



# Hard Submatrices for Non-Negative Rank and Communication Complexity

Pavel Hrubeš   

Institute of Mathematics of ASCR, Prague, Czech Republic

---

## Abstract

Given a non-negative real matrix  $M$  of non-negative rank at least  $r$ , can we witness this fact by a small submatrix of  $M$ ? While Moitra (SIAM J. Comput. 2013) proved that this cannot be achieved exactly, we show that such a witnessing is possible approximately: an  $m \times n$  matrix of non-negative rank  $r$  always contains a submatrix with at most  $r^3$  rows and columns with non-negative rank at least  $\Omega(\frac{r}{\log n \log m})$ . A similar result is proved for the 1-partition number of a Boolean matrix and, consequently, also for its two-player deterministic communication complexity. Tightness of the latter estimate is closely related to the log-rank conjecture of Lovász and Saks.

**2012 ACM Subject Classification** Theory of computation

**Keywords and phrases** Non-negative rank, communication complexity, extension complexity

**Digital Object Identifier** 10.4230/LIPIcs.CCC.2024.13

**Funding** *Pavel Hrubeš*: This work was supported by Czech Science Foundation GAČR grant 19-27871X.

**Acknowledgements** The author wants to thank Anup Rao for useful comments.

## 1 Introduction

The rank of a matrix is one of the most versatile concepts from linear algebra. A basic property of matrix rank is the following: if a matrix  $M$  has rank at least  $r$  then it contains an  $r \times r$  submatrix of rank  $r$ . Put differently, the fact that  $\text{rk}(M) \geq r$  can be witnessed by a hard  $r \times r$  submatrix. Can we extend this witnessing property to other matrix complexity measures? We will consider two such measures: the *non-negative rank* of a non-negative real matrix and the *1-partition number* of a Boolean matrix.

Given a matrix with non-negative real entries, its non-negative rank is defined similarly to rank, except that we want to express the matrix as a sum of non-negative rank-one matrices. This quantity has numerous applications in communication complexity and linear optimization [20], and other fields (cf. [15]). In [20], Yannakakis has discovered a geometric interpretation of non-negative rank in terms of linear projections of polytopes. This connection has been extended and exploited in many subsequent results, see, e.g., [18, 2, 5], including the current paper.

If  $M$  is a 0, 1-matrix, its 1-partition number can be defined as the smallest  $r$  such that  $M$  can be written as a sum of  $r$  rank-one Boolean matrices. This is an important concept in communication complexity [11, 16]. Interpreting a 0, 1-matrix as the adjacency matrix of a bipartite graph, it is also equivalent to the *biclique partition number* (see [3] and references within).

If  $M$  has non-negative rank  $\geq r$ , can this fact be witnessed by a small submatrix? The short answer is no. In [15], Moitra presented an  $n \times n$  matrix  $M$  of non-negative rank 4 such that every submatrix with less than  $n/3$  columns has non-negative rank at most 3 – in particular,  $M$  contains no constant-size submatrix of non-negative rank 4. In Section 6.3, we will give a different example where the gap is more dramatic. Similarly, we will see that the most optimistic form of witnessing fails for 1-partition number. On the positive side, we will



© Pavel Hrubeš;  
licensed under Creative Commons License CC-BY 4.0  
39th Computational Complexity Conference (CCC 2024).

Editor: Rahul Santhanam; Article No. 13; pp. 13:1–13:12  
Leibniz International Proceedings in Informatics



LIPICs Schloss Dagstuhl – Leibniz-Zentrum für Informatik, Dagstuhl Publishing, Germany



show that a weaker form of witnessing nevertheless holds: if a matrix has non-negative rank  $r$  then it contains a submatrix of size bounded by a polynomial in  $r$  whose non-negative rank is close to  $r$ ; similarly for 1-partition number.

The two-player deterministic communication complexity of  $M$  can be characterized by the logarithm of the 1-partition number of  $M$ . Hence our witnessing result for 1-partition number can be restated in the language of communication complexity: if a Boolean function has a large communication complexity, this fact can be approximately witnessed by a relatively small set of inputs. It should be noted that this statement immediately follows from the log-rank conjecture of Lovász and Saks (presented in [14]). This conjecture relates the communication complexity of a Boolean matrix with its rank. It implies that for a Boolean matrix  $M$ , the three parameters – rank, 1-partition number, non-negative rank – are essentially the same, with their logarithm being polynomially related to the communication complexity of  $M$ . This allows us deduce a witnessing property for these measures from the witnessing property of matrix rank. Our result to confirms this prediction of the conjecture and it may therefore be interpreted as a vote in its favor. On the other hand, the log-rank conjecture implies a stronger form of witnessing than what we actually prove. Hence, in principle, a counterexample to the conjecture may be given by a matrix for which this predicted form of witnessing fails (see Section 5 for more details). According to [6], the witnessing problem for communication complexity has been previously posed by H. Halem.

Our witnessing results could be easily converted to non-trivial *approximation* algorithms to compute non-negative rank or the 1-partition number. These algorithms would run in polynomial time whenever the complexity parameter in question is fixed. Interestingly, *exact* algorithms of this form were given by Moitra [15] and Chandran et al. [3]. While there are similarities between these algorithms and the witnessing perspective, these algorithms ultimately do not search for a witness.

On a more abstract level, the witnessing problem can be posed with respect to any complexity measure whatsoever. A related result in Boolean circuit complexity are “antichackers” of Lipton and Young [13]. In their work, it is shown that if a Boolean function  $f$  requires a Boolean circuit of size  $s$  then there is a subset of inputs of size roughly  $s$  such that  $f$  restricted to this subset still requires circuit size roughly  $s$ . A related topic are “hard-core predicates” of Impagliazzo [10]. Recently, Göös et al. [6] studied deterministic query complexity from this perspective. An example from the opposite side of the spectrum is the chromatic number of a graph. It is known that a large chromatic number imposes almost no local structure on a graph and cannot be witnessed by a small subgraph [4, 17].

## 2 Main results

Given an  $m \times n$  matrix  $M$  with real non-negative entries, its *non-negative rank*,  $\text{rk}_+(M)$ , is the smallest  $s$  such that  $M$  can be written as

$$M = LR,$$

where  $L$  and  $R$  are non-negative matrices of dimensions  $m \times s$  and  $s \times n$ , respectively.

We will show that every  $M$  with large non-negative rank contains a relatively small submatrix of large non-negative rank.

► **Theorem 1.** *Let  $M$  be an  $m \times n$  non-negative real matrix with  $n \geq 2$ . Then for every  $k \leq n$ ,  $M$  contains an  $m \times k$  submatrix of columns with non-negative rank  $\Omega(R)$ , where  $R := \min\left(\left(\frac{k}{\log n}\right)^{\frac{1}{3}}, \frac{\text{rk}_+(M)}{\log n}\right)$ .*

A remarkable consequence is the following:

- $M$  contains an  $s_1 \times s_2$  submatrix with  $s_1, s_2 \leq \text{rk}_+(M)^3$  and non-negative rank  $\Omega(\frac{\text{rk}_+(M)}{\log n \log m})$ . Moreover, If  $M$  is a square matrix then so is the submatrix.

In some cases, a stronger conclusion is possible. For example, if  $\text{rk}_+(M) = n$  then every  $m \times k$  submatrix of  $M$  has non-negative rank  $k$ . Theorem 1 becomes interesting if  $\log n \ll \text{rk}_+(M) \ll n$ . For example, if  $M$  is  $n \times n$  with  $\text{rk}_+(M)$  roughly  $n^\epsilon$ , we obtain an  $n^{3\epsilon} \times n^{3\epsilon}$  submatrix of non-negative rank roughly  $n^\epsilon$ , and also an  $n^\epsilon \times n^\epsilon$  submatrix of non-negative rank roughly  $n^{\epsilon/3}$ . How far from truth is the estimate from Theorem 1 is an interesting question. In Section 6.3, we will see that the result gives a qualitatively correct picture: the exponent  $1/3$  can be replaced by  $1/2$  at best.

Given a Boolean matrix  $M \in \{0, 1\}^{m \times n}$ , let us define its *1-partition number*,  $\chi_1(M)$ , as the smallest  $s$  such that  $M$  can be written as

$$M = LR, \quad \text{with } L \in \{0, 1\}^{m \times s}, R \in \{0, 1\}^{s \times m},$$

where the operations are over  $\mathbb{R}$ . The definition emphasizes the analogy with  $\text{rk}_+$ , and  $\chi_1$  is also sometimes referred to as *binary rank*. On the other hand, the phrase “partition number” comes from communication complexity. The name is justified: it is easy to see that  $\chi_1(M)$  equals the smallest  $s$  such that the 1-entries of  $M$  can be partitioned into  $s$  1-monochromatic rectangles (i.e., rank-one Boolean matrices). Finally, when  $M$  is viewed as the adjacency matrix of a bipartite graph,  $\chi_1(M)$  also appears under the name *biclique partition number* [3].

In the case of  $\chi_1$ , we obtain a similar but simpler result:

- ▶ **Theorem 2.** *Let  $M$  be an  $m \times n$  Boolean matrix with  $n \geq 2$ . Then for every  $k \leq n$ ,  $M$  contains an  $m \times k$  submatrix of  $k$  columns with 1-partition number  $\Omega(\min(\sqrt{k}, \frac{\chi_1(M)}{\log n}))$ .*

One consequence is the following (cf. Corollary 6):

- if  $\chi_1(M) = p$  then  $M$  contains a  $p \times p$  submatrix with 1-partition number  $\Omega(p^{1/4})$ .

The results on 1-partition number imply similar statements in communication complexity; they will be presented in Section 5. Whether these witnessing results can be significantly improved is an intriguing question. It is intimately related to the log-rank conjecture; this connection is discussed in Section 5.

Theorems 1 and 2 are proved in Sections 6.2 and 4, respectively. The proof of Theorem 2 is self-contained. Theorem 1 uses geometrical interpretation of non-negative rank in terms of extended formulations of polytopes and also employs known bounds on complexity of quantifier elimination.

## Notation

All logarithms are in base 2 and  $[n] := \{1, \dots, n\}$ .

### 3 A combinatorial lemma

Both Theorems 1 and 2 rely on a simple combinatorial lemma.

- ▶ **Lemma 3.** *Let  $\mathcal{A} \subseteq 2^{[n]}$  be a family of subsets of  $[n]$ . Assume that  $1 \leq k \leq n$  is such that every  $k$ -element subset of  $[n]$  is contained in some  $A \in \mathcal{A}$ . Then there exists a subfamily  $\mathcal{A}' \subseteq \mathcal{A}$  of size  $|\mathcal{A}'| \leq O(|\mathcal{A}|^{\frac{1}{k}} \log(n/k))$  with  $\bigcup \mathcal{A}' = [n]$ . In particular, if  $|\mathcal{A}| \leq 2^k$  then  $|\mathcal{A}'| \leq O(\log n)$ .*

## 13:4 Hard Submatrices for Non-Negative Rank and Communication Complexity

**Proof.** Assume that  $|\mathcal{A}| \leq a^k$ . Let  $t$  be the size of a largest set in  $\mathcal{A}$ . Then we have

$$\binom{n}{k} \leq a^k \binom{t}{k}.$$

Hence  $t \geq \frac{n}{ea}$ , using the estimates  $\binom{n}{k}^k \leq \binom{n}{k}$ ,  $\binom{t}{k} \leq \left(\frac{et}{k}\right)^k$ . Take some  $A_0 \in \mathcal{A}$  of size  $t$ . Let

$$\mathcal{A}_1 := \{A \setminus A_0 : A \in \mathcal{A}\}.$$

Then every subset of  $U_1 := [n] \setminus A_0$  of size *at most*  $k$  is contained in some member of  $\mathcal{A}_1$ . The size of  $U_1$  is at most  $n(1 - \frac{1}{ea})$ . Similarly, take a largest set  $A_1$  from  $\mathcal{A}_1$  and obtain a new family  $\mathcal{A}_2 \subseteq 2^{U_2}$  on  $U_2 := U_1 \setminus A_1$ . After  $s$  steps, the size of  $U_s$  is at most  $n(1 - \frac{1}{ea})^s$  and after  $s \leq O(a \log(n/k))$  steps we have  $|U_s| \leq k$ . This guarantees that the largest set in  $\mathcal{A}_s$  is  $U_s$  itself and  $[n] = \bigcup_{i=0}^s A_i$ . By construction, every  $A_i$  is contained in some element of the original family  $\mathcal{A}$ .  $\blacktriangleleft$

For some range of parameters, the lemma can be also proved from the Min Max Theorem of Lipton and Young in [13] which would also give an approximate version of it.

An application (which will not be explicitly used) is the following. A subadditive measure on  $[n]$  is a function  $\mu : 2^{[n]} \rightarrow \mathbb{R}$  such that  $\mu(A_1 \cup A_2) \leq \mu(A_1) + \mu(A_2)$  holds for every  $A_1, A_2 \subseteq [n]$ .

► **Corollary 4.** *Let  $\mu$  be a subadditive measure on  $[n]$ . Assume  $1 \leq k \leq n$  and that every  $k$ -element subset of  $[n]$  has measure at most  $s$ . Let  $N$  be the number of  $\subseteq$ -maximal subsets of  $[n]$  of measure at most  $s$ . Then  $\mu([n]) \leq O(sN^{\frac{1}{k}} \log(n/k))$ .*

### 4 1-Partition number

In this section, we prove Theorem 2.

Let  $M$  be an  $m \times n$  matrix with rows indexed by  $[n] = \{1, \dots, n\}$ . Given  $A \subseteq [n]$ ,  $M_A$  denotes the submatrix obtained by removing the rows outside of  $A$  from  $M$ . Observe that<sup>1</sup>

$$\chi_1(M_{A_1 \cup A_2}) \leq \chi_1(M_{A_1}) + \chi_1(M_{A_2}), \quad (1)$$

and so  $\chi_1(M_A)$  can be viewed as a subadditive measure on  $[n]$  whenever  $M$  is fixed.

If a matrix  $M$  has rank  $r$ , its rows are a linear combination of a subset of  $r$  rows of  $M$ . This means that every column of  $M$  is determined by a fixed subset of  $r$  coordinates. If  $M$  is Boolean, this leads to the following useful fact:

■ if  $M$  has distinct columns then  $n \leq 2^{\text{rk}(M)}$  (similarly for rows).

► **Lemma 5.** *Let  $M$  be an  $m \times n$  Boolean matrix of rank  $r$ . Given  $s \in [n]$ , let  $\mathcal{A}$  be the collection of maximal subsets  $A \subseteq [n]$  with  $\chi_1(M_A) \leq s$  (i.e.,  $\chi_1(M_A) \leq s$  and  $\chi_1(M_{A'}) > s$  for every  $A' \supsetneq A$ ). Then  $|\mathcal{A}| \leq 2^{(r+s)^2}$ .*

**Proof.** Let  $v_1, \dots, v_n \in \mathbb{R}^m$  be the columns of  $M$ . Given  $L \in \{0, 1\}^{m \times s}$ , let

$$L^* := \{i \in [n] : \exists y \in \{0, 1\}^s v_i = Ly\}.$$

Let  $\mathcal{L} := \{L^* : L \in \{0, 1\}^{m \times s}\}$ .

<sup>1</sup> If  $A_1, A_2$  are disjoint, this is quite obvious. Otherwise consider  $A_1, A_2 \setminus A_1$ .

We claim that  $\mathcal{A} \subseteq \mathcal{L}$ . If  $\chi_1(M_A) \leq s$ , we can write  $M_A = LR$  with  $L \in \{0, 1\}^{m \times s}$  and  $R \in \{0, 1\}^{s \times |A|}$ . This means that every  $v_i$ ,  $i \in A$ , is a Boolean linear combination of the columns of  $L$  and  $A \subseteq L^*$ . Furthermore, if  $A$  is maximal, we must have  $A = L^*$ .

We now want to estimate the size of  $\mathcal{L}$ . The set  $L^*$  consists of indices  $i \in [n]$  so that there exists  $x \in \mathbb{R}^n$ ,  $y \in \mathbb{R}^s$  satisfying

$$Mx - Ly = 0 \tag{2}$$

such that  $y \in \{0, 1\}^s$  and  $x$  is the  $i$ -th unit vector. Since  $M$  has rank  $r$  and  $L$  has rank at most  $s$ , the system (2) is equivalent to a subsystem of  $t := \min((s + r), m)$  equations. These correspond to rows of the matrix  $(M, L)$ . Hence, in order to determine  $L^*$ , it is sufficient to specify a  $t$ -element subset of  $[m]$  together with the  $t \times s$  submatrix of  $L$ . This gives the estimate

$$|\mathcal{L}| \leq \binom{m}{t} 2^{ts} \leq 2^{t(s + \log m)}.$$

Finally, we can assume that  $M$  has distinct rows and so  $\log m \leq r$ , obtaining the bound  $2^{(r+s)^2}$ . ◀

► **Theorem 2 (restated).** *Let  $M$  be an  $m \times n$  Boolean matrix with  $n \geq 2$ . Then for every  $k \leq n$ ,  $M$  contains an  $m \times k$  submatrix of  $k$  columns with 1-partition number  $\Omega(\min(\sqrt{k}, \frac{\chi_1(M)}{\log n}))$ .*

**Proof.** Let  $r$  be the rank of  $M$ . We will assume  $r \leq \frac{k^{1/2}}{2}$ . Otherwise, observe that  $M$  contains a full rank  $r \times r$  submatrix,  $\chi_1$  is lower-bounded by rank, and the conclusion of the theorem follows.

Let  $s$  be the maximum  $\chi_1(M_A)$  over all  $A \subseteq [n]$  of size  $k$ . Let  $\mathcal{A}$  be the family from the previous lemma. If  $|\mathcal{A}| \geq 2^k$ , we have  $2^k \leq 2^{(s+r)^2}$  and therefore  $s \geq \frac{k^{1/2}}{2}$  from the assumption on  $r$ .

Assume  $|\mathcal{A}| \leq 2^k$ . By Lemma 3, there exists a subfamily  $\mathcal{A}' \subseteq \mathcal{A}$  of size  $O(\log n)$  which covers  $[n]$ . Using (1), this implies  $\chi_1(M) \leq O(s \log n)$  and so  $s \geq \Omega(\chi_1(M)/\log n)$ . ◀

► **Corollary 6.** *Let  $M$  be as above with  $\chi_1(M) = p$ . Then  $M$  contains*

- (i) *a submatrix of at most  $p^2$  columns with partition number  $\Omega(p/\log n)$ ,*
- (ii) *a submatrix with at most  $p^2$  rows and columns with partition number  $\Omega(p/(\log n \log m))$ .*  
*If  $M$  is a square matrix then so is the submatrix.*
- (iii) *a submatrix with  $p$  columns with partition number  $\Omega(p^{\frac{1}{2}})$*
- (iv) *a  $p \times p$  submatrix with partition number  $\Omega(p^{\frac{1}{4}})$ .*

**Proof.** Part (i). If  $n \leq p^2$ ,  $M$  itself satisfies the statement. Otherwise apply the theorem with  $k = p^2$ .

Part (ii). Apply (i) again to the transpose of the submatrix obtained in (i). If  $m = n$ , we can enlarge the submatrix to a square matrix.

Part (iii). Without loss of generality, we can assume that the columns of  $M$  are distinct. This implies that  $M$  has rank at least  $\log n$ . If  $\sqrt{p} \leq p/\log n$ , apply the theorem to obtain the desired matrix. Otherwise, we have  $p \geq \log^2 n$ .  $M$  contains a submatrix of  $p$  columns of rank at least  $\min(p, \log n) \geq \sqrt{p}$ .

Part (iv) follows by taking the submatrix from (iii), and applying (iii) to its transpose. ◀

► **Remark 7.** The bound of Theorem 2 can be slightly improved to give  $\Omega(\sqrt{k \log(1 + \frac{\chi_1(M)}{k^{1/2} \log n})})$ , as long as  $k^{1/2} \leq \chi_1(M)/\log n$ . For example, if  $k = \chi_1(M)/\log n$ , we obtain a submatrix of  $k$  columns with 1-partition number  $\Omega(\sqrt{k \log k})$ .

Furthermore,  $M$  always contains a submatrix  $M'$  of  $k$  columns with  $\chi_1(M') \geq \chi_1(M) \cdot \left\lceil \frac{n}{k} \right\rceil^{-1}$ , which gives better parameters if  $\chi_1(M)$  is close to  $n$ .

#### 4.1 A somewhat non-trivial example

We now give a finite example which shows that the most optimistic form of witnessing fails for  $\chi_1$ .

► **Theorem 8.** *There exists a  $5 \times 6$  Boolean matrix  $M$  with  $\chi_1(M) = 5$  such that every  $5 \times 5$  submatrix of  $M$  has 1-partition number at most 4.*

**Proof.** Let

$$M := \begin{pmatrix} 1 & 0 & 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 \end{pmatrix}.$$

We first argue that  $\chi_1(M) > 4$ , which implies  $\chi_1(M) = 5$  since  $M$  has 5 rows.

Suppose that  $\chi_1(M) \leq 4$ . Then there exists a set of Boolean row-vectors  $V = \{v_1, \dots, v_4\}$  such that every row of  $M$  is their Boolean linear combination; i.e., of the form  $\sum_{i \in A} v_i$  for some  $A \subseteq \{1, \dots, 4\}$ . Note that in this expression, the non-zero coordinates of  $v_i$ ,  $i \in A$ , are a subset of the non-zero coordinates of the given row. Using this observation, it is easy to see that  $V$  must consist of the first 4 rows of  $M$ . If  $\chi_1(M) \leq 4$  this means that the last row of  $M$  is a Boolean combination of the first four rows, which is clearly impossible.

We now show that every submatrix obtained by removing a column from  $M$  has  $\chi_1$  at most 4.

First, assume that  $M'$  has been obtained by removing the third column. The resulting matrix, together with a partition into four 1-monochromatic rectangles  $a, b, c, d$ , is as follows:

$$M' = \begin{pmatrix} 1 & 0 & 0 & 1 & 1 \\ 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \end{pmatrix}, \quad \begin{pmatrix} a & 0 & 0 & a & b \\ 0 & c & c & 0 & b \\ 0 & 0 & d & d & 0 \\ 0 & 0 & d & d & b \\ a & c & c & a & b \end{pmatrix}.$$

Second, assume that  $M''$  has been obtained by removing the last column. The resulting matrix, together with its partition, is the following:

$$M'' = \begin{pmatrix} 1 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \end{pmatrix}, \quad \begin{pmatrix} a & 0 & 0 & 0 & a \\ 0 & b & 0 & b & 0 \\ 0 & 0 & c & d & d \\ 0 & 0 & 0 & d & d \\ a & b & c & b & a \end{pmatrix}.$$

Finally, note that if we remove from  $M$  the first or the second column, we obtain  $M'$  (up to a permutation of rows and columns). And, if we remove the fourth or fifth column, we obtain  $M''$ . Hence indeed, every  $5 \times 5$  submatrix has  $\chi_1$  at most 4 ◀

By placing  $n$  copies of the matrix from Theorem 8 on diagonal, we obtain:

► **Corollary 9.** *For every  $n$ , there exists a  $5n \times 6n$  Boolean matrix  $M$  with  $\chi_1(M) = 5n$  such that every submatrix obtained by removing a column of  $M$  has 1-partition number strictly less than  $5n$ .*

## 5 Communication complexity, and a comparison with the log-rank conjecture

Given an  $m \times n$  Boolean matrix  $M$ , consider the following two-player game: Alice knows  $i \in [m]$ , Bob knows  $j \in [n]$ , and they are supposed to compute the value of  $M_{i,j}$ . Denote by  $\text{cc}(M)$  the deterministic communication complexity of this game. For details about the communication model, see for example [11, 16].

In order to relate communication complexity with  $\chi_1$ , we need the following classical fact (the first inequality is due to Yao, the second is due to Yannakakis [20]): if  $M$  is non-constant then

$$\log(\chi_1(M) + 1) \leq \text{cc}(M) \leq O(\log^2 \chi_1(M)). \quad (3)$$

► **Proposition 10.** *Let  $M$  be a Boolean matrix with communication complexity  $c$ . Then there exist  $k \geq \Omega(\sqrt{c})$  and a  $2^k \times 2^k$  submatrix of  $M$  with communication complexity at least  $k/4 - O(1)$ .*

**Proof.** From (3), there exists  $k \geq \Omega(\sqrt{c})$  with  $\chi_1(M) \geq 2^k$ . Corollary 6, part (iv), gives  $2^k \times 2^k$  submatrix  $M'$  with  $\chi_1(M') \geq \Omega(2^{k/4})$ . By (3), we have  $\text{cc}(M') \geq k/4 - O(1)$ . ◀

It is worthwhile to compare this with what is predicted by the log-rank conjecture [14] of Lovász and Saks.

► **Log-rank conjecture.** *There is a constant  $\alpha$  such that  $\text{cc}(M) \leq O(\log^\alpha(\text{rk}(M)))$  for any non-zero Boolean matrix  $M$ .*

► **Proposition 11.** *Assume the log-rank conjecture. Then every Boolean matrix with communication complexity  $c$  contains a  $2^k \times 2^k$  submatrix  $M'$  with  $\chi_1(M') = 2^k$ , communication complexity  $k + 1$ , and  $k \geq \Omega(c^{1/\alpha})$ .*

**Proof.** If  $M$  has communication complexity  $c$  then, by the log-rank conjecture,  $M$  has rank at least  $2^k$  with  $k \geq \Omega(c^{1/\alpha})$ . Hence  $M$  contains a full-rank  $2^k \times 2^k$  submatrix  $M'$ . Since  $\chi_1(M') \geq \text{rk}(M')$ , we have  $\chi_1(M') = 2^k$ . If  $c$  is sufficiently large, so that  $k \geq 1$ , then  $M'$  is non-constant and we obtain  $\text{cc}(M') \geq k + 1$  by (3). ◀

This is almost what has been proved in Proposition 10. One difference is that the constant  $\alpha$  in Proposition 11 is unconditionally set to 2 in Proposition 10. However, there is a more important qualitative difference. The submatrix presented in Proposition 11 has *highest possible* communication complexity: the protocol in which Alice sends her input to Bob and Bob sends back the answer (or vice versa), is optimal. Any other protocol cannot save even *one bit* of communication. In contrast, Proposition 10 presents a submatrix with only a very high communication complexity. To summarize, Proposition 10 confirms a prediction of the log-rank conjecture. But with worse parameters than what the conjecture predicts: consequently the bound in the proposition is far from tight, or the conjecture is false.

Another consequence is:

► **Remark 12.** In order to solve the log-rank conjecture, it is sufficient to focus on  $2^k \times 2^k$  matrices with communication complexity at least  $k/4 - O(1)$ .



## 6 Non-negative rank

### 6.1 Extended formulations and separation complexity

Let us first make a short detour into extended formulations of convex polyhedra.

A *polyhedron*  $P \subseteq \mathbb{R}^r$  is a (possibly unbounded) set defined by a finite number of linear constraints. Following [20, 18, 2], define the *extension complexity* of  $P$ ,  $\text{xc}(P)$ , as the smallest  $s$  such that  $P$  is a linear projection of a polyhedron  $Q \subseteq \mathbb{R}^m$  where  $Q$  can be defined using  $s$  inequalities (and any number of equalities). Observe that  $P$  with extension complexity  $s$  can be expressed in the standard form

$$x \in P \text{ iff } \exists_{y \in \mathbb{R}^s} Cx + Dy = b, y \geq 0,$$

where  $C \in \mathbb{R}^{t \times r}$ ,  $D \in \mathbb{R}^{t \times s}$  and  $b \in \mathbb{R}^t$  for some  $t$ .

Let  $V$  be a finite subset of  $\mathbb{R}^r$ . Given  $A \subseteq V$ , its *separation complexity*,  $\text{sep}_V(A)$ , is the minimum  $\text{xc}(P)$  over all polyhedra  $P \subseteq \mathbb{R}^r$  with<sup>2</sup>

$$P \cap V = A;$$

such a  $P$  is called a *separating* polyhedron for  $A$ . In other words,  $\text{sep}_V(A)$  is the smallest  $s$  so that we can distinguish points in  $A$  from points in  $V \setminus A$  by means of a linear program with  $s$  inequalities. Moreover, such a program can be rewritten as

$$x \in A \text{ iff } (x \in V \text{ and } \exists_{y \in \mathbb{R}^s} Cx + Dy = b, y \geq 0).$$

The notion of separation complexity has been studied in [7, 8, 9] in the case when  $V = \{0, 1\}^n$  is the Boolean cube. The following theorem is of independent interest and can be seen as an extension of similar results in [7, 9]. The proof is a considerable simplification of the previous ones.

► **Theorem 13.** *Let  $V$  be a non-empty finite subset of  $\mathbb{R}^r$ . Given a parameter  $s \geq 1$ , let  $\mathcal{A}$  be the collection of subsets  $A$  of  $V$  with  $\text{sep}_V(A) \leq s$ . Then*

$$|\mathcal{A}| \leq 2^{O((s+r+s)^2 \log |V|)}.$$

The proof is delegated to the appendix.

An immediate consequence of Theorem 13 is a theorem from [9]:

- if  $V = \{0, 1\}^n$  then there exists  $A \subseteq V$  with  $\text{sep}_V(A) \geq 2^{n^{\frac{1}{3}(1-o(1))}}$ .

### 6.2 Submatrices of large non-negative rank

In order to apply Theorem 13, we also need a connection between extension complexity and non-negative rank. This is provided by the notion of slack matrix introduced in [20]. Following [20, 2], we now define what it is. Let  $V$  be a sequence  $v_1, \dots, v_{m_1}$  of points in  $\mathbb{R}^r$  and  $L(x)$  a system  $\ell_1(x) \geq b_1, \dots, \ell_{m_2}(x) \geq b_{m_2}$  of inequalities in  $\mathbb{R}^r$ . The slack matrix with respect to  $V$  and  $L(x)$  is the  $m_2 \times m_1$  matrix  $S$  such that

$$S_{i,j} = \ell_i(v_j) - b_i.$$

Let  $P_0 := \text{conv}(V)$  be the convex hull of  $V$  and  $P_1 := \{x \in \mathbb{R}^r : L(x) \text{ holds}\}$ . If  $P_0 \subseteq P_1$  then  $S$  is non-negative. In [2], we can find:

<sup>2</sup> If no such polyhedron exists, which may happen if  $V$  is not convexly independent, we set  $\text{sep}_V(A) := \infty$ .



► **Lemma 14** ([2]). *Let  $P_0 \subseteq P_1$  and  $S$  be as above. Define  $xc(P_0, P_1)$  as the minimum  $xc(P)$  over all polyhedra with  $P_0 \subseteq P \subseteq P_1$ . Then*

$$rk_+ S - 1 \leq xc(P_0, P_1) \leq rk_+ S.$$

► **Theorem 1** (restated). *Let  $M$  be an  $m \times n$  non-negative real matrix with  $n \geq 2$ . Then for every  $k \leq n$ ,  $M$  contains an  $m \times k$  submatrix of columns with non-negative rank  $\Omega(R)$ , where  $R := \min\left(\left(\frac{k}{\log n}\right)^{\frac{1}{3}}, \frac{rk_+(M)}{\log n}\right)$ .*

**Proof.** Let  $r$  be the rank of  $M$ . We can write  $M = LR$  where  $L \in \mathbb{R}^{m \times r}$ ,  $R \in \mathbb{R}^{r \times n}$ . Let  $V \subseteq \mathbb{R}^r$  be the set of columns  $v_1, \dots, v_n$  of  $R$ . (Without loss of generality, the columns of  $M$  are distinct). Given  $A \subseteq [n]$ , let  $M_A$  be the submatrix obtained by deleting columns outside of  $A$  from  $M$ . Also let  $V_A := \{v_i : i \in A\}$ . Then  $M_A$  can be interpreted as the slack matrix of the polytope  $P_A = \text{conv}(V_A)$  and the polyhedron  $Q = \{x \in \mathbb{R}^d : Lx \geq 0\}$ .

Suppose that for every  $A$  of size  $k$ ,  $rk_+(M_A) \leq s$ . Then for every such  $A$ , there is a polyhedron  $Q_A$  with  $V_A \subseteq Q_A \subseteq Q$  with  $xc(Q_A) \leq s$ . Let  $A^* := V \cap Q_A$ . Then  $Q_A$  is a separating polyhedron for  $A^* \supseteq A$ . Let  $\mathcal{A}$  be the collection of  $A^*$  over all  $A$  of size  $k$ . Theorem 13 implies

$$|\mathcal{A}| \leq 2^{c \log n (s+r)^3},$$

where  $c$  is an absolute constant.

We will assume  $r \leq \left(\frac{k}{2^c \log n}\right)^{1/3}$ . Otherwise  $M$  contains a full rank  $r \times r$  submatrix,  $rk_+$  is lower-bounded by rank, and the conclusion of the theorem follows.

If  $|\mathcal{A}| \geq 2^k$ , we obtain  $c \log n (s+r)^3 \geq k$  and hence  $s \geq \Omega((k/\log n)^{1/3})$  from the assumption on  $r$ .

Assume  $|\mathcal{A}| \leq 2^k$ . By Lemma 3, there exists a subfamily  $\mathcal{A}' \subseteq \mathcal{A}$  of size  $O(\log n)$  which covers  $[n]$ . This implies (note that (1) holds also for non-negative rank)  $rk_+(M) \leq O(s \log n)$  and  $s \geq \Omega(rk_+(M)/\log n)$ . ◀

The following is proved similarly to Corollary 6:

► **Corollary 15.** *Let  $M$  be a non-negative  $m \times n$  matrix with  $rk_+(M) = p$ . Then  $M$  contains*

- (i) *an  $s_1 \times s_2$  submatrix with  $s_1, s_2 \leq p^3$  with non-negative rank  $\Omega\left(\frac{p}{\log n \log m}\right)$ . If  $m = n$ , we can assume  $s_1 = s_2$ .*
- (ii) *a  $p \times p$  submatrix with non-negative rank  $\Omega\left(\frac{p^{\frac{1}{3}}}{\log^{\frac{1}{3}} n \log m}\right)$ .*

### 6.3 Tightness

In [15], Moitra has constructed a non-negative matrix  $M$  with the following properties:

- $M$  is  $3rn \times 3rn$ ,  $rk_+(M) \geq 4r$ , any submatrix with  $< n$  columns has non-negative rank at most  $3r$ .

Observe that in order to witness the non-negative rank of this  $M$  exactly, one needs a constant fraction of the columns of  $M$ . On the other hand, the gap between the non-negative rank of  $M$  and that of its submatrices is quite mild.

We now give a different example which is of a similar flavor as the bound from Theorem 1. It also shows that the constant  $\frac{1}{3}$  in the theorem can be replaced by  $\frac{1}{2}$  at best. The example follows from very non-trivial results of Kwan et al. [12]. A similar bound would follow from the more general result of Shitov [19].

► **Theorem 16.** For every  $n$ , there exists an  $n \times n$  matrix with non-negative rank  $\Omega(\sqrt{n})$  such that every  $n \times k$  submatrix has non-negative rank  $O(\sqrt{k})$ .

**Proof.** From [12], there exists an  $n$ -vertex polygon  $P \subseteq \mathbb{R}^2$  with vertices lying on the unit circle with extension complexity  $\Omega(\sqrt{n})$ . Let  $M$  be its slack matrix with columns corresponding to vertices  $v_1, \dots, v_n$  of  $P$ . From Lemma 14, we have  $\text{rk}_+(M) \geq \Omega(\sqrt{n})$ . Given an  $n \times k$  submatrix  $M'$  with columns  $i_1, \dots, i_k$ , Lemma 14 shows that  $\text{rk}_+(M')$  is at most the extension complexity of  $\text{conv}(v_{i_1}, \dots, v_{i_k})$  (plus 1). Using another result from [12], every  $k$ -gon with vertices on the unit circle has extension complexity at most  $O(\sqrt{k})$ . ◀

## 7 Open problems

Our first two open problems are concerned with tightness of the bounds in Theorems 1 and 2.

► **Open problem 1.** Let  $M$  be  $m \times n$  non-negative matrix. Does  $M$  contain a submatrix of at most  $\text{rk}_+(M)^2$  columns with non-negative rank  $\Omega(\text{rk}_+(M))$ ?

► **Open problem 2.** Find a Boolean matrix  $M$  with  $\chi_1(M) = p$  such that every  $p \times p$  submatrix has 1-partition number much smaller than  $p$ .

As far as we can see, the bound from Problem 1 is consistent with what we know about non-negative rank, and would be optimal. The task is to improve Corollary 15(i) in two different ways: first, to reduce the dependence on  $\text{rk}_+(M)$  from cubic to quadratic and, second, to eliminate the logarithmic dependence on the size of  $M$  altogether. For Problem 2, Theorem 8 gives an  $M$  with submatrices of  $\chi_1$  strictly less than  $p$ ; there should exist a construction with a larger gap.

As discussed in Section 5, in order to solve the log-rank conjecture, it is enough to focus on matrices with large 1-partition number. The following is the extreme case of this question:

► **Open problem 3.** Suppose  $M$  is  $n \times n$  Boolean matrix with  $\chi_1(M) = n$ . How small can the rank of  $M$  be?

---

## References

- 1 S. Basu, R. Pollack, and M.F. Roy. *Algorithms in real algebraic geometry*. Springer-Verlag, 2006.
- 2 G. Braun, S. Fiorini, S. Pokutta, and D. Steuer. Approximation limits of linear programs (beyond hierarchies). *Math. of Operations Research*, 40(3), 2015.
- 3 S. Chandran, D. Issac, and A. Karrenbauer. On the parameterized complexity of biclique cover and partition. In *International Symposium on Parameterized and Exact Computation*, 2016.
- 4 P. Erdős. Problems and results in combinatorial analysis and graph theory. *Annals of Discrete Mathematics*, 38:81–92, 1988.
- 5 S. Fiorini, S. Massar, S. Pokutta, H. R. Tiwary, and R. de Wolf. Linear vs. semidefinite extended formulations: exponential separation and strong lower bounds. In *Symposium on the Theory of Computing*, 2011.
- 6 M. Göös, I. Newman, A. Riazanov, and D. Sokolov. Hardness condensation by restriction. *ECCC*, 2023.
- 7 P. Hrubeš. On  $\epsilon$ -sensitive monotone computations. *Computational Complexity*, 29(2), 2020.
- 8 P. Hrubeš. On the complexity of computing a random Boolean function over the reals. *Theory of Computing*, 16(9):1–12, 2020.
- 9 P. Hrubeš and N. Talebanfard. On the extension complexity of polytopes separating subsets of the Boolean cube. *Disc. and Comp. Geom.*, 70(1), 2022.

- 10 R. Impagliazzo. Hard-core distributions for somewhat hard problems. In *Proceedings of IEEE 36th Annual Foundations of Computer Science*, pages 538–545, 1995.
- 11 Eyal Kushilevitz and Noam Nisan. *Communication Complexity*. Cambridge University Press, 1996.
- 12 Matthew Kwan, Lisa Sauermann, and Yufei Zhao. Extension complexity of low-dimensional polytopes. *Transactions of the American Mathematical Society*, 375(6), 2022.
- 13 Richard Lipton and Neal Young. Simple strategies for large zero-sum games with applications to complexity theory. *CoRR*, cs.CC/0205035, May 2002. doi:10.1145/195058.195447.
- 14 L. Lovász and M. Saks. Lattices, mobius functions and communications complexity. In *29th Annual Symposium on Foundations of Computer Science (FOCS 1988)*, pages 81–90, 1988.
- 15 Ankur Moitra. An almost optimal algorithm for computing nonnegative rank. In *SIAM J. Comput.*, 2013. URL: <https://api.semanticscholar.org/CorpusID:1920044>.
- 16 Anup Rao and Amir Yehudayoff. *Communication Complexity: and Applications*. Cambridge University Press, 2020.
- 17 V. Rödl and R. A. Duke. On graphs with small subgraphs of large chromatic number. *Graphs and Combinatorics*, 1:91–96, 1985.
- 18 Thomas Rothvoß. Some 0/1 polytopes need exponential size extended formulations. *CoRR*, abs/1105.0036, 2011. arXiv:1105.0036.
- 19 Y. Shitov. Sublinear extension of polygons. *arXiv*, 2014. arXiv:1412.0728.
- 20 Mihalis Yannakakis. Expressing combinatorial optimization problems by linear programs. *Journal of Computer and System Sciences*, 43(3):441–466, 1991.

## A Proof of Theorem 13

The proof uses known results on quantifier elimination which we first outline. We follow the monograph of Basu, Pollack and Roy [1]. Theorem 13 requires an elimination of only a single block of existential quantifiers, so we focus on this case only.

For  $b \in \mathbb{R}$ , let

$$\operatorname{sgn}(b) := \begin{cases} 1, & b > 0, \\ 0, & b = 0, \\ -1, & b < 0. \end{cases}$$

Given  $b = \langle b_1, \dots, b_m \rangle \in \mathbb{R}^m$ , let  $\operatorname{sgn}(b) := \langle \operatorname{sgn}(b_1), \dots, \operatorname{sgn}(b_m) \rangle \in \{-1, 0, 1\}^m$ . Let  $F = F(z, y)$  be a sequence of  $m$  polynomials  $f_1, \dots, f_m \in \mathbb{R}[z, y]$  in variables  $z = \{z_1, \dots, z_{k_1}\}$  and  $y = \{y_1, \dots, y_{k_2}\}$ . Given  $a \in \mathbb{R}^{k_1}$ , define  $\operatorname{SGN}_1(F, a) \subseteq \{-1, 0, 1\}^m$

$$\operatorname{SGN}_1(F, a) := \{\operatorname{sgn}(F(a, b)) : b \in \mathbb{R}^{k_2}\}.$$

Let

$$\operatorname{SGN}(F) := \{\operatorname{SGN}_1(F, a) : a \in \mathbb{R}^{k_1}\}.$$

Theorem 14.16 from [1] provides the following bound on the size of  $\operatorname{SGN}$ :

► **Theorem ([1]).** *If every polynomial in  $F$  has degree at most  $d$  then*

$$|\operatorname{SGN}(F)| \leq m^{(k_1+1)(k_2+1)} d^{O(k_1)O(k_2)}. \quad (4)$$

We now apply this result to the case of Theorem 13. Let  $V, s, \mathcal{A}$  be as in the assumption. Every  $A \in \mathcal{A}$  can be described by a linear system with  $s$  inequalities. Namely, for every  $x \in V$ ,

$$x \in A \text{ iff } \exists_{y \in \mathbb{R}^s} Cx + Dy = b, y \geq 0, \quad (5)$$

where  $C \in \mathbb{R}^{t \times r}$ ,  $D \in \mathbb{R}^{t \times s}$  and  $b \in \mathbb{R}^t$ . Since  $Cx + Dy = b$  is a system of equations in  $r + s$  variables  $x, y$ , we can also assume  $t = r + s$ .

### 13:12 Hard Submatrices for Non-Negative Rank and Communication Complexity

Let us view the parameters  $C, D, b$  in (5) as variables. Let  $z$  be the set of these variables, of size  $k_1 = (r+s)(r+s+1)$ . Given  $v \in V$ , let  $F_v(z, y)$  be the sequence of  $(r+s)$  polynomials

$$Cv + Dy - b$$

in variables  $z$  and  $y = \{y_1, \dots, y_s\}$ . Let  $F(z, y)$  be the union of  $F_v(z, y)$  over all  $v \in V$ , together with the polynomials  $y_1, \dots, y_s$ . Hence  $F$  consists of  $m = s + |V|(r+s)$  polynomials of degree at most two.

$F(z, y)$  is set up so that

$$|\mathcal{A}| \leq |\text{SGN}(F)|.$$

To see this, observe that whenever the parameters  $z$  are fixed, the set  $A \subseteq V$  given by (5) is uniquely determined by  $\text{SGN}_1(F(z, y))$ . Since every  $A \in \mathcal{A}$  is obtained by some fixing of the parameters, we indeed obtain  $|\mathcal{A}| \leq |\text{SGN}(F(z, y))|$ .

Finally, we can apply (4) to estimate  $|\text{SGN}(F)|$  with  $m = s + |V|(r+s)$ ,  $k_1 = (r+s)(r+s+1)$ ,  $k_2 = s$ , and  $d = 2$ . To simplify the expression, we can assume  $s+r \leq |V|$ ; otherwise the upper bound asserted in Theorem 13 exceeds the trivial bound  $|\mathcal{A}| \leq 2^{|V|}$ . This means that  $m \leq 2|V|^2$ . If we loosen the bound (4) as  $|\text{SGN}(F)| \leq (dm)^{O(k_1)O(k_2)}$ , we obtain (recall that  $s \geq 1$ )

$$|\text{SGN}(F)| \leq 2^{O(s(s+r)^2 \log |V|)},$$

as required.