1.1.** *Let \mathbf{X} be a Petri set. For every semilinear set \mathbf{S} there exists a partition $\mathbf{S} = \mathbf{S}_1 \cup \dots \cup \mathbf{S}_k$ into pairwise disjoint full linear sets such that for all $i \in \{1, \dots, k\}$ either $\mathbf{X} \cap \mathbf{S}_i = \emptyset$, $\mathbf{S}_i \subseteq \mathbf{X}$ or $\mathbf{X} \cap \mathbf{S}_i$ is irreducible with hybridization \mathbf{S}_i . Further, if \mathbf{X} is the reachability set of a VAS, then the partition is computable.*

Defining hybridization and irreducibility is beyond the scope of this introduction; in fact, they will be introduced in Section 4 and 5 of this paper. However, we can already explain two properties of the irreducible sets with a hybridization which, combined with Theorem 1.1, have important consequences.

Firstly, irreducible sets with hybridization are always non-semilinear. This leads to a simple algorithm for deciding whether the reachability set $\mathbf{X} \subseteq \mathbb{N}^d$ of a given VAS of dimension d is semilinear. Let $\mathbf{S} := \mathbb{N}^d$ and compute the partition $\mathbf{S}_1 \cup \dots \cup \mathbf{S}_k$ of Theorem 1.1. For every $1 \leq i \leq k$, check whether $\mathbf{X} \cap \mathbf{S}_i = \emptyset$ or $\mathbf{S}_i \subseteq \mathbf{X}$ hold¹. If this is the case for all i , then let J be the set of indices i , where $\mathbf{S}_i \subseteq \mathbf{X}$ holds. We have $\bigcup_{i \in J} \mathbf{S}_i = \mathbf{X} \cap \mathbf{S} = \mathbf{X}$, and so, since $\mathbf{S}_1, \dots, \mathbf{S}_k$ are linear, \mathbf{X} is semilinear. Otherwise, by Theorem 1.1 there exists an i such that $\mathbf{X} \cap \mathbf{S}_i$ is irreducible with hybridization \mathbf{S}_i , and hence non-semilinear. Since semilinear sets are closed under intersection, \mathbf{X} is not semilinear. The decidability of the semilinearity of VAS reachability sets was first proved by Hauschildt [6], and in fact we arrive at essentially the same algorithm. However, we provide a simpler correctness proof and a clear geometric intuition. Further, our theorem holds for arbitrary Petri sets, a larger class than VAS reachability sets.

Secondly, if a set \mathbf{X} is irreducible with hybridization \mathbf{S} , then there are infinitely many points in the boundary $\partial\mathbf{S}$ of \mathbf{S} that do not belong to \mathbf{X} , i.e., $|\partial\mathbf{S} \setminus \mathbf{X}| = \infty$. This allows to prove that if $\mathbf{S} \setminus \mathbf{X}$ is infinite, then $\mathbf{S} \setminus \mathbf{X}$ contains an infinite linear set, which was left as a conjecture in [7]. Namely the proof is now a simple induction on the dimension of the semilinear set \mathbf{S} : If $\mathbf{S} \setminus \mathbf{X}$ is infinite, then some $\mathbf{S}_i \setminus \mathbf{X}$ is infinite. If for this i , we have $\mathbf{X} \cap \mathbf{S}_i = \emptyset$ or $\mathbf{S}_i \subseteq \mathbf{X}$, then $\mathbf{S}_i \setminus \mathbf{X}$ is semilinear and hence contains an infinite line. Otherwise we have that $|\partial\mathbf{S}_i \setminus \mathbf{X}| = \infty$, and hence by induction $\partial\mathbf{S}_i \setminus \mathbf{X}$ contains an infinite line. This corollary is a first step towards understanding the complements of VAS reachability sets, for which little is known.

The sections of the paper follow the structure of the main theorem. Section 2 contains preliminaries. Section 3 introduces smooth sets, preparing for the introduction of hybridization and Petri sets in Section 4. Section 5 introduces irreducibility and proves Theorem 1.1. Section 6 proves the corollaries of Theorem 1.1.

2 Preliminaries

We let $\mathbb{N}, \mathbb{Z}, \mathbb{Q}, \mathbb{Q}_{\geq 0}$ denote the natural, integer, and (non-negative) rational numbers.

¹ It is well known that the first question can be reduced to the VAS reachability problem, and the second is decidable by the flatability results mentioned before.

Furthermore, we use uppercase letters except A for sets, with A being used for matrices. We use boldface for vectors and sets of vectors. We denote the cardinality of a set \mathbf{X} as $|\mathbf{X}|$.

Given sets $\mathbf{X}, \mathbf{Y} \subseteq \mathbb{Q}^n, Z \subseteq \mathbb{Q}$, we write $\mathbf{X} + \mathbf{Y} := \{\mathbf{x} + \mathbf{y} \mid \mathbf{x} \in \mathbf{X}, \mathbf{y} \in \mathbf{Y}\}$ and $Z \cdot \mathbf{X} := \{\lambda \cdot \mathbf{x} \mid \lambda \in Z, \mathbf{x} \in \mathbf{X}\}$. By identifying elements $\mathbf{x} \in \mathbb{Q}^n$ with $\{\mathbf{x}\}$, we define $\mathbf{x} + \mathbf{X} := \{\mathbf{x}\} + \mathbf{X}$, and similarly $\lambda \cdot \mathbf{X} := \{\lambda\} \cdot \mathbf{X}$ for $\lambda \in \mathbb{Q}$. We denote by \mathbf{X}^C the complement of \mathbf{X} . On \mathbb{Q}^n , we consider the usual Euclidean norm and its generated topology. We denote the closure of a set \mathbf{X} in this topology by $\overline{\mathbf{X}}$.

A *vector space* $\mathbf{V} \subseteq \mathbb{Q}^n$ is a set such that $\mathbf{0} \in \mathbf{V}$, $\mathbf{V} + \mathbf{V} \subseteq \mathbf{V}$ and $\mathbb{Q} \cdot \mathbf{V} \subseteq \mathbf{V}$. Given a set $\mathbf{F} \subseteq \mathbb{Q}^n$, the vector space generated by \mathbf{F} is the smallest vector space containing \mathbf{F} . Every vector space \mathbf{V} is *finitely generated* (f.g.), i.e. there exists a finite set $\mathbf{F} \subseteq \mathbb{Q}^n$ generating \mathbf{V} . Furthermore, it can also be expressed as $\{\mathbf{x} \in \mathbb{Q}^n \mid A\mathbf{x} = \mathbf{0}\}$ for some integer matrix A .

2.1 Cones, lattices, and periodic sets

A set $\mathbf{C} \subseteq \mathbb{Q}^n$ is a *cone* if $\mathbf{0} \in \mathbf{C}$, $\mathbf{C} + \mathbf{C} \subseteq \mathbf{C}$ and $\mathbb{Q}_{>0}\mathbf{C} \subseteq \mathbf{C}$. Given a set $\mathbf{F} \subseteq \mathbb{Q}^n$, the cone generated by \mathbf{F} is the smallest cone containing \mathbf{F} . If \mathbf{C} is a cone, then $\mathbf{C} - \mathbf{C}$ is the vector space generated by \mathbf{C} . Not every cone is finitely generated (f.g.). Instead, we have:

► **Lemma 2.1** ([19, Corollary 7.1a]). *Let $\mathbf{C} \subseteq \mathbb{Q}^n$ be a cone. Then \mathbf{C} is finitely generated if and only if $\mathbf{C} = \{\mathbf{x} \in \mathbf{C} - \mathbf{C} \mid A\mathbf{x} \geq \mathbf{0}\}$ for some integer matrix A .*

In particular, finitely generated cones are closed. The *interior* of a finitely generated cone \mathbf{C} is the set $\text{int}(\mathbf{C}) = \{\mathbf{x} \in \mathbf{C} - \mathbf{C} \mid A\mathbf{x} > \mathbf{0}\}$, where A is a matrix as above. The boundary of the cone is $\partial(\mathbf{C}) := \overline{\mathbf{C}} \setminus \text{int}(\mathbf{C})$. It is well known that the boundary of a cone is a finite union of lower dimensional cones, called *facets* [19]. In fact, there is a defining matrix A such that the facets are exactly the sets of solutions obtained by changing one of the inequalities of $A\mathbf{x} \geq \mathbf{0}$ into an equality. For example, the left part of Figure 1 shows the cone $\{(x, y) \mid x - y \geq y, y \geq 0\}$. Its facets are the sets $\{(x, y) \mid x - y = 0, y \geq 0\}$ and $\{(x, y) \mid x \geq y, y = 0\}$ (shown as black lines in the picture), and their union is the boundary of the cone.

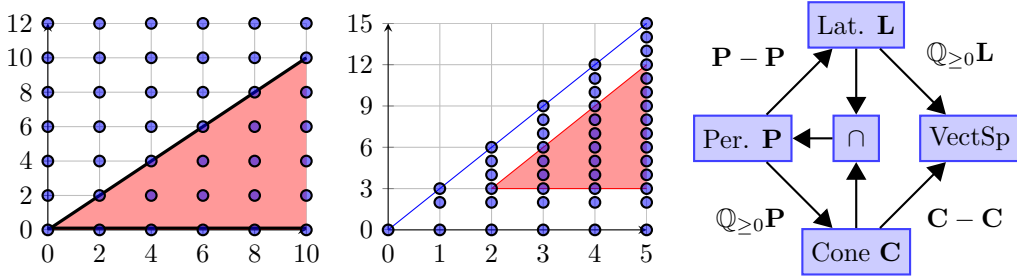
A cone \mathbf{C} is *definable* if it is definable in $\text{FO}(\mathbb{Q}, +, \geq)$. A cone \mathbf{C} is definable iff $\mathbf{C} \setminus \{\mathbf{0}\} = \{\mathbf{x} \in \mathbf{C} - \mathbf{C} \mid A_1\mathbf{x} > \mathbf{0}, A_2\mathbf{x} \geq \mathbf{0}\}$ for some integer matrices A_1, A_2 . In this case the closure $\overline{\mathbf{C}}$ is finitely generated. Intuitively, changing an equation from ≥ 0 to > 0 removes a facet. Removing all facets yields $\text{int}(\mathbf{C})$.

A set $\mathbf{L} \subseteq \mathbb{Z}^n$ is a *lattice* if $\mathbf{L} + \mathbf{L} \subseteq \mathbf{L}$, $-\mathbf{L} \subseteq \mathbf{L}$ and $\mathbf{0} \in \mathbf{L}$. For any finite set $\mathbf{F} = \{\mathbf{x}_1, \dots, \mathbf{x}_s\} \subseteq \mathbb{N}^n$, the lattice generated by \mathbf{F} is $\mathbb{Z}\mathbf{x}_1 + \dots + \mathbb{Z}\mathbf{x}_s$. Every lattice is finitely generated, and even has a generating set linearly independent over \mathbb{Q} .

A set $\mathbf{P} \subseteq \mathbb{N}^n$ is a *periodic set* if $\mathbf{P} + \mathbf{P} \subseteq \mathbf{P}$ and $\mathbf{0} \in \mathbf{P}$. For any set $\mathbf{F} \subseteq \mathbb{N}^n$, the periodic set \mathbf{F}^* generated by \mathbf{F} is the smallest periodic set containing \mathbf{F} . We have $\mathbf{F}^* = \{\mathbf{p}_1 + \dots + \mathbf{p}_r \mid r \in \mathbb{N}, \mathbf{p}_i \in \mathbf{F} \text{ for all } i\}$. A periodic set \mathbf{P} is *finitely generated* if $\mathbf{P} = \mathbf{F}^*$ for some finite set \mathbf{F} . Finitely generated periodic sets are characterized as follows:

► **Lemma 2.2** ([13, Lemma V.5]). *Let $\mathbf{P} \subseteq \mathbb{N}^n$ be a periodic set. Then \mathbf{P} is finitely generated as a periodic set if and only if $\mathbb{Q}_{\geq 0}\mathbf{P}$ is finitely generated as a cone.*

Any set generates a lattice, a cone and a vector space. In the case of periodic sets these have simple formulas; namely $\mathbf{P} - \mathbf{P}$, as well as $\mathbb{Q}_{\geq 0}\mathbf{P}$ and $\text{VectSp}(\mathbf{P}) := \mathbb{Q}_{\geq 0}(\mathbf{P} - \mathbf{P}) = \mathbb{Q}_{\geq 0}\mathbf{P} - \mathbb{Q}_{\geq 0}\mathbf{P}$ respectively. These are also depicted in the right of Figure 1. On the other hand, if \mathbf{C} is a cone and \mathbf{L} is a lattice, then $\mathbf{C} \cap \mathbf{L}$ is a periodic set. We will consider periodic sets of this form in more depth in Section 2.3.



■ **Figure 1** *Left:* The cone generated by $\{(1, 1), (1, 0)\}$ is shown in red, with its boundary in black. The lattice $(2, 0)\mathbb{Z} + (0, 2)\mathbb{Z}$ is the set of blue dots. Their intersection is the periodic set $\{(2, 0), (2, 2)\}^*$. *Middle:* The periodic set $\mathbf{P} = \{(1, 0), (1, 2), (1, 3)\}^*$ is shown in blue. Intuitively, the set $\{(1, 1), (2, 1), (3, 1), \dots\}$ is a “hole” of \mathbf{P} . Inside \mathbf{P} we find the red area $(2, 3) + \mathbf{P}$, whose blue points do not intersect the hole, i.e., $(2, 3) + \text{Fill}(\mathbf{P}) \subseteq \mathbf{P}$. *Right:* Graph comparing the classes of sets defined in Section 2.

2.2 Dimension

The *dimension* of a vector space defined as its number of generators is a well-known concept. It can be extended to arbitrary subsets of \mathbb{Q}^n as follows.

► **Definition 2.3** ([11, 12]). *Let $\mathbf{X} \subseteq \mathbb{Q}^n$. The dimension of \mathbf{X} , denoted $\text{dim}(\mathbf{X})$, is the smallest natural number k such that there exist finitely many vector spaces $\mathbf{V}_i \subseteq \mathbb{Q}^n$ with $\text{dim}(\mathbf{V}_i) \leq k$ and vectors $\mathbf{b}_i \in \mathbb{Q}^n$ such that $\mathbf{X} \subseteq \bigcup_{i=1}^r \mathbf{b}_i + \mathbf{V}_i$.*

This dimension function has the following properties.

► **Lemma 2.4.** *Let $\mathbf{X}, \mathbf{X}' \subseteq \mathbb{Q}^n, \mathbf{b} \in \mathbb{Q}^n$. Then $\text{dim}(\mathbf{X}) = \text{dim}(\mathbf{b} + \mathbf{X})$ and $\text{dim}(\mathbf{X} \cup \mathbf{X}') = \max\{\text{dim}(\mathbf{X}), \text{dim}(\mathbf{X}')\}$. Further, if $\mathbf{X} \subseteq \mathbf{X}'$, then $\text{dim}(\mathbf{X}) \leq \text{dim}(\mathbf{X}')$.*

► **Lemma 2.5** ([11, Lemma 5.3]). *Let \mathbf{P} be periodic. Then $\text{dim}(\mathbf{P}) = \text{dim}(\text{VectSp}(\mathbf{P}))$.*

Lemma 2.5 for example shows that the lattice and the cone depicted in the left of Figure 1, as well as the periodic set obtained as intersection have dimension 2, because all of them generate the vector space \mathbb{Q}^2 .

2.3 Finitely generated vs. full periodic sets

A set \mathbf{L} is *linear* if $\mathbf{L} = \mathbf{b} + \mathbf{P}$ with $\mathbf{b} \in \mathbb{N}^n$ and $\mathbf{P} \subseteq \mathbb{N}^n$ a finitely generated periodic set. A set \mathbf{S} is *semilinear* if it is a finite union of linear sets. The semilinear sets coincide with the sets definable via formulas $\varphi \in \text{FO}(\mathbb{N}, +, \geq)$, also called Presburger Arithmetic. This is the usual definition of a linear set in theoretical computer science, however, we will work with a slightly smaller class of linear sets, which we call full linear sets. As shown for example in [20], working with this smaller class does not change the class of semilinear sets: A set \mathbf{S} is semilinear if and only if it is a finite union of full linear sets, i.e. linear sets $\mathbf{b} + \mathbf{P}$ where \mathbf{P} is not only finitely generated, but even full, as in the following definition.

► **Definition 2.6.** *A periodic \mathbf{P} is full if $\mathbf{P} = \mathbf{C} \cap \mathbf{L}$, where \mathbf{C} is a f.g. cone and \mathbf{L} a lattice.*

Full linear sets have even been used as the main definition of linear set in the literature before, for example in [18]. Furthermore, while not directly defined, this class was also utilized in [12, 13] as well. For an example of a finitely generated periodic set which is not full, consider the middle of Figure 1.

There is another equivalent definition of full periodic sets, which uses an overapproximation of a periodic set we call $\text{Fill}(\mathbf{P})$. This overapproximation was first introduced in [11] with the terminology $\text{lin}(\mathbf{P})$. However, we avoid this terminology because in [12, 13], the same author used the same notation with a slightly different meaning.

► **Definition 2.7.** *Let \mathbf{P} be a periodic set. The fill of \mathbf{P} is the set $\text{Fill}(\mathbf{P}) := (\mathbf{P} - \mathbf{P}) \cap \overline{\mathbb{Q}_{\geq 0}\mathbf{P}}$.*

Intuitively, we overapproximate \mathbf{P} via the intersection of the obvious lattice and cone. The reason for using the closure of $\mathbb{Q}_{\geq 0}\mathbf{P}$ instead of the cone $\mathbb{Q}_{\geq 0}\mathbf{P}$ itself is Lemma 2.2: If the cone is not closed, then the periodic set, in our case $\text{Fill}(\mathbf{P})$, is not finitely generated. If \mathbf{P} was already finitely generated, the definitions coincide.

► **Lemma 2.8.** *A periodic set \mathbf{P} is full if and only if $\overline{\mathbb{Q}_{\geq 0}\mathbf{P}}$ is a f.g. cone and $\mathbf{P} = \text{Fill}(\mathbf{P})$.*

By Lemma 2.2, full periodic sets are finitely generated: Namely, their cone $\mathbb{Q}_{\geq 0}\mathbf{P}$ equals $\mathbf{C} \cap \mathbb{Q}_{\geq 0}\mathbf{L}$, which as intersection of f.g. cones is finitely generated by Lemma 2.1.

Let us conclude this subsection with the main advantage of full linear over linear sets.

► **Lemma 2.9.** *Let \mathbf{P}, \mathbf{Q} periodic, \mathbf{P} full, $\mathbf{b}, \mathbf{c} \in \mathbb{Q}^n$ such that $\mathbf{c} + \mathbf{Q} \subseteq \mathbf{b} + \mathbf{P}$. Then $\mathbf{Q} \subseteq \mathbf{P}$.*

Proof. Since \mathbf{P} is full, by Lemma 2.8 it is sufficient to prove $\mathbf{Q} \subseteq \mathbf{P} - \mathbf{P}$ and $\mathbf{Q} \subseteq \overline{\mathbb{Q}_{\geq 0}\mathbf{P}}$.

To prove $\mathbf{Q} \subseteq \mathbf{P} - \mathbf{P}$, observe that $\mathbf{Q} = (\mathbf{c} + \mathbf{Q}) - \mathbf{c} \subseteq (\mathbf{b} + \mathbf{P}) - (\mathbf{b} + \mathbf{P}) = \mathbf{P} - \mathbf{P}$.

To prove $\mathbf{Q} \subseteq \overline{\mathbb{Q}_{\geq 0}\mathbf{P}}$, write $\overline{\mathbb{Q}_{\geq 0}\mathbf{P}} = \{\mathbf{x} \in \text{VectSp}(\mathbf{P}) \mid A\mathbf{x} \geq 0\}$ for a matrix A , as in Lemma 2.1. Let A_k be the k -th row of A . It suffices to show $A_k\mathbf{x} \geq 0$ for all $\mathbf{x} \in \mathbf{Q}$. If we had $A_k\mathbf{x} < 0$, then $A_k(\mathbf{c} + \lambda\mathbf{x}) < A_k\mathbf{b}$ for large enough λ , contradicting $\mathbf{c} + \mathbf{Q} \subseteq \mathbf{b} + \mathbf{P}$. ◀

Observe that if we replace full by finitely generated, then the lemma does not hold: Choose \mathbf{P} as the periodic set in the middle of Figure 1, then $(2, 3) + \{(1, 1)\}^* \subseteq \mathbf{P}$, and the property is violated, since $(1, 1) \notin \mathbf{P}$.

Another advantage is that many proofs simplify in the full case. The following such case will be a cornerstone of our main algorithm:

► **Lemma 2.10** ([13, Corollary D.3]). *Let \mathbf{P} be a finitely generated periodic set. For every $\mathbf{x} \in \mathbf{P}$ the set $\mathbf{S} := \mathbf{P} \setminus (\mathbf{x} + \mathbf{P})$ is semilinear and satisfies $\dim(\mathbf{S}) < \dim(\mathbf{P})$.*

To prove this, first show that \mathbf{P} contains $\mathbf{v} + \text{Fill}(\mathbf{P})$, as in the middle of Figure 1, and reduce to the case of full periodic \mathbf{P} . For full \mathbf{P} it is geometrically clear; for example removing the red cone in the middle of Figure 1 from the set, we are left with a finite union of lines.

3 Smooth Periodic Sets

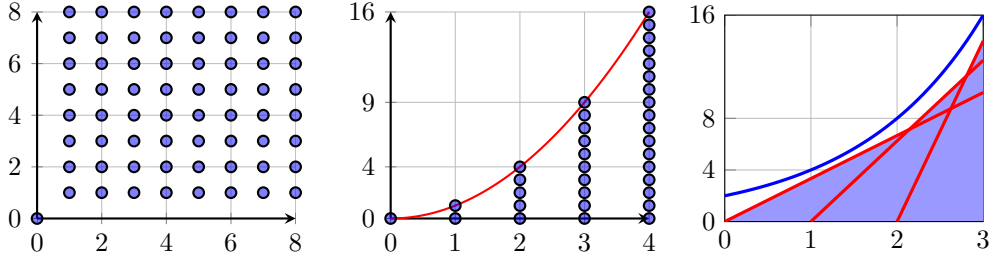
Not all periodic sets we need in the paper are finitely generated, but they are smooth, a class introduced by Leroux in [13]. Intuitively, a smooth set \mathbf{P} is “close” to being finitely generated, in the sense that $\text{Fill}(\mathbf{P})$ is finitely generated. This result (very similar to a result of [11]) is proven in Section 3.1. In the rest of the section we show that smooth sets satisfying a novel condition are closed under intersection and enjoy good properties (Proposition 3.9).

We first reintroduce the set of directions of a periodic set.

► **Definition 3.1** ([13]). *Let \mathbf{P} be a periodic set. A vector $\mathbf{d} \in \mathbb{Q}^n$ is a direction of \mathbf{P} if there exists $m \in \mathbb{N}_{>0}$ and a point \mathbf{x} such that $\mathbf{x} + \mathbb{N} \cdot m\mathbf{d} \subseteq \mathbf{P}$, i.e. some line in direction \mathbf{d} is fully contained in \mathbf{P} . The set of directions of \mathbf{P} is denoted $\text{dir}(\mathbf{P})$.*

We can now define smooth periodic sets.

- **Definition 3.2** ([13]). Let \mathbf{P} be a periodic set.
 - \mathbf{P} is asymptotically definable if $\text{dir}(\mathbf{P})$ is a definable cone, i.e. $\text{dir}(\mathbf{P}) \setminus \{\mathbf{0}\} = \{\mathbf{x} \in \text{VectSp}(\mathbf{P}) \mid A_1\mathbf{x} > 0, A_2\mathbf{x} \geq 0\}$ for some integer matrices A_1, A_2 .
 - \mathbf{P} is well-directed if every sequence $(\mathbf{p}_m)_{m \in \mathbb{N}}$ of vectors $\mathbf{p}_m \in \mathbf{P}$ has an infinite subsequence $(\mathbf{p}_{m_k})_{k \in \mathbb{N}}$ such that $\mathbf{p}_{m_k} - \mathbf{p}_{m_j} \in \text{dir}(\mathbf{P})$ for all $k \geq j$.
 - \mathbf{P} is smooth if it is asymptotically definable and well-directed.



■ **Figure 2** *Left and middle:* The periodic sets $\mathbf{P} = \{(0, 0)\} \cup \mathbb{N}_{>0}^2$ and $\mathbf{P} = \{(x, y) \in \mathbb{N}^2 \mid y \leq x^2\}$ respectively. Neither is finitely generated, but both are smooth with $\text{Fill}(\mathbf{P}) = \mathbb{N}^2$. *Right:* Underapproximation of $\{(x, y) \mid y \leq 2^{x+1}\}$ via a union of three cones. The starting points are respectively $(0, 0)$, $(1, 0)$ and $(2, 0)$.

Figure 2 shows two examples of smooth periodic sets that are not finitely generated.

- **Example 3.3.** Examples of non-smooth sets are $\mathbf{P}_1 = \{(x, y) \mid x \geq \sqrt{2}y\}$ and $\mathbf{P}_2 = ((\{0, 1\} \cup \{(2^m, 1) \mid m \in \mathbb{N}\})^*)^* = \{(x, n) \in \mathbb{N}^2 \mid x \text{ has at most } n \text{ bits set to 1 in the binary representation.}\}$. \mathbf{P}_1 is not asymptotically definable, because defining $\text{dir}(\mathbf{P})$ requires irrationals, while \mathbf{P}_2 is not well-directed (see observation 2 below).

Intuitively, the “boundaries” of a smooth periodic set in two dimensions are either straight lines or function graphs “curving outward”, as in the example on the right of Figure 2.

We make a few observations:

1. The set $\text{dir}(\mathbf{P})$ is a cone. Indeed, if two lines in different directions \mathbf{d} and \mathbf{d}' are contained in \mathbf{P} , then by periodicity \mathbf{P} also contains a \mathbf{d}, \mathbf{d}' plane, and so \mathbf{P} contains a line in every direction between \mathbf{d} and \mathbf{d}' .
2. The most important case of Definition 3.2 is when the \mathbf{p}_m are all on the same infinite line $\mathbf{x} + \mathbf{d} \cdot \mathbb{N}$. Then the definition equivalently states that $\mathbf{d} \in \text{dir}(\mathbf{P})$, i.e. some infinite line in direction \mathbf{d} is contained in \mathbf{P} . This makes sets where points are “too scarce” non-smooth. For instance, the set \mathbf{P}_2 of Example 3.3 contains infinitely many points on a horizontal line, but no full horizontal line, which would correspond to an arithmetic progression.

3.1 Fills of Smooth Sets are Finitely Generated

We show that, while a smooth periodic set \mathbf{P} may not be finitely generated, the set $\text{Fill}(\mathbf{P})$ always is. We start with the following lemma.

- **Lemma 3.4.** Let \mathbf{P} be a periodic set. Then $\text{int}(\overline{\mathbb{Q}_{\geq 0}\mathbf{P}}) \subseteq \mathbb{Q}_{\geq 0}\mathbf{P} \subseteq \text{dir}(\mathbf{P}) \subseteq \overline{\mathbb{Q}_{\geq 0}\mathbf{P}}$. In particular, all these sets have the same closure.

Proof. Let $\mathbf{x} \in \text{int}(\overline{\mathbf{C}})$, where $\mathbf{C} := \mathbb{Q}_{\geq 0}\mathbf{P}$. Then there exists $\varepsilon > 0$ such that the open ball $B(\mathbf{x}, \varepsilon)$ of radius ε around \mathbf{x} is contained in $\overline{\mathbf{C}}$ by definition of interior. Hence for every $\mathbf{y} \in B(\mathbf{x}, \frac{\varepsilon}{2})$, there exists $f(\mathbf{y}) \in B(\mathbf{y}, \frac{\varepsilon}{4}) \cap \mathbf{C}$ by definition of closure. We have surrounded \mathbf{x} by points $f(\mathbf{y}) \in \mathbf{C}$, hence by convexity of \mathbf{C} we have $\mathbf{x} \in \mathbf{C}$.

Let $\mathbf{d} \in \mathbb{Q}_{\geq 0}\mathbf{P}$. Then there exists $m \in \mathbb{N}$ such that $m\mathbf{d} \in \mathbf{P}$, in particular $\mathbb{N} \cdot m\mathbf{d} \subseteq \mathbf{P}$.

Let $\mathbf{d} \in \text{dir}(\mathbf{P})$. Then by replacing \mathbf{d} by a multiple $m\mathbf{d}$, there exists \mathbf{x} such that $\mathbf{x} + \mathbb{N} \cdot \mathbf{d} \subseteq \mathbf{P}$. We define the sequence $(\mathbf{x}_m)_{m \in \mathbb{N}}$ via $\mathbf{x}_m := \frac{1}{m}(\mathbf{x} + m \cdot \mathbf{d}) \in \mathbb{Q}_{\geq 0}\mathbf{P}$, and observe that its limit is \mathbf{d} , i.e. $\mathbf{d} \in \overline{\mathbb{Q}_{\geq 0}\mathbf{P}}$. \blacktriangleleft

► **Example 3.5.** The set on the left of Figure 2 satisfies $\text{int}(\overline{\mathbb{Q}_{\geq 0}\mathbf{P}}) = \mathbb{Q}_{> 0}\mathbf{P} \subsetneq \text{dir}(\mathbf{P}) = \overline{\mathbb{Q}_{\geq 0}\mathbf{P}}$. Indeed, $\text{int}(\overline{\mathbb{Q}_{\geq 0}\mathbf{P}})$ contains every direction except north and east, but they both belong to $\text{dir}(\mathbf{P})$. The middle set satisfies $\text{int}(\overline{\mathbb{Q}_{> 0}\mathbf{P}}) \subsetneq \mathbb{Q}_{> 0}\mathbf{P} = \text{dir}(\mathbf{P}) \subsetneq \overline{\mathbb{Q}_{\geq 0}\mathbf{P}}$, since $\text{int}(\overline{\mathbb{Q}_{\geq 0}\mathbf{P}})$ contains neither north nor east, $\text{dir}(\mathbf{P})$ contains east, and $\overline{\mathbb{Q}_{\geq 0}\mathbf{P}}$ contains both.

We are now ready to reprove the result:

► **Proposition 3.6** ([11, Lemma 5.1]). *Let \mathbf{P} be smooth. Then $\text{Fill}(\mathbf{P})$ is full and hence f.g.*

Proof. Since \mathbf{P} is smooth, $\text{dir}(\mathbf{P})$ is definable by definition. By Lemma 3.4 we have $\overline{\mathbb{Q}_{\geq 0}\mathbf{P}} = \overline{\text{dir}(\mathbf{P})}$. So $\overline{\mathbb{Q}_{\geq 0}\mathbf{P}}$ is the closure of a definable cone, and hence finitely generated by Lemma 2.1. Hence $\mathbf{P} = \text{Fill}(\mathbf{P})$ is the intersection of a f.g. cone and a lattice, and hence full. \blacktriangleleft

3.2 Underapproximating Periodic Sets

In Section 3.1 we have seen that smooth periodic sets can be overapproximated by full linear sets in a natural way. Let us combine this with an underapproximation, mainly to provide a formal basis for the boundary function intuition above.

► **Proposition 3.7** ([13, Lemma F.1]). *Let \mathbf{P} be a periodic set. Let $\mathbf{F} \subseteq \mathbb{Q}^n$ finite.*

$\mathbf{F} \subseteq (\mathbf{P} - \mathbf{P}) \cap \text{dir}(\mathbf{P})$ if and only if there exists \mathbf{x} such that $\mathbf{x} + \mathbf{F}^* \subseteq \mathbf{P}$.

Now consider any finitely generated cone $\mathbf{C} \subseteq \text{dir}(\mathbf{P})$. Then $\mathbf{C} \cap (\mathbf{P} - \mathbf{P})$ is full and hence finitely generated by some set \mathbf{F} . By applying Proposition 3.7, we obtain a vector $\mathbf{x}_{\mathbf{C}} \in \mathbf{P}$ such that $\mathbf{x}_{\mathbf{C}} + (\mathbf{C} \cap (\mathbf{P} - \mathbf{P})) \subseteq \mathbf{P}$. This should be viewed as follows: Interpret the lattice $\mathbf{P} - \mathbf{P}$ as the set of “candidates” for being in \mathbf{P} . Namely, since $\mathbf{x}_{\mathbf{C}} \in \mathbf{P}$, a vector $\mathbf{x}_{\mathbf{C}} + \mathbf{v}$ can only be in \mathbf{P} if $\mathbf{v} \in \mathbf{P} - \mathbf{P}$. Then $\mathbf{x}_{\mathbf{C}} + (\mathbf{C} \cap (\mathbf{P} - \mathbf{P})) \subseteq \mathbf{P}$ shows that every candidate in the given shifted cone (base point non-zero, so strictly speaking not a cone according to our definition) is actually in \mathbf{P} . Repeating this process for larger and larger cones \mathbf{C} , we obtain an underapproximation of \mathbf{P} of the form $\bigcup_{f.g. \mathbf{C}} (\mathbf{x}_{\mathbf{C}} + \mathbf{C}) \cap (\mathbf{P} - \mathbf{P})$. The union of wider and wider shifted cones intuitively has a convex function as upper and a concave function as lower bound, as shown in the right of Figure 2.

Observe that this lower bound did not use smoothness, in general this might hence be a strict underapproximation, as shown in the right of Figure 2.

3.3 Intersection of Smooth Sets

We would like smooth sets to be closed under intersection. Further, we would like that the fill of an intersection of smooth sets is the intersection of the fills. However, this does not hold in general. The following is a counterexample.

► **Example 3.8.** Define $\mathbf{P} := \{\mathbf{0}\} \cup \mathbb{N}_{> 0}^2$, see left of Figure 2, and $\mathbf{P}' = \{(0, 1)\}^*$, the y -axis. We have $\{\mathbf{0}\} = \text{dir}(\mathbf{P} \cap \mathbf{P}') \subsetneq \text{dir}(\mathbf{P}) \cap \text{dir}(\mathbf{P}')$. Also, $\{\mathbf{0}\} = \text{Fill}(\mathbf{P} \cap \mathbf{P}') \subsetneq \text{Fill}(\mathbf{P}) \cap \text{Fill}(\mathbf{P}') = \mathbf{P}'$.

Fortunately, we can prove (see the Full version): Smooth sets \mathbf{P}, \mathbf{P}' such that $\text{Fill}(\mathbf{P})$, $\text{Fill}(\mathbf{P}')$, and $\text{Fill}(\mathbf{P}) \cap \text{Fill}(\mathbf{P}')$ have the same dimension behave well under intersection.

- **Proposition 3.9.** *Let \mathbf{P}, \mathbf{P}' be smooth periodic sets such that $\dim(\text{Fill}(\mathbf{P}) \cap \text{Fill}(\mathbf{P}')) = \dim(\text{Fill}(\mathbf{P})) = \dim(\text{Fill}(\mathbf{P}'))$. Then*
1. $\dim(\mathbf{P} \cap \mathbf{P}') = \dim(\mathbf{P}) = \dim(\mathbf{P}')$.
 2. $\text{dir}(\mathbf{P} \cap \mathbf{P}') = \text{dir}(\mathbf{P}) \cap \text{dir}(\mathbf{P}')$.
 3. $\text{Fill}(\mathbf{P} \cap \mathbf{P}') = \text{Fill}(\mathbf{P}) \cap \text{Fill}(\mathbf{P}')$.
 4. $\mathbf{P} \cap \mathbf{P}'$ is smooth.

4 Petri sets and Hybridizations

We introduce the remaining classes of sets used in our main result: Petri sets and sets admitting a hybridization. Petri sets were introduced in [11–13]. Hybridizations are a novel notion, and play a fundamental role in our main result.

4.1 Petri sets

Leroux introduced almost semilinear sets and developed their theory in [12, 13]. Intuitively, they generalize semilinear sets by replacing linear sets with smooth periodic sets.

- **Definition 4.1** ([12, 13]). *A set \mathbf{X} is almost linear if $\mathbf{X} = \mathbf{b} + \mathbf{P}$, where $\mathbf{b} \in \mathbb{N}^n$ and \mathbf{P} is a smooth periodic set, and almost semilinear if it is a finite union of almost linear sets.*

It was shown in [12, 13] that VAS reachability sets are almost semilinear. However, it is easy to find almost semilinear sets that are not reachability sets of any VAS. Intuitively, the definition of a smooth periodic set only restricts the “asymptotic behavior” of the set, which can be “simple” even if the set itself is very “complex”.

- **Example 4.2.** Let $\mathbf{Y} \subseteq \mathbb{N}_{>0}$ be any set. Then $\mathbf{P} := \{(0, 0)\} \cup (\{1\} \times \mathbf{Y}) \cup \mathbb{N}_{>1}^2$ is a smooth periodic set; indeed, \mathbf{P} contains a line in every direction, and is thus well-directed and asymptotically definable. So \mathbf{P} is almost semilinear.

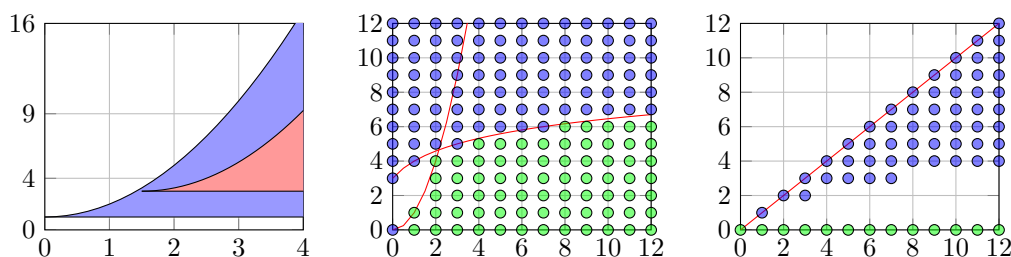
A way to eliminate at least some of these sets is to require that every intersection of the set with a semilinear set is still almost semilinear, a property enjoyed by all VAS reachability sets. For instance, assume that in Example 4.2 the set \mathbf{Y} is not almost semilinear. Since the intersection of \mathbf{P} and the linear set $(1, 0) + (0, 1) \cdot \mathbb{N}$ is equal to \mathbf{Y} , we can eliminate \mathbf{P} . This idea leads to the notion of a Petri set.

- **Definition 4.3** ([12, 13]). *A set \mathbf{X} is called a Petri set if every intersection $\mathbf{X} \cap \mathbf{S}$ with a semilinear set \mathbf{S} is almost semilinear.*

All smooth periodic sets shown so far are also Petri sets. To see that the positive examples are indeed Petri sets we can use the following strong theorem from [13].

- **Theorem 4.4** ([13, Theorem IX.1]). *Reachability sets of VAS are Petri sets.*

Many sets of the form $\{(x, y) \mid y \leq f(x)\}$ for convex f , or $\{(x, y) \mid y \geq f(x)\}$ for concave f , and boolean combinations thereof, are VAS reachability sets, and hence Petri sets.



■ **Figure 3** *Left:* An almost linear set $\mathbf{X} = \mathbf{b} + \mathbf{P}$ with $\mathbf{b} = (0, 1)$ and $\mathbf{P} = \{(x, y) \mid y \leq x^2\}$ (in blue). The property $\mathbf{X} + \mathbf{P} \subseteq \mathbf{X}$ implies that the “translation” of \mathbf{X} to *any* point in the set (shown in brown for a particular point) is included in the set.

Middle: The two smooth periodic sets $\mathbf{P}_1 := \{(x, y) \mid y \geq \log_2(x+1) + 3\} \cup \{(0, 0)\}$ in blue and $\mathbf{P}_2 := \{(x, y) \mid y \leq x^2\}$ in green. Their union is almost hybridlinear, but not almost linear.

Right: The smooth periodic sets $\mathbf{P}_1 := \{(x, y) \mid x \geq y \geq \log_2(x+1)\}$ and $\mathbf{P}_2 := \{(1, 0)\}^*$. The union \mathbf{X} does not have a hybridization, since $\mathbf{P} = \{(0, 0)\}$ is the only possibility to fulfill $\mathbf{X} + \mathbf{P} \subseteq \mathbf{X}$.

4.2 Hybridizations

Given a Petri set $\mathbf{X} \subseteq \mathbb{N}^n$, it would be very useful to be able to partition \mathbb{N}^n into finitely many semilinear regions $\mathbf{S}_1, \dots, \mathbf{S}_k$ such that the sets $\mathbf{S}_i \cap \mathbf{X}$ have a simpler structure. In particular, we would like $\mathbf{S}_i \cap \mathbf{X}$ to be almost linear. Unfortunately, for some Petri sets no such partition exists (an example can be found in the full version of the paper). We replace almost linearity by a slightly weaker notion for which the partition always exists: having a hybridization (Definition 4.5).

A set is almost linear if there exists a vector \mathbf{b} and a smooth periodic set \mathbf{P} such that $\mathbf{X} = \mathbf{b} + \mathbf{P}$. The following definition is equivalent: There exists a vector \mathbf{b} and a smooth periodic set \mathbf{P} such that $\mathbf{b} \in \mathbf{X}$ and $\mathbf{X} + \mathbf{P} \subseteq \mathbf{X} \subseteq \mathbf{b} + \mathbf{P}$.

We weaken this condition by requiring only the existence of a vector \mathbf{b} and a smooth periodic set \mathbf{P} such that $\mathbf{X} + \mathbf{P} \subseteq \mathbf{X} \subseteq \mathbf{b} + \text{Fill}(\mathbf{P})$.

That is, we drop the condition $\mathbf{b} \in \mathbf{X}$, and replace \mathbf{P} on the right by the possibly larger set $\text{Fill}(\mathbf{P})$. (For example, the periodic sets on the left of Figure 3 as well as in the middle satisfy $\text{Fill}(\mathbf{P}) = \mathbb{N}^2$). We then call the set $\mathbf{b} + \text{Fill}(\mathbf{P})$ a hybridization of \mathbf{X} . The formal definition is as follows, where for technical reasons we also introduce weak hybridizations.

► **Definition 4.5.** *Let $\mathbf{X} \subseteq \mathbb{N}^n$ be non-empty. A set \mathbf{H} is a weak hybridization of \mathbf{X} if there exists a finite set $\mathbf{B} \subseteq \mathbb{N}^n$ and a smooth periodic set \mathbf{P} such that $\mathbf{H} = \mathbf{B} + \text{Fill}(\mathbf{P})$ and $\mathbf{X} + \mathbf{P} \subseteq \mathbf{X} \subseteq \mathbf{H}$. If $\mathbf{B} = \{\mathbf{b}\}$, then \mathbf{H} is a hybridization of \mathbf{X} .*

► **Remark 4.6.** There are full linear weak hybridizations which are not hybridizations. For example $\mathbf{X} = 1 + 3\mathbb{N} \cup 2 + 3\mathbb{N}$ has weak hybridization $\mathbf{H} = \{0, 1, 2\} + 3\mathbb{N} = \mathbb{N}$. However, since \mathbf{X} does not contain any points congruent to 0 modulo 3, any periodic set \mathbf{P} fulfilling $\mathbf{X} + \mathbf{P} \subseteq \mathbf{X}$ has to fulfill $\mathbf{P} \subseteq 3\mathbb{N}$. Hence \mathbf{B} cannot be chosen as a singleton.

It follows from this definition that almost linear sets have hybridizations. The reason for the name (weak) hybridization is that the set \mathbf{H} is always hybridlinear, a notion introduced in [4] by Ginsburg and Spanier and later studied in [1] by Chistikov and Haase. We recall the definition for future reference.

► **Definition 4.7.** *A set $\mathbf{H} \subseteq \mathbb{N}^n$ is hybridlinear if $\mathbf{H} = \mathbf{B} + \mathbf{P}$ for some finite set \mathbf{B} and some finitely generated periodic set $\mathbf{P} \subseteq \mathbb{N}^n$.*

We end this section with a characterization of the sets that admit weak hybridizations.

► **Definition 4.8.** A non-empty set $\mathbf{X} \subseteq \mathbb{N}^n$ is almost hybridlinear if there exist $\mathbf{b}_1, \dots, \mathbf{b}_r \in \mathbb{N}^n$ and smooth $\mathbf{P}_1, \dots, \mathbf{P}_r$ with $\mathbf{X} = \bigcup_{i=1}^r \mathbf{b}_i + \mathbf{P}_i$, such that $\text{Fill}(\mathbf{P}_i) = \text{Fill}(\mathbf{P}_j)$ for all i, j .

► **Theorem 4.9.** A non-empty Petri set $\mathbf{X} \subseteq \mathbb{N}^n$ is almost hybridlinear if and only if it has a weak hybridization.

This theorem helps to find examples of non-trivial hybridizations (i.e. not of type \mathbf{P} has hybridization $\text{Fill}(\mathbf{P})$). For example $[(0, 1) + \mathbf{P}_1] \cup [(0, 6) + \mathbf{P}_2]$ for $\mathbf{P}_1 = \{(x, y) \in \mathbb{N}^2 \mid y \leq x^2\}$ and $\mathbf{P}_2 = \{(x, y) \in \mathbb{N}^2 \mid y \geq \log_2(x + 1)\}$ has weak hybridization \mathbb{N}^2 , since $\text{Fill}(\mathbf{P}_1) = \text{Fill}(\mathbf{P}_2) = \mathbb{N}^2$. This is very similar to the middle of Figure 3. On the other hand, in the right of Figure 3 the smooth periodic sets barely intersect, and then the union is usually not almost hybridlinear.

5 Proof of Theorem 1.1

In this section we prove Theorem 1.1. The algorithm and its proof will refine the partition in three steps, respectively described in Section 5.1, Section 5.2 and Section 5.3: During the first two steps the sets $\mathbf{X} \cap \mathbf{S}_i$ are not required to be irreducible, and in addition after the first step, the \mathbf{S}_i are allowed to be hybridlinear instead of full linear.

5.1 Existence of a Hybridlinear Partition

We collect five important properties of (weak) hybridizations in Proposition 5.2. Then, we use these properties to formulate a procedure for producing a partition $\mathbf{S} = \mathbf{S}_1 \cup \dots \cup \mathbf{S}_k$ of sets, not necessarily full linear, satisfying the properties of Theorem 1.1 except for irreducibility. The procedure is described in Figure 4. It is effective for VAS reachability sets, but not in general.

We start by reminding that the class of hybridlinear sets is closed under intersection.

► **Lemma 5.1** ([10, Lemma 7.8]). Let $\mathbf{b}_1 + \mathbf{Q}_1$ and $\mathbf{b}_2 + \mathbf{Q}_2$ be linear sets. Then $(\mathbf{b}_1 + \mathbf{Q}_1) \cap (\mathbf{b}_2 + \mathbf{Q}_2) = \mathbf{B} + (\mathbf{Q}_1 \cap \mathbf{Q}_2)$ for some finite \mathbf{B} .

► **Proposition 5.2.** The following statements hold:

- 1) If \mathbf{H} is a weak hybridization of \mathbf{X} , then $\dim(\mathbf{X}) = \dim(\mathbf{H})$.
- 2) If \mathbf{H} is a weak hybridization of \mathbf{X} and $\mathbf{L} = \mathbf{b} + \mathbf{Q}$ full linear s.t. $\dim(\mathbf{H} \cap \mathbf{L}) = \dim(\mathbf{H}) = \dim(\mathbf{L})$, then $\mathbf{H} \cap \mathbf{L}$ is a weak hybridization for $\mathbf{X} \cap \mathbf{L}$, or $\mathbf{X} \cap \mathbf{L}$ is empty.
- 3) If \mathbf{H} is a (weak) hybridization for both \mathbf{X}_1 and \mathbf{X}_2 , then \mathbf{H} is a (weak) hybridization for $\mathbf{X}_1 \cup \mathbf{X}_2$.
- 4) For every Petri set \mathbf{X} and semilinear \mathbf{S} there is a partition $\mathbf{X} \cap \mathbf{S} = \mathbf{X}_1 \cup \dots \cup \mathbf{X}_r$ of $\mathbf{X} \cap \mathbf{S}$ such that every \mathbf{X}_i has a (true) hybridization \mathbf{L}_i .
- 5) If \mathbf{X} is the reachability set of a VAS, then the set $\{\mathbf{L}_1, \dots, \mathbf{L}_r\}$ of hybridizations of part 4) is computable.

Proof. For proofs 1) and 2), write $\mathbf{H} := \mathbf{B} + \text{Fill}(\mathbf{P})$, where \mathbf{P} is smooth and $\mathbf{X} + \mathbf{P} \subseteq \mathbf{X}$.

1): This follows from the properties of dimension in Lemmas 2.4 and 2.5. In particular, $\dim(\mathbf{P}) = \dim(\mathbf{V})$, where \mathbf{V} is the vector space generated by \mathbf{P} , also implies $\dim(\mathbf{P}) = \dim(\text{Fill}(\mathbf{P}))$. Hence $\mathbf{X} \subseteq \mathbf{H}$ implies $\dim(\mathbf{X}) \leq \dim(\mathbf{P})$. Since \mathbf{X} is non-empty, $\mathbf{X} + \mathbf{P} \subseteq \mathbf{X}$ implies $\dim(\mathbf{X}) \geq \dim(\mathbf{P})$.

Partition(\mathbf{X}, \mathbf{S}). Input: Petri set \mathbf{X} and semilinear set \mathbf{S} :

1) If \mathbf{S} is empty, return \mathbf{S} . If \mathbf{S} is not full, compute a partition $\mathbf{S}_1, \dots, \mathbf{S}_r$ of \mathbf{S} into full linear sets, return $\bigcup_{i=1}^r \text{Partition}(\mathbf{X}, \mathbf{S}_i)$ and stop.

Otherwise, compute the set $\mathcal{L} = \{\mathbf{L}_1, \dots, \mathbf{L}_r\}$ of hybridizations of the partition $\mathbf{X}_1 \cup \dots \cup \mathbf{X}_r$ of $\mathbf{X} \cap \mathbf{S}$ given by Proposition 5.2(4), and move to step 2).

Remark: This step is not effective for arbitrary Petri sets, but it is effective for VAS reachability sets by Proposition 5.2(5).

If $r = 0$, i.e., if $\mathbf{X} \cap \mathbf{S}$ is empty, then return \mathbf{S} and stop. Otherwise, move to step 2).

2) For every $\mathbf{L}_i \in \mathcal{L}$ compute a decomposition \mathcal{K}_i of $\mathbf{L}_i^c \cap \mathbf{S}$ into full linear sets, where \mathbf{L}_i^c is the complement of \mathbf{L}_i , and move to step 3).

3) Let \mathcal{M} be the set of tuples $(\mathbf{M}_1, \dots, \mathbf{M}_r) \in (\{\mathbf{L}_1\} \cup \mathcal{K}_1) \times \dots \times (\{\mathbf{L}_r\} \cup \mathcal{K}_r)$.

For every $M \in \mathcal{M}$, let $\mathbf{S}_M := \mathbf{S} \cap \mathbf{M}_1 \cap \dots \cap \mathbf{M}_r$.

Remark: $\{\mathbf{S}_M \mid M \in \mathcal{M}\}$ is a partition of \mathbf{S} .

For every $M \in \mathcal{M}$, define P_M as follows: If $\dim(\mathbf{S}_M) < \dim(\mathbf{S})$, then $P_M := \text{Partition}(\mathbf{X}, \mathbf{S}_M)$, otherwise $P_M := \{\mathbf{S}_M\}$. Output $\bigcup_{M \in \mathcal{M}} P_M$.

■ **Figure 4** The procedure Partition(\mathbf{X}, \mathbf{S}).

2): By Lemma 5.1, $\mathbf{H} \cap \mathbf{L} = \mathbf{F} + (\text{Fill}(\mathbf{P}) \cap \mathbf{Q})$ for some finite set \mathbf{F} . By Proposition 3.9, we have that $\mathbf{P} \cap \mathbf{Q}$ is smooth and $\text{Fill}(\mathbf{P} \cap \mathbf{Q}) = \text{Fill}(\mathbf{P}) \cap \text{Fill}(\mathbf{Q}) = \text{Fill}(\mathbf{P}) \cap \mathbf{Q}$. We have $\mathbf{X} \cap \mathbf{L} \subseteq \mathbf{H} \cap \mathbf{L}$. We also have $(\mathbf{X} \cap \mathbf{L}) + (\mathbf{P} \cap \mathbf{Q}) \subseteq \mathbf{X} + \mathbf{P} \subseteq \mathbf{X}$ and $(\mathbf{X} \cap \mathbf{L}) + (\mathbf{P} \cap \mathbf{Q}) \subseteq \mathbf{L} + \mathbf{Q} \subseteq \mathbf{L}$, hence $\mathbf{H} \cap \mathbf{L}$ is a weak hybridization of $\mathbf{X} \cap \mathbf{L}$.

3): Write $\mathbf{B}_1 + \text{Fill}(\mathbf{P}_1) = \mathbf{H} = \mathbf{B}_2 + \text{Fill}(\mathbf{P}_2)$, where \mathbf{P}_1 for \mathbf{X}_1 and \mathbf{P}_2 for \mathbf{X}_2 are as in the definition of weak hybridization. By Lemma 5.1, we have $\mathbf{H} = \mathbf{H} \cap \mathbf{H} = \mathbf{F} + [\text{Fill}(\mathbf{P}_1) \cap \text{Fill}(\mathbf{P}_2)]$ for some finite set \mathbf{F} . Define $\mathbf{P} := \mathbf{P}_1 \cap \mathbf{P}_2$ and $\mathbf{X} := \mathbf{X}_1 \cup \mathbf{X}_2$. By Proposition 3.9, \mathbf{P} is smooth and $\text{Fill}(\mathbf{P}) = \text{Fill}(\mathbf{P}_1) \cap \text{Fill}(\mathbf{P}_2)$. We also have $\mathbf{X} + \mathbf{P} \subseteq \mathbf{X}$.

4): Since \mathbf{X} is a Petri set, $\mathbf{X} \cap \mathbf{S}$ is almost semilinear, and can hence be written as $\mathbf{X} = \bigcup_{i=1}^r \mathbf{b}_i + \mathbf{P}_i$ for smooth periodic sets $\mathbf{P}_i \subseteq \mathbb{N}^n$ and points $\mathbf{b}_i \in \mathbb{N}^n$. Every $\mathbf{X}_i := \mathbf{b}_i + \mathbf{P}_i$ is by definition almost hybridlinear with hybridization $\mathbf{b}_i + \text{Fill}(\mathbf{P}_i)$, which is a full linear set.

5): 4) can be computed using the Kosaraju-Lambert-Mayr-Sacerdote-Tenney (KLMST) decomposition [8–10, 16]. The KLMST decomposition constructs a finite set of VASS-like objects, called perfect marked graph transition sequences or perfect MGTSSs, such that the set of reachable configurations of the VAS is the union of the sets of reachable configurations of the perfect MGTSSs. Further, for every perfect MGTSS one can effectively construct a set of linear equations satisfying the following property: the set of solutions of the equation system is a hybridization of the set of reachable configurations of the perfect MGTSS. The set of solutions of a system of linear equations is always hybridlinear. Moreover, for the systems derived from MGTSSs one can show that the set has a full linear hybridization (e.g. [10, Lemma 5.1]). This gives us the desired hybridizations $\mathbf{L}_1, \dots, \mathbf{L}_r$. \blacktriangleleft

² While Hauschildt already used the KLMST decomposition in [6] in 1990, it took until 2019 [15, 16] to fully understand the theoretical aspects behind the algorithm and its complexity of Ackermann.

► **Proposition 5.3.** *Let \mathbf{X} be a Petri set and let \mathbf{S} be a semilinear set. $\text{Partition}(\mathbf{X}, \mathbf{S})$ produces a partition $\mathbf{S} = \mathbf{S}_1 \cup \dots \cup \mathbf{S}_k$ into pairwise disjoint hybridlinear sets (not necessarily full linear) such that for every i the set $\mathbf{X} \cap \mathbf{S}_i$ is either empty or has weak hybridization \mathbf{S}_i . Further, if \mathbf{X} is the reachability set of a VAS, then the partition is computable.*

Proof. The procedure is depicted in Figure 4, in addition we give an intuitive description of it: In Step 1) we first partition \mathbf{S} into full linear sets and consider them separately. So assume that \mathbf{S} is a full linear set. The procedure uses Proposition 5.2(5) to compute a set of full linear hybridizations $\mathbf{L}_1, \dots, \mathbf{L}_r$ of a partition $\mathbf{X}_1 \cup \dots \cup \mathbf{X}_r$ of $\mathbf{X} \cap \mathbf{S}$. Step 2) considers all possible sets obtained by picking for each $i \in \{1, \dots, r\}$ either the set \mathbf{L}_i or a linear set of its complement (its complement is semilinear, and so a finite union of linear sets), and intersecting all of them. The procedure adds all the sets having full dimension to the output partition, and does a recursive call on the others.

Every step can be performed: The set \mathcal{L} of Step 1 exists by Proposition 5.2(4). To check the dimension of a semilinear set $\mathbf{S} = \bigcup_{j=1}^r \mathbf{b}_j + \mathbf{F}_j^*$, which is needed in step 3), we use Lemma 2.5 to obtain that for \mathbf{F}_j^* this is simply the rank of the generator matrix, and by Lemma 2.4 we have $\dim(\mathbf{S}) = \max_j \dim(\mathbf{F}_j^*)$.

Termination: $\text{Partition}(\mathbf{X}, \mathbf{S})$ only performs a recursive call if \mathbf{S} is not a full linear set or on semilinear sets \mathbf{S}' with $\dim(\mathbf{S}') < \dim(\mathbf{S})$, hence recursion depth is at most $2 \dim(\mathbf{S}) + 1$ and termination immediate.

Correctness: The proof obligation for correctness is that for every $M = (\mathbf{M}_1, \dots, \mathbf{M}_r) \in \mathcal{M}$, where S_M fulfills $\dim(S_M) = \dim(\mathbf{S})$, $\mathbf{X} \cap S_M$ is either empty or has S_M as weak hybridization. Therefore fix such M .

▷ **Claim 5.4.** $\dim(\mathbf{M}_j) = \dim(\mathbf{S})$ for all j .

Proof of Claim. $\geq \dim(\mathbf{S})$ follows since all these sets contain S_M , which fulfills $\dim(S_M) = \dim(\mathbf{S})$. For the other direction, to prove “ \leq ” for j where we choose \mathbf{L}_j we have $\dim(\mathbf{S}) \geq \dim(\mathbf{X} \cap \mathbf{S}) = \max_j \dim(\mathbf{L}_j)$ by Proposition 5.2. For other j we use $\mathbf{L}_j^C \cap \mathbf{S} \subseteq \mathbf{S}$. ◀

The claim allows us to use Proposition 5.2(2). Let \mathbf{X}_j be such that $\mathbf{X} \cap \mathbf{S} = \bigcup_{j=1}^r \mathbf{X}_j$ and \mathbf{X}_j has hybridization \mathbf{L}_j . By applying Proposition 5.2(2) enough times, for every j with $\mathbf{M}_j = \mathbf{L}_j$, we obtain that $\mathbf{X}_j \cap S_M$ has weak hybridization S_M . This does not depend on j because intersecting with \mathbf{L}_j twice does not change the set. For all other j we have $\mathbf{X}_j \cap S_M = \emptyset$, since we intersect with the complement of an overapproximation. Hence $\mathbf{X} \cap S_M = \bigcup_{j, \mathbf{M}_j = \mathbf{L}_j} (\mathbf{X}_j \cap S_M)$ has weak hybridization S_M by Proposition 5.2(3), or is empty if we never chose $\mathbf{M}_j = \mathbf{L}_j$. ◀

5.2 Existence of a Full Linear Partition

We show that Proposition 5.3 can be strengthened to make the sets \mathbf{S}_i not only hybridlinear, but even full linear, in a way that the sets \mathbf{S}_i are actually (true) hybridizations.

► **Proposition 5.5.** *Let \mathbf{X} be a Petri set. For every semilinear set \mathbf{S} there exists a partition $\mathbf{S} = \mathbf{S}_1 \cup \dots \cup \mathbf{S}_k$ of \mathbf{S} into pairwise disjoint full linear sets such that for every i the set $\mathbf{X} \cap \mathbf{S}_i$ is either empty or has hybridization \mathbf{S}_i . Further, if \mathbf{X} is the reachability set of a VAS, then the partition is computable.*

Proof. The main algorithm uses a subroutine with the same inputs and outputs as itself, but with the promise that $\mathbf{X} \cap \mathbf{S}$ has weak hybridization \mathbf{S} . We first describe the main algorithm, and then the subroutine.

Main algorithm: First apply Proposition 5.3 to obtain a partition $\mathbf{S} = \mathbf{S}_1 \cup \dots \cup \mathbf{S}_k$ into hybridlinear sets otherwise satisfying the conditions. Output $\bigcup_{i=1}^k \text{Subroutine}(\mathbf{X}, \mathbf{S}_i)$.

Subroutine: If \mathbf{S} is already full linear, return \mathbf{S} . Otherwise write $\mathbf{S} = \{\mathbf{c}_1, \dots, \mathbf{c}_r\} + \text{Fill}(\mathbf{P})$. Let $j \sim k \iff \mathbf{c}_j - \mathbf{c}_k \in \text{Fill}(\mathbf{P}) - \text{Fill}(\mathbf{P}) = \mathbf{P} - \mathbf{P}$. Compute a system R of representatives for \sim . For every $i \in R$, define $\mathbf{S}_i := \mathbf{c}_i + \text{Fill}(\mathbf{P})$. Define $\mathbf{S}' := \mathbf{S} \setminus \bigcup_{i \in R} \mathbf{S}_i$ and output $\{\mathbf{S}_i \mid i \in R\} \cup \text{MainAlgorithm}(\mathbf{X}, \mathbf{S}')$.

Termination: We prove that recursion depth $\leq 2 \dim(\mathbf{S}) + 1$ by proving $\dim(\mathbf{S}') < \dim(\mathbf{S})$ in the subroutine. For every equivalence class C of \sim , there exists $\mathbf{c} \in \mathbb{Z}^n$ such that $\mathbf{c}_j - \mathbf{c} \in \mathbf{P}$ for all $j \in C$. To see this, fix some $i \in C$, and write $\mathbf{c}_j - \mathbf{c}_i = \mathbf{p}_j - \mathbf{p}'_j \in \mathbf{P} - \mathbf{P}$. Choose $\mathbf{c} := \mathbf{c}_i - \sum_{j \in C} \mathbf{p}'_j$.

Then $\bigcup_{j \in C} \mathbf{c}_j + \text{Fill}(\mathbf{P}) \subseteq \mathbf{c} + \text{Fill}(\mathbf{P})$, and hence using Lemma 2.10 we obtain $\dim(\bigcup_{j \in C} \mathbf{c}_j + \text{Fill}(\mathbf{P}) \setminus \mathbf{S}_i) \leq \dim(\mathbf{c} + \text{Fill}(\mathbf{P}) \setminus \mathbf{c}_i + \text{Fill}(\mathbf{P})) < \dim(\text{Fill}(\mathbf{P}))$.

Correctness: The main algorithm is clearly correct if the subroutine is. In the subroutine, we have $\mathbf{S}_i \cap \mathbf{S}_j = \emptyset$ since $i \not\sim j$ for $i, j \in R$. All \mathbf{S}_i are full linear by definition. Furthermore, $\mathbf{X} \cap \mathbf{S}_i$ has weak hybridization $\mathbf{H} \cap \mathbf{S}_i = \mathbf{S}_i$ by Proposition 5.2(2). To obtain that the hybridization is not weak, observe that Proposition 5.2(2) specifically shows that the intersection of the representations, which is the full linear representation of \mathbf{S}_i , is a weak hybridization. \blacktriangleleft

5.3 Reducibility of almost hybridlinear Sets

The final ingredient of our main result is reducibility. We name it after its counterpart in Hauschildt's PhD thesis [6].

► **Definition 5.6.** *A set \mathbf{X} with hybridization $\mathbf{c} + \text{Fill}(\mathbf{P})$ is reducible if there exists \mathbf{x} such that $\mathbf{x} + \text{Fill}(\mathbf{P}) \subseteq \mathbf{X}$.*

In other words, \mathbf{X} is reducible if every large enough point of its hybridization is already in \mathbf{X} . Observe that this does not follow from hybridization, as $\text{Fill}(\mathbf{P})$ is larger than \mathbf{P} . Our usual examples of sets with hybridization are smooth periodic sets, these also illustrate reducibility: The set in the left of Figure 2 is reducible, while the middle is not. Another example of hybridization was in the middle of Figure 3, this set is also reducible. In fact, whenever $\mathbf{X} = \mathbf{b} + \mathbf{P}$, \mathbf{X} is reducible if and only if $\text{dir}(\mathbf{P}) = \overline{\mathbb{Q}_{\geq 0} \mathbf{P}}$. Namely, use Proposition 3.7 with \mathbf{F} the generators of $\text{Fill}(\mathbf{P})$. For other sets \mathbf{X} , write $\mathbf{X} = \bigcup_{i=1}^r \mathbf{b}_i + \mathbf{P}_i$ as almost hybridlinear set. Whether it is reducible again only depends on the cones $\text{dir}(\mathbf{P}_i)$, for a proof see the full version. Since matrices for the definable cones $\text{dir}(\mathbf{P}_i)$ can in the case of VAS be determined using KLMST-decomposition [6], we obtain the following.

► **Theorem 5.7** ([6, even without promise]). *The following problem is decidable.*

Input: Reachability set \mathbf{R} , represented via the transitions of the VASS, full linear set \mathbf{S} .

Promise: $\mathbf{R} \cap \mathbf{S}$ has hybridization \mathbf{S} .

Output: Is $\mathbf{R} \cap \mathbf{S}$ reducible?

We can now prove our main result.

► **Theorem 1.1.** *Let \mathbf{X} be a Petri set. For every semilinear set \mathbf{S} there exists a partition $\mathbf{S} = \mathbf{S}_1 \cup \dots \cup \mathbf{S}_k$ into pairwise disjoint full linear sets such that for all $i \in \{1, \dots, k\}$ either $\mathbf{X} \cap \mathbf{S}_i = \emptyset$, $\mathbf{S}_i \subseteq \mathbf{X}$ or $\mathbf{X} \cap \mathbf{S}_i$ is irreducible with hybridization \mathbf{S}_i . Further, if \mathbf{X} is the reachability set of a VAS, then the partition is computable.*

Proof. Step 1: Use Proposition 5.5 to compute a partition $\mathbf{S} = \mathbf{S}_1 \cup \dots \cup \mathbf{S}_k$ into full linear sets such that $\mathbf{X} \cap \mathbf{S}_i$ has hybridization \mathbf{S}_i if it is non-empty. For every set \mathbf{S}_i with $\mathbf{X} \cap \mathbf{S}_i \neq \emptyset$ do Step 2.

Step 2: Decide whether $\mathbf{X} \cap \mathbf{S}_i$ is reducible using Theorem 5.7. If irreducible, output \mathbf{S}_i . Otherwise, there exists \mathbf{x} such that $\mathbf{x} + \mathbf{Q} \subseteq \mathbf{X} \cap \mathbf{S}_i$, where $\mathbf{S}_i = \mathbf{c} + \mathbf{Q}$. Find such an \mathbf{x} , add $\mathbf{x} + \mathbf{Q} \subseteq \mathbf{X}$ to the final partition and do a recursive call on $\mathbf{S}_i \setminus (\mathbf{x} + \mathbf{Q})$.

Termination: We claim that we only perform recursion on \mathbf{S}' with $\dim(\mathbf{S}') < \dim(\mathbf{S})$. To see this, take $\mathbf{S}_i = \mathbf{c} + \mathbf{Q}$ such that $\mathbf{X} \cap \mathbf{S}_i$ is reducible. We have $\dim(\mathbf{S}_i \setminus \mathbf{x} + \mathbf{Q}) = \dim(\mathbf{c} + \mathbf{Q} \setminus \mathbf{x} + \mathbf{Q}) < \dim(\mathbf{Q})$ by Lemma 2.10, wherefore the recursion uses a lower dimensional set, and termination follows from bounded recursion depth.

Correctness: Follows from correctness of Proposition 5.5.

The partition is computable for VAS: We have to be able to find \mathbf{x} with $\mathbf{x} + \mathbf{Q} \subseteq \mathbf{X}$ given the promise that such an \mathbf{x} exists. This is possible since containment of semilinear sets in reachability sets is decidable by [13] using flatability. ◀

6 Corollaries of Theorem 1.1

6.1 VAS semilinearity is decidable

We prove that the semilinearity problem for VAS is decidable. We start with a lemma, whose full proof is in the full version.

► **Lemma 6.1.** *Let \mathbf{X} be a semilinear Petri set with hybridization $\mathbf{c} + \mathbf{Q}$. Then \mathbf{X} is reducible.*

Proof idea. The hybridization describes all “limit directions”, with the problematic ones being for example “north” in case of the parabola $\{(x, y) \mid y \leq x^2\}$, which is a limit but not actually a direction. If \mathbf{X} is semilinear though, then the steepness can only increase finitely often, namely when changing to a different linear component, and all limit directions are actually also directions. Using this for generators of $\text{Fill}(\mathbf{P})$ we find $\mathbf{x} + \text{Fill}(\mathbf{P}) \subseteq \mathbf{X}$. ◀

► **Corollary 6.2** ([6]). *The following problem is decidable.*

Input: Reachability set \mathbf{R} of VAS, semilinear \mathbf{S} .

Output: Is $\mathbf{R} \cap \mathbf{S}$ semilinear?

Proof. As also mentioned in the introduction, the algorithm computes the partition of Theorem 1.1 and checks whether the third case does not occur.

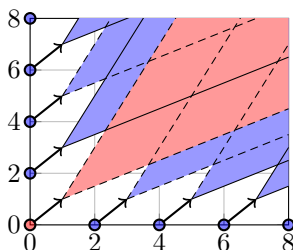
Correctness: If $\mathbf{R} \cap \mathbf{S}$ is semilinear, then in particular $\mathbf{R} \cap \mathbf{S}_i$ is semilinear for every part \mathbf{S}_i of the partition. By Lemma 6.1, $\mathbf{R} \cap \mathbf{S}_i$ cannot be irreducible, and so either $\mathbf{R} \cap \mathbf{S}_i = \emptyset$ or $\mathbf{S}_i \subseteq \mathbf{R}$ for all i .

On the other hand, if only the cases $\mathbf{R} \cap \mathbf{S}_i = \emptyset$ and $\mathbf{S}_i \subseteq \mathbf{R}$ occur, then the \mathbf{S}_i such that $\mathbf{S}_i \subseteq \mathbf{R}$ form a semilinear representation. ◀

6.2 On the Complement of a VAS Reachability Set

We show that if the complement of a VAS reachability set is infinite, then it contains an infinite linear set. The main part of the argument was already depicted in the middle of Figure 3: If \mathbf{X} contains enough of the boundary, then it is reducible.

We hence need to formalize the notion of boundary and interior also for full linear sets. If $\mathbf{L} = \mathbf{b} + \mathbf{Q}$ is a full linear set, then $\text{int}(\mathbf{L}) := \mathbf{b} + (\mathbf{Q} \cap \text{int}(\mathbb{Q}_{\geq 0}\mathbf{Q}))$ is the interior of \mathbf{L} and $\partial(\mathbf{L}) := \mathbf{b} + (\mathbf{Q} \cap \partial(\mathbb{Q}_{\geq 0}\mathbf{Q}))$ is the boundary of \mathbf{L} , both are inherited from the cone. These sets are both semilinear, as can be seen by using the definition expressible via $\varphi \in \text{FO}(\mathbb{N}, +, \geq)$, i.e. Presburger Arithmetic. Remember that we consider definable cones, i.e. cones expressible in $\text{FO}(\mathbb{Q}, +, \geq)$. In the full version, we prove the following proposition, formalizing the first part of the proof.



■ **Figure 5** Let \mathbf{C} be the cone generated by $(2, 1)$ and $(1, 2)$ and assume that $\mathbf{X} + [(1, 1) + \mathbf{C}] \subseteq \mathbf{X}$ holds. Then $(0, 0) \in \mathbf{X}$ implies that the whole red shifted cone is in \mathbf{X} . Importantly, we obtain a similar shifted cone for *every* point $\mathbf{x}' \in \mathbf{X}$. Hence if $\partial\mathbb{N}^2 \subseteq \mathbf{X}$, then almost all of \mathbb{N}^2 is contained in \mathbf{X} .

► **Proposition 6.3.** *Let \mathbf{X} be a set with hybridization $\mathbf{c} + \text{Fill}(\mathbf{P})$. Assume that $|\partial(\mathbf{c} + \text{Fill}(\mathbf{P})) \setminus \mathbf{X}| < \infty$. Then \mathbf{X} is reducible.*

The proof of Proposition 6.3 is illustrated in the above figure. The main difficulty is defining a “wide enough” cone \mathbf{C} , then Proposition 3.7 applied to $\mathbf{C} \cap (\mathbf{P} - \mathbf{P})$ does the rest.

► **Corollary 6.4.** *Let \mathbf{X} be a Petri set. Let \mathbf{S} be a semilinear set such that $\mathbf{S} \setminus \mathbf{X}$ is infinite. Then $\mathbf{S} \setminus \mathbf{X}$ contains an infinite linear set.*

Proof. Proof by induction on $\dim(\mathbf{S})$. If $\dim(\mathbf{S}) = 0$, the property holds vacuously. Else consider the partition of Theorem 1.1. Since $\mathbf{S} \setminus \mathbf{X}$ is infinite, some $\mathbf{S}_i \setminus \mathbf{X}$ is infinite. Fix such an i . Because of Theorem 1.1, $\mathbf{S}_i \subseteq \mathbf{X}$ or $\mathbf{X} \cap \mathbf{S}_i = \emptyset$ or $\mathbf{X} \cap \mathbf{S}_i$ is irreducible. In fact, only the third possibility is interesting. If $\mathbf{S}_i \subseteq \mathbf{X}$, then $\mathbf{S}_i \setminus \mathbf{X}$ can not be infinite. If $\mathbf{S}_i \cap \mathbf{X} = \emptyset$ then $\mathbf{S}_i = \mathbf{S}_i \setminus \mathbf{X}$, hence it contains a line. Let us consider the case when $\mathbf{S}_i \cap \mathbf{X}$ is irreducible. Assume for contradiction that $\mathbf{S}_i \setminus \mathbf{X}$ does not contain an infinite linear set. Then in particular $\partial(\mathbf{S}_i) \setminus \mathbf{X}$ does not. We have $\dim(\partial(\mathbf{S}_i)) < \dim(\mathbf{S}_i)$, since the boundary is contained in the finite union of the facets. Hence $|\partial(\mathbf{S}_i) \setminus \mathbf{X}| < \infty$ by induction. By Proposition 6.3, $\mathbf{X} \cap \mathbf{S}_i$ is reducible. Contradiction. ◀

In the full version, we even prove another corollary of the partition. The proof is based on the existence of a partition as in Theorem 1.1, which has the properties for two Petri sets \mathbf{X}_1 and \mathbf{X}_2 at once.

► **Corollary 6.5.** *Let \mathbf{X}_1 and \mathbf{X}_2 be Petri sets with $\mathbf{X}_1 \cap \mathbf{X}_2 = \emptyset$. Then there exists a semilinear set \mathbf{S}' such that $\mathbf{X}_1 \subseteq \mathbf{S}'$ and $\mathbf{X}_2 \cap \mathbf{S}' = \emptyset$.*

► **Corollary 6.6.** *Let \mathcal{V} be a VAS, and \mathbf{X} a Petri set such that $\text{Reach}(\mathcal{V}) \cap \mathbf{X} = \emptyset$. Then there exists a semilinear inductive invariant \mathbf{S}' of \mathcal{V} such that $\text{Reach}(\mathcal{V}) \subseteq \mathbf{S}'$ and $\mathbf{X} \cap \mathbf{S}' = \emptyset$.*

7 Conclusion

We have introduced hybridizations, and used them to prove a powerful decomposition theorem for Petri sets. For VAS reachability sets the decomposition can be effectively computed. We have derived several geometric and computational results. We think that our decomposition can help to study the computational power of VAS. For example, it leads to this corollary:

► **Corollary 7.1.** *Let $f: \mathbb{N} \rightarrow \mathbb{N}$ be a function whose graph does not contain an infinite line. Then either $\{(x, y) \mid y < f(x)\}$ or $\{(x, y) \mid y > f(x)\}$ is not a Petri set.*

Proof. Assume for contradiction that both are Petri sets. Then, since finite unions of Petri sets are again Petri sets, $\{(x, y) \mid y \neq f(x)\}$ is a Petri set. Its complement is the graph of f , which by assumption does not contain an infinite line. Contradiction to Corollary 6.4. ◀

We plan to study other possible applications of our result, derived from the fact that the reachability relation of a VAS is also a Petri set.

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