Decidable (Ac)counting with Parikh and Muller: Adding Presburger Arithmetic to Monadic Second-**Order Logic over Tree-Interpretable Structures**

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– Abstract

We propose ω MSO \rtimes BAPA, an expressive logic for describing countable structures, which subsumes and transcends both Counting Monadic Second-Order Logic (CMSO) and Boolean Algebra with Presburger Arithmetic (BAPA). We show that satisfiability of ω MSO \rtimes BAPA is decidable over the class of labeled infinite binary trees, whereas it becomes undecidable even for a rather mild relaxations. The decidability result is established by an elaborate multi-step transformation into a particular normal form, followed by the deployment of Parikh-Muller Tree Automata, a novel kind of automaton for infinite labeled binary trees, integrating and generalizing both Muller and Parikh automata while still exhibiting a decidable (in fact PSPACE-complete) emptiness problem. By means of MSO-interpretations, we lift the decidability result to all tree-interpretable classes of structures, including the classes of finite/countable structures of bounded treewidth/cliquewidth/partitionwidth. We generalize the result further by showing that decidability is even preserved when coupling width-restricted ω MSO \rtimes BAPA with width-unrestricted two-variable logic with advanced counting. A final showcase demonstrates how our results can be leveraged to harvest decidability results for expressive μ -calculi extended by global Presburger constraints.

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1 Introduction

Monadic second-order logic (MSO) is a popular, expressive, yet computationally reasonably well-behaved logical formalism to deal with various classes of finite or countable structures. It allows for expressing "mildly recursive" structural properties like connectedness or reachability, which go beyond first-order logic yet meet crucial modeling demands in verification, database theory, knowledge representation, and other fields of computational logic. The well-understood



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33:2 Adding Presburger Arithmetic to MSO Logic over Tree-Interpretable Structures

link between MSO and automata theory has been very fertile in theory and practice. In particular, the MSO theory of infinite binary trees is decidable by Rabin's famous result [50], and the same holds for structures of bounded treewidth, cliquewidth, and partitionwidth.

Unfortunately, MSO's native capabilities to express cardinality relationships are very limited; they are essentially restricted to fixed thresholds (e.g. "there are at least 10 leaves"). Counting MSO [18, 17], denoted CMSO, extends MSO by modulo counting and a finiteness test over sets (e.g. "there is an even number of nodes"), which increases expressiveness in general, while over finite and infinite words or trees, CMSO can be simulated in plain MSO. In contrast, enriching MSO with cardinality constraints [40, 41] (as in "all nodes have as many incoming as outgoing edges") increases the expressivity drastically, but causes satisfiability to become undecidable even over finite words. Decidability (over finite words, trees, or graphs of bounded treewidth [42]) can be recovered when confining set variables occurring in cardinality constraints to those existentially quantified in front (MSO^{\exists Card}). One way to show this is through Parikh automata extending finite automata by adding finitely many counters and exploiting the relationship of Presburger arithmetic and semilinear sets [31].

Very recent work [37, 33, 35] extended Parikh word automata to infinite words and investigated the impact of various acceptance conditions, but left a logical characterization as open question. As with the original Parikh automata, one central motivation behind these works is to provide automata-based approaches for specifying and verifying systems beyond regular languages. The study of ω -Parikh automata is motivated by reactive systems, whose behaviors are typically represented by infinite words. Then, the plethora of branching-time approaches in verification should call for a further generalization to ω -tree-automata. Yet, to our knowledge, Parikh automata have not been studied in the context of infinite trees so far.

Another, orthogonal logical approach for describing sets and their cardinalities, motivated by tasks from program analysis and verification, combines the first-order theory of *Boolean algebras* (BA) with *Presburger arithmetic* (PA), resulting in the theory of *BAPA* [44, 45]. As opposed to computationally benign extensions of MSO, BAPA provides stronger support for arithmetic (so one can talk about "all selections with the same number of blue and red nodes" or even "all selections with a share of 70%-80% red nodes", modeling statistical information). BAPA usually assumes a finite universe, but can be extended to the countable setting [46]; satisfiability is decidable in either case. However, very regrettably, BAPA lacks non-unary relations, which is outright fatal when it comes to expressing structural properties.

Combining both worlds, we introduce ω MSO×BAPA ['o:mzoll bapa],¹ a logic for countable structures, which extends CMSO by BAPA's set operations and Presburger statements, strictly contains MSO^{∃Card}, and allows for sophisticated structural-arithmetic statements (Section 3). We warrant computational manageability by gently controlling the usage of variables, noting that satisfiability turns undecidable otherwise (Section 4). Exhibiting an elaborate transformation (Section 5), we prove that ω MSO×BAPA formulae over trees can be brought into a very restricted *tree normal form* (TNF). We then provide a characterization showing that the sets of ω -trees satisfying TNF formulae coincide with the sets of trees recognized by *Parikh-Muller Tree Automata* (PMTA), a novel automata model designed by us – and the first-ever automaton model on infinite trees capable of testing Parikh conditions (Section 6). PMTA generalize both Muller and Parikh automata and their emptiness is decidable. The decidability of ω MSO×BAPA over the class of labeled infinite binary trees thereby obtained is then lifted to all *tree-interpretable classes*, including vast and practically

¹ Note that the "⋈" inside the name is meant to be pronounced as lateral click, commonly used by riders and coachmen to urge on their horses, and present in several African languages as a consonant.

relevant classes of finite or countable structures that are bounded in terms of certain width measures (Section 7). Such width-bounded ω MSO×BAPA can be decidably coupled with width-unbounded two-variable logics with advanced counting (Section 8). We demonstrate how to leverage our results to gain decidability results for statistics-enhanced formalisms of the μ -calculus family, which subsumes branching-time logics such as CTL^{*} (Section 9).

2 Preliminaries

As usual, for any $n \in \mathbb{N}$, let $[n] \coloneqq \{1, \ldots, n\}$. In order to **count to infinity**, we use \mathbb{N} extended by (countable) infinity ∞ , with arithmetics lifted in the usual way; in particular, $\infty + n = \infty + \infty = (n+1) \cdot \infty = \infty$ and $0 \cdot \infty = 0$ as well as $n \leq \infty$ and $\infty \leq \infty$. For countable sets A, let |A| denote the element of $\mathbb{N} \cup \{\infty\}$ that corresponds to their cardinality.

To define **countable structures**, assume the following countable, pairwise disjoint sets: a set **C** of *(individual) constants*, denoted by $\mathbf{a}, \mathbf{b}, \mathbf{c}, ...,$ and, for every $n \in \mathbb{N}$, a set \mathbf{P}_n of *n*-ary predicates, denoted by $\mathbf{P}, \mathbf{R}, \mathbf{Q}, ...$ The set of all predicates will be denoted by $\mathbf{P} := \bigcup_{i \in \mathbb{N}} \mathbf{P}_n$, and we let ar : $\mathbf{P} \to \mathbb{N}$ such that $\operatorname{ar}(\mathbf{Q}) = n$ iff $\mathbf{Q} \in \mathbf{P}_n$. A *(relational) signature* \mathbb{S} is a union $\mathbb{S}_{\mathbf{C}} \cup \mathbb{S}_{\mathbf{P}}$ of finite subsets of **C** and **P**, respectively. An \mathbb{S} -structure is a pair $\mathfrak{A} = (A, \cdot^{\mathfrak{A}})$, where A is a countable, nonempty set, called the *domain* of \mathfrak{A} and $\cdot^{\mathfrak{A}}$ is a function that maps every $\mathbf{a} \in \mathbb{S}_{\mathbf{C}}$ to a domain element $\mathbf{a}^{\mathfrak{A}} \in A$, and every $\mathbf{Q} \in \mathbb{S}_{\mathbf{P}}$ to an $\operatorname{ar}(\mathbf{Q})$ -ary relation $\mathbf{Q}^{\mathfrak{A}} \subseteq A^{\operatorname{ar}(\mathbf{Q})}$.

We define **infinite trees** starting from a finite, non-empty set Σ , called *alphabet*. A (full) infinite binary tree (often simply called a tree) labeled by some alphabet Σ is a mapping $\xi \colon \{0,1\}^* \to \Sigma$. We denote the set of all trees labeled by Σ by T_{Σ}^{ω} . A finite tree is a mapping $\xi \colon X \to \Sigma$ where X is a finite, prefix-closed subset of $\{0,1\}^*$. The set of all finite trees over Σ will be denoted by T_{Σ} . We sometimes refer to the domain X of ξ by $\operatorname{pos}(\xi)$, whose elements we call positions or nodes of ξ . Given a tree $\xi \in T_{\Sigma}^{\omega}$ and a finite, prefix-closed set $X \subseteq \{0,1\}^*$, we denote by $\xi_{|X}$ the finite tree in T_{Σ} that has X as domain and coincides with ξ on X.

An *(infinite)* path π is an infinite sequence $\pi = \pi_1 \pi_2 \dots$ of positions from $\{0, 1\}^*$ such that $\pi_1 = \varepsilon$ and, for each $i \ge 1$, $\pi_{i+1} \in (\pi_i \cdot \{0, 1\})$. Given a tree $\xi \in T_{\Sigma}^{\omega}$ and a path π , we denote by $\xi(\pi)$ the infinite word $\xi(\pi_1)\xi(\pi_2)\dots$ obtained by concatenating the labels of ξ along π . We denote by $\inf(\xi(\pi))$ the set of all labels occurring infinitely often in $\xi(\pi)$.

We will also find it convenient to represent trees over some given alphabet $\Sigma = \{a_1, \ldots, a_n\}$ as structures over the signature $\mathbb{S} = \mathbb{S}_{\mathbf{P}} = \{\succ_0, \succ_1, \mathbb{P}_{a_1}, \ldots, \mathbb{P}_{a_n}\}$: Thereby, a tree $\xi \in T_{\Sigma}^{\omega}$ will be represented by the structure \mathfrak{A}_{ξ} with $A_{\xi} = \{0, 1\}^*$, where $\succ_0^{\mathfrak{A}_{\xi}} = \{(w, w0) \mid w \in \{0, 1\}^*\}$ and $\succ_1^{\mathfrak{A}_{\xi}} = \{(w, w1) \mid w \in \{0, 1\}^*\}$ while $\mathbb{P}_{a_i}^{\mathfrak{A}_{\xi}} = \{u \in \{0, 1\}^* \mid \xi(u) = a_i\}$ for each $i \in [n]$. When there is no danger of confusion, we will simply write ξ instead of \mathfrak{A}_{ξ} .

3 Syntax and Semantics of ω MSO \rtimes BAPA

We now introduce the logic ω MSO×BAPA. The underlying "design principles" for this logical formalism are to have a language that syntactically subsumes and tightly integrates CMSO and BAPA, while still exhibiting favorable computational properties, even over countably infinite structures. To this end, we will first define the language ω MSO·BAPA and then obtain ω MSO×BAPA by imposing some syntactic restrictions on the usage of variables.

▶ Definition 1 (Syntax of ω MSO·BAPA). Given a signature $\mathbb{S} = \mathbb{S}_{\mathbf{C}} \cup \mathbb{S}_{\mathbf{P}}$, together with three countable and pairwise disjoint sets \mathbf{V}_{ind} of individual variables (denoted x, y, z, ...), \mathbf{V}_{set} of set variables (denoted X, Y, Z, ...), and \mathbf{V}_{num} of number variables (denoted $\mathcal{K}, \ell, m, n...$), we define the following sets of expressions by mutual induction:

33:4 Adding Presburger Arithmetic to MSO Logic over Tree-Interpretable Structures

- the set **I** of individual terms: $\iota ::= \mathbf{a} \mid x$
- the set **S** of set terms (P being a unary predicate): $S := \{a\} | P | X | S^c | S_1 \cap S_2 | S_1 \cup S_2$ ■ the set **N** of number terms:² $t := n | \infty | k | \#S | mt | t_1 + t_2$

(with $n \in \mathbb{N}$ and $m \in \mathbb{N} \setminus \{0\}$; we use typewriter font to indicate that we mean an explicit representation of a constant natural number n or m rather than the symbol "n" or "m") the set \mathbf{F} of (unrestricted) formulae:

$$\begin{split} \varphi &\coloneqq & \mathbb{Q}(\iota_1, \dots, \iota_n) \mid S(\iota) \mid t \leq_{\texttt{fin}} t' \mid t \leq t' \mid \texttt{\#}S \equiv_{\texttt{n}} \texttt{m} \mid \text{Fin}(S) \mid \texttt{true} \mid \texttt{false} \mid \\ & \neg \varphi \mid \varphi \land \varphi' \mid \varphi \lor \varphi' \mid \exists x.\varphi \mid \forall x.\varphi \mid \exists X.\varphi \mid \forall X.\varphi \mid \exists k.\varphi \mid \forall k.\varphi \end{split}$$

The first six types of atomic formulae will be referred to as predicate atoms, set atoms, classical Presburger atoms, modern Presburger atoms, modulo atoms, and finiteness atoms, respectively. We use Presburger atoms and write $t \leq_{(fin)} t'$ to jointly refer to the classical and modern variants. A Presburger atom $t \leq_{(fin)} t'$ is called simple, if it contains at most one occurrence of a term of the shape #S and no occurrences of number variables.

▶ Definition 2 (Semantics of ω MSO·BAPA). A variable assignment (for a structure \mathfrak{A}) is a function ν that maps

- every individual variable $x \in \mathbf{V}_{ind}$ to a domain element $\nu(x) \in A$,
- every set variable $X \in \mathbf{V}_{set}$ to a subset $\nu(X) \subseteq A$ of the domain, and
- every number variable $\& \& \in \mathbf{V}_{num}$ to a number $\nu(\&) \in \mathbb{N} \cup \{\infty\}$.
- We write $\nu_{x\mapsto a}$, $\nu_{X\mapsto A'}$, and $\nu_{\hbar\mapsto n}$ to denote ν updated in the way indicated in the subscript. Given an interpretation \mathfrak{A} and a variable assignment ν , we let the function \mathfrak{A}^{ν} map
- I to A by letting $a^{\mathfrak{A},\nu} = a^{\mathfrak{A}}$ and $x^{\mathfrak{A},\nu} = \nu(x)$,

S to 2^A by letting

$$\begin{cases} \mathbf{a} \}^{\mathfrak{A},\nu} = \{ \mathbf{a}^{\mathfrak{A},\nu} \} & X^{\mathfrak{A},\nu} = \nu(X) & (S_1 \cap S_2)^{\mathfrak{A},\nu} = S_1^{\mathfrak{A},\nu} \cap S_2^{\mathfrak{A},\nu} \\ \mathbf{P}^{\mathfrak{A},\nu} = \mathbf{P}^{\mathfrak{A}} & (S^c)^{\mathfrak{A},\nu} = A \setminus S^{\mathfrak{A},\nu} & (S_1 \cup S_2)^{\mathfrak{A},\nu} = S_1^{\mathfrak{A},\nu} \cup S_2^{\mathfrak{A},\nu} \end{cases}$$

N to $\mathbb{N} \cup \{\infty\}$ by letting

$$\begin{array}{lll} \mathbf{n}^{\mathfrak{A},\nu} = n & & & & & \\ \mathbf{n}^{\mathfrak{A},\nu} = n & & & & \\ \mathbf{m}^{\mathfrak{A},\nu} = & & & \\ \mathbf{m}^{\mathfrak{A},\nu} = & & & \\ \mathbf{m}^{\mathfrak{A},\nu} = & & & \\ \end{array}$$

Finally we define satisfaction of formulae from ${f F}$ as follows: ${\mathfrak A}, \nu$ satisfies

 $\mathbf{Q}(\iota_1,...,\iota_n) \text{ iff } ((\iota_1)^{\mathfrak{A},\nu},...,(\iota_n)^{\mathfrak{A},\nu}) \in \mathbf{Q}^{\mathfrak{A}}$ $\varphi_1 \land \varphi_2 \text{ iff } \mathfrak{A}, \nu \models \varphi_1 \text{ and } \mathfrak{A}, \nu \models \varphi_2$ iff $\iota^{\mathfrak{A},\nu} \in S^{\mathfrak{A},\nu}$ $S(\iota)$ $\varphi_1 \lor \varphi_2 \text{ iff } \mathfrak{A}, \nu \models \varphi_1 \text{ or } \mathfrak{A}, \nu \models \varphi_2$ iff $t_1^{\mathfrak{A},\nu} \leq t_2^{\mathfrak{A},\nu}$ $t_1 \leq t_2$ $\exists x. \varphi \quad iff \ \mathfrak{A}, \nu_{x \mapsto a} \models \varphi \ for \ some \ a \in A$ $\forall x.\varphi \quad iff \ \mathfrak{A}, \nu_{x\mapsto a} \models \varphi \ for \ all \ a \in A$ $iff \ (\#S)^{\mathfrak{A},\nu} = m \mod n$ $\#S \equiv_{\mathtt{n}} \mathtt{m}$ $\exists X.\varphi \quad i\!f\!f \ \mathfrak{A}, \nu_{X\mapsto A'} \models \varphi \ for \ some \ A' \subseteq A$ and $(\#S)^{\mathfrak{A},\nu} < \infty$ $\forall X.\varphi \quad i\!f\!f \ \mathfrak{A}, \nu_{X\mapsto A'} \models \varphi \ for \ all \ A' \subseteq A$ iff $|S^{\mathfrak{A},\nu}| < \infty$ $\exists \hbar. \varphi \quad iff \ \mathfrak{A}, \nu_{\hbar \mapsto n} \models \varphi \quad for \ some \ n \in \mathbb{N} \cup \{\infty\}$ $\operatorname{Fin}(S)$ $\forall k.\varphi \quad iff \ \mathfrak{A}, \nu_{h \mapsto n} \models \varphi \quad for \ all \ n \in \mathbb{N} \cup \{\infty\}$ iff $\mathfrak{A}, \nu \not\models \varphi$ $\neg \varphi$

Plus, we always let $\mathfrak{A}, \nu \models \text{true}$ and $\mathfrak{A}, \nu \not\models \text{false}$. For a formula φ , its free variables (denoted free(φ)) are defined as usual; φ is a sentence if free(φ) = \emptyset . For sentences, ν does not influence satisfaction, which allows us to write $\mathfrak{A} \models \varphi$ and call \mathfrak{A} a model of φ in case $\mathfrak{A}, \nu \models \varphi$ holds for any ν . We call φ satisfiable if it has a model.

² We will consider number terms obtainable from each other through basic transformations (reordering, factoring, summarizing, rules for ∞) as syntactically equal, allowing us to focus on simplified expressions.

Note that, for notational homogeneity, we choose to write $X(\iota)$ instead of $\iota \in X$. Where convenient, we will also make use of the Boolean connectives \Rightarrow and \Leftrightarrow as abbreviations with the usual meaning. While the original syntax of ω MSO·BAPA does not provide an explicit equality predicate, both individual and set equality can be expressed (see further below).

▶ Definition 3 (Syntax of ω MSO×BAPA). From now on, we will make the following assumption (which is easily obtainable via renaming): In every formula, all quantifications use different variable names and these are disjoint from the names of free variables. Given an ω MSO·BAPA formula φ satisfying this assumption, we analyze its constituents as follows:

- A (set or individual) variable is called assertive, if it is free, or it is existentially quantified and the quantification does not occur inside the scope of a negation or of a universal (set, individual, or number) quantifier.
- The set of delicate individual and set variables is the smallest set of (non-assertive) variables satisfying the following:
 - Every non-assertive set variable occurring in a non-simple Presburger atom is delicate.
 - If some atom contains a delicate (individual or set) variable, then all of this atom's non-assertive (individual or set) variables are delicate.

Then, φ is an ω MSO \rtimes BAPA formula iff each of its predicate atoms $Q(\cdots)$ contains at most one delicate variable (possibly in multiple occurrences).

It is easy to see that, despite the above restrictions, ω MSO \bowtie BAPA entirely encompasses CMSO and MSO \exists Card (no delicate variables) as well as BAPA (no predicates of arity >1). For convenience and better readability, we will make use of the following abbreviations.

$$\begin{array}{ll} x = y & := \forall Z.Z(x) \Leftrightarrow Z(y) & \exists x \in S.\varphi & := \exists x.S(x) \land \varphi \\ S \neq \emptyset & := \exists z.S(z) & \forall x \in S.\varphi & := \forall x.S(x) \Rightarrow \varphi \\ S \subseteq S' & := \forall z.S(z) \Rightarrow S'(z) & t = t' & := (t \leq t') \land (t' \leq t) \\ S = S' & := (S \subseteq S') \land (S' \subseteq S) & t =_{\mathrm{fin}} t' & := (t \leq_{\mathrm{fin}} t') \land (t' \leq_{\mathrm{fin}} t) \end{array}$$

An analysis of these abbreviations reveals that ω MSO \rtimes BAPA allows for the variables x, yand set variables in S, S' in these abbreviations to be delicate. We will also employ shortcuts specific to the signature $\{\succ_0, \succ_1, \mathsf{P}_a \mid a \in \Sigma\}$ for Σ -labeled trees. Contrary to above, in these shortcuts, x, y, X, Y must not be delicate to warrant inclusion in ω MSO \rtimes BAPA (Obs. \dagger).

$$\begin{split} X(x.i) &\coloneqq \exists y.x \succ_i y \land X(y) \\ x \succ y &\coloneqq (x \succ_0 y) \lor (x \succ_1 y) \\ \varphi_{\text{root}}(x) &\coloneqq \neg \exists z.(z \succ x) \\ \varphi_{\uparrow \text{clsd}}(X) &\coloneqq \forall z.X(z.0) \lor X(z.1) \Rightarrow X(z) \\ x \succ^* y &\coloneqq \forall Z.Z(y) \land \varphi_{\uparrow \text{clsd}}(Z) \Rightarrow Z(x) \\ x \succ^+ y &\coloneqq (x \succ^* y) \land (x \neq y) \\ \varphi_{\downarrow}(x,X) &\coloneqq \forall z.(X(z) \Leftrightarrow x \succ^* z) \\ \varphi_{\text{path}}(X) &\coloneqq X \neq \emptyset \land \varphi_{\uparrow \text{clsd}}(X) \land \forall z \in X.(X(z.0) \Leftrightarrow \neg X(z.1)) \\ \varphi_{\text{inf}}^{\cap}(X,Y) &\coloneqq \exists Z.Z \subseteq X \land Z \subseteq Y \land \varphi_{\text{inf}}(Z) \end{split}$$

► **Example 4.** We use ω MSO×BAPA to specify the class of all labeled infinite binary trees over the alphabet $\Sigma = \{$ blue, red, green, yellow, black $\}$ satisfying the following property:

"There is a path X and some node x on X such that the following hold:

- 1. For every infinite selection Y of blue nodes from the x-descendants on the path X, there is a selection Y' of red nodes from the whole tree, such that
 - **a.** Y and Y' contain the same number of nodes with infinitely many green descendants,
 - **b.** Y contains twice as many nodes as Y' having less than 10 yellow descendants.
- 2. For every finite selection Z of blue x-descendants, the total number of nodes lying on paths from x to nodes of Z is even."

 $\exists X.\exists x.\varphi_{\text{path}}(X) \land X(x) \land \exists V_0.\varphi_{\downarrow}(x,V_0) \land$

$$\left(\exists V_1. (\forall v_1.V_1(v_1) \Leftrightarrow \exists V_{\downarrow}^{v_1}. \varphi_{\downarrow}(v_1, V_{\downarrow}^{v_1}) \land \neg \operatorname{Fin}(V_{\downarrow}^{v_1} \cap \mathsf{P}_{\operatorname{green}}) \right) \land \\ \exists V_2. (\forall v_2.V_2(v_2) \Leftrightarrow \exists V_{\downarrow}^{v_2}. \varphi_{\downarrow}(v_2, V_{\downarrow}^{v_2}) \land \#(V_{\downarrow}^{v_2} \cap \mathsf{P}_{\operatorname{yellow}}) \leq \mathsf{10}) \land \\ \left(\forall Y. (\neg \operatorname{Fin}(Y) \land Y \subseteq X \cap V_0 \cap \mathsf{P}_{\operatorname{blue}}) \Rightarrow \\ \exists Y'.Y' \subseteq \mathsf{P}_{\operatorname{red}} \land \#(Y \cap V_1) = \#(Y' \cap V_1) \land \#(Y \cap V_2) = \mathsf{2} \, \#(Y' \cap V_2) \right) \right) \land \\ \left(\forall Z. (\operatorname{Fin}(Z) \land Z \subseteq V_0 \cap \mathsf{P}_{\operatorname{blue}}) \Rightarrow \\ \exists V_3. (\forall v_3.V_3(v_3) \Leftrightarrow (x \succ^+ v_3 \land \exists z \in Z.v_3 \succ^* z')) \land \#V_3 \equiv_2 \mathsf{0} \right)$$

Therein, we use set variables capturing all descendants of x (V_0); all nodes with infinitely many green descendants (V_1); all nodes with less than 10 yellow descendants (V_2); and all nodes between x and elements of Z (V_3). Analysing the variables yields that X, x, V_0 , V_1 , and V_2 are assertive, while Y and Y' are delicate due to their occurrence in the non-simple Presburger atoms in the fifth line. Delicacy is not inherited further, thus no two delicate variables occur in any predicate atom. Therefore the formula is indeed in ω MSO \rtimes BAPA. Note that it is crucial that V_1 and V_2 are defined "prematurely" outside the scope of $\forall Y$, so they become assertive and thus their occurrence in the (non-simple) Presburger atoms does not turn them delicate. This technique of "encapsulating" unary descriptions into assertive set variables unveils significant additional expressiveness of ω MSO \rtimes BAPA. See also Section 10 for a discussion on a handier syntax for this.

4 Mildly Extending ω MSO \rtimes BAPA Leads to Undecidability

Just slightly relaxing the syntax of ω MSO \bowtie BAPA allows us to express Hilbert's 10th Problem.

▶ Definition 5 (Positive Diophantine Equation). A positive Diophantine equation \mathcal{D} is a tuple $(NV, M, (n_w)_{w \in M}, (m_w)_{w \in M})$ where NV is a non-empty, ordered set $\{z_1, \ldots, z_k\}$ of number variables; M (the variable products or monomials) is a finite and non-empty, prefix-closed set of sorted variable sequences, i.e.,

$$M \subseteq \{\underbrace{z_1 \dots z_1}_{i_1} \dots \underbrace{z_k \dots z_k}_{i_k} \mid i_1, \dots, i_k \in \mathbb{N}\};$$

and all n_w and m_w are from \mathbb{N} and encode the monomial coefficients on either side of the equation. A positive Diophantine equation is solvable if it admits a solution, where a solution for $\mathcal{D} = (NV, M, (n_w)_{w \in M}, (m_w)_{w \in M})$ is a variable assignment $\nu : NV \to \mathbb{N}$ satisfying

$$\sum_{w=\mathbf{x}_1^{i_1}\ldots\mathbf{x}_k^{i_k}\in M} n_w\cdot\nu(\mathbf{x}_1)^{i_1}\cdot\ldots\cdot\nu(\mathbf{x}_k)^{i_k} = \sum_{w=\mathbf{x}_1^{i_1}\ldots\mathbf{x}_k^{i_k}\in M} m_w\cdot\nu(\mathbf{x}_1)^{i_1}\cdot\ldots\cdot\nu(\mathbf{x}_k)^{i_k}$$

$$\varphi_{\text{lab}} \coloneqq \exists x \in \mathsf{P}_{\varepsilon}.\varphi_{\text{root}}(x) \land \bigwedge_{w \in M} \left(\forall x \in \mathsf{P}_{w} \cup \mathsf{P}_{\hat{w}}.\forall y.x \succ y \Rightarrow \mathsf{P}_{\hat{w}}(y) \lor \bigvee_{w z_{i} \in M} \mathsf{P}_{w z_{i}}(y) \right)$$

$$\stackrel{'w}{\underset{w z_{i}}{\overset{'z_{i}}{w_{w}}}} \stackrel{'w}{\underset{w z_{i}}{\overset{w z_{i}}{w_{w}}}} \varphi_{\text{prod}} \coloneqq \bigwedge_{w,w z_{i} \in M} \forall y \in \mathsf{P}_{w}.\exists Z.\varphi_{\downarrow}(y,Z) \land \#(Z \cap \mathsf{P}_{w z_{i}}) =_{\text{fin}} \#_{\mathsf{P}_{z_{i}}}$$

$$\stackrel{'w}{\underset{w z_{i}}{\overset{w z_{i}}{w_{z_{i}}}}} \stackrel{'w}{\underset{w z_{i}}{\overset{w z_{i}}{w_{z_{i}}}}} \varphi_{\text{sol}} \coloneqq \sum_{w \in M} \mathsf{n}_{w} \#_{\mathsf{P}_{w}} =_{\text{fin}} \sum_{w \in M} \mathsf{n}_{w} \#_{\mathsf{P}_{w}}$$

Figure 1 Illustration of the intended model structure and definition of $\varphi_{\mathcal{D}} := \varphi_{\text{lab}} \land \varphi_{\text{prod}} \land \varphi_{\text{sol}}$.

Solvability of positive Diophantine equations is undecidable, which is a straightforward consequence of the undecidability of arbitrary Diophantine equations over integers [48].

We will show that for any \mathcal{D} , we can compute an ω MSO·BAPA sentence $\varphi_{\mathcal{D}}$ whose satisfiability over labeled trees coincides with solvability of \mathcal{D} , despite $\varphi_{\mathcal{D}}$ being only "minimally outside" ω MSO \rtimes BAPA — also contrasting the fact that sentences of this shape still warrant decidable satisfiability over finite words [39, Thm. 8.13].

As detailed in Figure 1, we let $\varphi_{\mathcal{D}} \coloneqq \varphi_{\text{lab}} \land \varphi_{\text{prod}} \land \varphi_{\text{sol}}$ characterize trees labeled by w and \hat{w} , for $w \in M$, such that each model ξ of $\varphi_{\mathcal{D}}$ corresponds to a solution ν of \mathcal{D} as follows: for each $z \in NV$, the number of nodes in ξ labeled with z (i.e., $\#P_z$) equals the number that ν assigns to z. Likewise, for each variable product $wz_i \in M$, we ensure that $\#P_{wz_i} = \#P_w \cdot \#P_{z_i}$. To this end, we stipulate via φ_{lab} that for any w, all w-labeled nodes are pairwise \succ^* -incomparable, and every wz-labeled node has exactly one w-labeled ancestor (using the label \hat{w} for "padding" between w and wz_i), and we enforce via φ_{prod} that for any $w, wz_i \in M$, each subtree rooted in a w-labeled node contains precisely as many wz_i -labeled nodes as there are z_i -labeled nodes in the whole tree. Finally, under the conditions enforced by φ_{lab} and $\varphi_{\text{prod}}, \varphi_{\text{sol}}$ implements that the model indeed encodes a solution of the given \mathcal{D} .

While the first conjunct is pure MSO and the third is a variable-free Presburger atom, the second is not in ω MSO \bowtie BAPA: $\exists Z$ occurs inside the scope of $\forall y$, thus Z is not assertive. Yet, as discussed in Section 3 (Obs. †), this is at odds with Z occurring in $\varphi_{\downarrow}(y, Z)$.

▶ **Proposition 6.** For any positive Diophantine equation \mathcal{D} , satisfaction of $\varphi_{\mathcal{D}}$ over (finite or infinite) labeled trees coincides with solvability of \mathcal{D} . Consequently, satisfiability of the class of $\omega MSO \cdot BAPA$ sentences of the shape $\varphi_{\mathcal{D}}$ is undecidable.

5 Transformation into Normal Form

Toward establishing our decidability result, we show that ω MSO \rtimes BAPA formulae can be transformed into a specific, very restricted normal form. To this end, we use a variety of techniques, mostly known from the literature, but with some adjustments to our setting; thus, due to space, we will restrict ourselves to a high-level description and examples. The normalization procedure is subdivided into two phases: The first phase, establishing the general normal form (GNF), is valid independently of the underlying class of structures. The second phase, yielding the tree normal form (TNF), is specific to the class of labeled trees.

Given an ω MSO \rtimes BAPA formula, substitute complex set expressions in modulo and finiteness atoms by new set variables (e.g. Fin($\mathbb{P} \cap X$) becomes $\exists Y.(Y = \mathbb{P} \cap X) \wedge \text{Fin}(Y)$), remove set operations from set atoms (e.g. turning ($\mathbb{P}^c \cap X$)(y) into $\neg \mathbb{P}(y) \wedge X(y)$), and rewrite all simple Presburger atoms into plain MSO (e.g. $2 \# \mathbb{P} \leq 3$ becomes $\forall xy.\mathbb{P}(x) \wedge \mathbb{P}(y) \Rightarrow x=y$). Then, *skolemize* all assertive variables (e.g. $\exists x.\exists X.\forall y.\mathbb{R}(x,y)\Rightarrow X(y)$ becomes $\forall y.\mathbb{R}(c_x,y)\Rightarrow\mathbb{P}_X(y)$). Next "*presburgerize*" all non-Presburger atoms containing (only) delicate variables (e.g. replacing $\# X \equiv_3 1$ with $\exists \pounds. \# X =_{fin} 3 \pounds + 1$), which may require to turn delicate individual

33:8 Adding Presburger Arithmetic to MSO Logic over Tree-Interpretable Structures

into set variables (e.g. $\forall y.P(y) \Rightarrow X(y)$ becomes $\forall Y.(\#Y = 1) \land 1 \leq \#(P \cap Y) \Rightarrow 1 \leq \#(X \cap Y)$). The resulting formula exhibits a clear separation of variable usage: Presburger atoms use delicate and number variables, all other atoms use non-delicate variables. In a subsequent step, we "disentangle" the quantifiers, such that the scopes of quantified number or delicate variables are strictly separated from those of non-delicate variables.³

We next apply "vennification": a technique known from BAPA. In essence, we introduce new number variables to count the number of elements contained in every Venn region, that is, every possible combination of set (non-)memberships (with this, $\#(\mathbb{P} \cup X) \leq \#\mathbb{P}^c$ becomes $\hbar_{\mathbb{P} \cap X} + \hbar_{\mathbb{P}^c \cap X} + \hbar_{\mathbb{P}^c \cap X^c} \leq \hbar_{\mathbb{P}^c \cap X^c}$). This allows us to remove all delicate set variables from our formula. We are now in the setting where we can apply the well-known quantifier elimination for Presburger Arithmetic over the "purely arithmetic" subformulae (which may produce new modulo atoms) – since the latter is classically defined for N instead of $\mathbb{N} \cup \{\infty\}$, we require a pre-processing step implementing a vast case-distinction as to which of the Venn regions are infinite. As a consequence, we obtain a formula free of number variables, with all Presburger atoms being classic and outside any quantifier scope.

Finally, we "de-skolemize": all constants and unary predicates introduced via the initial skolemization, but also by the intermediate transformation steps, are projected away from the signature, re-interpreting them as existentially quantified individual and set variables. We thus recover "proper" equivalence with the initial formula. Last, we bring the formula in disjunctive normal form and pull the trailing existential individual quantifiers inside.

▶ Definition 7 (General Normal Form). A Parikh constraint is a classical Presburger atom without number variables and where all occurring set terms are set variables. An ω MSO×BAPA formula is in general normal form (GNF), if it is of the shape

$$\exists X_1.\cdots \exists X_n. \bigvee_{i=1}^k \left(\varphi_i \wedge \bigwedge_{j=1}^{l_i} \chi_{i,j}\right),$$

where the φ_i are CMSO formulae,⁴ whereas the $\chi_{i,j}$ are (unnegated) Parikh constraints.

▶ **Theorem 8.** For every ω MSO×BAPA formula φ , it is possible to compute an equivalent formula φ' in general normal form.

We now focus on the case of labeled trees. Very similar to the case of CMSO, under this assumption, we can equivalently transform the GNF formula into one without occurrences of modulo and finiteness atoms. We rewrite $\#X \equiv_n m$ into the formula

$$\operatorname{Fin}(X) \wedge \exists X_{0} \dots \exists X_{n-1} \left(\exists x. \left(\varphi_{\operatorname{root}}(x) \wedge \bigwedge_{\substack{0 \le i < n \\ i \ne m}} \neg X_{i}(x) \right) \wedge \forall x. \left(\left(\exists y \in X. x \succ^{*} y \right) \vee X_{0}(x) \right) \wedge \right) \\ \bigwedge_{i,j \in \{0,\dots,n-1\}} \forall z. \left(X_{i}(z.0) \wedge X_{j}(z.1) \Rightarrow \left(\neg X(z) \Rightarrow X_{i \oplus j}(z) \right) \wedge \left(X(z) \Rightarrow X_{i \oplus j \oplus 1}(z) \right) \right) \right),$$

where \oplus denotes addition modulo *n*. Finally, we replace all occurrences of Fin(X) by $\varphi_{\text{fin}}(X)$, as defined in Section 3. Thus, when employing ω MSO \rtimes BAPA to describe labeled trees, we can confine ourselves to an even more restrictive normal form.

▶ **Definition 9** (Tree Normal Form). An ω MSO \rtimes BAPA formula is in tree normal form (*TNF*), if it is of the shape

 $\exists X_1.\cdots \exists X_n. \bigvee_{i=1}^k \left(\varphi_i \wedge \bigwedge_{j=1}^{l_i} \chi_{i,j}\right),\$

where the φ_i are plain MSO formulae and the $\chi_{i,j}$ are (unnegated) Parikh constraints.

▶ **Theorem 10.** For every ω MSO \rtimes BAPA formula φ , it is possible to compute a formula φ' in tree normal form that is equivalent to φ over all labeled infinite binary trees.

³ While this transformation is not very complicated technically, it may incur nonelementary blowup.

⁴ Recall that CMSO is MSO with modulo and finiteness atoms over set variables.

6 Parikh-Muller Tree Automata

In this section, we introduce a novel type of automata, combining and generalizing Parikh tree automata and Muller tree automata. We prove that the tree languages recognized by this automaton type coincide with those definable by TNF formulae. Moreover, we show that the emptiness problem of this automaton model is decidable. In combination, this yields us decidable satisfiability of ω MSO \rtimes BAPA over labeled infinite binary trees.

Variable-adorned Trees, Semilinear Sets, and Extended Parikh Maps

Given a finite set $\mathbf{V} \subseteq (\mathbf{V}_{ind} \cup \mathbf{V}_{set})$, we denote by $\Phi_{\mathbf{V}}$ the set of all variable assignments of variables from \mathbf{V} to elements/subsets of $\{0,1\}^*$. The set of \mathbf{V} -models of a formula φ is the set $\mathcal{L}_{\mathbf{V}}(\varphi) \coloneqq \{(\xi,\nu) \mid \xi \in T_{\Sigma}^{\omega}, \nu \in \Phi_{\mathbf{V}}, \xi, \nu \models \varphi\}$ and by $\mathcal{L}(\varphi)$ we mean $\mathcal{L}_{\text{free}(\varphi)}(\varphi)$. To represent \mathbf{V} -models, it is convenient to encode variable assignments $\nu \in \Phi_{\mathbf{V}}$ into the alphabet. For this, we let $\Sigma_{\mathbf{V}} = \Sigma \times 2^{\mathbf{V}}$ be a new alphabet and identify Σ_{\emptyset} with Σ . We say that a tree $\xi \in T_{\Sigma_{\mathbf{V}}}^{\omega}$ is valid (i.e., it encodes a variable assignment) if for each individual variable x in \mathbf{V} there is exactly one position in ξ where x occurs. As there is a bijection between $T_{\Sigma}^{\omega} \times \Phi_{\mathbf{V}}$ and the set of all valid trees in $T_{\Sigma_{\mathbf{V}}}^{\omega}$, we use these two views interchangeably.

A set $C \subseteq \mathbb{N}^s$, $s \ge 1$, is *linear* if it is of the form $C = \{\vec{v}_0 + \sum_{i \in [l]} m_i \vec{v}_i \mid m_1, \ldots, m_l \in \mathbb{N}\}$ for some $l \in \mathbb{N}$ and vectors $\vec{v}_0, \ldots, \vec{v}_l \in \mathbb{N}^s$. Any finite union of linear sets is called *semilinear*.

Given two vectors $\vec{v} = (v_1, \ldots, v_s) \in \mathbb{N}^s$ and $\vec{v}' = (v'_1, \ldots, v'_{s'}) \in \mathbb{N}^{s'}$, we define their concatenation $\vec{v} \cdot \vec{v}'$ as the vector $(v_1, \ldots, v_s, v'_1, \ldots, v'_{s'}) \in \mathbb{N}^{s+s'}$. This definition is lifted to sets by letting $C \cdot C' = \{\vec{v} \cdot \vec{v}' \mid \vec{v} \in C, \ \vec{v}' \in C'\} \subseteq \mathbb{N}^{s+s'}$ for $C \subseteq \mathbb{N}^s, C' \subseteq \mathbb{N}^{s'}$.

▶ Lemma 11 ([30, 31]). The family of semilinear sets of \mathbb{N}^s coincides with the family of Presburger sets of \mathbb{N}^s (i.e., sets of the form $\{(x_1, \ldots, x_s) \mid \varphi(x_1, \ldots, x_s)\}$ for a Presburger formula φ). Semilinear sets are closed under union, intersection, complement, and concatenation.

Given an alphabet Σ and some finite $D \subseteq \mathbb{N}^s$ for $s \geq 1$, our automaton model works with symbols from $\Sigma \times D$. Thus we use the *projections* $\cdot_{\Sigma} : \Sigma \times D \to \Sigma$ with $(a, d)_{\Sigma} = a$ and $\cdot_D : \Sigma \times D \to D$ with $(a, d)_D = d$, which we will also apply to finite and infinite trees, resulting in a pointwise substitution of labels. Moreover, the *extended Parikh map* $\Psi : T_{\Sigma \times D} \to \mathbb{N}^s$ is defined for each finite, non-empty tree $\xi \in T_{\Sigma \times D}$ by $\Psi(\xi) = \sum_{i \in \text{pos}(\xi)} (\xi(i))_D$.

Automaton Model

We now formally introduce our notion of a *Parikh-Muller Tree Automaton (PMTA)*, which recognizes infinite trees employing a Muller acceptance condition while also testing some finite initial tree part for an arithmetic property related to Parikh's commutative image [49]. This is implemented by utilizing a finite number of global counters, which are "blindly" increased throughout the run, but are read off only once a posteriori – when it is verified whether the tuple of the final counter values belongs to a given semilinear set.

▶ Definition 12 (Parikh-Muller Tree Automaton). Let Σ be an alphabet, let $s \in \mathbb{N} \setminus \{0\}$, let $D \subseteq \mathbb{N}^s$ be finite, and denote $(\Sigma \times D) \cup \Sigma$ by Ξ . A PMTA (of dimension s) is a tuple $\mathcal{A} = (Q, \Xi, q_I, \Delta, \mathcal{F}, C)$ where $Q = Q_P \cup Q_\omega \cup \{q_I\}$ is a finite set of states with Q_P, Q_ω disjoint and q_I being the initial state, $\Delta = \Delta_P \cup \Delta_\omega$ is the transition relation with

$$\Delta_P \subseteq (Q_P \cup \{q_I\}) \times (\Sigma \times D) \times Q \times Q \quad and \quad \Delta_\omega \subseteq (Q_\omega \cup \{q_I\}) \times \Sigma \times Q_\omega \times Q_\omega,$$

 $\mathcal{F} \subseteq 2^{Q_{\omega}}$ is a set of final state sets, and $C \subseteq \mathbb{N}^s$ is a semilinear set named final constraint.

33:10 Adding Presburger Arithmetic to MSO Logic over Tree-Interpretable Structures

▶ **Definition 13** (Semantics of PMTA). A run of \mathcal{A} on a tree $\zeta \in T_{\Xi}^{\omega}$ is a tree $\kappa_{\zeta} \in T_{Q}^{\omega}$ whose root is labeled with q_{I} and which respects Δ jointly with ζ . By definition of Δ , if a run exists, then $\zeta^{-1}(\Sigma \times D)$ is prefix-closed; we denote $\zeta_{|\zeta^{-1}(\Sigma \times D)}$ by ζ_{cnt} . A run κ_{ζ} is accepting if **1.** for each path π , we have $\inf(\kappa_{\zeta}(\pi)) \in \mathcal{F}$, and

2. if $pos(\zeta_{cnt}) \neq \emptyset$, then $\Psi(\zeta_{cnt}) \in C$.

Note that, by the first condition, κ_{ζ} being accepting implies finiteness of ζ_{cnt} and, thus, well-definedness of the sum in $\Psi(\zeta_{cnt})$. The set of all accepting runs of \mathcal{A} on ζ will be denoted by $\operatorname{Run}_{\mathcal{A}}(\zeta)$. Then, the tree language of \mathcal{A} , denoted by $\mathcal{L}(\mathcal{A})$, is the set

 $\mathcal{L}(\mathcal{A}) \coloneqq \{\xi \in T_{\Sigma}^{\omega} \mid \exists \zeta \in T_{\Xi}^{\omega} \text{ with } \operatorname{Run}_{\mathcal{A}}(\zeta) \neq \emptyset \text{ and } (\zeta)_{\Sigma} = \xi \}.$

We highlight that, by choosing $\Delta_P = \emptyset$, we reobtain the well-known concept of a *Muller* tree automaton (MTA). In this case, we can drop Q_P , D, Δ_P , and C from \mathcal{A} 's specification without affecting its semantics. Thus, we define an MTA \mathcal{A} by the tuple $(Q_{\omega}, \Sigma, q_I, \Delta_{\omega}, \mathcal{F})$.

For alphabets Σ, Γ , a relabeling (from Σ to Γ) is a mapping $\tau \colon \Sigma \to \mathcal{P}(\Gamma)$. We extend it to a mapping $\tau \colon T_{\Sigma}^{\omega} \to \mathcal{P}(T_{\Gamma}^{\omega})$ by letting $\xi' \in \tau(\xi)$ if and only if for each position $\varrho \in \{0,1\}^*$, we have $\xi'(\varrho) \in \tau(\xi(\varrho))$. Note that the reverse τ^{-1} of a relabeling τ is again a relabeling.

▶ **Proposition 14.** The set of tree languages recognized by Parikh-Muller tree automata is closed under union, intersection, and relabeling.

Proof (sketch). As the proof techniques are rather standard and some of them were already presented in earlier work [37], we only sketch the main ideas here. Let \mathcal{A}_1 and \mathcal{A}_2 be PMTA.

For the union, we construct a PMTA that starts in a fresh initial state. From there, it can either enter the transitions of \mathcal{A}_1 or of \mathcal{A}_2 ; we keep apart the final constraints of \mathcal{A}_1 and \mathcal{A}_2 by using one additional dimension. The *intersection* PMTA is constructed as the Cartesian product of \mathcal{A}_1 and \mathcal{A}_2 ; it uses the concatenation of final constraints of both given PMTA and, as \mathcal{A}_1 and \mathcal{A}_2 might not "arithmetically test" the same initial tree part, it can nondeterministically freeze parts of its counters on different paths. *Relabeling* is trivial.

Correspondence of PMTA and ω MSO \bowtie BAPA

We now provide a logical characterization of PMTAs, by showing that a tree language is recognized by a PMTA precisely if it is the set of tree models of some ω MSO×BAPA sentence. The "only if" part is established by Proposition 15 and the "if" part by Proposition 17.

▶ **Proposition 15.** For any PMTA \mathcal{A} , there is an ω MSO \bowtie BAPA sentence φ with $\mathcal{L}(\mathcal{A}) = \mathcal{L}(\varphi)$.

Proof. Given a PMTA $\mathcal{A} = (Q, \Xi, q_I, \Delta, \mathcal{F}, C)$, we adopt (and slightly simplify) the idea from [41, Thm. 10] of how to encode counter values and the semilinear set C, and combine it with the usual construction to define the behavior of an MTA by means of an MSO formula: The existence of a run is defined by a sequence of existential set quantifiers representing the states of \mathcal{A} ; one additional universal set quantifier ranging over paths is used to encode the Muller acceptance condition. Furthermore, we (outermost) existentially quantify over "counter contributions" using set quantifiers $Z_1^0, \ldots, Z_1^K, \ldots, Z_s^0, \ldots, Z_s^K$ (with s being the number of counters and K the greatest counter increment occurring in \mathcal{A} 's transitions) – the presence of a variable $Z_i^{d_i}$ at a position indicates that d_i has to be added to the *i*th counter to simulate the extended Parikh map. Then we enforce satisfaction of the final constraint Cby adding the conjunct φ_C defined as follows: By definition of C, there are $k, l \in \mathbb{N} \setminus \{0\}$ and linear polynomials $p_1, \ldots, p_k \colon \mathbb{N}^l \to \mathbb{N}^s$ such that C is the union of the images of p_1, \ldots, p_k .

Assume $p_g(m_1, \ldots, m_l) = \vec{v}_0 + m_1 \vec{v}_1 + \ldots + m_l \vec{v}_l$ with $\vec{v}_j = (v_{j,1}, \ldots, v_{j,s})$. Then, using number variables m_1, \ldots, m_l , we encode p_g by

$$\varphi_{p_g} \coloneqq \exists m_1 \ldots \exists m_l . \bigwedge_{i=1}^s \left(\sum_{d=0}^K \mathrm{d} \# Z_i^d =_{\texttt{fin}} \mathtt{v}_{0,i} + \mathtt{v}_{1,i} m_1 + \ldots + \mathtt{v}_{l,i} m_l \right),$$

and let $\varphi_C \coloneqq \left(\bigwedge_{i=1}^s \bigwedge_{d=0}^K \forall x. \neg Z_i^d(x) \right) \lor \varphi_{p_1} \lor \ldots \lor \varphi_{p_k}$. This finishes the construction of the overall sentence specifying $\mathcal{L}(\mathcal{A})$, which can be easily shown to be in ω MSO \bowtie BAPA.

The other direction is proved by an induction on the structure of TNF formulae involving the closure properties of PMTA. The last piece that needs to be shown for this is the recognizability of the models of a Parikh constraint.

▶ Lemma 16. For each Parikh constraint χ there is a PMTA \mathcal{A} with $\mathcal{L}(\mathcal{A}) = \mathcal{L}(\chi)$.

Proof. We assume w.l.o.g. that χ is of the form $\mathbf{c} + \sum_{i \in [r]} \mathbf{c_i} \# X_i \leq_{\mathtt{fin}} \mathbf{d} + \sum_{j \in [k]} \mathbf{d_j} \# Y_j$ where all X_i are pairwise distinct, and all Y_j likewise. Given a subset $\theta \subseteq \operatorname{free}(\chi)$, we denote by $|\theta|_X$ the number $\sum_{X_i \in \theta} c_i$ (and similar for $|\theta|_Y$). Then, assuming $\xi(\varrho) = (\sigma_{\varrho}^{\xi}, \theta_{\varrho}^{\xi})$, we get

$$\mathcal{L}(\chi) = \{\xi \in T^{\omega}_{\Sigma_{\mathrm{free}(\chi)}} \mid c + \sum_{\varrho \in \mathrm{pos}(\xi)} |\theta^{\xi}_{\varrho}|_{X} \le d + \sum_{\varrho \in \mathrm{pos}(\xi)} |\theta^{\xi}_{\varrho}|_{Y} < \infty\}$$

and, by the condition $<\infty$, both sums can add up only finitely many non-zero elements. Therefore, $\xi \in \mathcal{L}(\chi)$ holds exactly if there is a non-empty, finite, prefix-closed $Z \subset \{0,1\}^*$ that comprises all positions holding variable assignments and for which $\xi|_Z$ satisfies χ . This condition can be verified by a PMTA defined in the following.

Let $D = \{(i, j) \mid 0 \leq i \leq \sum_{l \in [r]} c_l, 0 \leq j \leq \sum_{l \in [k]} d_l\}$. We construct the PMTA $\mathcal{A} = (\{q_I, q_f\}, \Xi, q_I, \Delta, \{\{q_f\}\}, C)$ with $\Xi = (\Sigma_{\text{free}(\chi)} \times D) \cup \Sigma_{\text{free}(\chi)}, \Delta = \Delta_P \cup \Delta_\omega$ where $\Delta_P = \{(q_I, ((\sigma, \theta), (|\theta|_X, |\theta|_Y)), q', q') \mid (\sigma, \theta) \in \Sigma_{\text{free}(\chi)}, q' \in \{q_I, q_f\}\}$ and $\Delta_\omega = \{(q_f, (\sigma, \emptyset), q_f, q_f) \mid \sigma \in \Sigma\}$ and $C = \{(z_1, z_2) \mid c + z_1 \leq_{\text{fin}} d + z_2\}$.⁵ Then, one can easily show that $\mathcal{L}(\chi) = \mathcal{L}(\mathcal{A})$.

▶ **Proposition 17.** For every ω MSO \bowtie BAPA formula φ there is a PMTA \mathcal{A} with $\mathcal{L}(\mathcal{A}) = \mathcal{L}(\varphi)$.

Proof. Let φ be an ω MSO×BAPA formula. By Theorem 10, we can assume that φ is in tree normal form, i.e., of the form $\exists X_1 \dots \exists X_n . \bigvee_{i=1}^k (\varphi_i \wedge \bigwedge_{j=1}^{l_i} \chi_{i,j})$, where φ_i are plain MSO sentences and the $\chi_{i,j}$ are (unnegated) Parikh constraints. The proof of the statement is an induction on the (now restricted) structure of φ using the well-known recognizability of MSO sentences [50], Lemma 16, and Proposition 14.

The characterization obtained through Proposition 15 and Proposition 17 also provides an answer to the open problem posed by the authors in [35, 34] to find a logical characterization for their *reachability-regular Parikh automata* (RRPA) on words: in the usual way, our tree automata can simulate word automata (by embedding words in particular trees) and it is not too hard to see that the word version of PMTA is expressively equivalent to RRPA (details can be found in the appendix). Finally, by a routine inspection of the corresponding proofs we easily observe that our logical characterization also applies to the word setting.

⁵ Note that by Lemma 11 we can use this description for a semilinear set.

33:12 Adding Presburger Arithmetic to MSO Logic over Tree-Interpretable Structures

Deciding Emptiness of Parikh-Muller Tree Automata

Our proof of decidability (and complexity) of the emptiness problem of PMTA rests on the respective results for the two components it combines, MTA and PTA. Thus, let us first recall the definition of Parikh tree automata [40, 39], slightly adjusted to our setting.

▶ **Definition 18** (Parikh tree automaton [41]). Let Σ be an alphabet, let $s \ge 1$, and let $D \subseteq \mathbb{N}^s$ be finite. A Parikh tree automaton (PTA) is a tuple $\mathcal{A} = (Q, \Sigma \times D, \delta, q_I, F, C)$ where Q is a finite set of states, $\delta \subseteq Q \times (\Sigma \times D) \times Q \times Q$ is the transition relation, q_I is the initial state, $F \subseteq Q$ is a set of final states, and $C \subseteq \mathbb{N}^s$ is a semilinear set.⁶ Given a finite tree $\xi \in T_{\Sigma \times D}$, a run of \mathcal{A} on ξ is a tree $\kappa_{\xi} \in T_Q$ with $\operatorname{pos}(\kappa_{\xi}) = \{\varepsilon\} \cup \{ui \mid u \in \operatorname{pos}(\xi), i \in \{0, 1\}\}$ and $\kappa(\varepsilon) = q_I$ that respects the transition relation of \mathcal{A} . The run κ_{ξ} is said to be accepting if $\Psi(\xi) \in C$ and $\kappa_{\xi}(u) \in F$ for each leaf $u \in \operatorname{pos}(\kappa_{\xi}) \setminus \operatorname{pos}(\xi)$; we denote the set of all accepting runs of \mathcal{A} on ξ by $\operatorname{Run}_{\mathcal{A}}(\xi)$. Finally, the tree language of \mathcal{A} , denoted $\mathcal{L}(\mathcal{A})$, is the set

 $\mathcal{L}(\mathcal{A}) \coloneqq \{\xi \in T_{\Sigma} \mid \exists \xi' \in T_{\Sigma \times D} \text{ with } \operatorname{Run}_{\mathcal{A}}(\xi') \neq \emptyset \text{ and } (\xi')_{\Sigma} = \xi \}.$

It was shown in [39] that non-emptiness is decidable for PTA. The exact complexity can be obtained by adopting [28, Proposition III.2.] to the tree setting. This ultimately enables us to establish the desired result for our automaton model.

▶ **Proposition 19** (based on [39, 28]). Given a PTA \mathcal{A} , deciding $\mathcal{L}(\mathcal{A}) \neq \emptyset$ is NP-complete.

▶ Theorem 20. Given a PMTA \mathcal{A} , deciding $\mathcal{L}(\mathcal{A}) \neq \emptyset$ is PSPACE-complete.

Proof (sketch). Let $\mathcal{A} = (Q, \Xi, q_I, \Delta, \mathcal{F}, C)$ be a PMTA with $Q = Q_P \cup Q_\omega \cup \{q_I\}, \Xi = (\Sigma \times D) \cup \Sigma$, and $\Delta = \Delta_P \cup \Delta_\omega$. We observe that each tree in the language of \mathcal{A} can be seen as some finite tree over $\Sigma \times D$ (on which the Parikh constraint is tested), having infinite trees from T_{Σ} attached to all its leafs. This allows us to reduce PMTA non-emptiness testing to deciding non-emptiness of Muller tree automata and Parikh tree automata. To this end, consider

- the Muller tree automaton $\mathcal{A}_{q_I} = (Q_\omega \cup \{q_I\}, \Sigma, q_I, \Delta_\omega, \mathcal{F}),$
- the Muller tree automata $\mathcal{A}_q = (Q_\omega, \Sigma, q, \Delta_\omega, \mathcal{F})$ for all $q \in Q_\omega$, and
- the Parikh tree automaton $\mathcal{A}_P = (Q, \Sigma \times D, q_I, \Delta_P, F_P, C)$ with $F_P = \{q \in Q_\omega \mid \mathcal{L}(\mathcal{A}_q) \neq \emptyset\}.$

As deciding $\mathcal{L}(\mathcal{A}_q) \neq \emptyset$ is PSPACE-complete [50, 38], \mathcal{A}_P can be constructed in PSPACE and, by Proposition 19, its non-emptiness can be decided in NP. Thus, the overall PSPACE complexity follows from the observation that $\mathcal{L}(\mathcal{A}) \neq \emptyset$ iff $\mathcal{L}(\mathcal{A}_{q_I}) \neq \emptyset$ or $\mathcal{L}(\mathcal{A}_P) \neq \emptyset$.

▶ Corollary 21. Satisfiability of ω MSO×BAPA over labeled infinite binary trees is decidable.

7 Decidability over Tree-Interpretable Classes of Structures

Finally, we lift the obtained decidability result for labeled trees to much more general classes of structures, leveraging the well-known technique of MSO-interpretations (also referred to as MSO-transductions or MSO-definable functions in the literature [1, 19, 25, 20, 22]).

⁶ We note that the PTAs defined in [41] were total, i.e., δ is a function of type $Q \times (\Sigma \times D) \to \mathcal{P}(Q \times Q)$. Each PTA as defined here can be made total by using an additional sink state.

▶ Definition 22 (MSO-Interpretation). Given two signatures S and S', an MSO-interpretation is a sequence $\mathcal{I} = (\varphi_{\text{Dom}}(x), (\varphi_{c}(x))_{c \in \mathbb{S}_{C}}, (\varphi_{Q}(x_{1}, \ldots, x_{ar(Q)}))_{Q \in \mathbb{S}_{P}})$ of MSO-formulae over S' (with free variables as indicated). We identify \mathcal{I} with the partial function satisfying $\mathcal{I}(\mathfrak{A}) = \mathfrak{B}$ for an S'-structure \mathfrak{A} and an S-structure \mathfrak{B} if $\{a \in A \mid \mathfrak{A}, \{x \mapsto a\} \models \varphi_{\text{Dom}}(x)\} = B$ as well as $\{a \in B \mid \mathfrak{A}, \{x \mapsto a\} \models \varphi_{c}(x)\} = \{c^{\mathfrak{B}}\}$ for every $c \in \mathbb{S}_{C}$, and, for every $Q \in \mathbb{S}_{P}$, we have $Q^{\mathfrak{B}} = \{(a_{1}, \ldots, a_{ar(Q)}) \in B^{ar(Q)} \mid \mathfrak{A}, \{x_{i} \mapsto a_{i}\}_{1 \leq i \leq ar(Q)} \models \varphi_{Q}(x_{1}, \ldots, x_{ar(Q)})\}$. For a class S of S'-structures, let $\mathcal{I}(\mathfrak{S}) \coloneqq \{\mathfrak{B} \mid \mathcal{I}(\mathfrak{A}) = \mathfrak{B}, \mathfrak{A} \in \mathfrak{S}\}$. A class \mathcal{T} of S-structures is tree-interpretable, if it coincides with $\mathcal{I}(T^{\Sigma}_{\Sigma})$ for some Σ and corresponding MSO-interpretation \mathcal{I} .

The key insight for our result is that the well-known rewritability of MSO formulae under MSO-interpretations can be lifted to ω MSO \rtimes BAPA without much effort.

▶ Lemma 23. Let \mathcal{I} be an MSO-interpretation. Then, for every ω MSO \rtimes BAPA sentence φ over \mathbb{S} one can compute an ω MSO \rtimes BAPA sentence $\varphi^{\mathcal{I}}$ over \mathbb{S}' satisfying $\mathfrak{A} \models \varphi^{\mathcal{I}} \iff \mathfrak{B} \models \varphi$ for every \mathbb{S}' -structure \mathfrak{A} and \mathbb{S} -structure \mathfrak{B} with $\mathcal{I}(\mathfrak{A}) \cong \mathfrak{B}$.

This insight can be used to show that decidability is propagated through MSO-interpretations, and thus can be guaranteed for all tree-interpretable classes, thanks to Corollary 21.

▶ **Theorem 24.** Let \$ be a class of structures over which satisfiability of ω MSO \rtimes BAPA is decidable, let \mathcal{I} be an MSO-interpretation. Then satisfiability of ω MSO \rtimes BAPA over $\mathcal{I}(\$)$ is decidable as well. In particular, ω MSO \rtimes BAPA is decidable over any tree-interpretable class.

This result allows us, in one go, to harvest several decidability results, as tree-interpretability is able to capture classes of (finite or countable) structures whose treewidth [51], cliquewidth [27, 22, 21, 36], or partitionwidth [10, 11, 26] is bounded by some value $k \in \mathbb{N}$.

▶ Corollary 25. Given a signature S, satisfiability of ω MSO \rtimes BAPA is decidable over the classes of finite or countable S-structures of bounded treewidth, cliquewidth, and partitionwidth.

8 Incorporating Two-Variable-Logics without Width Restrictions

Corollary 25 constitutes a strong decidability result, also in view of the fact that lifting the width restriction immediately leads to undecidability even for much weaker logics like FO. A feasible way to nevertheless relax this restriction without putting decidability at risk and yet maintaining all the expressive power of ω MSO×BAPA is to "couple" it with another logic L whose satisfiability problem is decidable over arbitrary structures. Then, one considers sentences $\varphi \wedge \psi$, where φ is an ω MSO×BAPA sentence while ψ is an L-sentence, and asks for models whose reduct to the signature of φ adheres to the width restriction. That way, signature elements of ψ not occurring in φ can "behave freely" and are not subject to the imposed width constraint.⁷ Such a "coupling" of ω MSO×BAPA and L can be made more or less "tight" depending on the arity of the predicates allowed to be shared between φ and ψ .

We can show that a decidable coupling with shared unary predicates can be done for $\mathbb{L} = \mathrm{FO}_{\mathrm{Pres}}^2$ [7], an expressive extension of 2-variable first-order logic by Presburger-like counting quantifiers of the form \exists^S , where $S \subseteq \mathbb{N} \cup \{\infty\}$ is an ultimately periodic set from $\mathbb{N} \cup \{\infty\}$ with the semantics defined by $\mathfrak{A}, \nu \models \exists^S x. \varphi$ iff $|\{a \in A \mid \mathfrak{A}, \nu_{x \mapsto a} \models \varphi\}| \in S$. $\mathrm{FO}_{\mathrm{Pres}}^2$ subsumes the prominent counting 2-variable first-order fragment C² [32], but goes beyond first-order logic. Its satisfiability problem was shown to be decidable only recently [7].

⁷ We refer to Kotek et al. [42] for a result that is similar in spirit, establishing decidability of finite satisfiability of treewidth-bounded MSO₂ coupled with C².

33:14 Adding Presburger Arithmetic to MSO Logic over Tree-Interpretable Structures

▶ **Theorem 26.** Let w be any of treewidth, cliquewidth, or partitionwidth, and let $n \in \mathbb{N}$. Let \mathbb{S}_a and \mathbb{S}_b be signatures whose only joint elements are unary predicates. Then the following problem is decidable: Given a ω MSO×BAPA sentence φ over \mathbb{S}_a and a FO²_{Pres} sentence ψ over \mathbb{S}_b , does there exist a countable $\mathbb{S}_a \cup \mathbb{S}_b$ -structure \mathfrak{C} satisfying $w(\mathfrak{C}|_{\mathbb{S}_a}) \leq n$ and $\mathfrak{C} \models \varphi \wedge \psi$.

In a nutshell, this result is obtained by exploiting the fact that, for every $\operatorname{FO}_{\operatorname{Pres}}^2$ formula ψ over \mathbb{S}_b , one can construct a ω MSO \rtimes BAPA formula ψ' over the purely unary signature $\mathbb{S}_a \cap \mathbb{S}_b$ that is satisfied by precisely those \mathbb{S}_a -structures that are " $\mathbb{S}_a \cap \mathbb{S}_b$ -compatible" with some model of ψ . Consequently, the ω MSO \rtimes BAPA formula $\varphi \wedge \psi'$ over \mathbb{S}_a is such that for any of its models \mathfrak{A} one finds a " $\mathbb{S}_a \cap \mathbb{S}_b$ -compatible" model \mathfrak{B} of ψ . Then, superimposing \mathfrak{A} and \mathfrak{B} would yield a model \mathfrak{C} of $\varphi \wedge \psi$, which by construction satisfies $w(\mathfrak{C}|_{\mathbb{S}_a}) = w(\mathfrak{A})$. Consequently, to solve the decision problem of Theorem 26, it suffices to check if the ω MSO \rtimes BAPA formula $\varphi \wedge \psi'$ has a model \mathfrak{A} satisfying $w(\mathfrak{A}|_{\mathbb{S}_a}) \leq n$ which is decidable by Corollary 25. We note that the extended arithmetic capabilities of ω MSO \rtimes BAPA are essential for this result, as ψ' needs to encode linear inequalities over counts of realized atomic 1-types.

9 Showcase: Decidability of Tame Satisfiability of the Fully Enriched μ-Calculus with Global Presburger Counting

An important and practically relevant class of expressive logical formalisms, which play a pivotal role in logic-based knowledge representation and verification, is obtained from variations and extensions of propositional modal logics [8, 9] and description logics [4, 53]. This class contains most ontology languages as well as PDL [29], CTL* [24], the propositional modal μ -calculus [43] and their extensions. Modulo some representational variations, all these logics' model-theoretic semantics rest on structures over unary and binary predicates (often interpreted as a transition system's state space). While the simpler variants of this family can be seen as fragments of first-order logic, the more expressive ones cannot, as they feature fixed-point capabilities (through regular path expressions or explicit fixed-point operators). Typically, decidability of the satisfiability problem in these logics follows from some sort of tree-model property. Many of these logics exhibit some limited local counting capabilities [54], but recently, there has been an increased interest in accommodating more advanced arithmetic constraints [23, 47, 2, 5], including global constraints [3, 52] expressing statistical information such as "more than 50% of the state space's final states are successful".

We will demonstrate the usefulness of ω MSO×BAPA for establishing decidability results at the example of adding global Presburger constraints to the *fully enriched* μ -calculus, a very powerful formalism used in verification. We first introduce syntax and semantics.⁸

▶ Definition 27. Given a signature $S = S_{\mathbf{C}} \cup S_{\mathbf{P},1} \cup S_{\mathbf{P},2}$ of constants, unary predicates and binary predicates, the formulas of the fully enriched μ -calculus (FE μ) are defined by

 $\varphi \coloneqq \mathbf{true} \mid \mathbf{false} \mid X \mid \mathbf{c} \mid \neg \mathbf{c} \mid \mathbf{P} \mid \neg \mathbf{P} \mid \varphi \land \varphi' \mid \varphi \lor \varphi' \mid \langle n, \alpha \rangle \varphi \mid [n, \alpha] \varphi \mid \mu X.\varphi \mid \mathbf{v} X.\varphi$

where X is a set variable from some countable set \mathbf{V}_{set} , $\mathbf{P} \in \mathbb{S}_{\mathbf{P},1}$, $n \in \mathbb{N}$ and α has the form \mathbf{R} or \mathbf{R}^- for some $\mathbf{R} \in \mathbb{S}_{\mathbf{P},2}$. For ease of presentation, we assume positive normal form.

⁸ For brevity and coherence, we slightly adjust the syntax and use classical model-theoretic semantics (structures with unary and binary predicates) instead of the original one of modal logic (Kripke structures with propositional variables and programs), as the two are well known to be equivalent.

Given a structure \mathfrak{A} and a set variable assignment $\nu : \mathbf{V}_{set} \to 2^A$, the semantics $\llbracket \varphi \rrbracket_{\nu}^{\mathfrak{A}} \subseteq A$ of formulae φ is defined by the following function (stipulating $(\mathbf{R}^-)^{\mathfrak{A}} = \{(a, a') \mid (a', a) \in \mathbf{R}^{\mathfrak{A}}\}$):

$$\begin{array}{ll} \mathbf{true} \mapsto A & X \mapsto \nu(X) & \mathbf{c} \mapsto \{\mathbf{c}^{\mathfrak{A}}\} & \mathbf{P} \mapsto \mathbf{P}^{\mathfrak{A}} & \varphi \wedge \varphi' \mapsto \llbracket \varphi \rrbracket_{\nu}^{\mathfrak{A}} \cap \llbracket \varphi' \rrbracket_{\nu}^{\mathfrak{A}} \\ \mathbf{false} \mapsto \emptyset & \neg \mathbf{c} \mapsto A \setminus \{\mathbf{c}^{\mathfrak{A}}\} & \neg \mathbf{P} \mapsto A \setminus \mathbf{P}^{\mathfrak{A}} & \varphi \vee \varphi' \mapsto \llbracket \varphi \rrbracket_{\nu}^{\mathfrak{A}} \cup \llbracket \varphi' \rrbracket_{\nu}^{\mathfrak{A}} \\ \langle n, \alpha \rangle \varphi \mapsto \{a \mid |\{\alpha^{\mathfrak{A}} \cap (\{a\} \times \llbracket \varphi \rrbracket_{\nu}^{\mathfrak{A}})\}| \ge n\} & \mu X.\varphi \mapsto \bigcap \{A' \subseteq A \mid \llbracket \varphi \rrbracket_{\nu_{X \mapsto A'}}^{\mathfrak{A}} \subseteq A'\} \\ \llbracket n, \alpha \rrbracket \varphi \mapsto \{a \mid |\{\alpha^{\mathfrak{A}} \cap (\{a\} \times (A \setminus \llbracket \varphi \rrbracket_{\nu}^{\mathfrak{A}}))\}| \le n\} & \nu X.\varphi \mapsto \bigcup \{A' \subseteq A \mid \llbracket \varphi \rrbracket_{\nu_{X \mapsto A'}}^{\mathfrak{A}} \in A'\} \end{array}$$

A FEµ formula is closed if all occurrences of set variables are in the scope of some µ or \mathbf{v} . A global FEµ Presburger constraint is a Parikh constraint (cf. Definition 7), where all set variables have been replaced by closed FEµ formulae. Given a set Π of global FEµ Presburger constraints, we let $\mathfrak{A} \models \Pi$ if for every element of Π , replacing each of its closed FEµ formulae ψ by $\llbracket \psi \rrbracket_{\emptyset}^{\mathfrak{A}}$ produces a statement valid in \mathfrak{A} . A closed FEµ formula φ is satisfiable wrt. Π if there is some structure $\mathfrak{A} \models \Pi$ with $\llbracket \varphi \rrbracket_{\emptyset}^{\mathfrak{A}} \neq \emptyset$, in which case we call \mathfrak{A} a model of (φ, Π) .

In fact, unrestricted satisfiability in FEµ (even without Presburger constraints) is undecidable [13]. Decidability can be regained, however, when restricting to *tame structures*, also commonly known as "quasi-forests" [15, 12, 16, 6].

▶ Definition 28 (tame structures). Let $S = S_{\mathbf{C}} \cup S_{\mathbf{P},1} \cup S_{\mathbf{P},2}$ be a signature as above. A tame structure \mathfrak{A} over S is a countable structure such that, for some finite set Roots,

- the domain A of \mathfrak{A} is a forest, i.e., a prefix-closed subset of $\{rw \mid r \in Roots, w \in \mathbb{N}^*\}$,
- the roots coincide with the named elements, i.e., $Roots = \{a^{\mathfrak{A}} \mid a \in \mathbb{S}_{\mathbf{C}}\}$, and
- for every $a, a' \in A$ with $(a, a') \in \mathbb{R}^{\mathfrak{A}}$ for some $\mathbb{R} \in \mathbb{S}_{\mathbf{P},2}$, either (i) $\{a, a'\} \cap Roots \neq \emptyset$, or (ii) a = a', or (iii) a is a child of a', or (iv) a' is a child of a.

A logic has the tame model property if every satisfiable formula φ has a model that is tame over the signature used by φ . The tame satisfiability problem consists in deciding if a given formula has a tame model.

While the restriction to tame structures may seem somewhat arbitrary at first, it is well justified: three maximal decidable sublogics of FEµ have the tame-model-property [12], in which case satisfiability over arbitrary structures and tame structures coincide. Also, the structural restriction has some plausibility from a transition system perspective in that one distinguishes between a finite set of "named" states with arbitrary transitions between them and potentially infinitely many "anonymous" states with more restricted access. It is easy to see that all tame structures over $\mathbb{S} = \mathbb{S}_{\mathbb{C}} \cup \mathbb{S}_{\mathbb{P}}$ have a treewidth not larger than $|\mathbb{S}_{\mathbb{C}}| + 1$.

▶ **Theorem 29.** The tame satisfiability problem of the fully enriched μ -calculus with global Presburger constraints is decidable.

Proof (sketch). Let S be a finite signature, φ a closed FEµ formula over S, and II a finite set of global FEµ Presburger constraints. Being a tame structure over S can be expressed by an MSO sentence ψ_{tame} . We define a translation trans_x mapping closed FEµ formulae to ω MSO×BAPA formulae with free variable x such that $\mathfrak{A}, \{x \mapsto a\} \models \text{trans}_x(\varphi)$ iff $a \in [\![\varphi]\!]_{\emptyset}^{\mathfrak{A}}$. Based on this, we exhibit another translation trans, which maps global FEµ Presburger constraints to equivalent ω MSO×BAPA sentences. Then, tame satisfiability of (φ, Π) corresponds to satisfiability of the ω MSO×BAPA sentence $\psi_{\text{tame}} \land \exists x. \text{trans}_x(\varphi) \land \land \text{trans}(\Pi)$ over all countable structures of treewidth $\leq |\mathbb{S}_{\mathbf{C}}| + 1$, which is decidable by Corollary 25.

Thanks to the expressive power of FEµ, the above result transfers to numerous other prominent logics (and their fragments), including PDL and CTL^{*} as well as the description logics $\mu ALCOIQ$ and $ALCOIQ^{reg}$ [14], for all of which tame satisfiability is thus decidable even in the presence of global Presburger constraints. The argument easily extends to the description logic ZOIQ [16], adding Boolean combinations of binary predicates (programs).

33:16 Adding Presburger Arithmetic to MSO Logic over Tree-Interpretable Structures

10 Conclusion

We have proposed ω MSO \bowtie BAPA, a logic with a high combined structural and arithmetic expressivity, subsuming and properly extending existing popular formalisms for either purpose. We have established decidability of the satisfiability of ω MSO \bowtie BAPA formulae over arbitrary tree-interpretable classes of structures. A key role is played by Parikh-Muller Tree Automata, a novel type of automaton over labeled infinite binary trees with decidable emptiness.

For improving readability and succinctness, the syntax of our formalism could be extended by "comprehension expressions": set terms of the form $\{x \mid \psi\}$ with $x \in \mathbf{V}_{\text{ind}}$ and $\psi \in \mathbf{F}$, whose semantics is straightforwardly defined by $\{x \mid \psi\}^{\mathfrak{A},\nu} = \{a \in A \mid \mathfrak{A}, \nu_{x\mapsto a} \models \psi\}$. E.g., this allows us to write $2 \#\{x \mid \exists y. \mathbb{R}(x, y)\} = 3 \#\{y \mid \exists x. \mathbb{R}(x, y)\}$ rather than the more unwieldy

 $\exists V_1.(\forall x.V_1(x) \Leftrightarrow \exists y.\mathbf{R}(x,y)) \land \exists V_2.(\forall y.V_2(y) \Leftrightarrow \exists x.\mathbf{R}(x,y)) \land 2 \#V_1 = 3 \#V_2.$

Note that comprehension expressions do not increase expressivity; they can be removed from a formula φ yielding an equivalent formula φ' as follows: Let χ be the largest subformula of φ that contains the expression $\{x \mid \psi\}$ but no quantifiers binding any of the free variables of ψ . Then, obtain φ' from φ by replacing χ by χ' , where $\chi' \coloneqq \exists Z.(\forall x.Z(x) \Leftrightarrow \psi) \land \chi[\{x \mid \psi\} \mapsto Z].$ ω MSO \bowtie BAPA membership of such extended formulae can then be decided based on their "purified" variant,⁹ or by means of an elaborately refined analysis of variable interactions.

Concluding, we are quite confident that this paper's findings and techniques will prove useful as a generic tool for establishing decidability results for formalisms from various areas of computer science such as knowledge representation or verification. That said, in view of the non-elementary blow-ups abounding in our methods, we concede that they are unlikely to be helpful in more fine-grained complexity analyses, once decidability is established.

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 $^{^9\,}$ The described removal technique is optimized toward producing formulae in $\omega {\rm MSO} \rtimes {\rm BAPA}.$

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33:18 Adding Presburger Arithmetic to MSO Logic over Tree-Interpretable Structures

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