




# Oracle-Augmented Prophet Inequalities

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## Abstract

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In the classical prophet inequality setting, a gambler is given a sequence of  $n$  random variables  $X_1, \dots, X_n$ , taken from known distributions, observes their values in adversarial order and selects one of them, immediately after it is being observed, aiming to select a value that is as high as possible. The classical *prophet inequality* shows a strategy that guarantees a value at least half of the value of an omniscience prophet that always picks the maximum, and this ratio is optimal.

Here, we generalize the prophet inequality, allowing the gambler some additional information about the future that is otherwise privy only to the prophet. Specifically, at any point in the process, the gambler is allowed to query an oracle  $\mathcal{O}$ . The oracle responds with a single bit answer: YES if the current realization is greater than the remaining realizations, and NO otherwise. We show that the oracle model with  $m$  oracle calls is equivalent to the TOP-1-OF- $(m + 1)$  model when the objective is maximizing the probability of selecting the maximum. This equivalence fails to hold when the objective is maximizing the competitive ratio, but we still show that any algorithm for the oracle model implies an equivalent competitive ratio for the TOP-1-OF- $(m + 1)$  model.

We resolve the oracle model for any  $m$ , giving tight lower and upper bound on the best possible competitive ratio compared to an almighty adversary. As a consequence, we provide new results as well as improvements on known results for the TOP-1-OF- $m$  model.

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## 1 Introduction

The field of optimal stopping theory concerns optimization settings where one makes decisions in a sequential manner, given imperfect information about the future, in a bid to maximize a reward or minimize a cost. A canonical setting in this area is the *prophet inequality* [18, 19]. In these settings, a gambler is presented with rewards  $X_1, \dots, X_n$ , one after the other, drawn independently from known distributions. Upon seeing a reward  $X_i$ , the gambler must immediately make an irrevocable decision to either accept  $X_i$ , in which case the process ends, or to reject  $X_i$  and continue, losing the option to select  $X_i$  in the future. The goal of the gambler is to maximize the selected reward comparing against a *prophet* who knows all realizations in advance and selects the maximum realized reward. Throughout, we assume, without loss of generality, that  $X_1, \dots, X_n$  are continuous random variables.



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The performance of the gambler can be measured in terms of several objectives. A common metric used in the literature is the *competitive ratio*, which is also known as the *Ratio of Expectations (RoE)* (see Definition 1.1). Another common distinction is between the case in which the given distributions are different and the case in which they are identical. For the former, Krengel et al. [18, 19] showed an optimal strategy that is  $1/2$ -competitive. In this setting, the optimal competitive ratio can be achieved by simple, single-threshold algorithms [21, 17]. For IID and non-IID random variables, Hill and Kertz [15] initially gave a  $(1 - 1/e)$ -competitive algorithm. This was improved to  $\approx 0.738$  [1] and later  $\approx 0.745$  [7], which is tight, due to a matching upper bound [15, 16].

Another relevant metric, introduced by Gilbert and Mosteller [12] for IID random variables, is that of maximizing the *Probability of selecting the Maximum realization* ( $\mathbb{P}_{\max}$ ) - see Definition 1.2. For this objective and IID random variables, Gilbert and Mosteller [12] gave an algorithm that achieves a probability of  $\approx 0.58$ , which is the best possible. Later, Esfandiari, Hajiaghayi, Lucier and Mitzenmacher [9] studied the same objective for general random variables, obtaining a tight probability equal to  $1/e$  when the random variables arrive in adversarial order and  $0.517$  when the random variables arrive in random order. The latter case was recently improved to the tight  $\approx 0.58$  by Nuti [20], showing that the IID setting is not easier than the non-IID setting with random order. In this paper, we introduce a new model as a means to study variations of both the IID and the general settings, for both the RoE and  $\mathbb{P}_{\max}$  objectives.

A setting that is related to ours is the TOP-1-OF- $m$  model, formally introduced by Assaf and Samuel-Cahn [3] for IID random variables, although it had been studied initially by Gilbert and Mosteller [12]. In this setting, the algorithm is allowed to select  $m \geq 1$  values, but the value it gets judged by is the maximum selected value. Gilbert and Mosteller [12] gave numerical approximations of the  $\mathbb{P}_{\max}$  objective for  $2 \leq m \leq 10$ , using a simple, single-threshold algorithm. Later, Assaf and Samuel-Cahn [3] studied the RoE objective for general distributions and gave an elegant and simple  $(1 - 1/(m+1))$ -competitive algorithm. This was improved [2] by bounding the competitive ratio of the optimal algorithm by a recursive differential equation. They gave numerical approximations for  $2 \leq m \leq 5$ , but studying the asymptotic nature of the constants for large  $m$  turned out to be difficult. Ezra et al. [11] later revisited the problem and gave a new algorithm for large  $m$  that is  $1 - \mathcal{O}(e^{-m/6})$ -competitive for the same problem. This improves the error term from [2] from linear in  $m$  to exponential in  $m$ . Harb [14] recently improved this into a  $1 - e^{-mW_0(\frac{\sqrt[m]{m!}}{m})}$ -competitive algorithm, where  $W_0$  is the Lambert- $W$  function<sup>1</sup>, and improved the lower bound for  $m = 2$  separately. However, the asymptotic nature of this function is difficult to analyze.

## Model

We introduce a new model that generalizes the standard prophet inequality setting, and analyze it as a means to obtain new results and improvements in the TOP-1-OF- $m$  model. Our model allows the algorithm some information about the future that is otherwise privy only to the prophet. Specifically, at any point in the process, upon seeing a reward  $X_i$ , the algorithm is allowed to query an oracle  $\mathcal{O}$ . The oracle  $\mathcal{O}$  responds with a single bit answer: YES if the current realization is larger than the remaining realizations, i.e.,  $X_i > \max_{j=i+1}^n X_j$  and NO otherwise. In other words, the oracle  $\mathcal{O}$  informs the algorithm it should select  $X_i$ , or reject it, because there is a reward coming up that is at least as good. Clearly, with no

<sup>1</sup> The Lambert- $W$  function is  $W_0(x)$  defined as the solution  $y$  to the equation  $ye^y = x$ .

queries available, one recovers the classical prophet inequality setting, whereas with  $n - 1$  queries, the strategy of using a query on every  $X_i$ , for  $i = 1, \dots, n - 1$ , leads to the algorithm selecting the highest realization always. Thus, this model interpolates nicely between the two extremes of full or no information about the future.

In this paper, we consider the following different settings.

► **Definition 1.1** (Competitive Ratio). *The competitive ratio or Ratio of Expectations is denoted by  $\text{RoE}$ . Specifically, for an instance  $\mathcal{I}$  of a prophet inequality setting, we denote by  $\text{RoE}(x, \mathcal{I})$  the competitive ratio of an optimal algorithm for  $\mathcal{I}$ . An algorithm  $ALG$  is  $\alpha$ -competitive, for  $\alpha \in [0, 1]$ , if  $\mathbb{E}[ALG] \geq \alpha \cdot \mathbb{E}[\max_i X_i]$ , and  $\alpha$  is called the competitive ratio.*

► **Definition 1.2** (Probability of Selecting the Maximum). *The Probability of selecting the Maximum realization is denoted by  $\mathbb{P}_{\max}$ . An algorithm  $ALG$  achieves a  $\mathbb{P}_{\max}$  of  $\alpha$  if it returns a value  $v$  such that  $\mathbb{P}[v = Z] \geq \alpha$ , where  $Z = \max\{X_1, \dots, X_n\}$ . In some works (for example [12]), the notation  $PbM$  has also been used.*

► **Definition 1.3** (IID Setting). *We use the term IID to refer to the setting where  $X_1, \dots, X_n$  are independent and identically distributed random variables. We use non-IID to refer to the more general setting where  $X_1, \dots, X_n$  are independent, but not necessarily identical.*

► **Definition 1.4** ( $\text{PROPH}_m$ ). *We use  $\text{PROPH}_m$  to refer to the TOP-1-OF- $m$  model, in which the algorithm can choose up to  $m$  values, and its payoff is the maximum of the chosen values. We use  $\mathcal{O}_m$  refers to our oracle model where the algorithm has access to  $m$  oracle calls, and can only select one value.*

Note that the model  $\text{PROPH}_{m+1}$  is comparable to  $\mathcal{O}_m$ , since in the former the algorithm can choose  $m + 1$  values, where as the later can ask the oracle  $m$  times and then choose an item. To help distinguish between the different settings, we denote each model as  $\mathcal{M}(x, y, z)$ , where

- $x$  is either  $\text{PROPH}_m$  or  $\mathcal{O}_m$  with  $m \in \mathbb{N}$ ,
- $y$  is either IID or non-IID, and
- $z$  is either  $\mathbb{P}_{\max}$  or RoE.

## Our Contributions

In this paper, we study the oracle model for independent random variables following identical or general distributions with the  $\mathbb{P}_{\max}$  and RoE objectives and make the following contributions:

- (I) We establish an *equivalence* between the oracle model and the TOP-1-OF- $m$  model for the  $\mathbb{P}_{\max}$  objective.
- (II) We show that this equivalence fails to hold for the RoE objective. However, we show that guarantees for RoE in the oracle model translate to guarantees in the TOP-1-OF- $m$  model, thus further motivating our study of the oracle model.
- (III) We resolve the oracle model  $\mathcal{M}(\mathcal{O}_m, \text{non-IID}, \text{RoE})$  by presenting a single-threshold algorithm. Our algorithm achieves a competitive ratio of  $1 - e^{-\xi_m} = 1 - \mathcal{O}e^{-m/e}$  for general  $m$ , where  $\xi_m$  is the unique *positive* solution<sup>2</sup> to the equation  $1 - e^{-\xi_m} =$

<sup>2</sup> In Section 3, we prove that there is indeed a unique positive solution.

$\frac{\Gamma(m+1, \xi_m)}{m!}$ <sup>3</sup>. Furthermore, we show that this lower bound is optimal by showing a construction that yields an equal upper bound. Since we showed that lower bound guarantees for  $\mathcal{M}(\mathcal{O}_m, \text{non-IID}, \text{RoE})$  also hold for the  $\mathcal{M}(\text{PROPH}_{m+1}, \text{non-IID}, \text{RoE})$  setting, this strictly improves the current state of the art bounds of [14], even though the guarantees are obtained in the weaker oracle model.

- (IV) We give a single-threshold algorithm for the  $\mathcal{M}(\mathcal{O}_m, \text{IID}, \mathbb{P}_{\max})$  model that achieves a  $1 - \mathcal{O}(m^{-m/5})$  probability of selecting the maximum, as well as providing an upper bound that is asymptotically (almost) tight. To the best of our knowledge, this is the first result for the  $\mathbb{P}_{\max}$  objective and general  $m$  in the well studied TOP-1-OF- $m$  model. Our algorithm achieves a probability of  $\approx 0.797$  even with  $m = 1$  calls to the oracle, a significant improvement on the  $\approx 0.58$  achieved without oracle calls [12].

As discussed earlier, the main motivation behind our oracle model comes from our first two results which relate it to the TOP-1-OF- $m$  model.

### Equivalence of Models for $\mathbb{P}_{\max}$

► **Theorem 1.5.** *The  $\mathcal{M}(\mathcal{O}_m, y, \mathbb{P}_{\max})$  model is equivalent to the  $\mathcal{M}(\text{PROPH}_{m+1}, y, \mathbb{P}_{\max})$  model, where  $y = \text{IID}$  or  $\text{non-IID}$ . In other words, for every prophet inequality instance, the probability achieved by the best-possible algorithm in the  $\mathcal{M}(\mathcal{O}_m, y, \mathbb{P}_{\max})$  model is the same as the one achieved by the best-possible algorithm in the  $\mathcal{M}(\text{PROPH}_{m+1}, y, \mathbb{P}_{\max})$  model.*

In Section 2 and Theorem 1.5, we establish the equivalence between the  $\mathcal{M}(\mathcal{O}_m, y, \mathbb{P}_{\max})$  and  $\mathcal{M}(\text{PROPH}_{m+1}, y, \mathbb{P}_{\max})$  models, for  $y = \text{IID}$  or  $\text{non-IID}$ . In other words, the best algorithms in these models achieve the same probability of selecting the maximum.

This result might not seem that surprising due to the apparent similarity of the two models. However, thinking about the TOP-1-OF- $m$  setting from the viewpoint of oracle calls allows for a different perspective that we exploit in our analysis. Furthermore, such intuition can sometimes be wrong, as our next result shows.

### Difference of Models for RoE

► **Theorem 1.6.** *For every  $m \geq 1$ , and for all input instances  $\mathcal{J}$  (of IID or non-IID variables), we have  $\text{RoE}(\mathcal{O}_m, \mathcal{J}) \leq \text{RoE}(\text{PROPH}_{m+1}, \mathcal{J})$ . Furthermore, for every  $m \geq 1$ , there exists an input instance  $\mathcal{I}$  with  $m + 2$  non-IID random variables, such that  $\text{RoE}(\mathcal{O}_m, \mathcal{I}) \leq (1 - 1/2^{m+1})\text{RoE}(\text{PROPH}_2, \mathcal{I})$ .*

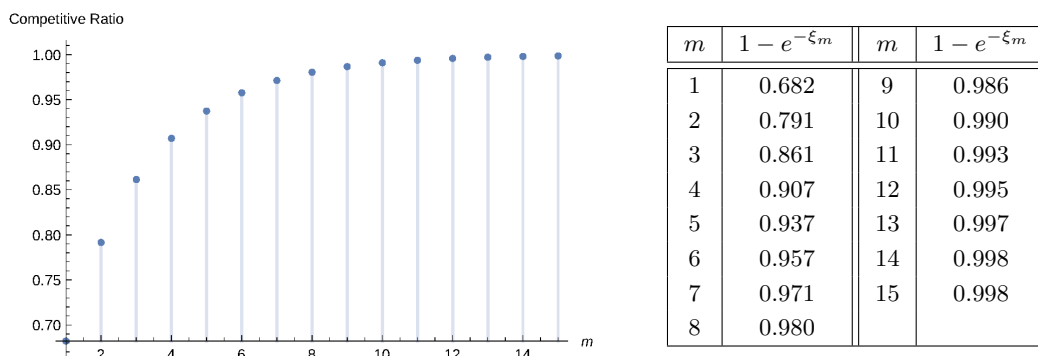
Perhaps more surprisingly, our oracle model and the TOP-1-OF- $m$  model stop being equivalent when one considers the RoE objective, with the oracle model being strictly weaker.

In Section 2, we show Theorem 1.6, which gives a prophet inequality instance, and an algorithm  $\mathcal{A}$  for  $\mathcal{M}(\text{PROPH}_{m+1}, \text{non-IID}, \text{RoE})$ , such that no algorithm for  $\mathcal{M}(\mathcal{O}_m, \text{non-IID}, \text{RoE})$  can achieve the same competitive ratio as that of  $\mathcal{A}$ . Furthermore, we show that any algorithm for  $\mathcal{M}(\mathcal{O}_m, y, \text{RoE})$  can be modified to an algorithm for  $\mathcal{M}(\text{PROPH}_{m+1}, y, \text{RoE})$  that achieves an equal or greater competitive ratio.

### Bounding the Performance of the Oracle Model

► **Theorem 1.7.** *For every  $m \geq 1$ , let  $\alpha_m = 1 - e^{-\xi_m}$ , where  $\xi_m$  is the unique positive solution to the equation  $1 - e^{-\xi_m} = \frac{\Gamma(m+1, \xi_m)}{m!}$ . For any finite sequence  $\mathbf{X}$  of non-IID variables, one can compute a value  $\tau$ , such that the single-threshold algorithm (with initial threshold  $\tau$ ) has competitive ratio  $\geq \alpha_m$ .*

<sup>3</sup>  $\Gamma(n, x) = \int_x^\infty t^{n-1} e^{-t} dt$  denotes the upper incomplete gamma function.



■ **Figure 1.1** The value of  $1 - e^{-\xi_m}$ , for  $m = 1, \dots, 15$ .

After establishing the relationship between our oracle model and the TOP-1-OF- $m$  model, we turn our attention to upper and lower bounds for the oracle model. First, for the non-IID setting and the RoE objective, we present a simple, single-threshold algorithm achieving a competitive ratio that approaches 1 exponentially fast with respect to  $m$ . Even though our algorithm is for the oracle model, for which weaker guarantees are expected due to Theorem 1.6, it improves upon the best-known guarantee for the TOP-1-OF- $m$  setting, due to Harb [14]. Our algorithm relies on two techniques; sharding and Poissonization, introduced by [14] for the analysis of threshold-based algorithms for prophet inequalities. As an added benefit, the algorithm’s analysis is easy to understand.

Specifically, in Section 3, Theorem 1.7, we show that there is a constant  $\xi_m$ , such that for the oracle model  $\mathcal{M}(\mathcal{O}_m, \text{non-IID}, \text{RoE})$ , there exists an algorithm with competitive ratio at least  $1 - e^{-\xi_m}$ . As  $m \rightarrow +\infty$ , this behaves as  $1 - e^{-m/e+o(m)}$ . The competitive ratio plot for  $m = 1, \dots, 15$  is shown in Figure 1.1.

### Matching Upper Bound

► **Theorem 1.8.** *For any  $m \geq 1$  and  $\delta > 0$ , there exists an input instance  $\mathcal{I}$  such that for any algorithm, we have  $\text{RoE}(\mathcal{A}) \leq 1 - e^{-\xi_m} + \delta$ .*

In addition, we provide a construction for every  $m$  that gives a matching upper bound to the competitive ratio, thus resolving the problem for the case of general distributions and the RoE objective. The construction we have is perhaps of independent interest in the design of counterexamples for other settings, as it combines and generalizes standard counterexamples of prophet inequalities.

In Section 3 and Theorem 1.8, we show that for any  $\delta > 0$ , there exists an instance of  $\mathcal{M}(\mathcal{O}_m, \text{non-IID}, z)$ , where  $z = \text{RoE}$  or  $\mathbb{P}_{\max}$ , in which no single-threshold algorithm can achieve a  $(1 - e^{-\xi_m} + \delta)$ -competitive ratio or select the maximum realization with probability at least  $(1 - e^{-\xi_m} + \delta)$ .

Intuitively, the above follows since an algorithm for the oracle model performs poorly when, every time it uses an oracle call and gets a YES answer, the next value it sees that is at least the queried value is roughly equal, and thus the oracle call was used without any real gain. The idea behind the worst-case for this setting is to have what is essentially a Poisson random variable with rate  $\xi_m$ , providing the algorithm with several non-zero values, each roughly the same. By carefully selecting  $\xi_m$  in order to equate the probability of having no non-zero values and the probability of having more than  $m$  non-zero values, we are forcing the algorithm to use a query for every non-zero realization, thus rendering the oracle calls as useless as possible.

| Model                             | Lower Bound                      |  | Upper Bound |   |
|-----------------------------------|----------------------------------|--|-------------|---|
|                                   | Prev. Best                       | Current Best   | Prev.       | Current Best                            |
| RoE, General Setting              | $1 - \mathcal{O}(e^{-m/6})$ [11] | $1 - e^{-m/e+o(m)}$  | -           | $1 - e^{-m/e+o(m)}$<br>single-threshold |
| $\mathbb{P}_{\max}$ , IID Setting | $\approx 0.58$ [12]              | $\approx 0.797$ ( $m = 1$ )<br>$1 - \mathcal{O}(m^{-m/5})$ | -           | $1 - \mathcal{O}(m^{-m})$               |

■ **Figure 1.2** State of the art.

### The IID Setting

► **Theorem 1.9** (see [13] for proof). *For sufficiently large  $m, n$ , there exists an algorithm for the  $\mathcal{M}(\mathcal{O}_m, \text{IID}, \mathbb{P}_{\max})$  model that selects the maximum realization with probability at least  $1 - \mathcal{O}(m^{-m/5})$ .*

Next, we turn our attention to the IID setting with  $m$  oracle calls and the  $\mathbb{P}_{\max}$  objective. We present a simple, single-threshold algorithm that selects the maximum realization with probability that approaches 1 in a super-exponential fashion. As a warm-up, we first present the analysis for  $m = 1$  before generalizing it to all  $m$ .

Specifically, in Section 4, Theorem 1.9, we show that for  $\mathcal{M}(\mathcal{O}_m, \text{IID}, \mathbb{P}_{\max})$ , one can select the maximum realization with probability at least  $1 - \mathcal{O}(m^{-m/5})$ .

► **Theorem 1.10** (see [13] for proof). *There exists an instance of  $\mathcal{M}(\mathcal{O}_m, \text{IID}, \mathbb{P}_{\max})$  for which no algorithm can select the maximum realization with probability greater than  $1 - \mathcal{O}(m^{-m})$ .*

We also present, in Section 4, Theorem 1.10, an upper bound on the probability of success that is asymptotically tight, up to small multiplicative constants in the exponent. Because of Theorem 1.5, both upper and lower bounds on the probability of success carry over in the TOP-1-OF- $m$  settings as well. Figure 1.2 contains a summary of our results for the oracle model in the different settings.

### 1.1 Additional related work

We have already mentioned the works of Gilbert and Mosteller [12], Esfandiari, Hajiaghayi, Lucier and Mitzenmacher [9] and Nuti [20] for the  $\mathbb{P}_{\max}$  objective. Related work includes the study of order-aware algorithms by Ezra, Feldman et al. [10], algorithms with fairness guarantees by Correa et al. [6] and algorithms with a-priori information of some of the values by Correa et al. [4]. In addition to these, Esfandiari et al. [9] study a related but distinct variant to ours. They relax the objective to allow the return of one out of the top  $k$  realizations, and show exponential upper and lower bounds. Their model, however, is incomparable to ours.

### Organization

In Section 2 we relate our model to TOP-1-OF- $m$  model of Assaf and Samuel-Cahn [3] and prove the reductions. In Section 3 we present our tight algorithm for the non-IID setting. Section 4 contains our algorithms and upper bounds for the IID setting. Due to space constraints, some of the proofs as well as background information on concentration inequalities that we use for our results can be found in the full version [13].

## 2 Reductions

To motivate our oracle model, we start by establishing an equivalence between  $\mathcal{M}(\mathcal{O}_m, y, \mathbb{P}_{\max})$  and  $\mathcal{M}(\text{PROPH}_{m+1}, y, \mathbb{P}_{\max})$ , for both the  $y = \text{IID}$  and  $y = \text{non-IID}$  case (see Theorem 1.5 below). We also show that, perhaps surprisingly, this equivalence does not hold for the RoE objective; lower bound guarantees for  $\mathcal{M}(\mathcal{O}_m, y, \text{RoE})$  translate to guarantees for  $\mathcal{M}(\text{PROPH}_{m+1}, y, \text{RoE})$  (Theorem 1.6), but not the converse. Later, we use this result to improve the best-known lower bound guarantees on  $\mathcal{M}(\text{PROPH}_{m+1}, y, \text{RoE})$ .

### 2.1 The $\mathbb{P}_{\max}$ objective

► **Lemma 2.1.** *Fix an instance of the prophet problem. Let  $\mathcal{A}$  be an algorithm for this instance in  $\mathcal{M}(\mathcal{O}_m, y, \mathbb{P}_{\max})$ , where  $y = \text{IID}$  or  $\text{non-IID}$ . Then, there exists an algorithm  $\mathcal{B}$  for this instance in  $\mathcal{M}(\text{PROPH}_{m+1}, y, \mathbb{P}_{\max})$ , with black-box access to  $\mathcal{A}$ , such that  $\mathbb{P}_{\max}(\mathcal{B}) \geq \mathbb{P}_{\max}(\mathcal{A})$ .*

**Proof.** The idea is for  $\mathcal{B}$  to simulate  $\mathcal{A}$ 's behavior by selecting each realization that  $\mathcal{A}$  decides to query. Initially,  $\mathcal{B}$  starts with an empty set  $S$  of selected values. Whenever  $\mathcal{B}$  is presented with a realization  $X_i$ , it feeds it to  $\mathcal{A}$ . If  $\mathcal{A}$  decides to select  $X_i$  or expend a query for  $X_i$ , regardless of the outcome of the query,  $\mathcal{B}$  always selects  $X_i$  into  $S$ , otherwise  $\mathcal{B}$  decides not to select  $X_i$ . By induction,  $S$  contains exactly all the realizations that were queried by  $\mathcal{A}$  as well as at most one more realization that might have been selected by  $\mathcal{A}$  if it run out of queries. Therefore,  $|S| \leq m + 1$ .

Observe that  $\mathcal{A}$  succeeds if and only if it selects the maximum, and it only selects a realization  $X_i$  if (i) it chose to expend a query on  $X_i$ , or (ii) when it observed  $X_i$  it run out of queries. In both cases, by the description of  $\mathcal{B}$ , we know that  $X_i \in S$ , and thus the probability that  $\mathcal{B}$  succeeds is at least  $\mathbb{P}_{\max}(\mathcal{A})$ . ◀

► **Lemma 2.2** (see [13] for proof). *Fix an input instance of the prophet problem. Fix an algorithm  $\mathcal{B}$  for  $\mathcal{M}(\text{PROPH}_{m+1}, y, \mathbb{P}_{\max})$ , where  $y = \text{IID}$  or  $\text{non-IID}$ . Then, there exists an algorithm  $\mathcal{A}$  for  $\mathcal{M}(\mathcal{O}_m, y, \mathbb{P}_{\max})$ , with black-box access to  $\mathcal{B}$ , such that  $\mathbb{P}_{\max}(\mathcal{A}) \geq \mathbb{P}_{\max}(\mathcal{B})$ .*

Combining the above two lemmas, we get the following result.

► **Theorem 1.5.** *The  $\mathcal{M}(\mathcal{O}_m, y, \mathbb{P}_{\max})$  model is equivalent to the  $\mathcal{M}(\text{PROPH}_{m+1}, y, \mathbb{P}_{\max})$  model, where  $y = \text{IID}$  or  $\text{non-IID}$ . In other words, for every prophet inequality instance, the probability achieved by the best-possible algorithm in the  $\mathcal{M}(\mathcal{O}_m, y, \mathbb{P}_{\max})$  model is the same as the one achieved by the best-possible algorithm in the  $\mathcal{M}(\text{PROPH}_{m+1}, y, \mathbb{P}_{\max})$  model.*

### 2.2 For the RoE objective $\mathcal{O}_m \leq \text{Proph}_{m+1}$

We demonstrate that the  $\text{PROPH}_m$  model strictly surpasses the  $\mathcal{O}_m$  for non-IID random variables.

► **Definition 2.3.** *For two integers  $i \leq j$ , let  $\llbracket i : j \rrbracket = \{i, i + 1, \dots, j\}$ .*

► **Lemma 2.4.** *For  $m = 1$ , there exists an input instance  $\mathcal{I}$  with 3 non-IID random variables, such that  $\text{RoE}(\mathcal{O}_1, \mathcal{I}) \leq \frac{3}{4} \text{RoE}(\text{PROPH}_2, \mathcal{I})$ .*



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**Proof.** For a fixed  $\varepsilon > 0$ , consider the input instance  $\mathcal{I}$  of three independent random variables  $X_1, X_2, X_3$ , where

$$X_1 = 1 \text{ w.p. } 1, \quad X_2 = \begin{cases} 1 + \varepsilon & \text{w.p. } \frac{1}{2} - \varepsilon \\ 0 & \text{otherwise} \end{cases}, \quad \text{and} \quad X_3 = \begin{cases} \frac{1}{\varepsilon} & \text{w.p. } \varepsilon \\ 0 & \text{otherwise} \end{cases}.$$

We have that

$$\mathbb{E}[\max\{X_1, X_2, X_3\}] = \frac{1}{\varepsilon}\varepsilon + (1 + \varepsilon)(1 - \varepsilon)\left(\frac{1}{2} - \varepsilon\right) + 1(1 - \varepsilon)\left(\frac{1}{2} + \varepsilon\right) = 2 - O(\varepsilon).$$

For small  $\varepsilon$ , an algorithm  $\mathcal{B}$  that is optimal for the  $\text{PROPH}_2$  model in this instance is to select  $X_1$ , ignore  $X_2$  and then select  $X_3$  if it is non-zero. This yields

$$\mathbb{E}[\mathcal{B}] = 1(1 - \varepsilon) + 1/\varepsilon \cdot \varepsilon = 2 - \varepsilon.$$

However, the optimal  $\mathcal{A}$  for the oracle model queries  $\mathcal{O}$  at  $X_1$ . With probability  $(1 - \varepsilon)(1/2 + \varepsilon)$ , it stops and select  $X_1$ , getting a value of 1. Otherwise, it continues, with no oracle calls left. It ignores  $X_2$  and select  $X_3$ . Thus,

$$\mathbb{E}[\mathcal{A}] = 1\left(\frac{1}{2} + \varepsilon\right)(1 - \varepsilon) + \frac{1}{\varepsilon}\varepsilon = \frac{3}{2} + \frac{\varepsilon}{2} - \varepsilon^2.$$

The competitive ratios of  $\mathcal{A}$  is  $\text{RoE}(\mathcal{O}_1, \mathcal{I}) = \frac{\frac{3}{2} + \frac{\varepsilon}{2} - \varepsilon^2}{2 - O(\varepsilon)} = \frac{3}{4} + O(\varepsilon) \rightarrow \frac{3}{4}$ , as  $\varepsilon \rightarrow 0$ , whereas the competitive ratio of  $\mathcal{B}$ , as  $\varepsilon \rightarrow 0$ , is

$$\text{RoE}(\text{PROPH}_2, \mathcal{I}) = \frac{2 - \varepsilon}{2 + O(\varepsilon)} = 1 - O(\varepsilon) \rightarrow 1. \quad \blacktriangleleft$$

The above example, appropriately generalized for  $m > 1$  by having random variables

$$X_1 = 1 \text{ w.p. } 1, \quad X_i = \begin{cases} 1 + (i - 1)\varepsilon & \text{w.p. } \frac{1}{2} - \varepsilon \\ 0 & \text{w.p. } \frac{1}{2} + \varepsilon \end{cases}, \quad \text{for } i = 2, \dots, m + 1, \text{ and} \\ X_{m+2} = \begin{cases} \frac{1}{\varepsilon} & \text{w.p. } \varepsilon \\ 0 & \text{w.p. } 1 - \varepsilon \end{cases},$$

shows that the gap between  $\text{RoE}(\mathcal{O}_m, \mathcal{I})$  and  $\text{RoE}(\text{PROPH}_{m+1}, \mathcal{I})$  is at most  $1 - 1/2^{m+1}$  for general  $m$ . The analysis of this example for general  $m$  is similar to the  $m = 1$  case. We do not present it here as, even though this example is very simple, this gap is not the tightest possible. For a tighter gap between the competitive ratio of the two models, see the example in the proof of Theorem 1.8.

► **Lemma 2.5.** *For any input instance  $\mathcal{I}$ , we have  $\text{RoE}(\text{PROPH}_{m+1}, \mathcal{I}) \geq \text{RoE}(\mathcal{O}_m, \mathcal{I})$ , for IID or non-IID variables.*

**Proof.** Let  $\mathcal{A}$  be the algorithm in  $\mathcal{M}(\mathcal{O}_m, \text{RoE}, \mathcal{I})$  realizing the maximum RoE for  $\mathcal{I}$ . We construct an algorithm  $\mathcal{B} \in \mathcal{M}(\mathcal{O}_m, \text{RoE}, \mathcal{I})$ .

The algorithm  $\mathcal{B}$  simulates  $\mathcal{A}$ 's behavior by selecting each realization that  $\mathcal{A}$  decides to query. Initially,  $\mathcal{B}$  starts with an empty set  $S$ . Whenever  $\mathcal{B}$  is presented with a realization  $X_i$ , it feeds it to  $\mathcal{A}$ . If  $\mathcal{A}$  decides to return  $X_i$ , or performs an oracle query for  $X_i$ , the algorithm  $\mathcal{B}$  adds  $X_i$  to  $S$ .



Observe that the algorithm  $\mathcal{A}$  stops as soon as an oracle query returns NO. Thus, the simulation  $\mathcal{B}$  of  $\mathcal{A}$ , assumes the oracle always answers YES (i.e., a larger value is coming up in the future). (i.e., the simulation replaces a call to the oracle by a function that always returns YES), as this enables it (potentially) to save more values into the available slots, thus increasing its RoE.

The set  $S$  contains exactly all the realizations that were queried by  $\mathcal{A}$ , as well as at most one additional realization returned by  $\mathcal{A}$ . Therefore,  $|S| \leq m + 1$ .

Every possible sequence of realizations  $\mathcal{A}$  queried (or selected to return) are in  $S$ . Therefore, if  $V_{\mathcal{A}}$  is the value returned by  $\mathcal{A}$  and  $V_{\mathcal{B}}$  is the value returned by  $\mathcal{B}$ , we have  $V_{\mathcal{B}} \geq V_{\mathcal{A}}$ , which readily implies that  $\text{RoE}(\mathcal{B}) \geq \text{RoE}(\mathcal{A})$ . ◀

► **Theorem 1.6.** *For every  $m \geq 1$ , and for all input instances  $\mathcal{J}$  (of IID or non-IID variables), we have  $\text{RoE}(\mathcal{O}_m, \mathcal{J}) \leq \text{RoE}(\text{PROPH}_{m+1}, \mathcal{J})$ . Furthermore, for every  $m \geq 1$ , there exists an input instance  $\mathcal{I}$  with  $m + 2$  non-IID random variables, such that  $\text{RoE}(\mathcal{O}_m, \mathcal{I}) \leq (1 - 1/2^{m+1})\text{RoE}(\text{PROPH}_2, \mathcal{I})$ .*

### 3 The non-IID settings

By Theorem 1.6, any guarantees we provide for the oracle model with the RoE objective can be directly translated to guarantees for the TOP-1-OF- $m$  model, improving upon the previous work on this model [3, 2, 11, 14]. We provide a simple, single-threshold algorithm that resolves the RoE objective in the oracle model.

#### 3.1 The exponent sequence

► **Definition 3.1** (Exponent Sequence). *For every  $m \geq 1$ , let  $\xi_m$  denote the unique positive solution to the following equation:*

$$1 - e^{-\xi_m} = \frac{\Gamma(m+1, \xi_m)}{m!},$$

where  $\Gamma(m+1, x) = \int_{t=x}^{\infty} t^m e^{-t} dt$  denotes the upper incomplete gamma function. We call the sequence  $\{\xi_m\}_{m \in \mathbb{N}}$  the exponent sequence.

We show below that the optimal competitive ratio of  $\mathcal{M}(\mathcal{O}_m, \text{non-IID}, \text{RoE})$  is exactly  $1 - e^{-\xi_m}$ . It is known that, for  $x \geq 0$  and an integer  $m+1 > 0$ , we have

$$\Gamma(m+1, x) = m! e^{-x} \sum_{k=0}^m \frac{x^k}{k!} \leq m! e^{-x} e^x \leq m!. \quad (3.1)$$

As such, the above equation on the value of  $\xi_m$ , becomes

$$1 - e^{-\xi_m} = e^{-\xi_m} \sum_{k=0}^m \frac{(\xi_m)^k}{k!} \iff \sum_{k=m+1}^{\infty} \frac{(\xi_m)^k}{k!} = 1.$$

This readily implies that the exponent sequence is monotonically increasing, and  $m/e^2 \leq \xi_m \leq m$ .

► **Definition 3.2.** *Let  $q_{k+1}(x) = \frac{\Gamma(k+1, x)}{k!} = e^{-x} \sum_{j=0}^k \frac{x^j}{j!}$ . This implies  $q_{m+1}(\xi_m) = 1 - e^{-\xi_m}$ .*

► **Lemma 3.3.**  $q'_{m+1}(x) = -e^{-x} \frac{x^m}{m!}$ .

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**Proof.** As  $(e^{-x})' = -e^{-x}$ , we have  $q'_{m+1}(x) = -e^{-x} + \sum_{j=1}^m \left( e^{-x} \frac{x^{j-1}}{(j-1)!} - e^{-x} \frac{x^j}{j!} \right) = -e^{-x} + e^{-x} - e^{-x} \frac{x^m}{m!} = -e^{-x} \frac{x^m}{m!}$ .  $\blacktriangleleft$

► **Lemma 3.4** (see [13] for proof). *For all  $m \geq 1$ , we have  $(m!)^{1/m} < \xi_m < ((m+1)!)^{1/m+1}$ .*

► **Remark 3.5.** Setting  $\nu(x) = \nu(m, x) = \frac{\Gamma(m+1, x)}{m!}$ , and arguing as in Lemma 3.4, we have  $\nu'(x) < 0$ , which readily implies that  $\nu(x)$  is monotonically decreasing.

Stirling's formula applied to Lemma 3.4 readily implies the following.

► **Lemma 3.6.** *We have  $\lim_{m \rightarrow \infty} \frac{\xi_m}{m} = \frac{1}{e}$ .*

► **Lemma 3.7** (see [13] for proof). *For all  $k, m \geq 0$  integers, we have*

$$f(k, m) = \sum_{j=1}^k \frac{\xi_m^j}{j!} - \sum_{j=m+1}^{m+k} \frac{\xi_m^j}{j!} \geq 0.$$

## 3.2 Background: Sharding, poissonization, and stochastic dominance

For a sequence of random variables  $\mathbf{X} = X_1, \dots, X_n$ , let  $|\alpha \leq \mathbf{X} \leq \beta| = |\{i \mid \alpha \leq X_i \leq \beta\}|$  denote the number of realizations in this sequence falling in the interval  $[\alpha, \beta]$ .

### 3.2.1 Sharding

For the lower bound, we use poissonization and sharding [14]. Given random variables  $X_1, \dots, X_n$  with cdfs  $F_1, \dots, F_n$ , instead of sampling  $X_i$  from  $F_i$ , we instead replace it with a sequence of  $K$  independent random variables  $\mathbf{H}_i = Y_{i,1}, \dots, Y_{i,K}$ , such that  $\max_j Y_{i,j}$  has the same distribution as  $X_i$ . Specifically, the cdf of  $Y_{i,j}$ , for all  $j$ , is  $F_i^{1/K}$ . Thus, the distribution of  $\max\{Y_{i,1}, \dots, Y_{i,K}\}$  is the same as  $X_i$ . This creates a new sequence of  $Kn$  samples  $\mathbf{S} = \mathbf{H}_1 \cdot \mathbf{H}_2 \cdot \dots \cdot \mathbf{H}_n$ , where  $\cdot$  is the concatenation operator. Observe that for any  $\alpha \geq 0$  and integer  $t$ , we have

$$\mathbb{P}[|\mathbf{X} \geq \alpha| > t] < \mathbb{P}[|\mathbf{S} \geq \alpha| > t].$$

Intuitively, this implies that, for threshold algorithms, an instance consisting of  $\mathbf{S}$  instead of  $\mathbf{X}$  can only generate worse results. We emphasize that this sharding technique is done only for analysis purposes.

### 3.2.2 Poissonization

► **Definition 3.8** (Poisson Distribution). *A random variable  $X$  has Poisson distribution with rate  $\lambda$ , denoted by  $X \sim \text{Pois}(\lambda)$ , if  $\mathbb{P}[X = i] = \lambda^i e^{-\lambda} / i!$ . Conveniently,  $\mathbb{E}[X] = \mathbb{V}[X] = \lambda$ .*

The purpose of the sharding is to be able to bound quantities of the form  $\mathbb{P}[|\beta \leq \mathbf{S} \leq \tau| = t]$ . As  $K$  grows, the underlying random variable  $|\beta \leq \mathbf{S} \leq \tau|$  has a binomial distribution that converges to a Poisson distribution.

► **Observation 3.9.** *For  $c \in (0, 1]$ , we have, using L'Hôpital's rule, that  $\lim_{x \rightarrow \infty} x(1 - c^{1/x}) = \lim_{x \rightarrow \infty} \frac{1 - \exp(\log(c)/x)}{1/x} = \lim_{x \rightarrow \infty} \frac{\log(c) \exp(\log(c)/x)/x^2}{-1/x^2} = -\log c$ , where  $\log = \log_e$ .*

Let  $\tau$  be a threshold such that  $\sum_{i=1}^n \sum_{j=1}^K \mathbb{P}[Y_{i,j} \geq \tau] = c$  for some constant  $c$  to be determined shortly. We can rewrite this into the following.

$$\sum_{i=1}^n K \left(1 - \mathbb{P}[X_i \leq \tau]^{1/K}\right) = c. \quad (3.2)$$

The limit of Eq. (3.2), as  $K \rightarrow +\infty$ , is  $\sum_{i=1}^n -\log \mathbb{P}[X_i \leq \tau] = c$ , by Observation 3.9. Equivalently, for  $Z = \max\{X_1, \dots, X_n\}$ , we have

$$e^{-c} = \exp\left(\sum_{i=1}^n \log \mathbb{P}[X_i \leq \tau]\right) = \prod_{i=1}^n \mathbb{P}[X_i \leq \tau] = \mathbb{P}[X_1, \dots, X_n \leq \tau] = \mathbb{P}[Z \leq \tau].$$

In particular, the distribution of the number of indices  $j$ , such that  $Y_{i,j} \geq \tau$  can be well approximated with a Poisson distribution. Specifically, let  $V_{i,j} = 1 \iff Y_{i,j} \geq \tau$ , and consider the sum  $V_i = \sum_{j=1}^K V_{i,j}$ . The variable  $V_i \sim \text{bin}(K, \psi_i)$ , where  $\psi_i = 1 - \mathbb{P}[X_i \leq \tau]^{1/K}$ .

Let  $\lambda_i = \psi_i K$ , and consider the random variable  $U_i \sim \text{Pois}(\lambda_i)$  (i.e.,  $U_i$  has a Poisson distribution with rate  $\lambda_i$ ). Intuitively,  $V_i$  and  $U_i$  have similar distributions. Formally, Le Cam theorem implies that for any set  $T \subseteq \{0, 1, \dots, K\}$ , we have  $|\mathbb{P}[V_i \in T] - \mathbb{P}[U_i \in T]| \leq 2K\psi_i^2 = 2\lambda_i^2/K \leq 2c^2/K$ , by Eq. (3.2). The later quantity goes to zero as  $K$  increases.

Thus, we get a variable  $U_i$  with a Poisson distribution for each shard sequence  $\mathbf{H}_i$ , with rate  $\lambda_i$ , where  $U_i$  models the number of times we encounter in  $\mathbf{H}_i$  values larger than  $\tau$ . Thus,  $U_\tau = \sum_i U_i$  models the total number of times in the splintered sequence  $\mathbf{S}$  that values encountered are larger than  $\tau$ . The variable  $U_\tau$  has a Poisson distribution with rate  $\lambda_\tau = \sum_{i=1}^n \lambda_i$ .

### 3.2.3 The distribution in a range

Repeating the same process with a bigger threshold  $\beta > \tau$ , would yield a similar Poisson random variable  $U_\beta$  with a *lower* rate  $\lambda_\beta$ . The quantity  $\Delta = U_\tau - U_\beta$  is the number of values in  $\mathbf{S}$  in the range  $[\tau, \beta]$ . Furthermore,  $\Delta$  has a Poisson distribution with rate  $\lambda_\tau - \lambda_\beta$ . Specifically,  $\mathbb{P}[\beta \leq \mathbf{S} \leq \tau] = t] = \mathbb{P}[\Delta = t]$ .

The key to our analysis is that the variables  $\Delta$  and  $U_\beta$  are independent (in the limit as  $K$  increases).

### 3.2.4 Stochastic dominance

A standard observation is that for a non-negative random variable  $X$ , we have that  $\mathbb{E}[X] = \int_{x=0}^{\infty} \mathbb{P}[X \geq x] dx$ . Thus, for  $Z = \max\{X_1, \dots, X_n\}$ , and for an algorithm  $\mathcal{A}$ , if one can guarantee that there is  $c \in [0, 1]$ , such that for all  $\nu \geq 0$ ,  $\mathbb{P}[\mathcal{A} \geq \nu] \geq c \mathbb{P}[Z \geq \nu]$ , then

$$\mathbb{E}[\mathcal{A}] = \int_0^{\infty} \mathbb{P}[\mathcal{A} \geq x] dx \geq c \int_0^{\infty} \mathbb{P}[Z \geq x] dx \geq c \mathbb{E}[Z],$$

and thus  $c$  is a lower bound on the competitive ratio of  $\mathcal{A}$ . This argument is used in several results on prophet inequalities and is often referred to as *majorizing*  $\mathcal{A}$  with  $Z$ .

## 3.3 An optimal single-threshold algorithm

Here, we describe a single-threshold algorithm that achieves the optimal competitive ratio in the oracle model.

► **Definition 3.10** (Single-Threshold Algorithm). A single threshold algorithm for  $\mathcal{O}_m$  sets a threshold  $\tau$ , and starts observing the sequence. Whenever it encounters a realization  $> \tau$ , the algorithm stops and queries the oracle whether all the values remaining in the suffix of the sequence are of value  $\leq \tau$ . If the oracle returns YES, the algorithm accepts the current value and stops. Otherwise, it raises its threshold to  $\tau = X_i$  and continues. If the oracle runs out of oracle calls, it selects the first value encountered after the last oracle call that is bigger than  $\tau$  (which exists, since all oracle calls returned NO).

While technically, the querying threshold of the algorithm might change during its execution, we call the algorithm a single-threshold algorithm since it uses a single-threshold to decide whether to query the oracle or not, and this threshold *does not change with  $i$* , unlike for example the optimal DP for the IID prophet inequality or the prophet secretary model. Our oracle model is quite different than most other prophet inequality models in the sense that the algorithm has some knowledge of the (true) future. Of course, any algorithm that knows that the maximum of  $X_{i+1}, \dots, X_n$  is larger than  $X_i$  would be wasting queries if it expended them on some  $X_j < X_i$  for  $j > i$ , and thus the spirit of it being a single-threshold algorithm to decide whether to query the oracle or not remains.

► **Theorem 1.7.** For every  $m \geq 1$ , let  $\alpha_m = 1 - e^{-\xi_m}$ , where  $\xi_m$  is the unique positive solution to the equation  $1 - e^{-\xi_m} = \frac{\Gamma(m+1, \xi_m)}{m!}$ . For any finite sequence  $\mathbf{X}$  of non-IID variables, one can compute a value  $\tau$ , such that the single-threshold algorithm (with initial threshold  $\tau$ ) has competitive ratio  $\geq \alpha_m$ .

**Proof.** Let  $\mathbf{X} = X_1, \dots, X_n$ , and  $Z = \max_i X_i$ . The threshold  $\tau$  is the  $e^{-\xi_m}$  quantile of the maximum, i.e.  $\mathbb{P}[Z \leq \tau] = e^{-\xi_m}$ . We use  $\mathcal{A}(\mathbf{X})$  to denote the result of running the algorithm on  $\mathbf{X}$ .

As suggested in Section 3.2.1 (for the analysis), we imagine running the algorithm on the splintered sequence  $\mathbf{S}$ . Somewhat counterintuitively, imagine first generating  $\mathbf{S}$ , and computing  $X_i = \max_j Y_{i,j}$ , see Section 3.2.1. Thus,  $\max \mathbf{S} = \max \mathbf{X}$ . For the sequence  $\mathbf{S}$ , let  $\mathbf{S}_{\geq \tau}$  denote the subsequence of elements of  $\mathbf{S}$  that their values are above  $\tau$ . Observe that  $\mathbf{X}_{\geq \tau}$  is a subsequence of  $\mathbf{S}_{\geq \tau}$ . Thus, we analyze the algorithm performance on  $\mathbf{S}$ .

Let  $\beta \in [0, \tau]$ . The probability the algorithm selects a value above  $\beta$  is equal to the probability it selects any value. Thus,

$$\mathbb{P}[\mathcal{A}(\mathbf{X}) \geq \beta] = \mathbb{P}[\mathcal{A} \geq \tau] = \mathbb{P}[Z \geq \tau] = 1 - e^{-\xi_m} \geq (1 - e^{-\xi_m}) \mathbb{P}[Z \geq \beta]. \quad (3.3)$$

For  $\beta \in [\tau, +\infty)$ , let  $\mathbb{P}[Z \leq \beta] = e^{-q} > e^{-\xi_m}$ , implying  $\mathbb{P}[Z \geq \beta] = 1 - e^{-q}$ . By sharding and Poissonization, the number of shards in the range  $[\tau, \beta]$  (resp.  $\geq \beta$ ) is a Poisson random variable  $\Delta$  (resp.  $U_\beta$ ) with rate  $\xi_m - q$  (resp.  $q$ ), see Section 3.2.3. Critically,  $U_\beta$  and  $\Delta$  are independent. Consider the event of there being at most  $m$  values in the range  $[\tau, \beta]$ , and there being at least one value in  $[\beta, +\infty)$ . The value  $\mathcal{A}(\mathbf{X}) \geq \beta$  in that case. Hence, by the independence of  $\Delta$  and  $U_\beta$ , we have

$$\frac{\mathbb{P}[\mathcal{A}(\mathbf{X}) \geq \beta]}{\mathbb{P}[Z \geq \beta]} \geq \frac{\mathbb{P}[(U_\beta \geq 1) \cap (0 \leq \Delta \leq m)]}{\mathbb{P}[Z \geq \beta]} = \frac{\mathbb{P}[U_\beta \geq 1]}{\mathbb{P}[Z \geq \beta]} \mathbb{P}[0 \leq \Delta \leq m] = \mathbb{P}[0 \leq \Delta \leq m].$$

Now, we have

$$\mathbb{P}[0 \leq \Delta \leq m] = \sum_{i=0}^m e^{-(\xi_m - q)} \frac{(\xi_m - q)^i}{i!} = \frac{\Gamma(m+1, \xi_m - q)}{m!} \geq \frac{\Gamma(m+1, \xi_m)}{m!} = 1 - e^{-\xi_m}.$$

by Eq. (3.1), Remark 3.5 and Definition 3.1.

The above implies that, for any  $\beta \geq 0$ , we have  $\mathbb{P}[\mathcal{A}(\mathbf{X}) \geq \beta] \geq (1 - e^{-\xi_m}) \mathbb{P}[Z \geq \beta]$ , Namely,  $\text{RoE}(\mathcal{A}) \geq 1 - e^{-\xi_m}$ . ◀

### 3.4 A matching upper bound for single-threshold algorithms

To this end, we present an input sequence for which no algorithm can do better for the oracle that answers if  $X_i > \max_{j=i+1}^n X_j$ . Our upper bound is with respect to the strongest possible form of adversary, the almighty adversary, who knows from the beginning all possible realizations as well as the outcome of any random coins tossed by the algorithm.

#### Input instance

The input instance  $\mathcal{I}$  consists of  $n+2$  random variables, for sufficiently large  $n$ . Each of these random variables can have only two values – either zero or some positive value. Specifically, for  $\varepsilon > 0$  sufficiently small, let

$$X_1 = 1, \quad X_i = \begin{cases} 1 + \varepsilon(i-1) & \text{w.p. } \frac{\xi_m}{n} \\ 0 & \text{otherwise} \end{cases}, \quad \text{for } i \in \llbracket 2 : n+1 \rrbracket, \quad \text{and}$$

$$X_{n+2} = \begin{cases} \frac{1}{\varepsilon} & \text{w.p. } \varepsilon \\ 0 & \text{otherwise} \end{cases}.$$

By Lemma 3.6, we have  $\xi_m \approx m/e$  and as such, the expected number of non-zero entries in this sequence is (roughly)  $m/e + 1$ .

► **Lemma 3.11.** *For  $Z = \max_i X_i$ , we have  $\mathbb{E}[Z] = 2$  as  $\varepsilon \rightarrow 0$ .*

**Proof.** Let  $Z' = \max_{i \in \llbracket n+1 \rrbracket} X_i$ . Observe that  $Z' = 1$ . As such, for  $Z = \max(Z', X_{n+2})$ , we have  $\mathbb{E}[Z] = \mathbb{E}[\max_i X_i] = (1/\varepsilon)\varepsilon + (1-\varepsilon)\mathbb{E}[Z'] \xrightarrow{\varepsilon \rightarrow 0} 2$ . ◀

Next, we will need the following result on the approximation of a binomial distribution by a Poisson distribution, known as Le Cam's theorem ([5, 8]).

► **Theorem 3.12 (Le Cam's theorem).** *Let  $X_1, \dots, X_n$  be independent Bernoulli random variables, with  $p_i = \mathbb{P}[X_i = 1]$ , for  $i \in \llbracket n \rrbracket$ . Let  $S = \sum_i X_i$  and  $\lambda = \sum_i p_i$ . Then  $S$  has a Poisson binomial distribution with expectation  $\lambda$ . Furthermore, let  $Y \sim \text{Pois } \lambda$ . Then we have*

$$\sum_{i=0}^n |\mathbb{P}[S = i] - \mathbb{P}[Y = i]| = \sum_{i=0}^n \left| \mathbb{P}[S = i] - e^{-\lambda} \frac{\lambda^i}{i!} \right| \leq 2 \sum_{i=1}^n p_i^2.$$

► **Observation 3.13.** *Let  $\widehat{X}_i$  be an indicator variable for the event that  $X_i = 1$ . For sufficiently large  $n$ ,  $\nabla = \sum_{i=2}^{n+1} \widehat{X}_i$  has a binomial distribution that can be well approximated by a Poisson distribution (Theorem 3.12) with rate  $\xi_m$ . That is,  $\lim_{n \rightarrow \infty} \mathbb{P}[\nabla = k] = e^{-\xi_m} \frac{(\xi_m)^k}{k!}$ .*

Observe that  $\lim_{n \rightarrow \infty} \mathbb{P}[\nabla \leq k] = \sum_{i=0}^k e^{-\xi_m} \frac{(\xi_m)^i}{i!} = \mathbf{q}_{k+1}(\xi_m)$ . In the analysis to follow, we assume  $n \rightarrow \infty$ .

► **Theorem 1.8.** *For any  $m \geq 1$  and  $\delta > 0$ , there exists an input instance  $\mathcal{I}$  such that for any algorithm, we have  $\text{RoE}(\mathcal{A}) \leq 1 - e^{-\xi_m} + \delta$ .*

**Proof.** First, we discuss the strategy that the adversary adopts: the adversary first observes all values. Suppose  $k$  nonzero values show up from  $X_2, \dots, X_n$  at indices  $U = \{i_1, \dots, i_k\}$ , and all other  $n-k$  values from  $X_2, \dots, X_{n+1}$  at indices  $B = \{\hat{i}_1, \dots, \hat{i}_{n-k}\}$  are zero. One can easily see that it is optimal for the adversary to provide the random variables in the order  $X_{\sigma(1)}, \dots, X_{\sigma(n+2)}$  where  $\sigma$  is defined as  $\sigma(1) = 1$ ,  $\sigma(j) = i_j, j = 2, \dots, k+1$ ,  $\sigma(j) = \hat{i}_j$  and finally  $\sigma(n+2) = n+2$ . In other words, the adversary stacks all the  $k$  non zero values from  $X_2, \dots, X_{n+1}$  starting from index 2 to index  $k+1$ .

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Now we consider an algorithm for this setting. The algorithm is aware of the adversary's strategy and thus knows that it will observe  $X_{\sigma(1)} = X_1$ , then a stream of  $k$  ones (where  $k$  is unknown), then  $n - k$  zeros, and finally  $X_{\sigma(n+2)} = X_{n+2}$ . The algorithm has a simple decision to make in the beginning; it either queries at  $X_1$  and if the answer is NO it continues to  $X_{\sigma(2)}, \dots, X_{\sigma(n+1)}$  with  $m - 1$  oracle calls, or it can just proceed to  $X_{\sigma(2)}, \dots, X_{\sigma(n+1)}$  with  $m$  oracle calls. Thus, the only difference in the two cases is that in the former, it has only  $m - 1$  oracle calls for  $X_{\sigma(2)}, \dots, X_{\sigma(n+1)}$  but it gets an expected reward of 1 if  $X_{\sigma(2)} = \dots = X_{\sigma(n+2)} = 0$ , and in the later case, it has  $m$  oracle calls for  $X_{\sigma(2)}, \dots, X_{\sigma(n+1)}$ , but it gets 0 reward if  $X_{\sigma(2)} = \dots = X_{\sigma(n+2)} = 0$ .

Let  $k$  be the number of non-zeros in  $X_2, \dots, X_{n+1}$  (i.e.,  $X_{\sigma(k+1)}$  is the last 1). When the algorithm observes the stream of approximate ones from  $X_{\sigma(2)}, \dots, X_{\sigma(n+1)}$ , it needs to decide indices  $S \subseteq \llbracket 2 : n+1 \rrbracket$ ,  $|S| \leq m$  where it will expend the oracle call. Clearly, it is suboptimal to use the oracle at a 0 value, since regardless, the algorithm will receive a value of 0 in the end if it fails. Consider what happens if the algorithm decides to query at index  $i \in \llbracket 2 : n+1 \rrbracket$  with  $X_{\sigma(i)} = 1$ . If  $X_{\sigma(i+1)} = \dots = X_{\sigma(n+1)} = 0$ , then the algorithm gets on expectation  $1/\varepsilon \cdot \varepsilon + (1 - \varepsilon) \cdot 1 \xrightarrow{\varepsilon \rightarrow 0} 2$  reward on expectation. However, if  $X_{\sigma(i+1)} > 0$ , then the oracle will return NO because  $X_{\sigma(i)} \not\geq \max(X_{\sigma(i+1)}, \dots, X_{\sigma(n+2)})$ . On the other hand, if the algorithm does not query at index  $k + 1$  (i.e.,  $(k + 1) \notin S$ ), then the algorithm gets on expectation  $\mathbb{E}[X_{\sigma(n+2)}] = \mathbb{E}[X_{n+2}] = 1/\varepsilon \cdot \varepsilon = 1$ .

Hence, the crucial observation is that an algorithm starting at  $X_{\sigma(2)}$  that uses its query calls at indices  $S \subseteq \llbracket 2 : n+1 \rrbracket$  gets on expectation 2 if and only if  $(k + 1) \in S$ , and 1 otherwise. Thus, for algorithm  $\mathcal{A}_1$  that skips  $X_{\sigma(1)}$  and uses its oracles at indices  $S$ ,  $|S| = m$ , it satisfies

$$\begin{aligned} \mathbb{E}[\mathcal{A}_1] &= 2 \cdot \sum_{i \geq 0, (i+1) \in S} e^{-\xi_m} \frac{\xi_m^i}{i!} + 1 \cdot \sum_{i \geq 0, (i+1) \notin S} e^{-\xi_m} \frac{\xi_m^i}{i!} \\ &= \sum_{i \geq 0} e^{-\xi_m} \frac{\xi_m^i}{i!} + \sum_{i \geq 0, (i+1) \in S} e^{-\xi_m} \frac{\xi_m^i}{i!} \\ &= 1 + \sum_{(i+1) \in S} e^{-\xi_m} \frac{\xi_m^i}{i!} \end{aligned}$$

On the other hand, for algorithm  $\mathcal{A}_2$  that uses its oracle at  $X_{\sigma(1)}$  and uses its remaining oracles at indices  $S' \in \llbracket 2 : n+1 \rrbracket$ ,  $|S'| = m - 1$ , it gets an extra benefit of getting a reward with expected value 2 (as  $\varepsilon \rightarrow 0$ ) if  $X_{\sigma(2)} = \dots = X_{\sigma(n+1)} = 0$ . Hence, it satisfies

$$\begin{aligned} \mathbb{E}[\mathcal{A}_2] &= (e^{-\xi_m} \cdot 2) + \left( 2 \cdot \sum_{i \geq 0, (i+1) \in S'} e^{-\xi_m} \frac{\xi_m^i}{i!} \right) + \left( 1 \cdot \sum_{i \geq 1, (i+1) \notin S'} e^{-\xi_m} \frac{\xi_m^i}{i!} \right) \\ &= \left( \sum_{i \geq 0} e^{-\xi_m} \frac{\xi_m^i}{i!} \right) + e^{-\xi_m} + \sum_{(i+1) \in S'} e^{-\xi_m} \frac{\xi_m^i}{i!} \\ &= 1 + e^{-\xi_m} + \sum_{(i+1) \in S'} e^{-\xi_m} \frac{\xi_m^i}{i!}. \end{aligned}$$

First, we show that the expression  $\sum_{(i+1) \in S} e^{-\xi_m} \frac{\xi_m^i}{i!}$  subject to  $S \subseteq \llbracket 2 : n+1 \rrbracket$ ,  $|S| = m$  is maximized for  $S^* = \llbracket 2 : m+1 \rrbracket$ . Note that it is easy to verify that for a Poisson distribution with rate  $\lambda$ , its probability mass function  $e^{-\lambda} \lambda^i / i!$  is increasing for  $i < \lambda$ , and decreasing

after  $i > \lambda$ . Hence, the optimal  $S^* = \llbracket k : k + m - 1 \rrbracket$  for some  $k \geq 2$  that “covers” the rate  $\xi_m$  (this is the region with the most mass for a Poisson distribution). The optimal choice of  $k$  is  $k = 2$  because

$$\sum_{i=1}^m e^{-\xi_m} \frac{\xi_m^i}{i!} - \sum_{i=k-1}^{k+m-2} e^{-\xi_m} \frac{\xi_m^i}{i!} = \sum_{i=1}^{k-2} e^{-\xi_m} \frac{\xi_m^i}{i!} - \sum_{i=m+1}^{m+k-2} e^{-\xi_m} \frac{\xi_m^i}{i!} \geq 0,$$

where the last inequality holds by Lemma 3.7. Similarly,  $k = 2$  is optimal for when  $|S| = m - 1$ . Hence, we get the inequalities

$$\begin{aligned} \mathbb{E}[\mathcal{A}_1] &\leq 1 + \sum_{i=1}^m e^{-\xi_m} \frac{\xi_m^i}{i!} = 1 + \mathfrak{q}_{m+1}(\xi_m) - e^{-\xi_m}, \\ \mathbb{E}[\mathcal{A}_2] &\leq 1 + e^{-\xi_m} + \sum_{i=1}^{m-1} e^{-\xi_m} \frac{\xi_m^i}{i!} = 1 + \mathfrak{q}_m(\xi_m). \end{aligned}$$

Thus, we have

$$\max(\mathbb{E}[\mathcal{A}_1], \mathbb{E}[\mathcal{A}_2]) \leq 1 - e^{-\xi_m} + \mathfrak{q}_m(\xi_m) + e^{-\xi_m} \max\left\{1, \frac{\xi_m^m}{m!}\right\}$$

But recall from Lemma 3.4 that  $\xi_m^m \geq m!$ , thus

$$\begin{aligned} \max(\mathbb{E}[\mathcal{A}_1], \mathbb{E}[\mathcal{A}_2]) &\leq 1 - e^{-\xi_m} + \mathfrak{q}_m(\xi_m) + e^{-\xi_m} \cdot \frac{\xi_m^m}{m!} \\ &= 1 - e^{-\xi_m} + \mathfrak{q}_{m+1}(\xi_m) \\ &= 2(1 - e^{-\xi_m}). \end{aligned}$$

Therefore, the competitive ratio of every algorithm is

$$\text{RoE} \leq \frac{2(1 - e^{-\xi_m})}{2} = 1 - e^{-\xi_m}. \quad \blacktriangleleft$$

## 4 The IID settings

Motivated by the early work of [12] for the TOP-1-OF- $m$  model, in this section we study the IID setting and the  $\mathbb{P}_{\max}$  objective. As a warm-up, we take a look at the IID setting with the  $\mathbb{P}_{\max}$  objective and the case of  $m = 1$ , providing a simple, single-threshold algorithm.

### 4.1 A single-threshold algorithm for $m = 1$

Our single-threshold algorithm  $\mathcal{A}_p$  for  $\mathcal{M}(\mathcal{O}_1, \text{IID}, \mathbb{P}_{\max})$  selects a threshold  $\tau$  equal to the  $p$ th quantile of the given distribution  $\mathcal{D}$ , for some  $p \in [0, 1]$ . In other words,  $\tau$  is set such that  $p = \mathbb{P}[X_i \geq \tau]$ . The first time the algorithm observes a realization above  $\tau$ , it queries the oracle to see whether the realization should be selected or not. If it continues, it simply accepts the first value encountered above the observed realization on which it queried  $\mathcal{O}$ .

► **Lemma 4.1.** *There exists  $p \in [0, 1]$  such that  $\mathcal{A}_p$  selects the maximum realization with probability at least 0.797 in the  $\mathcal{M}(\mathcal{O}_1, \text{IID}, \mathbb{P}_{\max})$  model for large  $n$ .*

**Proof.** Let  $Y$  be the total number of realizations above  $\tau$ , and  $i_1 < i_2 < \dots < i_Y$  be the indices of the random variables above  $\tau$ , i.e.  $X_{i_t} > \tau$ , for  $t = 1, \dots, Y$ . Furthermore, let  $r_t$  be the rank of  $X_{i_t}$  in  $\mathcal{X} = \{X_{i_1}, \dots, X_{i_Y}\}$ , i.e. the number  $k$  such that  $X_{i_t}$  is the  $k$ th largest number in  $\mathcal{X}$ , and  $Z$  be the maximum realization of  $X_1, \dots, X_n$ .



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$X_{i_1}$  is the first realization we observe above  $\tau$ . Notice that if  $r_1 = 1$  or  $r_1 = 2$  then the algorithm always selects the maximum realization  $Z$ . In other words, given that  $Y = 1$  or  $Y = 2$ , the algorithm selects  $Z$  with probability 1. Consider the case  $Y > 2$ . Again, if  $r_1 \leq 2$ , the algorithm selects  $Z$  with probability 1. Otherwise, if  $r_1 > 2$ , the algorithm returns  $Z$  if and only if for all realizations above  $\tau$  that appear after  $X_{i_1}$  and are also larger than  $X_{i_1}$ , the first to encounter is  $Z$ . In other words, for the algorithm to succeed in this case, it must be that among the  $r_1 - 1$  values of rank smaller than  $r_1$ , the first one in the arrival order is the element of rank 1. Since the random variables are IID, the probability of this event is exactly  $1/r_1 - 1$ .

Let  $j$  be the first index such that  $X_{i_j} > X_{i_1}$ , and  $\alpha(Y) = \mathbb{P}[\mathcal{A} \text{ selects } Z \mid Y]$ . Conditioned on  $Y \geq 3$ , the probability that the algorithm selects  $Z$  is

$$\begin{aligned} \alpha(Y \mid Y \geq 3) &= \mathbb{P}[r_1 = 1] + \mathbb{P}[r_1 = 2] + \sum_{t=3}^Y \mathbb{P}[r_1 = t] \mathbb{P}[r_j = 1 \mid r_1 = t] \\ &= \frac{2}{Y} + \sum_{t=3}^Y \frac{\mathbb{P}[r_z = 1 \mid r_1 = t]}{Y} = \frac{1}{Y} \left( 2 + \sum_{t=3}^Y \mathbb{P}[r_z = 1 \mid r_1 = t] \right) \\ &= \frac{1}{Y} \left( 2 + \sum_{t=3}^Y \frac{1}{t-1} \right) = \frac{1}{Y} \left( 1 + \sum_{t=1}^{Y-1} \frac{1}{t} \right) \\ &= \frac{1}{Y} (1 + H_{Y-1}), \end{aligned}$$

where  $H_n$  denotes the  $n$ th harmonic number. Recall also that  $\alpha(Y \mid Y = 1) = \alpha(Y \mid Y = 2) = 1$ .

Next, we estimate  $\mathbb{P}[Y = i]$ , by approximating  $Y$  with a Poisson distribution via Le Cam's theorem. Let  $\delta_i = \left| \binom{n}{i} p^i (1-p)^{n-i} - e^{-np} \frac{(np)^i}{i!} \right|$ . The idea is to set  $p$  such that  $np = q$ , where  $q \geq 1$  is a fixed constant. We know that  $\mathbb{P}[Y = i] = \binom{n}{i} p^i (1-p)^{n-i}$ , and thus, by Theorem 3.12, we have

$$\sum_{i=0}^{\infty} \delta_i = \sum_{i=0}^{\infty} \left| \mathbb{P}[Y = i] - e^{-np} \frac{(np)^i}{i!} \right| = \sum_{i=0}^{\infty} \left| \mathbb{P}[Y = i] - e^{-q} \frac{q^i}{i!} \right| \leq \frac{2qp}{\max\{1, q\}} \leq 2p = \frac{2q}{n}.$$

Overall, the probability that  $\mathcal{A}$  selects  $Z$  is

$$\begin{aligned} \alpha(Y) &= \sum_{i=0}^n \mathbb{P}[Y = i] \cdot \alpha(Y \mid Y = i) \\ &= \mathbb{P}[Y = 1] + \sum_{i=2}^n \mathbb{P}[Y = i] \cdot \alpha(Y \mid Y = i) \\ &\geq np(1-p)^{(n-1)} + \sum_{i=2}^n \left( e^{-q} \frac{q^i}{i!} - \delta_i \right) \cdot \alpha(Y \mid Y = i), \end{aligned}$$

where the last inequality follows by the definition of  $\delta_i$ . Thus,

$$\begin{aligned} \alpha(Y) &= q(1-q/n)^{(n-1)} + \sum_{i=2}^n e^{-q} \frac{q^i}{i!} \cdot \alpha(Y \mid Y = i) - \sum_{i=2}^n \delta_i \cdot \alpha(Y \mid Y = i) \\ &\geq q(1-q/n)^{(n-1)} + \sum_{i=2}^n e^{-q} \frac{q^i}{i!} \frac{1 + H_{i-1}}{i} - \sum_{i=2}^n \delta_i \\ &\geq q(1-q/n)^{(n-1)} + e^{-q} \sum_{i=2}^n \frac{q^i (1 + H_{i-1})}{i! \cdot i} - \frac{2q}{n}. \end{aligned} \tag{4.1}$$

◀

It is easy to see that simply setting  $q = 2$ , which corresponds to  $p = 2/n$  and  $\tau$  being the  $2/n$ th quantile of  $\mathcal{D}$ , yields  $\alpha(Y) > 0.5801$  for all  $n \geq 20$ . Thus, our simple single-threshold algorithm, augmented with a single oracle call, beats, even for small  $n$ , the optimal algorithm for the IID prophet inequality which uses different thresholds per distribution and achieves a probability of success approximately 0.5801 [12].

Since the worst-case probability of  $\approx 0.5801$  by [12] is achieved for  $n \rightarrow \infty$ , one might be interested in the asymptotic behavior of the probability of our algorithm,  $\alpha(Y)$ , for large  $n$ . It is not too difficult to see after some calculations that, as  $n \rightarrow \infty$ , Eq. (4.1) is maximized for  $q \approx 2.435$ , yielding  $\alpha(Y) \approx 0.798$ .

## 4.2 A single-threshold algorithm for general $m$

As we saw in the previous section, even for a simple, single-threshold algorithm, the analysis of the winning probability gets tedious quickly. In this section, we generalize our single-threshold algorithm to the case of general  $m$ , and use the fact that the maximum of a uniformly random permutation of  $n$  values changes  $\mathcal{O}(\log n)$  times with high probability to obtain a guarantee on the winning probability that is super-exponential with respect to  $m$ .

As before, our algorithm selects a threshold  $\tau$  such that  $p = \mathbb{P}[X \geq \tau]$  and every time the algorithm observes a realization above  $\tau$ , it uses an oracle query and asks  $\mathcal{O}$  if the realization should be selected or not. If not, then it updates the threshold to the new higher value. If the algorithm runs out of oracle calls, then it selects the first element above the current threshold  $\tau$  that it encounters, if any. In other words, the algorithm uses the oracle calls greedily for all realizations above  $\tau$ .

► **Theorem 1.9** (see [13] for proof). *For sufficiently large  $m, n$ , there exists an algorithm for the  $\mathcal{M}(\mathcal{O}_m, \text{IID}, \mathbb{P}_{\max})$  model that selects the maximum realization with probability at least  $1 - \mathcal{O}(m^{-m/5})$ .*

## 4.3 An (almost) tight upper bound

Given that we have a simple, single-threshold algorithm for the  $\mathcal{M}(\mathcal{O}_m, \text{IID}, \mathbb{P}_{\max})$  setting, a reasonable question to ask is how far it is from being optimal. As we show in this section, the algorithm is asymptotically almost optimal.

► **Theorem 1.10** (see [13] for proof). *There exists an instance of  $\mathcal{M}(\mathcal{O}_m, \text{IID}, \mathbb{P}_{\max})$  for which no algorithm can select the maximum realization with probability greater than  $1 - \mathcal{O}(m^{-m})$ .*

## 5 Conclusion

In this work, we improved on the known results for the TOP-1-OF- $m$  model, for both the RoE and  $\mathbb{P}_{\max}$  objectives, via the lens of a simple prophet inequality augmented with oracle calls. All our results hold with respect to the strongest possible adversary, the almighty adversary. A weaker, offline, adversary is forced to select the order of distributions upfront, given only access to the same information as the algorithm. For such an adversary, one can do very slightly better than Theorem 1.8 – see the full version [13] for more details.

Our oracle choice was motivated by our efforts to reformulate the TOP-1-OF- $m$  model in order to improve upon the current known bounds. We mention a few other oracle models that are interesting and could potentially be useful in analyzing other prophet inequality settings: (i) the oracle can predict a *range* for the maximum value, but formalizing this in a more general setting turns out to be difficult without assuming something about the

support of each random variable, (ii) the algorithm can ask the oracle if there is a value that is greater than  $c \cdot X_i$ , for some constant  $c$ . This latter oracle is more powerful, as it doesn't exhibit the same limitations that our oracle model has in the example of Theorem 1.8. We leave exploring more complex oracle models for future work.

Finally, there are subtle differences between an oracle that answers queries of the form  $X_i > \max\{X_{i+1}, \dots, X_n\}$  and one that answers queries of the form  $X_i \geq \max\{X_{i+1}, \dots, X_n\}$ ; in particular, the  $>$  oracle is weaker than the  $\geq$  oracle. We refer the reader to the full version [13] for a discussion on this topic.

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