



# Level Planarity Is More Difficult Than We Thought

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## Abstract

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We consider three simple quadratic-time algorithms for LEVEL PLANARITY and give a level-planar instance that they either falsely classify as negative or for which they output a non-planar drawing.

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## 1 Introduction

Given a graph  $G = (V, E)$  and a *level assignment*  $\ell : V(G) \rightarrow \mathbb{N}$ , the problem LEVEL PLANARITY asks for a crossing-free drawing of  $G$  where vertices have their prescribed level as  $y$ -coordinate and all edges are  $y$ -monotone. When initially considering the problem in 1988, Di Battista and Nardelli [1] gave a linear-time algorithm for the restricted case where the graph is a hierarchy, i.e., only one vertex has no neighbors on a lower level. A subsequent attempt to extend this algorithm to the general case [7] was shown to be incomplete [10]. Jünger et al. finally gave the first linear-time algorithm for testing [11] and embedding [8, 9] level graphs around the turn of the millennium. Because this algorithm is quite involved, slower but simpler algorithms were developed by Randerath et al. [12], Healy and Kuusik [6], as well as Harrigan and Healy [5] in the decade thereafter. All these algorithms consider the pairwise ordering of vertices on the same level, greedily fixing an order for a (certain) pair and then checking for further orders implied by this. If the process terminates without finding a contradiction, we obtain a total vertex order for each level and thereby a level planar embedding. In the following, we give a level-planar counterexample that each known variant of this algorithm either incorrectly classifies as negative instance or correctly identifies as positive instance but outputs a drawing that is not planar. To the best of our knowledge, this leaves no correct *simple* embedding algorithm for level graphs. In particular, we are not aware of *any* correct implementation for embedding level-planar graphs.

Randerath et al. use an explicit 2-SAT formulation for the pairwise orders of vertices on the same level. Due to known gaps in the proof of Randerath et al., Brückner et al. [2, 3] showed this characterization via a 2-SAT formula is equivalent to the Hanani-Tutte-style characterization of LEVEL PLANARITY [4]. Thereby, our counterexample only breaks the proof of correctness as well as the embedder by Randerath et al., while their 2-SAT formulation still yields a correct *test* for LEVEL PLANARITY via this indirect proof [2, 3].



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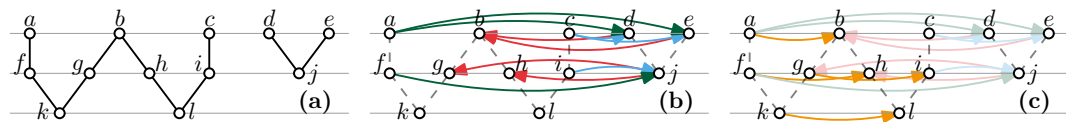
**2 Randerath et al.**

The algorithm by Randerath et al. [12] works as follows. First, edges spanning multiple levels are subdivided such that subsequently edges only occur between adjacent levels, resulting in a *proper* level graph. The planarity of the resulting graph is then tested using a 2-SAT formula. The formula contains a variable  $(a < b)$  for every pair  $a, b$  of vertices that appear on the same level, encoding the relative order of these two vertices. For every pair of edges  $uv, xy \in E$  with  $\ell(u) = \ell(x) = \ell(v) + 1 = \ell(y) + 1$  with  $u \neq x, v \neq y$  it adds the 2-SAT constraint  $(u < x) \Leftrightarrow (v < y)$ . Combining this with the constraints for antisymmetry  $((a < b) \Leftrightarrow \neg(b < a))$  and transitivity  $((a < b) \wedge (b < c) \Rightarrow (a < c))$  necessary for finding total orders yields a 3-SAT formula. However, Randerath et al. [12] show that omitting the transitivity constraints yields an *equisatisfiable* 2-SAT formula. To prove this equivalence, they show that the 2-SAT formula can be used to compute a level-planar embedding of the input graph. They greedily pick and assign equivalence classes of the formula in arbitrary order, but prioritize transitive closures where possible. Figure 1 shows a counterexample where the algorithm gives a false-negative answer when assigning classes in the shown order.

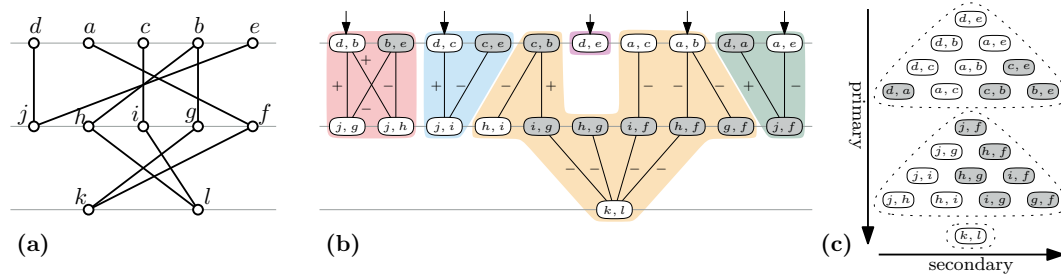
**3 Healy and Kuusik & Harrigan and Healy**

The algorithms by Healy and Kuusik [6] as well as the one by Harrigan and Healy [5] uses a similar concept. Instead of working with equivalence classes of a 2-SAT formula, they work with connected components of the closely related *vertex exchange graph* (ve-graph). This graph contains one vertex for every ordered pair of vertices that appear on the same level. Two vertices of the ve-graph are adjacent if they correspond to a pair of independent edges between the same levels. Starting with an arbitrary drawing  $\mathcal{L}$  of the input graph, the edges of the ve-graph are first labeled with  $+$  or  $-$ , depending on whether the corresponding edges cross in  $\mathcal{L}$ . Subsequently, a DFS is used to test the ve-graph for odd-labeled cycles, which corresponds to a contradiction within a 2-SAT equivalence class. The two algorithms now differ slightly in how they continue to construct an embedding. Similar to Randerath et al., Healy and Kuusik [6] fix the orders of vertex pairs (i.e., whether all pairs of a connected ve-graph component are swapped or not) in an arbitrary order, also performing the transitive closure if possible. Thus, the processing order from Figure 1 also breaks this approach.

The later Harrigan and Healy approach [5] is slightly more involved. During the DFS traversal, they already change the relative order of some vertex pairs compared to the initial drawing  $\mathcal{L}$  [5, Algorithm 1]. Subsequently, the ve-graph is traversed again in a specific order and, for some vertices of  $\mathcal{L}$ , the chosen vertex order is flipped [5, Algorithm 2]. Using choices as shown in Figure 2, this does not yield a planar embedding even for a positive instance.



**Figure 1** (a) A level-planar graph  $G$ . (b) The green, blue, and red 2-SAT equivalence classes can be greedily assigned in this order. Subsequently, transitive closure forces  $a < b$  as well as  $i < g$ , but the planarity constraints force  $a < b \leftrightarrow f < h \leftrightarrow k < l \leftrightarrow g < i$  (c), yielding a contradiction.



■ **Figure 2** (a) An initial drawing  $\mathcal{L}$  for Figure 1a. (b) The corresponding labeled ve-graph. Arrows mark the chosen DFS entry points, pairs marked as swapped by Algorithm 1 are shown in gray. (c) The processing order for the vertices of the ve-graph in Algorithm 2.

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