

Bi-Reachability in Petri Nets with Data

Łukasz Kamiński 

University of Warsaw, Poland

Sławomir Lasota 

University of Warsaw, Poland

Abstract

We investigate Petri nets with data, an extension of plain Petri nets where tokens carry values from an infinite data domain, and executability of transitions is conditioned by equalities between data values. We provide a decision procedure for the bi-reachability problem: given a Petri net and its two configurations, we ask if each of the configurations is reachable from the other. This pushes forward the decidability borderline, as the bi-reachability problem subsumes the coverability problem (which is known to be decidable) and is subsumed by the reachability problem (whose decidability status is unknown).

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1 Introduction

We investigate the model of Petri nets with data, where tokens carry values from some fixed data domain, and executability of transitions is conditioned by relations between data values involved. We study Petri nets with *equality* data [20, 22, 28], i.e., a countable infinite data domain with equality as the only relation. Other data domains have been also studied, for instance Petri nets with *ordered* data [22], i.e., a countable infinite, densely and totally ordered data domain (the model subsumes Petri nets with equality data). One can also consider an abstract setting of Petri nets with an arbitrary fixed data domain [20].

As an illustrating example, consider a Petri net with equality data which has two places p_1, p_2 and two transitions t_1, t_2 , as depicted in Fig. 1. Transition t_1 outputs two tokens with arbitrary but distinct data values onto place p_1 . Transition t_2 inputs two tokens with the same data value, say a , one from p_1 and one from p_2 , and outputs three tokens: two tokens with arbitrary but equal data values b , where $b \neq a$, one onto p_1 and the other onto p_2 , plus one token with a data value $c \neq a$ onto p_1 . Note that transition t_2 does not specify whether $b = c$ or not, and therefore both options are allowed.

The most fundamental decision problem for Petri nets, the *reachability* problem, asks, given a net together with source and target configurations, if there is a run from source to target. It is well known that the reachability problem is undecidable for Petri nets with ordered data [22], while the decidability status of this problem for equality data still remains an intriguing open question. The same applies to two other major extensions of plain Petri nets, namely pushdown Petri nets [23] and branching Petri nets [9, 29]. On the other hand, the *coverability* problem (where we ask if there is a run from source to a configuration that possibly extends target by some extra tokens) is decidable for both equality and ordered



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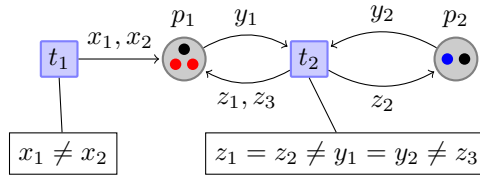
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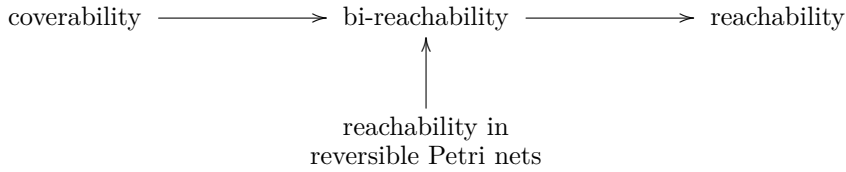
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■ **Figure 1** A Petri net with equality data, with places $\{p_1, p_2\}$ and transitions $\{t_1, t_2\}$. The shown configuration engages 5 tokens, carrying 3 different data values, depicted through different colors.

data [20]. As widely known, coverability easily reduces to reachability. Furthermore, the reachability problem is decidable, also for equality and ordered data, in the special case of *reversible* Petri nets (where transitions are closed under reverse), as recently shown in [15].

In this paper we do a step towards decidability of reachability in Petri nets with equality data, and study a relevant decision problem sandwiched between reachability and the two latter decidable problems: the *bi-reachability* problem (also called *mutual reachability problem* or *reversible reachability problem* [24]). It asks, for a net and two its configurations, if each of the configurations is reachable from the other one. In other words, the problem asks if two given configurations are in the same bi-reachability equivalence class. Here are all known reductions, valid for Petri nets with either equality or ordered data, as well as for plain Petri nets (without data):



As our main result we prove decidability of this problem for equality data domain. This result pushes further the decidability border, subsuming decidability of coverability, and of reachability in reversible Petri nets with equality data. Our approach is specific to equality data, and thus we leave unresolved the status of bi-reachability in case of ordered data.

The decision procedure for bi-reachability is inspired by the classical decomposition approach used to decide reachability in plain Petri nets [18, 19, 27]. There, it is often more convenient to work with *vector addition systems with states* (VASS) instead of Petri nets [18, 27]. Following this line, for technical convenience we prefer to work with the model of *data VASS* (DVASS) [16] rather than with Petri nets. In short, our approach consists of two ingredients. First, we provide a sufficient condition for a DVASS to admit bi-reachability (resembling Θ_1 and Θ_2 conditions of [18, 27]), which is effectively testable. Second, in case the condition fails, we provide an effective way of reducing a DVASS to an equivalent one, with respect to bi-reachability, which has smaller *rank*. As ranks are well founded, the reduction step guarantees correctness and termination. Importantly, the decision procedure manipulates DVASS, and does not need to resort to manipulation of more general structures (like generalised VASS of [18, 27], or graph-transition sequences of [19], or witness graph sequences of [25], or KLM sequences of [26]). This allows us to avoid similar generalisations in the data setting, and allows to keep the algorithm relatively simple.

Our work leaves two exciting open questions: can one extend our approach to bi-reachability in case of ordered data, or to reachability in case of equality data. Clearly, if attempting to solve the latter problem, one unavoidably will be faced with some generalisation of the above-mentioned structures to the data setting.

Related research. Petri nets with equality data are a well established and widely studied model of concurrent systems, as data allow to model important aspects of such systems not captured by plain Petri nets, e.g. process identity [1, 5]. The model can be also seen as a reinterpretation of the classical definition of Petri nets with a relaxed notion of finiteness, namely orbit-finiteness, where one allows for orbit-finite sets of places and transitions instead of just finite ones; this is along the lines of [3, 4]. Similar net models have been proposed already in the early 80ies: high-level Petri nets [13] and colored Petri nets [17]. Since then, similar formalisms seem to have been rediscovered, for instance constraint multiset rewriting [6, 7, 8].

In plain Petri nets, bi-reachability is decidable as a consequence of decidability of reachability [18, 19, 27]. Later, exact EXPSPACE complexity was established in [24]. In our setting, the problem is ACKERMANN-hard due to [23]. In pushdown Petri nets, decidability of reachability in the reversible subclass has been shown only recently [12], while decidability status of bi-reachability is still open. Indeed, it is known that reachability in pushdown Petri nets with d places reduces to coverability in pushdown Petri nets with $d + 1$ places, and the latter problem reduces to bi-reachability in pushdown Petri nets. Hence, decidability of bi-reachability would imply decidability of reachability in case of pushdown Petri nets.

2 Preliminaries: orbit-finite sets and vectors

In the sequel, let \mathbb{A} denote a fixed countable infinite set of data values (called also *atoms*). By $\text{Aut}(\mathbb{A})$ we denote the set of all permutations of \mathbb{A} (called also *automorphisms*). For a subset $S \subseteq \mathbb{A}$ we define the subgroup $\text{Aut}_S(\mathbb{A}) = \{\sigma \in \text{Aut}(\mathbb{A}) \mid \sigma(s) = s \text{ for all } s \in S\}$. Permutations in $\text{Aut}_S(\mathbb{A})$ we call *S-automorphisms*.

Orbit-finite sets. In the following we study actions of the group $\text{Aut}(\mathbb{A})$ on different sets. An action of $\text{Aut}(\mathbb{A})$ on a set Z is a group homomorphism ι from $\text{Aut}(\mathbb{A})$ to functions $Z \rightarrow Z$. We write $\sigma(z)$ instead of $\iota(\sigma)(z)$ for $\sigma \in \text{Aut}(\mathbb{A})$ and $z \in Z$. In the sequel we always use the natural action of $\text{Aut}(\mathbb{A})$ that, regardless of Z , renames atoms $a \in \mathbb{A}$ but leaves other elements intact. Here are two specific examples of such action that will serve later as building blocks in the definition of our model:

► **Example 1.** Let $\perp \notin \mathbb{A}$. For any finite sets L and \mathcal{R} of *locations* and *register names*, respectively, the group $\text{Aut}(\mathbb{A})$ acts naturally on the set of *states* $Q = L \times (\mathcal{R} \rightarrow (\mathbb{A} \cup \{\perp\}))$, namely given $\sigma \in \text{Aut}(\mathbb{A})$ and $q = (\ell, \nu) \in Q$, we put

$$\sigma(q) := (\ell, \sigma(\nu)) \quad \text{where } \sigma(\nu)(r) = \begin{cases} \sigma(\nu(r)), & \text{if } \nu(r) \in \mathbb{A} \\ \perp & \text{if } \nu(r) = \perp. \end{cases}$$

Furthermore, for any finite sets H, P of plain *places* and atom *places*, respectively, $\text{Aut}(\mathbb{A})$ acts naturally on functions $H \cup P \times \mathbb{A} \rightarrow \mathbb{Z}$, namely given $\sigma \in \text{Aut}(\mathbb{A})$ and $\mathbf{v} : H \cup P \times \mathbb{A} \rightarrow \mathbb{Z}$ we put $\sigma(\mathbf{v})(h) := \mathbf{v}(h)$ for $h \in H$, and $\sigma(\mathbf{v})(p, \sigma(a)) := \mathbf{v}(p, a)$ for $p \in P$. ◻

Roughly speaking, a set is *orbit-finite* if it has a finite number of elements up to automorphisms of atoms. We define the *orbit* of an element $z \in Z$:

$$\text{ORBIT}(z) := \{\sigma(z) \mid \sigma \in \text{Aut}(\mathbb{A})\}.$$

As different orbits are necessarily disjoint, Z partitions uniquely into orbits. A subset $X \subseteq Z$ is *orbit-finite* if it is a finite union of orbits. Clearly all orbits, and hence also all finite unions thereof, are closed under the action of $\text{Aut}(\mathbb{A})$. Orbit-finite sets are closed under finite unions and products [2, Lem. 3.24].

► **Example 2.** We continue Example 1. The whole set $Q = L \times (\mathcal{R} \rightarrow (\mathbb{A} \cup \{\perp\}))$ is orbit-finite, since the orbit of a state $q = (\ell, \nu) \in Q$ is determined by its location ℓ , the inverse image of \perp , namely $\{r \in \mathcal{R} \mid \nu(r) = \perp\}$, and the *equality type* of ν , namely the set $\{(r, r') \in \mathcal{R}^2 \mid \nu(r) = \nu(r') \neq \perp\}$. Indeed, for every two states $q = (\ell, \nu)$ and $q' = (\ell', \nu')$ such that $\ell = \ell'$, and ν and ν' have the same inverse image of \perp and the same equality type, there is an automorphism $\sigma \in \text{Aut}(\mathbb{A})$ such that $\sigma(q) = q'$.

On the other hand, the function space $(H \cup P \times \mathbb{A}) \rightarrow \mathbb{Z}$ is not orbit-infinite. \lrcorner

Vectors. Given a set X , by $X \rightarrow_{\text{fin}} \mathbb{Z}$ we denote the commutative group freely generated by X , and the group operation we denote by \oplus . We write $\mathbf{v} \ominus \mathbf{w}$ instead of $\mathbf{v} \oplus \mathbf{w}^{-1}$. Equivalently, $X \rightarrow_{\text{fin}} \mathbb{Z}$ can be identified with the set of all functions $\mathbf{v} : X \rightarrow \mathbb{Z}$ which map almost all elements of X to 0, i.e., those functions where the set $\{x \in X \mid \mathbf{v}(x) \neq 0\}$ is finite. Elements of $X \rightarrow_{\text{fin}} \mathbb{Z}$ we call *X-vectors*, or simply *vectors* if the generating set X is clear from the context. The zero vector we denote by $\mathbf{0}$, irrespectively of X , and a single-generator vector $x \in X$ we denote by $\mathbf{1}_x$. Seen as a function $X \rightarrow \mathbb{Z}$, the vector $\mathbf{1}_x$ maps x to 1 and all other elements of X to 0. When X is finite, we call *X-vectors* finite as well. Nonnegative vectors, denoted $X \rightarrow_{\text{fin}} \mathbb{N}$, are elements of the commutative monoid freely generated by X , or functions $\mathbf{v} : X \rightarrow \mathbb{N}$ which map almost all elements of X to 0 or, equivalently, finite multisets of elements of X . We write $\oplus W$ to denote the sum of a finite set W of vectors.

In the sequel the generating set X is most often of the form $H \cup P \times \mathbb{A}$ for some finite sets P, H . Clearly, $(H \cup P \times \mathbb{A}) \rightarrow_{\text{fin}} \mathbb{Z}$ is isomorphic to $(H \rightarrow_{\text{fin}} \mathbb{Z}) \times (P \times \mathbb{A} \rightarrow_{\text{fin}} \mathbb{Z})$, as every vector $\mathbf{v} : (H \cup P \times \mathbb{A}) \rightarrow_{\text{fin}} \mathbb{Z}$ decomposes uniquely as the sum $\mathbf{v} = \mathbf{u} \oplus \mathbf{w}$, where $\mathbf{u} : H \rightarrow_{\text{fin}} \mathbb{Z}$, $\mathbf{w} : P \times \mathbb{A} \rightarrow_{\text{fin}} \mathbb{Z}$. Given $\mathbf{v} : (H \cup P \times \mathbb{A}) \rightarrow_{\text{fin}} \mathbb{Z}$, we define its support $\text{SUPP}(\mathbf{v}) \subseteq \mathbb{A}$, as the (necessarily finite) set of those atoms which are sent by \mathbf{v} to a nonzero value:

$$\text{SUPP}(\mathbf{v}) := \{a \in \mathbb{A} \mid \exists p \in P : \mathbf{v}(p, a) \neq 0\}.$$

Intuitively, $\text{SUPP}(\mathbf{v})$ contains those atoms that 'appear' in \mathbf{v} . We observe that $\sigma(\mathbf{v}) = \mathbf{v}$ as long as $\sigma(a) = a$ for all $a \in \text{SUPP}(\mathbf{v})$. The natural action of $\text{Aut}(\mathbb{A})$ given in Example 1 restricts to the set of vectors $(H \cup P \times \mathbb{A}) \rightarrow_{\text{fin}} \mathbb{Z}$, which is still not orbit-infinite.

► **Example 3.** Transitions t_1, t_2 of Petri net in Figure 1 are semantically orbit-finite sets of $(P \times \mathbb{A})$ -vectors, where $P = \{p_1, p_2\}$ (i.e., $H = \emptyset$). Indeed, the effect of firing t_1 amounts to adding two arbitrary but different atoms $a \neq b$ to place p_1 , i.e., is described by an *X*-vector

$$\mathbf{v}_1 = (p_1, a) \oplus (p_1, b) \quad (a \neq b).$$

As the choice of atoms $a \neq b$ is arbitrary, all possible effects of firing the transition span one orbit of vectors: $V_1 = \text{ORBIT}(\mathbf{v}_1)$. The effect of firing t_2 amounts to removing some arbitrary atom a from both p_1 and p_2 , and adding two further atoms b, c not equal to a : one of them is added to both p_1 and p_2 , while the other one only to p_1 . As it is not specified whether $b = c$ or not, we describe t_2 by two *X*-vectors:

$$\mathbf{v}_2 = (p_1, c) \oplus (p_1, b) \oplus (p_2, b) \ominus (p_1, a) \ominus (p_2, a) \quad (a \neq b \neq c \neq a) \quad (1)$$

$$\mathbf{v}'_2 = (p_1, b) \oplus (p_1, b) \oplus (p_2, b) \ominus (p_1, a) \ominus (p_2, a) \quad (a \neq b). \quad (2)$$

As before, the choice of atoms is arbitrary, and hence all possible effects of firing t_2 span the union of two orbits of vectors: $V_2 = \text{ORBIT}(\mathbf{v}_2) \cup \text{ORBIT}(\mathbf{v}'_2)$. Intuitively, different orbits in T_2 correspond to different *equality types* of a tuple of atoms (a, b, c) : one defined by inequalities $a \neq b \neq c \neq a$, and another defined by $a \neq b = c$. This example illustrates a transformation of Petri nets to data VASS, the model we work with in this paper.¹ \lrcorner

Multiset sum problem. The following core decision problem, parametrised by an orbit-finite set X , will be useful later:

MULTISET SUM

Input: an orbit-finite set M of X -vectors, and an X -vector \mathbf{b} .

Question: is \mathbf{b} equal to the sum of a finite multiset of vectors from M ?

In other words, we ask if \mathbf{b} is a nonnegative integer linear combination of vectors from M . We assume that M is represented by a finite set of representatives, one per orbit.

► **Lemma 4** ([14, Thm. 17]). MULTISET SUM *is decidable*.

3 Data vector addition systems with states

Classical Petri nets are equivalent, with respect to most decision problems, to vector addition systems (VASS). Likewise, we introduce here a formalism equivalent to Petri nets with data, called data vector addition systems with states (DVASS). It is an extension of (stateless) data vector addition systems (DVAS) studied in [16].

Data VASS. A data VASS (DVASS) $\mathcal{V} = (L, \mathcal{R}, H, P, T)$ consists of pairwise disjoint finite sets of locations L , register names \mathcal{R} , plain places H , atom places P , and an *orbit-finite* set

$$T \subseteq Q \times ((H \cup P \times \mathbb{A}) \rightarrow_{\text{fin}} \mathbb{Z}) \times Q$$

of *transitions*, where $Q = L \times (\mathcal{R} \rightarrow (\mathbb{A} \cup \{\perp\}))$ is the set of *states*. The set T is thus assumed to be a finite union of orbits, under the natural action of $\text{Aut}(\mathbb{A})$ on transitions that extends the action on vectors and states given in Example 1: for $t = (q, \mathbf{v}, q') \in T$ we put $\sigma(t) := (\sigma(q), \sigma(\mathbf{v}), \sigma(q'))$. In particular, T is closed under the action of $\text{Aut}(\mathbb{A})$. Given a state $q = (\ell, \nu) \in Q$, the function ν is called *register valuation*. Intuitively, $\nu(r) = a$ means that register r contains atom a , while $\nu(r) = \perp$ means that r is empty. The vector \mathbf{v} is called the *effect* of transition (q, \mathbf{v}, q') .

The model of (plain) VASS corresponds to the special case where $\mathcal{R} = \emptyset$ and $P = \emptyset$, i.e., DVASS without registers and atom places. In this case the set $T \subseteq Q \times (H \rightarrow_{\text{fin}} \mathbb{Z}) \times Q$, being orbit-finite, is necessarily finite. The model of DVAS corresponds to the special case when $L = \{*\}$ is a singleton and $\mathcal{R} = \emptyset$ and $H = \emptyset$, i.e., DVASS without locations, registers and plain places.

A *pseudo-configuration* of \mathcal{V} is a pair $(q, \mathbf{v}) \in Q \times ((H \cup P \times \mathbb{A}) \rightarrow_{\text{fin}} \mathbb{Z})$, written $q(\mathbf{v})$. A *pseudo-run* from $q_1(\mathbf{v}_0)$ to $q_k(\mathbf{v}_k)$ is a sequence of pseudo-configurations $\pi = q_0(\mathbf{v}_0) q_1(\mathbf{v}_1) \dots q_k(\mathbf{v}_k)$ such that $t_i = (q_{i-1}, \mathbf{v}_i - \mathbf{v}_{i-1}, q_i) \in T$ for every $i = 1, \dots, k$. We say that the pseudo-run π *uses* the transitions $t_1, \dots, t_k \in T$. The support of a state $q = (\ell, \nu)$ is the set of all atoms used in registers, i.e. $\text{SUPP}(q) = \nu(\mathcal{R}) \cap \mathbb{A}$. The support of a transition $t = (q, \mathbf{v}, q')$ is $\text{SUPP}(t) = \text{SUPP}(q) \cup \text{SUPP}(\mathbf{v}) \cup \text{SUPP}(q')$. We also

¹ As in a transformation from plain Petri nets to VASS, in case of Petri net with *tight loops*, i.e., transitions that simultaneously input and output the same atom from/to the same place, we would have to split every such transition into input and output part.

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define the support of a pseudo-run as the union of supports of all its pseudo-configurations: $\text{SUPP}(\pi) = \text{SUPP}(q_0) \cup \text{SUPP}(\mathbf{v}_0) \cup \text{SUPP}(q_1) \cup \dots \cup \text{SUPP}(q_k) \cup \text{SUPP}(\mathbf{v}_k)$. We again extend the action of $\text{Aut}(\mathbb{A})$, this time to pseudo-runs, in an expected way:

$$\sigma(q_0(\mathbf{v}_0) q_1(\mathbf{v}_1) \dots q_k(\mathbf{v}_k)) := \sigma(q_0)(\sigma(\mathbf{v}_0)) \sigma(q_1)(\sigma(\mathbf{v}_1)) \dots \sigma(q_k)(\sigma(\mathbf{v}_k)).$$

The set of pseudo-runs is closed under the action of $\text{Aut}(\mathbb{A})$.

Configurations are those pseudo-configurations $q(\mathbf{v})$ where the vector \mathbf{v} is nonnegative, i.e., $\mathbf{v} : (H \cup P \times \mathbb{A}) \rightarrow_{\text{fin}} \mathbb{N}$. Let $\text{CONF} = Q \times ((H \cup P \times \mathbb{A}) \rightarrow_{\text{fin}} \mathbb{N})$ denote the set of all configurations. A *run* is a pseudo-run where every pseudo-configuration $q_i(\mathbf{v}_i)$ is actually a configuration. We write $q(\mathbf{v}) \dashrightarrow q'(\mathbf{v}')$ (resp. $q(\mathbf{v}) \rightarrow q'(\mathbf{v}')$) if there is a pseudo-run (resp. a run) from $q(\mathbf{v})$ to $q'(\mathbf{v}')$.

► **Example 5.** Continuing Example 3, Petri net in Figure 1 is equivalent to a DVAS $\mathcal{V} = (\{*\}, \emptyset, \emptyset, \{p_1, p_2\}, T)$, whose transitions are (as $\mathcal{R} = \emptyset$, we omit register valuations)

$$T = \{*\} \times (V_1 \cup V_2) \times \{*\}.$$

The initial configuration shown in Figure 1 is $*(\mathbf{v})$, where $\mathbf{v} = (p_1, a) \oplus (p_1, c) \oplus (p_1, c) \oplus (p_2, a) \oplus (p_2, b)$ for some distinct atoms $a, b, c \in \mathbb{A}$. In order to illustrate DVASS, we drop the first inequality in the constraint on t_2 , and consider the relaxed constraint $z_1 = z_2 \wedge y_1 = y_2 \neq z_3$ instead. This adds a third orbit of possible effects of firing t_2 , when the atom b added to places p_1 and p_2 is the same as the atom a removed (c.f. (1) in Example 3):

$$\mathbf{v}_2'' = (p_1, c) \oplus (p_1, a) \oplus (p_2, a) \ominus (p_1, a) \ominus (p_2, a) \quad (a \neq c).$$

The modified Petri net is equivalent to a DVASS $\mathcal{V}' = (L, \emptyset, \emptyset, P, T')$ with two locations $L = \{\ell, \ell'\}$, still no registers, a larger set of atom places $P = \{p_1, p_2, \bar{p}\}$, and transitions:

$$T' = \{\ell\} \times (V_1 \cup V_2) \times \{\ell\} \cup \{\ell\} \times \text{ORBIT}(\mathbf{w}) \times \{\ell'\} \cup \{\ell'\} \times \text{ORBIT}(\mathbf{w}') \times \{\ell\},$$

where vectors \mathbf{w}, \mathbf{w}' are splitting \mathbf{v}_2'' into input and output part, using an auxiliary place \bar{p} to temporarily store atom a :

$$\mathbf{w} = (\bar{p}, a) \ominus (p_1, a) \ominus (p_2, a) \quad \mathbf{w}' = (p_1, c) \oplus (p_1, a) \oplus (p_2, a) \ominus (\bar{p}, a) \quad (a \neq c). \quad (3)$$

Transitions in T' corresponding to $V_1 \cup V_2$ go from ℓ to ℓ , while the other transitions go from ℓ to ℓ' , or from ℓ' to ℓ . The initial configuration of \mathcal{V}' is $\ell(\mathbf{v})$. Instead of place \bar{p} one could also use a single register $\mathcal{R} = \{r\}$, and transitions of the form

$$((\ell, \perp), \ominus(p_1, a) \ominus (p_2, a), (\ell', a)) \quad ((\ell', a), (p_1, c) \oplus (p_1, a) \oplus (p_2, a), (\ell, \perp)) \quad (a \neq c),$$

to the same effect as in (3). The initial configuration would be then $q(\mathbf{v})$, where $q = (\ell, \perp)$. ◻

► **Remark 6.** Our model of DVASS syntactically extends DVAS by locations, registers and plain places. The extended model is convenient for our decidability argument, while being equivalent to DVAS with respect to most of decision problems. Indeed, a DVASS may be transformed into an essentially equivalent DVAS in three steps (as in the proof of Lemma 12):

$$\begin{array}{ccc} \text{locations} & \xrightarrow{2} & \text{plain places} \\ \uparrow 1 & & \downarrow 3 \\ \text{registers} & \xrightarrow{1} & \text{atom places} \end{array} \quad (4)$$

First, we eliminate registers using locations and atom places, then we encode locations into plain places, and finally we encode plain places into atom ones.

State graph. We define the *state graph* $\text{GRAPH}(T) = (Q, E)$ of a DVASS \mathcal{V} . Its nodes are states Q , and its edges $E \subseteq Q \times Q$ are pairs of states related by some transition of \mathcal{V} :

$$E = \{(q, q') \in Q^2 \mid (q, \mathbf{v}, q') \in T \text{ for some vector } \mathbf{v} : (H \cup P \times \mathbb{A}) \rightarrow_{\text{fin}} \mathbb{Z}\}.$$

When \mathcal{R} is non-empty, the sets of nodes and edges of $\text{GRAPH}(T)$ are infinite but orbit-finite.

Bi-reachability problem. We say that a configuration $q'(\mathbf{v}')$ is *reachable* from $q(\mathbf{v})$ if there is a run $q(\mathbf{v}) \rightarrow q'(\mathbf{v}')$. Two configurations $q(\mathbf{v}), q'(\mathbf{v}')$ are *bi-reachable* if each of them is reachable from the other: $q(\mathbf{v}) \rightarrow q'(\mathbf{v}')$ and $q(\mathbf{v}) \leftarrow q'(\mathbf{v}')$.

DVASS BI-REACHABILITY

Input: a DVASS $(L, \mathcal{R}, H, P, T)$ and two configurations, $q(\mathbf{v})$ and $q'(\mathbf{v}')$.

Question: are $q(\mathbf{v}), q'(\mathbf{v}')$ bi-reachable?

As before, we assume that the orbit-finite set T of transitions is represented by a finite set of representatives, one per orbit. As our main result we prove:

► **Theorem 7.** DVASS *bi-reachability problem is decidable.*

Since our model of DVASS includes plain places, we can assume w.l.o.g. a convenient form of source and target configuration that consists, essentially, of just a location. Let \perp denote the empty register valuation: $\perp(r) = \perp$ for every $r \in \mathcal{R}$.

► **Lemma 8.** *In DVASS BI-REACHABILITY problem we may assume, w.l.o.g., that $q = (\ell, \perp)$, $q' = (\ell', \perp)$, and $\mathbf{v} = \mathbf{v}' = \mathbf{0}$.*

4 Toolset

Our decision procedure relies on a number of existing tools. One of them is solvability of MULTISSET SUM (Lemma 4). Here we introduce two further tools: a sufficient condition for VASS reachability, and computability of coverability sets in DVAS.

Sufficient condition for VASS reachability. We recall a condition that guarantees existence of a run in a VASS. It is a simplification of the classical condition of [18, 19, 27] which guarantees existence of a run in a *generalised* VASS. Consider a VASS \mathcal{V} with plain places H . For $\mathbf{v} : H \rightarrow_{\text{fin}} \mathbb{N}$ we write $\mathbf{v} \gg \mathbf{0}$ to mean that for every $h \in H$ we have $\mathbf{v}(h) > 0$.

- Θ_1 : For every $m \in \mathbb{N}$, there is a pseudo-run $q(\mathbf{0}) \dashrightarrow q'(\mathbf{0})$ using every transition at least m times.
- Θ_2 : For some vectors $\Delta, \Delta' \gg \mathbf{0}$, there are runs: $q(\mathbf{0}) \rightarrow q(\Delta)$ and $q'(\Delta') \rightarrow q'(\mathbf{0})$.

► **Lemma 9** (Thm. 2 in [18], Prop. 1 in [21]). *For every VASS, $\Theta_1 \wedge \Theta_2$ implies $q(\mathbf{0}) \rightarrow q'(\mathbf{0})$.*

Coverability sets in DVASS. Let $\mathcal{V} = (L, \mathcal{R}, H, P, T)$ be a DVASS, and let $X = H \cup (P \times \mathbb{A})$. We define the pointwise order on nonnegative vectors $X \rightarrow_{\text{fin}} \mathbb{N}$: $\mathbf{v} \leq \mathbf{v}'$ if and only if for every $x \in X$ we have $\mathbf{v}(x) \leq \mathbf{v}'(x)$. We define a quasi-order by relaxation of \leq , up to automorphisms: $\mathbf{v} \sqsubseteq \mathbf{v}'$ if $\sigma(\mathbf{v}) \leq \mathbf{v}'$ for some $\sigma \in \text{Aut}(\mathbb{A})$. We extend the relation \sqsubseteq to configurations: for states q, q' and vectors $\mathbf{v}, \mathbf{v}' \in X \rightarrow_{\text{fin}} \mathbb{N}$ we put $q(\mathbf{v}) \sqsubseteq q'(\mathbf{v}')$ if $\sigma(q) = q'$ and $\sigma(\mathbf{v}) \leq \mathbf{v}'$ for some $\sigma \in \text{Aut}(\mathbb{A})$.

► **Lemma 10.** \sqsubseteq *is a WQO on configurations.*

The *coverability set* of a configuration $q(\mathbf{v})$ is defined as the downward closure, with respect to \sqsubseteq , of the reachability set:

$$\text{COVER}(q(\mathbf{v})) = \{\bar{s}(\bar{\mathbf{w}}) \in \text{CONF} \mid \exists s(\mathbf{w}) \in \text{CONF} : \bar{s}(\bar{\mathbf{w}}) \sqsubseteq s(\mathbf{w}) \wedge q(\mathbf{v}) \longrightarrow s(\mathbf{w})\}.$$

It is known that the coverability set is representable by a finite union of *ideals* (downward closed directed sets) [10, 11]. Let's complete \mathbb{N} with a top element, $\mathbb{N}_\omega \stackrel{\text{def}}{=} \mathbb{N} \cup \{\omega\}$, which is larger than all numbers: $n < \omega$ for all $n \in \mathbb{N}$. We consider pairs $(q, f) \in Q \times (X \rightarrow \mathbb{N}_\omega)$, written $q(f)$, and called ω -configurations. Each such pair determines a set of configurations (we extend \sqsubseteq to all ω -configurations in the expected way):

$$q(f)\downarrow := \{s(\mathbf{v}) \in \text{CONF} \mid s(\mathbf{v}) \sqsubseteq q(f)\},$$

which is downward closed (whenever $s(\mathbf{v}) \in q(f)\downarrow$ and $s'(\mathbf{v}') \sqsubseteq s(\mathbf{v})$ then $s'(\mathbf{v}') \in q(f)\downarrow$) and directed (for every two $s(\mathbf{v}), s'(\mathbf{v}') \in q(f)\downarrow$ there is $\bar{s}(\bar{\mathbf{v}}) \in q(f)\downarrow$ such that $s(\mathbf{v}) \sqsubseteq \bar{s}(\bar{\mathbf{v}})$ and $s'(\mathbf{v}') \sqsubseteq \bar{s}(\bar{\mathbf{v}})$). The set $q(f)\downarrow$ is thus an *ideal*. We call an ω -configuration $q(f)$ *simple* if for every $p \in P$, either $f(p, a) = 0$ for *almost all* $a \in \mathbb{A}$ (i.e., for all $a \in \mathbb{A}$ except finitely many), or $f(p, a) = \omega$ for almost all $a \in \mathbb{A}$. Simple ω -configurations are thus finitely representable. Ideals determined by simple ω -configurations we call simple too.

► **Example 11.** In the DVASS \mathcal{V}' in Example 5, $\text{COVER}(\ell(\mathbf{v})) = \ell(f)\downarrow \cup \ell(g)\downarrow \cup \ell'(f')\downarrow \cup \ell'(g')\downarrow$, where $f(p_1, c) = g(p_1, c) = f'(p_1, c) = g'(p_1, c) = \omega$ for every $c \in \mathbb{A}$,

$$\begin{aligned} f(p_2, a) = f(p_2, b) &= 1 & g(p_2, a) &= 2 \\ f'(p_2, a) = f'(\bar{p}, b) &= 1 & g'(p_2, a) = g'(\bar{p}, a) &= 1 \end{aligned}$$

for some $a \neq b \in \mathbb{A}$, and all other arguments are mapped by f, g, f' and g' to 0. Indeed, due to transition t_1 , place p_1 can be filled up with arbitrary many tokens with any atoms. On the other hand place p_2 has two tokens in the initial configuration $\ell(\mathbf{v})$, and hence will invariantly have, in location ℓ , two tokens whose atoms may be equal or not. Furthermore, in location ℓ' , places p_2 and \bar{p} have always one token each, with atoms equal or not. \lrcorner

Simple ω -configurations provide finite representations of simple ideals. Relying on the result of [16], the coverability set in a DVAS is a union of a finite set of simple ideals, which is computable. We lift this result to the model of DVASS:

► **Lemma 12.** *Given a DVASS and its configuration $q(\mathbf{v})$, one can compute a finite set of simple ω -configurations $\{s_1(f_1), \dots, s_n(f_n)\}$ such that $\text{COVER}(q(\mathbf{v})) = s_1(f_1)\downarrow \cup \dots \cup s_n(f_n)\downarrow$.*

Proof. Let $\mathcal{V} = (L, \mathcal{R}, H, P, T)$ be a DVASS, let $q(\mathbf{v})$ be its configuration, where $q = (\ell, \eta)$. Theorem 3.5 in [16] proves the claim in the special case of DVAS. We reduce DVASS to DVAS in three steps, as shown in the diagram (4) in Remark 6.

As the first step we get rid of registers by considering them as additional atom places that store at most one token, while keeping track, in locations, of the set of currently empty registers. We set $P_1 := P \cup \mathcal{R} \cup \bar{\mathcal{R}}$, where $\bar{\mathcal{R}} = \{\bar{r} \mid r \in \mathcal{R}\}$ is distinct a copy of \mathcal{R} , and $L_1 = (L \cup \bar{L}) \times \mathcal{P}(\mathcal{R})$, where $\bar{L} = \{\bar{\ell} \mid \ell \in L\}$, and define the new set of transitions T_1 by transforming transitions from T as follows. In the construction we identify a register valuation μ with a vector $\mu = \oplus \{(r, a) \mid \mu(r) = a \neq \perp\}$, or with a vector $\bar{\mu} = \oplus \{(\bar{r}, a) \mid \mu(r) = a \neq \perp\}$. Every transition $t = ((\ell, \mu), \mathbf{v}, (\ell', \mu')) \in T$ gives rise to a transition in T_1

$$\left((\ell, \mu^{-1}(\perp)), \mathbf{v} \oplus \mu \oplus \bar{\mu}', (\bar{\ell}', (\mu')^{-1}(\perp)) \right)$$

that starts in location $(\ell, \mu^{-1}(\perp))$, ends in a location $(\bar{\ell}', (\mu')^{-1}(\perp))$ and whose effect is \mathbf{v} plus, intuitively speaking, removing μ from places \mathcal{R} and putting μ' to places $\bar{\mathcal{R}}$. In addition, all transitions of the form

$$\left((\bar{\ell}', \nu^{-1}(\perp)), \nu \ominus \bar{\nu}, (\ell', \nu^{-1}(\perp)) \right)$$

are added to T_1 , where $\nu : \mathcal{R} \rightarrow (\mathbb{A} \cup \{\perp\})$ is any register valuation. Intuitively, these transitions flash back all tokens from places $\bar{\mathcal{R}}$ to the corresponding places \mathcal{R} . This yields a DVASS $\mathcal{V}_1 := (L_1, \emptyset, H, P_1, T_1)$ computable from \mathcal{V} , and its location $\ell_1 = (\ell, \eta^{-1}(\perp))$ corresponding to state q such that the coverability sets in \mathcal{V} (on the left) is computable from the one in \mathcal{V}_1 (on the right):

▷ **Claim 13.** $\text{COVER}(q(\mathbf{v})) = \{(\ell', \mu')(\mathbf{v}') \mid (\ell', (\mu')^{-1}(\perp))(\mathbf{v}' \oplus \mu') \in \text{COVER}(\ell_1(\mathbf{v} \oplus \eta))\}$.

As the second step, we dispose of locations L_1 by moving them to plain places. We set $H_2 := H \cup L_1 \cup \widetilde{L}_1$, where $\widetilde{L}_1 = \{\widetilde{\ell} \mid \ell \in L_1\}$, and transform each transition $t = (\ell, \mathbf{v}, \ell') \in T_1$ into a transition in T_2 :

$$(*, \mathbf{v} \ominus \ell \oplus \widetilde{\ell}', *)$$

We also add a new transition $(*, \ell \ominus \widetilde{\ell}, *)$ for every $\ell \in L_1$. This yields a DVASS $\mathcal{V}_2 := (\{*\}, \emptyset, H_2, P_1, T_2)$ computable from \mathcal{V}_1 , and the corresponding configuration $*(\mathbf{v} \oplus \ell)$ such that the coverability sets in \mathcal{V}_1 (on the left) is computable from the one in \mathcal{V}_2 (on the right):

▷ **Claim 14.** $\text{COVER}(\ell(\mathbf{v})) = \{\ell'(\mathbf{v}') \mid \mathbf{v}' \oplus \ell' \in \text{COVER}(*(\mathbf{v} \oplus \ell))\}$.

Eventually, as the last step we get rid of plain places H_2 by moving them to atom ones, and considering atoms residing on these atom places irrelevant. Let $P_3 := H_2 \cup P_1$. In order to transfer transitions T_2 from plain places to the new atom places, we introduce the projection mapping $\pi : (H_2 \cup P_1) \times \mathbb{A} \rightarrow H_2 \cup (P_1 \times \mathbb{A})$,

$$(h, a) \mapsto h \quad (p, a) \mapsto (p, a) \quad (h \in H_2, p \in P_1, a \in \mathbb{A}),$$

that forgets, intuitively speaking, about atoms on the new atom places. It extends uniquely to a commutative group homomorphism π from $(H_2 \cup P_1) \times \mathbb{A} \rightarrow_{\text{fin}} \mathbb{Z}$ to $H_2 \cup (P_1 \times \mathbb{A}) \rightarrow_{\text{fin}} \mathbb{Z}$. We define transitions as the inverse image of T_2 along π :

$$T_3 := \pi^{-1}(T_2).$$

This yields a DVAS $\mathcal{V}_3 := (\{*\}, \emptyset, P_3, T_3)$. We observe that $\pi^{-1}(\mathbf{v})$ is orbit-finite for every vector \mathbf{v} , and therefore $\pi^{-1}(T_2)$, being orbit-finite union of orbit-finite sets, is itself orbit-finite [2, Ex. 62]. Therefore \mathcal{V}_3 is computable from \mathcal{V}_2 . The coverability set in \mathcal{V}_2 is computable from the one in \mathcal{V}_3 , since coverability sets commute the projection (the coverability set on the left is in \mathcal{V}_2 , while the one on the right is in \mathcal{V}_3):

▷ **Claim 15.** $\text{COVER}(*(\pi(\mathbf{w}))) = \pi(\text{COVER}(*(\mathbf{w})))$.

Indeed, in order to compute a representation $\text{COVER}(*(\mathbf{v})) = g_1 \downarrow \cup \dots \cup g_n \downarrow$ in \mathcal{V}_2 , we take any \mathbf{w} with $\pi(\mathbf{w}) = \mathbf{v}$, compute a representation $\text{COVER}(*(\mathbf{w})) = f_1 \downarrow \cup \dots \cup f_n \downarrow$ in \mathcal{V}_3 using [16, Thm. 3.5], and modify the functions f_i by summing up, for every $h \in H_2$, namely (under the proviso that $\omega + n = \omega + \omega = \omega$):

$$g_i(h) := \sum_{a \in \mathbb{A}} f_i(h, a) \quad g_i(p, a) := f_i(p, a) \quad (h \in H_2, p \in P_1, a \in \mathbb{A}).$$

This concludes the proof. ◀

5 Sufficient condition for DVASS bi-reachability

In this and in the next section we prove Theorem 7. Throughout the rest of the paper let $\mathcal{V} = (L, \mathcal{R}, H, P, T)$ be an input DVASS. Relying on Lemma 8 we investigate bi-reachability of $q(\mathbf{0})$ and $q'(\mathbf{0})$, for states $q = (\ell, \perp) \in Q$ and $q' = (\ell', \perp') \in Q$ with empty register valuations. The states q, q' are invariant under the action of $\text{Aut}(\mathbb{A})$, which is crucial in the sequel:

▷ **Claim 16.** For every $\sigma \in \text{Aut}(\mathbb{A})$, we have $\sigma(q) = q$ and $\sigma(q') = q'$.

We now formulate a sufficient condition for bi-reachability of $q(\mathbf{0})$ and $q'(\mathbf{0})$, as an adaptation of the classical Θ_1 and Θ_2 conditions. In the context of bi-reachability, it is enough to rely on a simplified version of these conditions given by Lemma 9. We write below $\mathbf{v} \gg \mathbf{0}$ to mean that $\mathbf{v}(h) > 0$ for every $h \in H$, and for every $p \in P$ there is some $a \in \mathbb{A}$ such that $\mathbf{v}(p, a) > 0$.

■ Φ_1 : There are pseudo-runs, each of them using some transition from every orbit in T :

$$q(\mathbf{0}) \dashrightarrow q'(\mathbf{0}) \quad q(\mathbf{0}) \dashleftarrow q'(\mathbf{0}). \quad (5)$$

■ Φ_2 : For some vectors $\Delta, \Delta', \Gamma, \Gamma' \gg \mathbf{0}$, there are runs:

$$\begin{aligned} q(\mathbf{0}) &\longrightarrow q(\Delta) & q'(\Delta') &\longrightarrow q'(\mathbf{0}) \\ q(\mathbf{0}) &\longleftarrow q(\Gamma) & q'(\Gamma') &\longleftarrow q'(\mathbf{0}). \end{aligned} \quad (6)$$

► **Lemma 17.** $\Phi_1 \wedge \Phi_2$ implies $q(\mathbf{0}) \longrightarrow q'(\mathbf{0})$ and $q(\mathbf{0}) \longleftarrow q'(\mathbf{0})$.

Proof. Assume \mathcal{V} satisfies $\Phi_1 \wedge \Phi_2$. Let S be the union of supports of the two pseudo-runs (5) and the four runs (6). Recall that $\text{Aut}_{\mathbb{A} \setminus S}(\mathbb{A}) \subseteq \text{Aut}(\mathbb{A})$ denotes the subset of those automorphisms σ that are identity outside S : $\sigma(a) = a$ for every $a \notin S$. When restricted to S , each such automorphism is a permutation, i.e., $\sigma(S) = S$. In the sequel we will apply permutations $\sigma \in \text{Aut}_{\mathbb{A} \setminus S}(\mathbb{A})$ to atoms from S only, and therefore the value $\sigma(a) = a$, for $a \notin S$, will be irrelevant. The set $\text{Aut}_{\mathbb{A} \setminus S}(\mathbb{A})$ is finite, $|\text{Aut}_{\mathbb{A} \setminus S}(\mathbb{A})| = |S|!$.

We define a (plain) VASS \mathcal{V}_S by, intuitively speaking, restricting the set of atoms to the finite set S . The set of locations of \mathcal{V}_S is $L_S := L \times (\mathcal{R} \rightarrow S \cup \{\perp\})$, its places are $H_S := H \cup P \times S$, and its transitions $T_S \subseteq T$ are all transitions of \mathcal{V} that use only atoms from S . Formally, $\mathcal{V}_S = (L_S, \emptyset, H_S, \emptyset, T_S)$, where $T_S := \{t \in T \mid \text{SUPP}(t) \subseteq S\}$. We claim that the VASS satisfies the conditions Θ_1 and Θ_2 of Lemma 9.

We consider Θ_1 first. Let $\pi : q(\mathbf{0}) \dashrightarrow q'(\mathbf{0})$ and $\pi' : q'(\mathbf{0}) \dashrightarrow q(\mathbf{0})$ be the pseudo-runs in (5). By applying all permutations $\sigma \in \text{Aut}_{\mathbb{A} \setminus S}(\mathbb{A})$ to their concatenation $\pi; \pi' : q(\mathbf{0}) \dashrightarrow q'(\mathbf{0}) \dashrightarrow q(\mathbf{0})$, and concatenating all the $|S|!$ resulting cyclic pseudo-runs, we get a cyclic pseudo-run $\delta : q(\mathbf{0}) \dashrightarrow q(\mathbf{0})$. This pseudo-run uses every transition from T_S at least once, since π uses a representative of every orbit of T , and the following fact holds:

▷ **Claim 18.** Let $t, t' \in T$ be two transitions in the same orbit such that $\text{SUPP}(t), \text{SUPP}(t') \subseteq S$. Then $t' = \sigma(t)$ for some $\sigma \in \text{Aut}_{\mathbb{A} \setminus S}(\mathbb{A})$.

Likewise we get a cyclic pseudo-run $\delta' : q'(\mathbf{0}) \dashrightarrow q'(\mathbf{0})$ that uses every transition from T_S at least once. Furthermore, for every $m \in \mathbb{N}$, the m -fold concatenation of δ or δ' yields a cyclic pseudo-run that uses every transition from T_S at least m times. We thus have two pseudo-runs

$$\delta^m; \pi : q(\mathbf{0}) \dashrightarrow q'(\mathbf{0}) \quad (\delta')^m; \pi' : q(\mathbf{0}) \dashleftarrow q'(\mathbf{0})$$

each of them using every transition from T_S at least m times. Thus the VASS \mathcal{V}_S satisfies two instances of Θ_1 , one towards a run $q(\mathbf{0}) \longrightarrow q'(\mathbf{0})$ and the other one towards a run $q'(\mathbf{0}) \longrightarrow q(\mathbf{0})$.

Now we concentrate on Θ_2 . We proceed similarly as before, namely apply all automorphisms $\sigma \in \text{Aut}_{\mathbb{A} \setminus S}(\mathbb{A})$ to Δ , and sum up all the resulting vectors:

$$\Delta_S := \oplus \{ \sigma(\Delta) \mid \sigma \in \text{Aut}_{\mathbb{A} \setminus S}(\mathbb{A}) \}.$$

Let $\overline{\Delta}_S : H \cup P \times S \rightarrow_{\text{fin}} \mathbb{N}$ be the restriction of Δ_S to $H \cup P \times S$. Knowing that $\Delta \gg \mathbf{0}$, we deduce that $\Delta_S(h) > 0$ for every $h \in H$, and $\Delta_S(p, a) > 0$ for every $(p, a) \in P \times S$. In other words, $\overline{\Delta}_S \gg \mathbf{0}$. By applying all automorphisms $\sigma \in \text{Aut}_{\mathbb{A} \setminus S}(\mathbb{A})$ to the run $q(\mathbf{0}) \longrightarrow q(\Delta)$ in Φ_2 , and concatenating all the resulting runs, we get a run $q(\mathbf{0}) \longrightarrow q(\Delta_S)$ in \mathcal{V} . Clearly, only atoms from S appear in this run, and therefore it is also a run $q(\mathbf{0}) \longrightarrow q(\overline{\Delta}_S)$ in \mathcal{V}_S . In a similar way we define vectors $\overline{\Delta}'_S$, $\overline{\Gamma}_S$ and $\overline{\Gamma}'_S$, and the corresponding runs in \mathcal{V}_S :

$$q(\mathbf{0}) \longrightarrow q(\overline{\Delta}_S) \quad q'(\overline{\Delta}'_S) \longrightarrow q'(\mathbf{0}) \quad (7)$$

$$q(\mathbf{0}) \longleftarrow q(\overline{\Gamma}_S) \quad q'(\overline{\Gamma}'_S) \longleftarrow q'(\mathbf{0}). \quad (8)$$

Therefore, the VASS \mathcal{V}_S satisfies two instances of Θ_2 , one towards a run $q(\mathbf{0}) \longrightarrow q'(\mathbf{0})$ and the other one towards a run $q'(\mathbf{0}) \longrightarrow q(\mathbf{0})$.

Finally, using Lemma 9 we deduce two runs in \mathcal{V}_S , which are automatically also runs in \mathcal{V} . This completes the proof. \blacktriangleleft

6 Reduction algorithm

As the *rank* of a DVASS $\mathcal{V} = (L, \mathcal{R}, H, P, T)$ we take the triple $\text{RANK}(\mathcal{V}) = (|P|, |H|, ||T||)$, consisting of the number of atom places, the number of plain places, and the number of orbits $||T||$ the set T partitions into. Ranks are compared lexicographically.

Given a DVASS \mathcal{V} , the algorithm verifies the conditions Φ_1 and Φ_2 . If they are all satisfied, it answers positively, relying on Lemma 17. Otherwise, depending on which of the conditions is violated, the algorithm either immediately answers negatively, or applies a reduction step, as outlined below in Sections 6.1 and 6.2. Each of the steps produces a new DVASS $\widehat{\mathcal{V}}$ of strictly smaller rank, which guarantees termination. Finally, when both P and H are empty, the problem reduces to reachability from q to q' in state graph $\text{GRAPH}(\mathcal{V})$, which is decidable due to:

► **Lemma 19.** *For a set $E \subseteq Q \times Q$ of edges between states, given as a finite union of orbits, and a pair $(s, s') \in Q \times Q$, it is decidable if there is a path from s to s' in the graph (Q, E) .*

Proof. The orbit of an edge $((\ell, \nu), (\ell', \nu')) \in E$ is determined by the following data: locations ℓ, ℓ' ; the inverse images $\nu^{-1}(\perp)$, $(\nu')^{-1}(\perp)$; and the equality type of the remaining entries in ν and ν' , that is:

$$\{(r, r') \mid \nu(r) = \nu(r') \neq \perp\} \quad \{(r, r') \mid \nu'(r) = \nu'(r') \neq \perp\} \quad \{(r, r') \mid \nu(r) = \nu'(r') \neq \perp\}.$$

Using equational reasoning, one computes the transitive closure E^* of E , by consecutively adding to E^* every new orbit which is forced to be included in E^* by some two orbits already included in E^* , until saturation. Termination is guaranteed as $Q \times Q$ is orbit-finite. The transitive closure is thus forcedly a finite union of orbits. Finally, one tests if the orbit of (s, s') is included in E^* . \blacktriangleleft

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For future use we note an immediate consequence of the above proof: for every pair of states, if there is a path from one to the other, then there is also a path of bounded length. This implies a bound on the number of atoms involved:

► **Corollary 20.** *There is an effective bound $b(Q) \in \mathbb{N}$ such that whenever there is a path from $s \in Q$ to $s' \in Q$ in the graph (Q, E) , then there is such a path π with $|\text{SUPP}(\pi)| \leq b(Q)$.*

Below we describe the two reduction steps, proving their progress property (decreasing rank), correctness and effectiveness.

6.1 Violation of Φ_1

Suppose \mathcal{V} violates Φ_1 . If states q, q' are not in the same strongly connected component of $\text{GRAPH}(T)$, which is testable using Lemma 19, the configurations $q(\mathbf{0})$, $q'(\mathbf{0})$ are clearly not bi-reachable and the algorithm answers negatively. Otherwise, the algorithm constructs a DVASS $\widehat{\mathcal{V}}$ of smaller rank, as defined below, such that bi-reachability of $q(\mathbf{0})$ and $q'(\mathbf{0})$ in \mathcal{V} is equivalent to their bi-reachability in $\widehat{\mathcal{V}}$.

Let $\text{GRAPH}(T) = (Q, E)$. Transitions witnessing bi-reachability of $q(\mathbf{0})$ and $q'(\mathbf{0})$, namely used in some cyclic run $q(\mathbf{0}) \rightarrow q'(\mathbf{0}) \rightarrow q(\mathbf{0})$, form a cycle in $\text{GRAPH}(T)$. As a consequence, a transition $(s, \mathbf{v}, s') \in T$ may be useful for bi-reachability only if the edge (s, s') belongs to the strongly connected component of $\text{GRAPH}(T)$ containing q and q' . Therefore, bi-reachability of $q(\mathbf{0})$, $q'(\mathbf{0})$ in \mathcal{V} reduces to bi-reachability of $q(\mathbf{0})$, $q'(\mathbf{0})$ in $\widehat{\mathcal{V}}$ obtained by restriction to the strongly connected component of q and q' . This component is computed by enumerating all orbits included in E . For every orbit $o \subseteq E$ one chooses a representative $(s, s') \in o$, and uses Lemma 19 to test reachability, in $\text{GRAPH}(T)$, for the four pairs: (q, s) , (s', q) , (q', s) or (s', q') . Then one removes from T all orbits of transitions (s, \mathbf{v}, s') such that reachability test fails for any of the four pairs above. The resulting set of transitions is still a finite union of orbits. Consequently, from now on we may assume, w.l.o.g., that $\text{GRAPH}(T)$ is strongly connected (we ignore isolated vertices).

Useful transitions. By a finite multiset of transitions we mean a nonnegative vector $\mathbf{f} : T \rightarrow_{\text{fin}} \mathbb{N}$. Given such a finite multiset, let $\text{STATE-EQ}(q, q')$ denote conjunction of the following conditions:

- (a) the sum of effects of all transitions in the multiset is $\mathbf{0}$,
- (b) for every state $s \notin \{q, q'\}$, the number of transitions incoming to s equals the number of ones outgoing from s ,
- (c) the number of transitions outgoing from q exceeds by one the number of incoming ones,
- (d) the number of transitions incoming to q' exceeds by one the number of outgoing ones;

Symmetrically, let $\text{STATE-EQ}(q', q)$ denote the conjunction of (a), (b) and the symmetric versions of (c) and (d) with q and q' swapped. Let $O = \{\text{ORBIT}(t) \mid t \in T\}$ be the set of all orbits in T . We call an orbit $o \in O$ *useful* if there are two finite multisets of transitions \mathbf{f}, \mathbf{f}' satisfying $\text{STATE-EQ}(q, q')$ and $\text{STATE-EQ}(q', q)$, respectively, each of them containing some transition from o .

► **Lemma 21.** Φ_1 holds if and only if all orbits of transitions are useful.

Proof. The only if direction of the characterisation is immediate, as the multiset of transitions used in a pseudo-run $q(\mathbf{0}) \dashrightarrow q'(\mathbf{0})$ necessarily contains some transition from every orbit and satisfies all the conditions (a)–(d), and likewise for a pseudo-run $q'(\mathbf{0}) \dashrightarrow q(\mathbf{0})$. For

the opposite direction, suppose that for every orbit $o \in O$ there are finite multisets $\mathbf{f}_o, \mathbf{f}'_o$ satisfying STATE-EQ(q, q') and STATE-EQ(q', q), respectively, each of them containing some transition from o . Let

$$\mathbf{f} := \oplus \{\mathbf{f}_o \mid o \in O\} \quad \mathbf{f}' := \oplus \{\mathbf{f}'_o \mid o \in O\} \quad S := \text{SUPP}(\mathbf{f}) \cup \text{SUPP}(\mathbf{f}'),$$

where \oplus denotes the multiset sum operator. Thus S is the (finite) set of atoms used in all the transitions appearing in \mathbf{f} or \mathbf{f}' . Similarly as in the proof of Lemma 17 we use the subgroup $\text{Aut}_{\mathbb{A} \setminus S}(\mathbb{A}) \subseteq \text{Aut}(\mathbb{A})$ of automorphisms σ of \mathbb{A} that are identity outside S , and define a plain VASS $\mathcal{V}_S = (L_S, \emptyset, H_S, \emptyset, T_S)$ by restricting the set of atoms to S . Locations of \mathcal{V}_S are $L_S := L \times (\mathcal{R} \rightarrow S \cup \{\perp\})$, its places are $H_S := H \cup P \times S$, and its transitions $T_S \subseteq T$ are all transitions of \mathcal{V} that use only atoms from S : $T_S = \{t \in T \mid \text{SUPP}(t) \subseteq S\}$. The state graph $\text{GRAPH}(T_S)$ is a subgraph of $\text{GRAPH}(T)$. As $\text{GRAPH}(T)$ is strongly connected, we use Corollary 20 to deduce that, for sufficiently large S , the state graph $\text{GRAPH}(T_S)$ is also strongly connected. Therefore we enlarge S , if necessary, to assure that $\text{GRAPH}(T_S)$ is strongly connected.

As finite multisets \mathbf{f}, \mathbf{f}' are just nonnegative vectors $T \rightarrow_{\text{fin}} \mathbb{N}$, they inherit the natural (pointwise) action of $\text{Aut}(\mathbb{A})$. Basing on \mathbf{f}, \mathbf{f}' we define two larger multisets of transitions by applying all automorphisms from $\text{Aut}_{\mathbb{A} \setminus S}(\mathbb{A})$ to \mathbf{f} and \mathbf{f}' , respectively, and summing up all the resulting multisets:

$$\mathbf{g} := \oplus \{\sigma(\mathbf{f}) \mid \sigma \in \text{Aut}_{\mathbb{A} \setminus S}(\mathbb{A})\} \quad \mathbf{g}' := \oplus \{\sigma(\mathbf{f}') \mid \sigma \in \text{Aut}_{\mathbb{A} \setminus S}(\mathbb{A})\}.$$

By Claim 18, each of \mathbf{g}, \mathbf{g}' contains all transitions from T_S . Furthermore, the multiset $\mathbf{h} = \mathbf{f} \oplus \mathbf{g} \oplus \mathbf{g}'$ satisfies STATE-EQ(\hat{q}, \hat{q}'), where \hat{q}, \hat{q}' are locations (=states) of \mathcal{V}_S corresponding to q and q' respectively. Likewise, the multiset $\mathbf{h}' = \mathbf{f}' \oplus \mathbf{g} \oplus \mathbf{g}'$ satisfies STATE-EQ(\hat{q}', \hat{q}). Using the standard Euler argument in the (strongly) connected graph $\text{GRAPH}(T_S)$, and relying on conditions (b)–(d), we deduce existence of a pseudo-run in \mathcal{V}_S that uses exactly transitions \mathbf{h} . Due to condition (a), this is a pseudo-run $\hat{q}(\mathbf{0}) \dashrightarrow \hat{q}'(\mathbf{0})$ in \mathcal{V}_S . Likewise we deduce a pseudo-run $\hat{q}'(\mathbf{0}) \dashrightarrow \hat{q}(\mathbf{0})$ in \mathcal{V}_S . The pseudo-runs are essentially also pseudo-runs in \mathcal{V} , both supported by S , and both using some transition from every orbit in T . This completes the proof of the characterisation. \blacktriangleleft

Reduction step. We define a DVASS $\hat{\mathcal{V}}$ by removing some useless orbit of transitions, $\hat{\mathcal{V}} = (L, \mathcal{R}, H, P, \hat{T})$. It has the same locations, registers and places as \mathcal{V} .

► **Lemma 22 (Progress).** $\|\hat{T}\| < \|T\|$, and hence $\text{RANK}(\hat{\mathcal{V}}) < \text{RANK}(\mathcal{V})$.

Proof. As some useless orbit of transitions is removed from \hat{T} , we have $\|\hat{T}\| < \|T\|$, and therefore $\text{RANK}(\hat{\mathcal{V}}) = (|P|, |H|, \|\hat{T}\|) < (|P|, |H|, \|T\|) = \text{RANK}(\mathcal{V})$. \blacktriangleleft

► **Lemma 23 (Correctness).** *The configurations $q(\mathbf{0}), q'(\mathbf{0})$ are bi-reachable in \mathcal{V} if and only if they are bi-reachable in $\hat{\mathcal{V}}$.*

Proof. Indeed, useless transitions can not be used in runs between $q(\mathbf{0})$ and $q'(\mathbf{0})$. \blacktriangleleft

► **Lemma 24 (Effectiveness).** *The condition Φ_1 is decidable. When it fails, some useless orbit of transitions is computable.*

Proof. It is sufficient to prove that it is decidable if a given orbit $o \in O$ is useful. We show decidability by reduction to MULTISSET SUM (recall Lemma 4), i.e., we use the algorithm for MULTISSET SUM to check existence of a finite multiset \mathbf{f} that satisfies conditions (a)–(d) and

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contains a transition from o (and likewise to check existence of \mathbf{f}'). Let $X = H \cup P \times \mathbb{A}$ and $Y = X \cup Q \cup \{*\}$. The set Y is orbit-finite. Let every transition $t = (s, \mathbf{v}, s') \in T$ determine a vector $\mathbf{y}_t : Y \rightarrow_{\text{fin}} \mathbb{Z}$, and let every transition $t = (s, \mathbf{v}, s') \in o$ determine additionally a vector $\mathbf{x}_t : Y \rightarrow_{\text{fin}} \mathbb{Z}$, each of them extending the vector $\mathbf{v} : X \rightarrow_{\text{fin}} \mathbb{Z}$ as follows:

$$\begin{array}{lll} \mathbf{x}_t(s) = -1 & \mathbf{x}_t(s') = 1 & \mathbf{x}_t(*) = 1, \\ \mathbf{y}_t(s) = -1 & \mathbf{y}_t(s') = 1 & \mathbf{y}_t(*) = 0, \end{array} \quad (9)$$

and $\mathbf{x}_t(r) = \mathbf{y}_t(r) = 0$ for other states $r \in Q \setminus \{s, s'\}$. Intuitively, the first two columns track contribution of t to the number of transitions outgoing from s , or incoming to s' , while the latter column tracks the number of usages of transitions from o . Likewise, let the target vector $\mathbf{b} : Y \rightarrow_{\text{fin}} \mathbb{Z}$ extend $\mathbf{0} : X \rightarrow_{\text{fin}} \mathbb{Z}$ by

$$\mathbf{b}(q) = -1 \quad \mathbf{b}(q') = 1 \quad \mathbf{b}(*) = 1, \quad (10)$$

and $\mathbf{b}(s) = 0$ for other states $s \in Q \setminus \{q, q'\}$. Let $M = \{\mathbf{y}_t \mid t \in T\} \cup \{\mathbf{x}_t \mid t \in o\}$, and consider the instance let (M, \mathbf{b}) of MULTISUM. Observe that solutions of (M, \mathbf{b}) necessarily use exactly one vector \mathbf{x}_t exactly once, as in (11) below. It remains to prove that some finite multiset $\mathbf{f} = \{t, u_1, \dots, u_m\}$ of transitions from T , where $t \in o$, satisfies the conditions (a)–(d) exactly when

$$\mathbf{b} = \mathbf{x}_t + \mathbf{y}_{u_1} + \dots + \mathbf{y}_{u_m}. \quad (11)$$

As $\mathbf{b}(c) = 0$ for all $c \in H \cup P \times \mathbb{A}$, condition (a) is equivalent to the equality (11) restricted to $H \cup P \times \mathbb{A}$. By the first two columns in (9) and (10), and since $\mathbf{b}(s) = 0$ for $s \in Q \setminus \{q, q'\}$, condition (b) is equivalent to the equality (11) restricted to $Q \setminus \{q, q'\}$, and the conditions (c) and (d) are equivalent to the equality (11) restricted to $\{q, q'\}$. ◀

6.2 Violation of Φ_2

Suppose \mathcal{V} violates Φ_2 . We define a DVASS $\widehat{\mathcal{V}}$ of smaller rank and two its states $\widehat{q}, \widehat{q}'$ such that bi-reachability of $q(\mathbf{0})$ and $q'(\mathbf{0})$ in \mathcal{V} is equivalent to bi-reachability of $\widehat{q}(\mathbf{0})$ and $\widehat{q}'(\mathbf{0})$ in $\widehat{\mathcal{V}}$.

Pumpability and boundedness. Any run of the form $q(\mathbf{0}) \longrightarrow q(\Delta)$ (resp. $q(\Delta) \longrightarrow q(\mathbf{0})$) we call *forward* (resp. *backward*) *pump* from q . Likewise we define forward (resp. backward) pumps from q' .

A plain place $h \in H$ (resp. an atom place $p \in P$) we call *forward pumpable* from q if there is a pump $q(\mathbf{0}) \longrightarrow q(\Delta)$ such that $\Delta(h) > 0$ (resp. $\Delta(p, a) > 0$ for some atom $a \in \mathbb{A}$). Symmetrically, a place $h \in H$ (resp. $p \in P$) we call *backward pumpable* from q if there is a pump $q(\Delta) \longrightarrow q(\mathbf{0})$ such that $\Delta(h) > 0$ (resp. $\Delta(p, a) > 0$ for some atom $a \in \mathbb{A}$). Likewise we define places forward (resp. backward) pumpable from q' . Finally, a (plain or atom) place is called *pumpable* if it is forward and backward pumpable both from q and from q' . Otherwise, the place is called *unpumpable*.

► **Lemma 25.** Φ_2 holds if and only if all places are pumpable.

Proof. In one direction, Φ_2 amounts to *simultaneous* (= using one pump) forward and backward pumpability of all places, from both q and q' . In the converse direction, suppose all places are forward and backward pumpable from both q and q' . We observe that forward (resp. backward) pumps from q compose, and hence all places are *simultaneously* forward (resp. backward) pumpable from q . Likewise for q' . ◀

We now introduce a suitable version of boundedness. In case of plain places $h \in H$ boundedness applies, as expected, to the value $\mathbf{v}(h)$ in a configuration $s(\mathbf{v})$. On the other hand in case of atom places $p \in P$, boundedness applies to the number of tokens on a place. For uniformity we define the size of a place $p \in P$ in a vector \mathbf{v} as

$$\mathbf{v}(p) = \sum \{\mathbf{v}(p, a) \mid a \in \mathbb{A}, \mathbf{v}(p, a) > 0\} \in \mathbb{N}. \quad (12)$$

For a family \mathcal{F} of runs, we say that a place $c \in H \cup P$ is *bounded on \mathcal{F} by $B \in \mathbb{N}$* if for every configuration $s(\mathbf{v})$ appearing in every run in the family \mathcal{F} , $\mathbf{v}(c) \leq B$. A place is *bounded on \mathcal{F}* , if it is bounded on \mathcal{F} by some B . Otherwise, the place is called *unbounded on \mathcal{F}* .

As forward (resp. backward) pumps compose, every place which is forward (resp. backward) pumpable from q (resp. q') is necessarily unbounded on respective pumps. We show the opposite implication, namely unpumpable places are bounded on respective pumps:

► **Lemma 26.** *A place which is not forward (resp. backward) pumpable from q is bounded on forward (resp. backward) pumps from q . Likewise for q' .*

Proof. W.l.o.g. we focus on forward pumps from q only. (Backward pumps are tackled similarly as forward ones, but in the *reversed* DVASS, whose transitions $\{(s', -\mathbf{v}, s) \mid (s, \mathbf{v}, s') \in T\}$ are inverses of transitions of \mathcal{V} .) Assuming that a place $c \in H \cup P$ is unbounded on forward pumps from q , we show that c is forward pumpable from q . Unboundedness of c means that for every $i \in \mathbb{N}$ there is a run

$$q(\mathbf{0}) \longrightarrow s_i(\mathbf{v}_i) \longrightarrow q(\mathbf{\Delta}_i) \quad (13)$$

such that $n_i := \mathbf{v}_i(c) > i$. By choosing a subsequence of $(n_i)_i$ we may assume w.l.o.g. that this sequence is strictly increasing. As \sqsubseteq is a WQO, for some $j < i$ we have $s_j(\mathbf{v}_j) \sqsubseteq s_i(\mathbf{v}_i)$, i.e., there is some $\sigma \in \text{Aut}(\mathbb{A})$ such that $\sigma(s_j) = s_i$ and $\sigma(\mathbf{v}_j) \leq \mathbf{v}_i$. Equivalently, $\sigma(\mathbf{v}_j) + \mathbf{\Delta} = \mathbf{v}_i$ for some nonnegative vector $\mathbf{\Delta}$. Recall that $q = (\ell, \perp)$ and hence $\sigma(q) = q$. Therefore, we can construct a new run, by first using the first half of (13) to go from $p(\mathbf{0})$ to $s_i(\mathbf{v}_i)$, and then applying σ to the second half $s_j(\mathbf{v}_j) \longrightarrow q(\mathbf{\Delta}_j)$ to return from $\sigma(s_j(\mathbf{v}_j)) = \sigma(s_j)(\sigma(\mathbf{v}_j))$:

$$q(\mathbf{0}) \longrightarrow s_i(\mathbf{v}_i) = \sigma(s_j)(\sigma(\mathbf{v}_j) + \mathbf{\Delta}) \longrightarrow q(\sigma(\mathbf{\Delta}_j) + \mathbf{\Delta}).$$

By strict monotonicity of $(n_i)_i$ we have $n_j < n_i$, i.e., $\mathbf{v}_j(c) < \mathbf{v}_i(c)$, which implies $\mathbf{\Delta}(c) > 0$. The place c is thus forward pumpable from q , as required. ◀

Reduction step. Let $B \in \mathbb{N}$ be the universal bound for all unpumpable places on all respective pumps. Formally, let's assume that B bounds every place which is not forward (resp. backward) pumpable from q , on all forward (resp. backward) pumps from q , and B also bounds every place which is not forward (resp. backward) pumpable from q' , on all forward (resp. backward) pumps from q' . As \mathcal{V} violates Φ_2 , we know by Lemma 25 that there are some unpumpable places. We define a DVASS $\widehat{\mathcal{V}} = (\widehat{L}, \widehat{\mathcal{R}}, \widehat{H}, \widehat{P}, \widehat{T})$ by, intuitively speaking, removing some such place. Let $X = H \cup P \times \mathbb{A}$.

Case 1: some plain place is unpumpable. Let $\widehat{P} := P$ and $\widehat{\mathcal{R}} = \mathcal{R}$. We choose an arbitrary unpumpable $h \in H$, and let $\widehat{H} := H \setminus \{h\}$. We keep track of values on h by extending the locations $\widehat{L} := L \times \{0 \dots B\}$. Finally, transitions \widehat{T} are obtained from transitions T by replacing each $t = ((\ell, \mu), \mathbf{v}, (\ell', \mu')) \in T$ by all the transitions of the form

$$\widehat{t} = (((\ell, n), \mu), \mathbf{w}, ((\ell', n + \mathbf{v}(h)), \mu')),$$

where \mathbf{w} is the restriction of $\mathbf{v} : (H \cup P \times \mathbb{A}) \rightarrow_{\text{fin}} \mathbb{Z}$ to $\widehat{H} \cup P \times \mathbb{A}$. Let $\widehat{q} = ((\ell, 0), \perp)$ and $\widehat{q}' = ((\ell', 0), \perp)$.

Case 2: some atom place is unpumpable. Let $\widehat{L} := L$ and $\widehat{H} := H$. We choose an arbitrary unpumpable $p \in P$, remove place p , namely $\widehat{P} := P \setminus \{p\}$, and add B new registers, namely $\widehat{\mathcal{R}} = \mathcal{R} \cup \{r_1, \dots, r_B\}$, which store, intuitively speaking, every possible content of the place p . Using the new registers the transitions \widehat{T} track, intuitively speaking, the effect of transitions from T on the removed place p . Every register valuation μ naturally induces a vector $\widehat{\mu} : \{p\} \times \mathbb{A} \rightarrow_{\text{fin}} \mathbb{N}$, namely $\widehat{\mu} := \oplus \{(p, a) \mid \mu(r_i) = a \neq \perp, i \in \{1 \dots B\}\}$. Using this notation we define the transitions \widehat{T} by replacing every transition $((\ell, \nu), \mathbf{v}, (\ell', \nu')) \in T$ with all the transitions of the form

$$((\ell, \nu \oplus \mu), \mathbf{w}, (\ell', \nu' \oplus \mu')),$$

where \mathbf{w} is the restriction of $\mathbf{v} : (H \cup P \times \mathbb{A}) \rightarrow_{\text{fin}} \mathbb{Z}$ to $H \cup \widehat{P} \times \mathbb{A}$, and $\mathbf{v} = \mathbf{w} \oplus \widehat{\mu}' \ominus \widehat{\mu}$. Let $\widehat{q}, \widehat{q}'$ be extensions of the states q, q' , respectively, by empty valuation of all the new registers $\{r_1, \dots, r_B\}$.

► **Lemma 27 (Progress).** $\text{RANK}(\widehat{\mathcal{V}}) < \text{RANK}(\mathcal{V})$.

Proof. In the former case $\widehat{P} = P$ and $|\widehat{H}| < |H|$, while in the latter case $|\widehat{P}| < |P|$. In each case, $\text{RANK}(\widehat{\mathcal{V}}) = (|\widehat{P}|, |\widehat{H}|, |\widehat{T}|) < (|P|, |H|, |T|) = \text{RANK}(\mathcal{V})$. ◀

► **Lemma 28 (Correctness).** *The configurations $q(\mathbf{0}), q'(\mathbf{0})$ are bi-reachable in \mathcal{V} if and only if $\widehat{q}(\mathbf{0}), \widehat{q}'(\mathbf{0})$ are bi-reachable in $\widehat{\mathcal{V}}$.*

Proof. As $\widehat{\mathcal{V}}$ is obtained from \mathcal{V} by restricting values in configurations on some places, each run in $\widehat{\mathcal{V}}$ is automatically a run in \mathcal{V} , and bi-reachability in $\widehat{\mathcal{V}}$ implies bi-reachability in \mathcal{V} .

For the converse implication, suppose $q(\mathbf{0}), q'(\mathbf{0})$ are bi-reachable in \mathcal{V} , and fix two arbitrary runs $\pi : q(\mathbf{0}) \rightarrow q'(\mathbf{0})$ and $\pi' : q'(\mathbf{0}) \rightarrow q(\mathbf{0})$. Consider any unpumpable place $c \in H \cup P$ and suppose, w.l.o.g., that the place is not forward pumpable from q . By Lemma 26 the place is bounded by B on all forward pumps from q . In particular, it is bounded by B on the composed run $\pi; \pi' : q(\mathbf{0}) \rightarrow q(\mathbf{0})$, i.e., on both π and π' . Therefore we know that in each configuration (s, \mathbf{v}) in both runs, $\mathbf{v}(c) \leq B$. If $c \in H$ we keep track of $\mathbf{v}(c)$ in locations; and if $c \in P$, we keep track of all tokens on c by storing their atoms in the new registers $\{r_1, \dots, r_B\}$. Therefore, both runs are realisable in $\widehat{\mathcal{V}}$. ◀

► **Lemma 29 (Effectiveness).** *The set of pumpable places and the universal bound B are computable (and therefore the condition Φ_2 is decidable).*

Proof. For a simple ω -configuration $s(f)$ and an atom place $p \in P$ we define $f(p) = \omega$ if $f(p, a) = \omega$ for some atom $a \in \mathbb{A}$, and otherwise $f(p) := \sum \{f(p, a) \mid f(p, a) > 0, a \in \mathbb{A}\}$. Relying on Lemma 25, we test forward (resp. backward) pumpability of every place from q (and likewise from q'). Specifically, to test if a place is forward pumpable from q , we apply Lemma 12 and compute a simple-ideal representation of the coverability set $\text{COVER}(q(\mathbf{0}))$, given by simple ω -configurations $G = \{s_1(g_1), \dots, s_n(g_n)\}$. A plain or atom place $c \in H \cup P$ is forward pumpable from q if for some $i \in \{1 \dots n\}$ we have $s_i = q$ and $g_i(c) > 0$. Likewise we test if a place is backward pumpable from q (using the reverse DVASS), or forward (resp. backward) pumpable from q' . The set of pumpable places is thus computable.

Suppose there is some unpumpable place c , w.l.o.g. say not forward pumpable from q . By Lemma 26, the place c is bounded on all forward pumps from q , but may be a priori unbounded on some other run, and therefore it may happen that $g_i(c) = \omega$ for some $i \in \{1 \dots n\}$. Nevertheless we claim the following bound on forward pumps:

$$B := \max \{g_i(c) \mid g_i(c) < \omega, i \in \{1 \dots n\}\}. \quad (14)$$

▷ Claim 30. The place c is bounded on all forward pumps from q by B .

Proof. Consider an atom place $p \in P$ (the argument for plain places is similar but simpler). Towards contradiction, suppose that some configuration $s(\mathbf{v})$ on some forward pump from q satisfies $\mathbf{v}(p) > B$. We have thus two runs:

$$\pi : q(\mathbf{0}) \longrightarrow s(\mathbf{v}) \quad \rho : s(\mathbf{v}) \longrightarrow q(\mathbf{w})$$

for some $s \in Q$ and nonnegative vector \mathbf{w} . Therefore $s(\mathbf{v}) \in \text{COVER}(q(\mathbf{0}))$, and hence $s(\mathbf{v}) \in I = s_j(g_j) \downarrow$ for some $j \in \{1 \dots n\}$. As $\mathbf{v}(p)$ is larger than all $g_i(p) < \omega$ for $i \in \{1 \dots n\}$, we deduce that $g_j(p) = \omega$. Therefore the ideal I contains configurations $s'(\mathbf{v}')$ with arbitrary large values of $\mathbf{v}'(p)$. In particular, I contains some configuration $s'(\mathbf{v}')$ with $\mathbf{v}(p) < \mathbf{v}'(p)$. As I is directed, it contains a configuration $s''(\mathbf{v}'')$ such that

$$s(\mathbf{v}) \sqsubseteq s''(\mathbf{v}'') \quad s'(\mathbf{v}') \sqsubseteq s''(\mathbf{v}''),$$

which implies $\mathbf{v}(p) < \mathbf{v}''(p)$. Finally, as $I \subseteq \text{COVER}(q(\mathbf{0}))$, it must contain a configuration $\bar{s}(\bar{\mathbf{v}})$ reachable from $q(\mathbf{0})$, such that $s''(\mathbf{v}'') \sqsubseteq \bar{s}(\bar{\mathbf{v}})$. We thus have $s(\mathbf{v}) \sqsubseteq \bar{s}(\bar{\mathbf{v}})$ and $\mathbf{v}(p) < \bar{\mathbf{v}}(p)$, which means that for some automorphism $\sigma \in \text{Aut}(A)$ and vector $\bar{\mathbf{w}}$ we have

$$\sigma(s) = \bar{s} \quad \sigma(\mathbf{v}) + \bar{\mathbf{w}} = \bar{\mathbf{v}} \quad \bar{\mathbf{w}}(p) > 0.$$

By composing runs $\bar{\pi} : q(\mathbf{0}) \rightarrow \bar{s}(\bar{\mathbf{v}})$ and $\sigma(\rho) : \bar{s}(\sigma(\mathbf{v})) \rightarrow q(\sigma(\mathbf{w}))$ we get a run

$$\bar{\pi}; \sigma(\rho) : q(\mathbf{0}) \longrightarrow q(\sigma(\mathbf{w}) + \bar{\mathbf{w}}),$$

i.e., we deduce that p is forward pumpable from q , which is a contradiction. ◁

The universal bound is computed as the maximum of (14) for forward and backward pumps from q and q' , for all unbounded places c . ◀

7 Final remarks

We show decidability of the bi-reachability problem for Petri nets with equality data. The problem subsumes coverability, and reachability in the reversible subclass, and therefore the result pushes further the decidability border towards the reachability problem. The latter problem (which we believe to be decidable) is still beyond our reach, and development of this paper is not sufficient. For instance, the approach of proving of Lemma 17 would fail for reachability, as we rely on the fact that bi-reachability implies a cycle. Moreover, Φ_1 reduction step would fail as well, as it assumes that a transition (orbit) is either unusable, or usable unboundedly, while in case of reachability a transition can be usable only *boundedly*.

Our approach is specific to equality data, and thus we leave unresolved the status of bi-reachability in case of ordered data. In case of ordered data domain the approach of proving Lemma 17 would fail again, as the trick of applying all permutations of S would be impossible. Moreover, it is not clear how to implement Φ_2 reduction step, as no procedure computing coverability sets is known.

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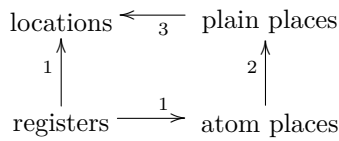
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A Proofs for Section 3 (Data vector addition systems with states)

► **Lemma 8.** In DVASS BI-REACHABILITY problem we may assume, w.l.o.g., that $q = (\ell, \perp)$, $q' = (\ell', \perp)$, and $\mathbf{v} = \mathbf{v}' = \mathbf{0}$.

Proof. Consider a DVASS $\mathcal{V} = (L, \mathcal{R}, P, H, T)$ and two configurations $q(\mathbf{v}), q'(\mathbf{v}')$, where $q = (\ell, \nu)$, $q' = (\ell', \nu')$. We proceed in three steps, as shown in the diagram (cf. diagram (4) in Remark 6):



As the first step we redo the first step of the proof of Lemma 12 which yields a DVASS $\mathcal{V}_1 = (L_1, \emptyset, H, P_1, T_1)$ without registers (which implies $q = (\ell, \perp)$ and $q' = (\ell', \perp)$). We choose initial and final location

$$\bar{\ell} := (\ell, \nu^{-1}(\perp)) \quad \bar{\ell}' := (\ell', (\nu')^{-1}(\perp)) \in L_1$$

and, identifying a register valuation ν with the vector $\oplus \{(r, a) \mid \nu(r) = a \neq \perp\}$, we choose initial and final vector $H \cup P_1 \times \mathbb{A} \rightarrow_{\text{fin}} \mathbb{N}$,

$$\bar{\mathbf{v}} := \mathbf{v} \oplus \nu \quad \bar{\mathbf{v}}' := \mathbf{v}' \oplus \nu',$$

and claim that the reachability is preserved (we omit registers, and write e.g. $\bar{\ell}(\bar{\mathbf{v}})$):

▷ **Claim 31.** The configurations $q(\mathbf{v}), q'(\mathbf{v}')$ are bi-reachable in \mathcal{V} if and only if $\bar{\ell}(\bar{\mathbf{v}}), \bar{\ell}'(\bar{\mathbf{v}}')$ are bi-reachable in \mathcal{V}_1 .

Second, consider a register-less DVASS $\mathcal{V}_1 = (L_1, \emptyset, H_1, P_1, T_1)$ and two configurations $\ell(\mathbf{v}) = q(\mathbf{u} \oplus \mathbf{w})$ and $\ell'(\mathbf{v}') = q'(\mathbf{u}' \oplus \mathbf{w}')$, where $\mathbf{u}, \mathbf{u}' : H_1 \rightarrow_{\text{fin}} \mathbb{N}$ and $\mathbf{w}, \mathbf{w}' : P_1 \times \mathbb{A} \rightarrow_{\text{fin}} \mathbb{N}$. We argue that w.l.o.g. we can assume $\mathbf{w} = \mathbf{w}' = \mathbf{0}$. Let $S = \text{SUPP}(\mathbf{v}) \cup \text{SUPP}(\mathbf{v}')$ be the set of those atoms which appear in \mathbf{w} or \mathbf{w}' . Intuitively, we move the set $P_1 \times S$ to plain places. We take $H_2 = H_1 \cup P_1 \times S$ as plain places, and consider atoms $\mathbb{A}' = \mathbb{A} \setminus S$ instead of \mathbb{A} . Clearly,

$$H_1 \cup (P_1 \times \mathbb{A}) = H_2 \cup (P_1 \times \mathbb{A}')$$

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and therefore we may take the same transitions T_1 as transitions of the new DVASS $\mathcal{V}_2 = (L_1, \emptyset, H_2, P_1, T_1)$. As S is finite, the set T_1 is still orbit-finite with respect to $\text{Aut}(\mathbb{A}')$.

▷ **Claim 32.** The configurations $\ell(\mathbf{v})$, $\ell'(\mathbf{v}')$ are bi-reachable in \mathcal{V}_1 if and only if $\ell(\mathbf{v})$, $\ell'(\mathbf{v}')$ are bi-reachable in \mathcal{V}_2 .

In the last third step, consider a DVASS $\mathcal{V} = (L_2, \emptyset, H_2, P_2, T_2)$ without registers and two configurations $\ell(\mathbf{u})$ and $\ell'(\mathbf{u}')$, where $\mathbf{u}, \mathbf{u}' : H_2 \rightarrow_{\text{fin}} \mathbb{N}$. We eliminate the initial and final values \mathbf{u}, \mathbf{u}' on plain places in a classical way, by introducing new initial and final locations $\bar{\ell}, \bar{\ell}'$ and adding to T_2 the following four transitions, and thus defining $\mathcal{V}_3 = (L_2 \cup \{\bar{\ell}, \bar{\ell}'\}, \emptyset, H_2, P_2, T_3)$:

$$(\bar{\ell}, \mathbf{u}, \ell) \quad (\ell', -\mathbf{u}', \bar{\ell}') \quad (\ell, -\mathbf{u}, \bar{\ell}) \quad (\bar{\ell}', \mathbf{u}', \ell'). \quad (15)$$

▷ **Claim 33.** The configurations $\ell(\mathbf{u})$, $\ell'(\mathbf{u}')$ are bi-reachable in \mathcal{V}_2 if and only if $\bar{\ell}(\mathbf{0})$, $\bar{\ell}'(\mathbf{0})$ are bi-reachable in \mathcal{V}_3 .

Indeed, a run $\ell(\mathbf{u}) \rightarrow \ell'(\mathbf{u}')$ in \mathcal{V}_2 extended with the first two transitions in (15) yields a run $\bar{\ell}(\mathbf{0}) \rightarrow \bar{\ell}'(\mathbf{0})$ in \mathcal{V}_3 , and likewise a run $\ell'(\mathbf{u}')$ in \mathcal{V}_2 extended with the last two transitions in (15) yields a run $\bar{\ell}'(\mathbf{0}) \rightarrow \bar{\ell}(\mathbf{0})$ in \mathcal{V}_3 . Conversely, consider a run $\pi : \bar{\ell}(\mathbf{0}) \rightarrow \bar{\ell}'(\mathbf{0})$ in \mathcal{V}_3 . It necessarily starts with the first transition in (15), and ends with the second one. If transitions (15) are used elsewhere in π , they are necessarily used in pairs, namely the second one followed immediately by the fourth one, or the third one is followed immediately by the first one. Effects of each such pair cancel out, and thus each pair can be safely removed from π . Finally, removing the first and the last transition makes π into a run $\ell(\mathbf{u}) \rightarrow \ell'(\mathbf{u}')$ in \mathcal{V}_2 , as required. Likewise we transform a run $\bar{\ell}'(\mathbf{0}) \rightarrow \bar{\ell}(\mathbf{0})$ in \mathcal{V}_3 . ◀

B Proofs for Section 4 (Toolset)

► **Lemma 10.** \sqsubseteq is a WQO on configurations.

Proof. Recall the sets of states $Q = L \times (\mathcal{R} \rightarrow (\mathbb{A} \cup \{\perp\}))$ and configurations $\text{CONF} = Q \times ((H \cup P \times \mathbb{A}) \rightarrow_{\text{fin}} \mathbb{N})$. The quasi-order \sqsubseteq is a WQO on the set of nonnegative vectors $P \times \mathbb{A} \rightarrow_{\text{fin}} \mathbb{N}$, as it is quasi-order-isomorphic to $M(P \rightarrow_{\text{fin}} \mathbb{Z})$, the set of finite multisets of finite vectors from $P \rightarrow_{\text{fin}} \mathbb{Z}$, ordered by multiset inclusion. Furthermore, \sqsubseteq is a WQO on $(H \cup P \times \mathbb{A}) \rightarrow_{\text{fin}} \mathbb{N}$, as it is quasi-order-isomorphic to the Cartesian product $(H \rightarrow_{\text{fin}} \mathbb{N}) \times (P \times \mathbb{A} \rightarrow_{\text{fin}} \mathbb{N})$ of two WQO's, and Cartesian product preserves WQO.

Every register valuation $\nu : \mathcal{R} \rightarrow (\mathbb{A} \cup \{\perp\})$ may be seen as an \mathcal{R}' -vector, where $\mathcal{R}' = \nu^{-1}(\mathbb{A})$ is the set of non-empty registers, namely $\hat{\nu} = \oplus \{(r, a) \mid \nu(r) = a \neq \perp\} : \mathcal{R}' \rightarrow_{\text{fin}} \mathbb{N}$. We use this fact to argue that \sqsubseteq is a WQO on $Y = (\mathcal{R} \rightarrow (\mathbb{A} \cup \{\perp\})) \times ((H \cup P \times \mathbb{A}) \rightarrow_{\text{fin}} \mathbb{N})$. Indeed, we split this set into $2^{|\mathcal{R}|}$ subsets, determined by non-empty registers, i.e., for every subset $\mathcal{R}' \subseteq \mathcal{R}$ we consider a subset

$$C_{\mathcal{R}'} := \{(\nu, \mathbf{v}) \mid \nu^{-1}(\mathbb{A}) = \mathcal{R}'\} \subseteq Y.$$

For every fixed \mathcal{R}' , the set $C_{\mathcal{R}'}$ is essentially a subset of $H \cup (P \cup \mathcal{R}') \times \mathbb{A} \rightarrow_{\text{fin}} \mathbb{N}$, due to the bijection $(\nu, \mathbf{v}) \mapsto \hat{\nu} \oplus \mathbf{v}$, containing those vectors which use exactly one generator from $\mathcal{R}' \times \mathbb{A}$. Therefore $C_{\mathcal{R}'}$ is a WQO. In consequence, Y is a WQO too, as finite sums preserve WQO.

Finally, the set $\text{CONF} = L \times Y$ is a WQO, as Cartesian product of the finite set L and a WQO. ◀