Strongly Sublinear Separators and Bounded Asymptotic Dimension for Sphere Intersection Graphs

James Davies ☑

University of Cambridge, UK

University of Warwick, UK

Meike Hatzel **□**

Institute for Basic Science (IBS), Daejeon, South Korea

Rose McCarty \square

Georgia Institute of Technology, Atlanta, GA, USA

Abstract

In this paper, we consider the class C^d of sphere intersection graphs in \mathbb{R}^d for $d \geq 2$. We show that for each integer t, the class of all graphs in C^d that exclude $K_{t,t}$ as a subgraph has strongly sublinear separators. We also prove that C^d has asymptotic dimension at most 2d + 2.

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1 Introduction

We write C^d for the class of intersection graphs of spheres in \mathbb{R}^d for $d \geq 2$. The *sphere dimension* of a graph G is the smallest integer so that G is contained in C^d . This notion of dimension is analogous to the *boxicity*, *cubicity*, or *sphericity*¹ of a graph. These "dimensionality" parameters were introduced by Roberts [47], further studied by Maehara [42], and have since become a topic of much research; see for instance [7, 23, 49, 52]. We formulate an equivalent definition of C^d utilising an appealing application of stereographic projection, allowing us to think of C^d as a higher-dimensional generalisation of the class of circle graphs. (See [5, 29, 45] for some classical work on circle graphs and [16, 48] for surveys.) It will, therefore, become natural to let C^1 denote the class of circle graphs, which then have sphere dimension 1. Thus, C^d simultaneously generalises various well-studied graph classes.

Of particular note, graphs with low dimension often satisfy strong separator theorems along the lines of Lipton and Tarjan's [38] famous separator theorem for planar graphs. Formally, a balanced separator in an n-vertex graph G is a set $S \subseteq V(G)$ so that each

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¹ We note that sphericity is more restrictive than sphere dimension as it only considers unit spheres.

component of G-S has at most $\frac{2}{3}n$ many vertices². Lipton and Tarjan showed that every n-vertex planar graph has a balanced separator of size $\mathcal{O}(\sqrt{n})$. These separator theorems have many applications as they can be combined with divide-and-conquer techniques [9, 12, 39, 50].

Planar graphs are intersection graphs of internally disjoint circles by the Circle Packing Theorem of Andreev [1], Koebe [35], and Thurston [51]. So Miller, Teng, Thurston, and Vavasis [44] generalised the planar separator theorem by proving that the intersection graph of any sphere packing of size n in \mathbb{R}^d has a balanced separator of size $\mathcal{O}(n^{1-\frac{1}{d}})$. In fact, their results hold for any collection of balls of bounded ply; the ply of a collection of geometric objects is the maximum number of objects with a non-empty common intersection. The ply of a collection of balls in \mathbb{R}^d is closely related to the clique number of its intersection graph.

Many other geometric generalisations of Lipton and Tarjan's theorem have been proven, including some very recently [13, 14, 17, 30, 34, 50]. Some of these results, such as [13, 14, 34], consider relaxations of separators and allow for more general geometric objects that way. However, if we keep the original notion of balanced separators, then two main improvements have been made. First, instead of considering balls, we can consider compact convex subsets of \mathbb{R}^d of bounded aspect ratio (the ratio of their diameter to their height) by [30, Lemma 2.21]. Second, it is enough that for any pair of objects under consideration, we can "move one of them around inside the other to roughly trace its boundary"; see [17, Theorem 2].

All the results discussed above are for convex subsets of \mathbb{R}^d . We prove a new separator theorem for the intersection graphs of spheres in \mathbb{R}^d . Instead of bounding the ply, there is a different natural obstruction which we must bound the size of: the class of all complete bipartite graphs has bounded sphere dimension, but does not admit small balanced separators. Our first result is that this is the only obstruction. For any integers $t, d \geq 2$, we write \mathcal{C}_t^d for the class of all graphs that have sphere dimension at most d and do not contain the complete bipartite graph $K_{t,t}$ as a subgraph. (This subgraph need not be induced.)

▶ **Theorem 1.** For any integers $t, d \geq 2$, the class C_t^d has strongly sublinear separators. More precisely, every n-vertex graph $G \in C_t^d$ has a balanced separator of size $\widetilde{\mathcal{O}}_d(t^{10}n^{1-\frac{1}{2d+8}})$.

To the best of our knowledge, this is the first high-dimensional separator theorem that applies to classes that contain large induced complete bipartite graphs. In two dimensions, Lee [37] proved that every string graph with m edges has a balanced separator of size $\mathcal{O}(\sqrt{m})$. This implies a separator theorem for string graphs with a forbidden $K_{t,t}$ -subgraph by the Kővári-Sós-Turán Theorem [36]. This theorem of Lee was conjectured by Fox and Pach [24], and a slightly weaker version with an extra $\log(m)$ factor was proven by Matoušek [43]. As far as we know, the same bound could hold for graphs with sphere dimension at most d; maybe every graph with m edges and sphere dimension d has a balanced separator of size $\mathcal{O}_d(\sqrt{m})$. If so, a theorem of Fox, Pach, Sheffer, Suk, and Zahl [25] about semi-algebraic graphs could then be used to obtain a strong separator theorem for \mathcal{C}_t^d .

Next, we turn our attention to the asymptotic dimension of our graphs. Gromov [28] introduced the notion of asymptotic dimension of a metric space as a coarse version of the classical topological dimension. This was part of his coarse-geometric approach, which has tremendously impacted geometric group theory. For instance, Yu [53] showed that (any Cayley graph of) every finitely generated group G with finite asymptotic dimension embeds coarsely into Hilbert space, and therefore G satisfies a seminal conjecture of Novikov. Roughly speaking, asymptotic dimension corresponds to the number of colours needed to colour a graph, or family of graphs, with certain restrictions on the diameters and spacing of monochromatic components; the precise definition is given in Section 2.

The exact constant does not matter much; we could replace $\frac{2}{3}$ by any constant $c \in (0,1)$.

Although asymptotic dimension was originally introduced to study spaces of infinite diameter, the notion can be applied to classes of finite graphs, and it is gaining popularity in this setting [4, 15, 17, 26, 27, 33, 40]. This popularity is partly motivated by a connection to sparse partition schemes in algorithm development, as we discuss in Section 6. It is also motivated by connections to graph colouring, as discussed in [20].

Thus, understanding how the asymptotic dimension of a graph class interacts with other geometric properties is important. In this spirit, Bonamy et al. [4] proved that planar graphs have asymptotic dimension at most 2, and asked if every class with strongly sublinear separators has bounded asymptotic dimension [4]. (We note that this question was phrased in terms of classes of polynomial expansion; however, a class has polynomial expansion if and only if it has strongly sublinear separators [18, 46]. Formally, a class has strongly sublinear separators if there exists $\delta > 0$ so that every n-vertex graph that is an induced subgraph of some graph in the class admits a balanced separator of size $\mathcal{O}(n^{1-\delta})$.) We prove that the answer is positive for graphs of bounded sphere dimension.

▶ **Theorem 2.** For any integer $d \ge 1$, the class of graphs of sphere dimension at most d has asymptotic dimension at most 2d + 2.

This theorem generalises and also uses a theorem of Dvořák and Norin [19], at the cost of increasing the dimension by 1. In fact, we prove a more general result by considering intersection graphs of shapes other than spheres (Theorem 18).

Paper structure. We introduce some preliminaries in Section 2. In Section 3, we discuss basic properties of sphere dimension, particularly the connection to circle graphs. In Section 4, we prove our main result that C_t^d has strongly sublinear separators. We prove that C_t^d has bounded asymptotic dimension in Section 5. We conclude with some open problems in Section 6.

2 Preliminaries

All graphs in this paper can be assumed to be finite and simple, although some of our results extend verbatim to the infinite case. We use $\widetilde{\mathcal{O}}_d$ for the version of big- \mathcal{O} notation where we view d as being fixed and suppress polylogarithmic factors. (In fact it will be clear from our proof of Theorem 1 that we only suppress a single $\log n$ factor and a constant factor of the form c^d for c a universal constant.)

Geometric intersection graphs. Let \mathcal{G} be a class of geometric objects in a given space, for example, unit squares in the plane. Then an *intersection graph of* \mathcal{G} is a graph G whose vertices can be identified with objects in \mathcal{G} such that there is an edge between two vertices in G if and only if the two corresponding objects intersect. Similarly, we write $G(\mathcal{G})$ for the graph with vertex-set \mathcal{G} where two vertices are adjacent if they have a non-empty intersection. The ply of \mathcal{G} is the maximum size of a set of objects in \mathcal{G} with a non-empty common intersection.

Shallow minors. Our proof of Theorem 1 relies on a theorem of Plotkin, Rao, and Smith [46] and Dvořák and Norin [18] which characterises classes that admit strongly sublinear separators in terms of forbidden shallow minors. We give some relevant definitions.

Given a positive integer r, we say that a graph H is an r-shallow minor of a graph G if there is a function $\varphi: V(H) \to 2^{V(G)}$ such that:

- for every $x \in V(H)$, the subgraph of G induced by $\varphi(x)$ contains a rooted spanning tree of height at most r,
- for all distinct $x, y \in V(H)$, the sets $\varphi(x)$ and $\varphi(y)$ are disjoint, and
- for every $xy \in E(H)$, there is an edge in G with one end in $\varphi(x)$ and the other in $\varphi(y)$. We call φ an r-shallow minor model of H in G. For $v \in V(H)$, we call $\varphi(v)$ the bag of v.

Strongly sublinear separators. Recall that a balanced separator in an n-vertex graph G is a set $S \subseteq V(G)$ so that each component of G-S has at most $\frac{2}{3}n$ vertices. A graph class \mathcal{C} has strongly sublinear separators if there exist $\varepsilon>0$ so that for any n-vertex graph H which is an induced subgraph of a graph in \mathcal{C} , the graph H has a balanced separator of size $\mathcal{O}(n^{1-\varepsilon})$. (The big- \mathcal{O} notation can hide a constant factor that depends on \mathcal{C} .) Note that to obtain strongly sublinear separators, it suffices to show that there exists $\delta>0$ so that there are balanced separators of size $\widetilde{\mathcal{O}}(n^{1-\delta})$. In order to provide this, we show that there exists $\delta>0$ so that there are separators of size $\widetilde{\mathcal{O}}(n^{1-\delta})$. Plotkin, Rao, and Smith [46] proved that any graph with a forbidden shallow minor has a small balanced separator.

▶ **Theorem 3** (Plotkin, Rao, and Smith [46]). For any $r, h \in \mathbb{N}$, any n-vertex graph without an r-shallow K_h minor has a balanced separator of size $\mathcal{O}(rh^2 \log n + \frac{n}{r})$.

We apply this theorem with r being a small power of n and h being a polynomial in r. With this choice of parameters, Theorem 3 yields a sufficiently small balanced separator.

Strong colouring number. Let G be a graph, $r \in \mathbb{N}$, and \leq be an ordering of the vertices of G. For a vertex $v \in V(G)$, we call a vertex $u \in V(G)$ strongly r-reachable from v if $u \leq v$ and there exists a v-u-path P of length at most r in G such that u is the only vertex in P that is smaller than v with respect to \leq . The r-width of \leq is the maximum over all $v \in V(G)$ of the number of vertices which are strongly r-reachable from v. Finally, the r-strong colouring number of a graph G, denoted $\mathsf{scol}_r(G)$, is the minimum r-width over all possible vertex orderings of G. We require the observation that intersection graphs of balls of bounded ply have bounded strong colouring numbers.

▶ Lemma 4 ([21, Lemma 1]). Let \mathcal{B} be a finite collection of balls in \mathbb{R}^d of ply at most t. Then the intersection graph $G(\mathcal{B})$ has r-strong colouring number at most $t(2r+2)^d$.

We also use the following well-known observation that graphs with large shallow clique minors have large strong colouring numbers.

▶ **Observation 5.** If a graph G contains an r-shallow K_h -minor, then $scol_{4r+1}(G) \ge h-1$.

Asymptotic and Assouad–Nagata dimension. Let G be a graph, and let $\mathsf{dist}_G(\cdot, \cdot)$ denote its usual graph metric. If the graph is clear from the context, we drop the index. Let \mathcal{U} be a family of subsets of V(G). We say that \mathcal{U} is D-bounded if each set $U \in \mathcal{U}$ has diameter at most D. We say that \mathcal{U} is r-disjoint if for any a, b belonging to different elements of \mathcal{U} we have $\mathsf{dist}(a,b) > r$.

We say that $D: \mathbb{R}_+ \to \mathbb{R}_+$ is an n-dimensional control function for a graph class \mathcal{C} , if for any $G \in \mathcal{C}$ and r > 0, V(G) has a cover $\mathcal{U} = \bigcup_{i=1}^{n+1} \mathcal{U}_i$ such that each \mathcal{U}_i is r-disjoint and each element of \mathcal{U} is D(r)-bounded. The asymptotic dimension of \mathcal{C} denoted by $\operatorname{asdim}(\mathcal{C})$, is the least integer n such that \mathcal{C} has an n-dimensional control function. If no such integer n exists, then $\operatorname{asdim}(\mathcal{C})$ is infinite. The $\operatorname{Assouad-Nagata\ dimension\ of\ } \mathcal{C}$, denoted by $\operatorname{ANdim}(\mathcal{C})$, is defined similarly, except that we insist that $D(r) \in \mathcal{O}(r)$.

3 Sphere graphs and sphere dimension

In this section, we show that the graph classes C^d can be thought of as a higher-dimensional analogue of the well-studied class of circle graphs. Recall that a *circle graph* is an intersection graph of a family of chords of S^1 . We generalise this definition as follows. A *d-sphere graph* is an intersection graph of a subfamily of

$$\mathcal{H}_d := \{ \mathbb{D}^d \cap H \mid H \text{ is a hyperplane of } \mathbb{R}^{d+1} \},$$

where the d-disc \mathbb{D}^d is the set $\{x \in \mathbb{R}^{d+1} \mid |x,0| \leq 1\}$, and \mathbb{S}^d is its boundary. In particular, \mathcal{H}_1 consists of all chords of the circle \mathbb{S}^1 , and \mathcal{H}_2 consists of the flat discs with boundary on \mathbb{S}^2 . Thus, 1-sphere graphs are exactly the circle graphs, which by definition are the graphs in \mathcal{C}^1 . We observe that the class of d-sphere graphs coincides with \mathcal{C}^d :

▶ **Observation 6.** For every $d \ge 1$, a countable graph G is a d-sphere graph if and only if it belongs to C^d .

Proof. For d=1 this is so by definition. For $d\geq 2$, suppose $\Theta=\{H_v\mid v\in V(G)\}$ is a d-sphere representation of G, i.e. a family of elements of \mathcal{H}_d witnessing that G is a d-sphere graph. Assume that no H_v contains the *north pole* $\{0,\ldots,0,1\}$ of \mathbb{S}^d , which we can since G is countable (which is a much stronger assumption than we actually need). Notice that $H_v\cap\mathbb{S}^d$ is homeomorphic to \mathbb{S}^{d-1} for every v. Letting f be the stereographic projection of \mathbb{S}^d onto \mathbb{R}^d , we observe that $f(H_v\cap\mathbb{S}^d)=:H'_v$ is also homeomorphic to \mathbb{S}^{d-1} , where we use the well-known property of stereographic projection that it preserves spheres not containing the north pole [44, Lemma 4.2]. Then G is isomorphic to the intersection graph of the family $\Theta'=\{H'_v\mid v\in V(G)\}$ by construction.

Conversely, we use f^{-1} to stereographically project a representation of G as an intersection graph of spheres in \mathbb{R}^d (avoiding the origin) to a d-sphere graph representation.

We now give some other observations about sphere graphs and sphere dimension. As a warm-up, we observe that if G is planar, then it has sphere dimension 2. This is because the Circle Packing Theorem [35] asserts that every finite³ planar graph admits a sphere packing in \mathbb{R}^2 . (A sphere packing of a graph G is an arrangement of closed euclidean spheres $\{S_v : v \in V(G)\}$ in \mathbb{R}^d or \mathbb{S}^d such that $S_v \cap S_w$ is empty whenever $vw \notin E(G)$ and $S_v \cap S_w$ is a single point whenever $vw \in E(G)$. In other words, G is the tangency graph of the family $\{S_v : v \in V(G)\}$.) It is known that every finite graph G admits a sphere packing in \mathbb{R}^d for $d \leq |V(G)| - 1$ [22], and so $G \in \mathbb{C}^{|V(G)|-1}$. This proves the following observation.

- ▶ Observation 7. Every graph G with $|V(G)| \ge 3$ has sphere dimension at most |V(G)| 1. Conversely, we prove the following.
- ▶ **Observation 8.** For every $d \in \mathbb{N}$, there is a finite graph which is not a d-sphere graph.

Proof. We may assume that $d \ge 2$ since it is well known that not every graph is a circle graph; see [5]. Let n be an integer; we think of n as being large in comparison to d.

Let G_n be a graph of minimum degree n that does not contain a triangle as a subgraph, and such that G_n remains connected after removing the closed neighbourhood $N[y] := N(y) \cup \{y\}$ of any $y \in V(G_n)$; for example, G_n could be a portion of the n-dimensional cubic lattice.

 $^{^3}$ More generally, this applies to any connected, locally finite, planar graph; see [31] and references therein.

Suppose G_n can be realised as a d-sphere graph, and therefore as an intersection graph of spheres $\{S_v \mid v \in V(G_n)\}$ in \mathbb{R}^d by Observation 6. Pick a sphere of minimum radius among the S_v . Then, the spheres representing the neighbours of v intersect S_v and are mutually disjoint since G_n is triangle-free. Moreover, there is no triple S_x, S_y, S_z of such spheres such that S_y lies in the interior of S_x and S_z lies in the interior of S_y because N[y] would separate x from z in this case. Thus, after deleting any such spheres lying in the interior of others, we are left with at least n/2 spheres with disjoint interiors intersecting S_v , each of radius at least that of S_v . By a volume argument, the number of such spheres is bounded by a function of d. Thus G_n is not a d-sphere graph when n is large enough.

It is possible to strengthen Observation 8 by providing cubic graphs of arbitrarily high sphere dimension. Indeed, this is a corollary of Theorem 1, as we now discuss. Let $\{G_n^d:n\in\mathbb{N}\}\$ be a family of cubic expander graphs with $\lim_{n\to\infty}|V(G_n^d)|=\infty$. Then, since expanders do not have small separators, at most finitely many members of this family can have sphere dimension at most d by Theorem 1 and by Lee's [37] separator theorem for circle graphs. Alternatively, we can let $\{G_n^d : n \in \mathbb{N}\}$ be a family of finite cubic graphs of asymptotic dimension more than 2d+1; for instance, such graphs can be obtained from a portion of the (2d+2)-dimensional hypercubic lattice by replacing each vertex with a subcubic tree. Then at most finitely many members of this family can have sphere dimension at most d by the result of [19] that our Theorem 18 generalises.

Strongly sublinear separators

In this section, we prove Theorem 1, the separator theorem for the class \mathcal{C}_t^d of all graphs which have sphere dimension at most d and do not have $K_{t,t}$ as a subgraph.

We need some additional notation. Given a sphere S in \mathbb{R}^d , we write ball(S) for the (closed) ball with boundary S. We say that a sphere S' contains a different sphere S if $\mathsf{ball}(S')$ contains $\mathsf{ball}(S)$. Given a collection S of spheres in \mathbb{R}^d , we say that a sphere $S \in S$ is maximal if there is no $S' \in \mathcal{S} \setminus \{S\}$ such that S' contains S. Likewise, a sphere $S \in \mathcal{S}$ is minimal if there is no $S' \in \mathcal{S} \setminus \{S\}$ such that S contains S'. We call S nested if for any two spheres in \mathcal{S} , one contains the other. In this section, every collection of spheres is finite.

We start by noting that excluding $K_{t,t}$ provides a bound on the number of short paths between the "inside" and the "outside" of a large set of nested spheres.

- ▶ Lemma 9. Let $r, t \in \mathbb{N}$, let S be a collection of spheres in \mathbb{R}^d , and let $\mathcal{N} \subseteq \mathcal{S}$ be a set of t(r+1)-many nested spheres. Suppose that the intersection graph $G(S \setminus N)$ contains a collection \mathcal{P} of $t^2(r+1)$ -many pairwise vertex-disjoint paths such that for each path $P \in \mathcal{P}$,
- one end of P intersects the minimal sphere in \mathcal{N} ,
- the other end of P intersects the maximal sphere in \mathcal{N} , and
- \blacksquare P has length at most r.

Then, G(S) contains a $K_{t,t}$ as a subgraph.

Proof. We sort the vertices in \mathcal{N} by containment and consider \leq to be this ordering. For every path $P \in \mathcal{P}$ and every vertex $x \in V(P)$, the neighbourhood of x in \mathcal{N} is an interval with respect to \leq . We denote this interval by I_x . The first two conditions of the lemma guarantee that every sphere in \mathcal{N} is a neighbour of at least one vertex in P. Thus, since $|\mathcal{N}| = t(r+1)$ and P has length at most r, every $P \in \mathcal{P}$ contains a vertex x_P with $|I_{x_P}| \geq t$. Also, there are at most t(r+1) choices for the first vertex (according to \leq) inside I_{x_P} . Therefore, there are t vertices of the form x_P (on different paths) such that their intervals all start in the same vertex. These t vertices, plus the first t vertices in their intervals, yield the desired $K_{t,t}$ -subgraph.

Using this insight, we next prove that "minimal" graphs that contain a certain shallow clique minor cannot be represented by spheres with too much nesting.

▶ Lemma 10. Let $t, d, r, h \in \mathbb{N}$ with $t, d \geq 2$, and suppose that $G \in \mathcal{C}_t^d$ has as few vertices as possible subject to containing an r-shallow K_h -minor. Let \mathcal{S} be a collection of spheres in \mathbb{R}^d such that $G = G(\mathcal{S})$. Then every nested subset of \mathcal{S} has size at most $36t^4(3r+1)^3$.

Proof. Suppose towards a contradiction that there is a nested set $\mathcal{N} \subseteq \mathcal{S}$ of size at least $36t^4(3r+1)^3$. Let φ be an r-shallow minor model of K_h in G. For each vertex $x \in V(K_h)$, we fix some rooted spanning tree T_x of the subgraph of G induced on $\varphi(x)$ of height at most r. Note that, as G is minimal with respect to containing an r-shallow K_h -minor, every vertex of G is in a bag of φ . Similarly, for every vertex $x \in V(K_h)$, every leaf of T_x has an edge to some other bag which has no other neighbours in T_x . We now break into cases based on whether many vertices in \mathcal{N} lie in the same bag or in different bags.

First, consider the case that at least $6t^2(3r+1)^2$ vertices of \mathcal{N} lie in a single bag, say the bag of $x \in V(K_h)$. As T_x has height at most r, at least a $\frac{1}{(r+1)}$ proportion of these elements all have the same distance to the root of T_x . Thus, there exists a set $\mathcal{X} \subseteq \mathcal{N}$ of size at least $6t^2(3r+1)$ such that all vertices in \mathcal{X} are not only in T_x but also have the same distance to the root of T_x . So, no vertex in \mathcal{X} lies on the path between the root of T_x and another vertex in \mathcal{X} . For each $X \in \mathcal{X}$, we fix an arbitrary leaf vertex $\ell(X)$ of T_x that is a descendent of X in T_x . (It is possible that $\ell(X) = X$.) Let us denote the path of T_x joining X and $\ell(X)$ by $\ell(X)$. Since all of the vertices in \mathcal{X} have the same distance to the root, the paths $\ell(X) = \mathcal{X}$ are pairwise vertex-disjoint. Additionally, for each of these leaves $\ell(X)$, there is a vertex $\ell(X) \in \ell(K_h)$ such the bag of $\ell(X)$ has an edge to $\ell(X)$ and does not have an edge to any other vertex in $\ell(X)$. Thus, since the leaves $\ell(X) = \mathcal{X}$ are all distinct, the vertices $\ell(X) = \mathcal{X}$ are also all distinct.

Now we sort the elements of \mathcal{X} by containment as $X_1,\ldots,X_{|\mathcal{X}|}$. We pair up the first $t^2(6r+2)$ elements of \mathcal{X} with the last $t^2(6r+2)$ elements of \mathcal{X} . So we consider the pairs $(X_1,X_{|\mathcal{X}|})$, $(X_2,X_{|\mathcal{X}|-1})$, and so on. As K_h is the complete graph, for every pair $(X_i,X_{|\mathcal{X}|-i+1})$ there is a path between X_i and $X_{|\mathcal{X}|-i+1}$ whose vertex-set is contained in $P(X_i)\cup\varphi(y(X_i))\cup\varphi(y(X_{|\mathcal{X}|-i+1}))\cup P(X_{|\mathcal{X}|-i+1})$. The two paths $P(X_i)$ and $P(X_{|\mathcal{X}|-i+1})$ have length at most r-1 since no vertex in \mathcal{X} is the root of T_x . In each of the two bags $\varphi(y(X_i))$ and $\varphi(y(X_{|\mathcal{X}|-i+1}))$, we can choose paths of length at most 2r. Finally, we need 3 edges to join the parts together. So overall, this path between X_i and $X_{|\mathcal{X}|-i+1}$ has length at most 2(r-1)+2(2r)+3=6r+1 (see Figure 1). Note that $|\mathcal{X}| \geq 6t^2(3r+1)=3t^2(6r+2) \geq 2t^2(6r+2)+t(6r+2)$. So at least t(6r+2) spheres lie between any two paired spheres in \mathcal{X} . Thus, by Lemma 9, G contains $K_{t,t}$ as a subgraph, a contradiction.

Second, consider the case that there exists a set $\mathcal{X} \subseteq \mathcal{N}$ of size at least $6t^2(3r+1)$ so that every pair of vertices in \mathcal{X} lie in different bags of φ . So for every $X \in \mathcal{X}$, there exists a vertex $y(X) \in V(K_h)$ such that X lies in $\varphi(y(X))$. Again, we sort the elements of \mathcal{X} by containment as $X_1, \ldots, X_{|\mathcal{X}|}$ and pair the first and last elements. This time, we pair the first t(4r+2) elements of \mathcal{X} with the last t(4r+2) elements of \mathcal{X} . So for $1 \leq i \leq t(4r+2)$, the sphere X_i is paired to the sphere $X_{|\mathcal{X}|-i+1}$. As K_h is the complete graph, there exists a path between X_i and $X_{|\mathcal{X}|-i+1}$ of length at most 4r+1 in the subgraph of G induced by $\varphi(y(X_i)) \cup \varphi(y(X_{|\mathcal{X}|-i+1}))$ (see Figure 2). Additionally, $|\mathcal{X}| \geq 6t^2(3r+1) = 3t^2(6r+2) \geq 2t(4r+2) + t^2(4r+2)$. Thus, at least $t^2(4r+2)$ spheres lie between any two paired spheres in \mathcal{X} . Thus, again by Lemma 9, G contains $K_{t,t}$ as a subgraph, a contradiction.

One of the two cases must occur, and so this completes the proof of Lemma 10.

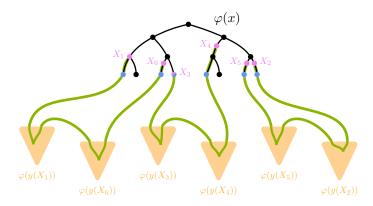


Figure 1 This illustrates the case that many vertices of \mathcal{N} lie in a single bag. The set $\mathcal{X} = \{X_1, \ldots, X_6\}$ is depicted together with the corresponding leaves (note that X_3 is equal to its leaf). Using two paired bags, the green paths are of length at most 6r + 1 and pairwise disjoint.

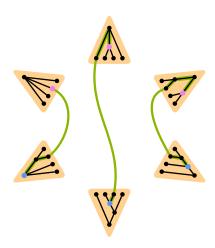


Figure 2 This illustrates the case that many vertices of \mathcal{N} lie in different bags. The outermost spheres are mapped to the innermost spheres such that the green paths (all of length at most 4r+2) have to cross the spheres lying in between.

It is known, as seen in Lemma 4, that intersection graphs of balls of small ply have bounded strong colouring number. We make use of this to show that we can obtain a similar result for sphere intersection graphs excluding a $K_{t,t}$ -subgraph, assuming they can be represented without a large set of nested spheres.

▶ Lemma 11. Let S be a collection of spheres in \mathbb{R}^d whose intersection graph G = G(S) does not contain $K_{t,t}$ as a subgraph. Suppose that every nested subset of S has size at most k. Then for every $r \in \mathbb{N}$, the r-strong colouring number of G is at most $2kt(2r+2)^d$.

Proof. We claim that the collection $\{\mathsf{ball}(S) \mid S \in \mathcal{S}\}$ of balls in \mathbb{R}^d has ply at most 2kt. This yields the desired statement by Lemma 4.

So, let $\mathcal{X} \subseteq \mathcal{S}$ be a collection of spheres such that their common intersection as balls is non-empty, that is, such that $\bigcap_{X \in \mathcal{X}} \mathsf{ball}(X) \neq \emptyset$. Let us consider the poset \preceq on \mathcal{X} where for any spheres $X, X' \in \mathcal{X}$, we have $X \preceq X'$ if X is contained in X'. Every chain in this poset has size at most k by the assumption about nested sets. Next, note that a single point in

 \mathbb{R}^d lies in at most 2t pairwise incomparable (according to \preceq) spheres in \mathcal{X} , as otherwise, G would contain a clique of size 2t and therefore have $K_{t,t}$ as a subgraph. Thus, every antichain in this poset has size at most 2t, and the lemma follows.

The penultimate step is to combine lemmata 10 and 11 with Observation 5 in order to exclude shallow minors from the class C_t^d .

▶ **Lemma 12.** For any integers $t, d \ge 2$ and any $r \in \mathbb{N}$, no graph $G \in \mathcal{C}_t^d$ has a clique of size $72t^5(3r+2)^{d+3}$ as an r-shallow minor.

Proof. For convenience, we set $h = 72t^5(3r+2)^{d+3}$. Suppose for a contradiction that there is a graph $G \in \mathcal{C}_t^d$ which contains K_h as an r-shallow minor. Choose such a graph G with as few vertices as possible. Let \mathcal{S} be a collection of spheres in \mathbb{R}^d such that $G = G(\mathcal{S})$. Then by Lemma 10, every nested subset of \mathcal{S} has size at most $36t^4(3r+1)^3$. So by Lemma 11, the (4r+1)-strong colouring number of G is at most $2(36t^4(3r+1)^3)t(2r+2)^d$. Note that

$$2(36t^{4}(3r+1)^{3})t(2r+2)^{d} = 72t^{5}(3r+1)^{3}(2r+2)^{d} \le 72t^{5}(3r+2)^{d+3} - 2 = h - 2.$$

Finally, by Observation 5, the (4r+1)-strong colouring number of G is at least h-1. So $h-1 \le \operatorname{scol}_{4r+1}(G) \le h-2$, a contradiction.

Now we can combine our results with the theorem of Plotkin, Rao, and Smith [46] (stated as Theorem 3) to obtain strongly sublinear separators in graphs of sphere dimension at most d which exclude a $K_{t,t}$ -subgraph. We restate the theorem below for convenience.

▶ **Theorem 1.** For any integers $t, d \geq 2$, the class C_t^d has strongly sublinear separators. More precisely, every n-vertex graph $G \in C_t^d$ has a balanced separator of size $\widetilde{\mathcal{O}}_d(t^{10}n^{1-\frac{1}{2d+8}})$.

Proof. Let $G \in \mathcal{C}_t^d$. For convenience, set $r = n^{\frac{1}{2d+8}}$. (We omit floors and ceilings for the sake of readability when they do not affect the proof.) By Lemma 12, G does not have a clique of size $72t^5(3r+2)^{d+3}$ as an r-shallow minor. Since $72t^5(3r+2)^{d+3} \in \mathcal{O}_d(t^5r^{d+3})$, by Theorem 3 we have that G contains a balanced separator of size

$$\mathcal{O}_d\left(rt^{10}r^{2d+6}\log n + \frac{n}{r}\right) = \widetilde{\mathcal{O}}_d\left(t^{10}r^{2d+7} + n^{1-\frac{1}{2d+8}}\right) = \widetilde{\mathcal{O}}_d\left(t^{10}n^{1-\frac{1}{2d+8}}\right).$$

5 Asymptotic dimension

In this section, we prove that \mathcal{C}^d has bounded asymptotic dimension. In fact, we prove that the following more general class of graphs has bounded asymptotic dimension. Let \mathcal{C}^d_{α} be the class of connected intersection graphs of systems of path-connected sets in \mathbb{R}^d , each of which is obtained from a compact convex set of aspect ratio at most α by removing some subset of its interior. Clearly, the class \mathcal{C}^d of intersection graphs of spheres in \mathbb{R}^d is a subclass of \mathcal{C}^d_{α} . If the sets are restricted so that none of their interiors is removed, then this subclass was proved to have bounded asymptotic dimension by Dvořák and Norin [19]. This theorem shall be one of our main tools.

▶ Theorem 13 ([19]). For every positive integer d and every $\alpha \geq 1$, the class of intersection graphs of systems of compact convex sets of aspect ratio at most α in \mathbb{R}^d has asymptotic dimension at most 2d + 1.

We introduce some notations similar to those used for spheres as in Section 4. For a graph $G \in \mathcal{C}^d_\alpha$ and a vertex $x \in V(G)$ we refer by $\operatorname{ccl}(x)$ to the convex closure of x. We say that a vertex y contains a different vertex x if $\operatorname{ccl}(y)$ contains $\operatorname{ccl}(x)$. We say the vertex x is maximal if there is no $y \in V(G) \setminus \{x\}$ such that y contains x.

The *height* of a bounded convex set $X \subset \mathbb{R}^d$ is the infimum $h \geq 0$ such that X is contained between two parallel hyperplanes at distance h. The *aspect ratio* of X is the ratio of the diameter of X over its *height*. Let \mathcal{B}^d_α denote the class of intersection graphs of systems of compact convex sets of aspect ratio at most α in \mathbb{R}^d . If $G \in \mathcal{C}^d_\alpha$ contains no pair of distinct vertices x, y with y containing x, then G belongs to \mathcal{B}^d_α , i.e. Theorem 13 applies.

Our next main tool is a theorem of Bonamy, Bousquet, Esperet, Groenland, Liu, Pirot, and Scott [4] that shall allow us to apply Theorem 13. Before introducing this theorem, we require some further definitions.

A weighted graph (G, λ) consists of a graph G and a function $\lambda : E(G) \to \mathbb{R}^+$. We call $\lambda(e)$ the weight of e for each $e \in E(G)$. The length in (G, λ) of a path P in G is the sum of the weights of the edges of P. Given two vertices $x, y \in V(G)$, we define $\operatorname{dist}_{(G,\lambda)}(x,y)$ to be the infimum of the length in (G,λ) of a path between x and y; we define $\operatorname{dist}_{(G,\lambda)}(x,y) = \infty$ if there exists no path between x and y. We remark that all the weighted graphs we consider are actually graphs whose edges have weights 1 or 2. Given $A \subseteq V(G)$, we let G[A] denote the induced subgraph of G on vertex set G[A] is the subgraph of G[A] obtained by restricting to the vertex set G[A]. For weighted graphs, we define G[A] similarly.

A real projection of a (weighted) graph (G,λ) is a function $p:V(G)\to\mathbb{R}$ such that $|p(x)-p(y)|\leq \operatorname{dist}(x,y)$ for every pair of vertices $x,y\in V(G)$. Given S>0 and a real projection p of a weighted graph G, we say that a vertex set $A\subseteq V(G)$ is (p,S)-bounded if $\max_{x,y\in A}|p(x)-p(y)|\leq S$. Given a class $\mathcal C$ of weighted graphs and a sequence $\mathcal L=(\mathcal L^1,\mathcal L^2,\ldots)$ of classes of weighted graphs with $\mathcal L^1\subseteq\mathcal L^2\subseteq\cdots$, we say that $\mathcal C$ is $\mathcal L$ -layerable if there is a function $f:\mathbb R^+\to\mathbb N$ such that any weighted graph $(G,\lambda)\in\mathcal C$ has a real projection $p:V(G)\to\mathbb R$ such that for any S>0, any maximal (p,S)-bounded set in (G,λ) induces a (weighted) subgraph that belongs to $\mathcal L^{f(S)}$.

▶ **Theorem 14** ([4, Theorem 4.3]). Let $\mathcal{L} = (\mathcal{L}_1, \mathcal{L}_2, \ldots)$ be a sequence of classes of weighted graphs of asymptotic dimension at most n. Let \mathcal{C} be an \mathcal{L} -layerable class of weighted graphs. Then the asymptotic dimension of \mathcal{C} is at most n+1.

We use the well-known fact that quasi-isometric classes of graphs have equal asymptotic dimension. A (Π, Σ) -quasi-isometry between (weighted) graphs (G, λ) and (H, ψ) is a map $f: V(G) \to V(H)$ such that the following hold for fixed constants $\Pi \geq 1, \Sigma \geq 0$:

- 1. $\Pi^{-1} \operatorname{dist}(x,y) \Sigma \leq \operatorname{dist}(f(x),f(y)) \leq \Pi \operatorname{dist}(x,y) + \Sigma$ for every $x,y \in V(G)$, and
- **2.** for every $z \in V(H)$, there is a $x \in V(G)$ such that $\operatorname{dist}(z, f(x)) \leq \Sigma$.

We say that classes of weighted graphs \mathcal{G} and \mathcal{H} are quasi-isometric, if there exist fixed constants $\Pi \geq 1$, $\Sigma \geq 0$ such that for every $G \in \mathcal{G}$ there exists a $H \in \mathcal{H}$ and a (Π, Σ) -quasi-isometry between G and H. It is well known that quasi-isometric classes of (weighted) graphs have equal asymptotic dimension (see for instance [4]).

▶ **Lemma 15.** If classes of weighted graphs G_1, G_2 are quasi-isometric, then they have equal asymptotic dimension.

Instead of working with \mathcal{C}^d_{α} , we shall define an essentially equivalent (we only add edges of weight 2 between some vertices at distance 2) class of weighted graphs $\widehat{\mathcal{C}}^d_{\alpha}$ that is layerable by a class of weighted graphs that are quasi-isometric to graphs in \mathcal{B}^d_{α} .

For $G \in \mathcal{C}^d_{\alpha}$, choose some maximal $v \in V(G)$. We call v the *pivot* vertex of G. Now, for each non-negative integer i, let D_i be the vertices in G at distance i from v. Let (\widehat{G}, λ) be the weighted graph obtained from G by adding, for each pair $x, y \in V(G)$ with $x, y \in D_i$ for some i, an edge of weight 2 between x and y if x is contained in y (all the edges (E(G)) have weight 1 in (\widehat{G}, λ)). The following observation is key.

▶ Lemma 16. Let $G \in \mathcal{C}^d_\alpha$. Then for every pair $x, y \in V(G)$ holds $\operatorname{dist}_G(x, y) = \operatorname{dist}_{(\widehat{G}, \lambda)}(x, y)$.

Proof. It is enough to show that if there is an edge of weight 2 between vertices x, y in (\widehat{G}, λ) , then in G, there is a vertex adjacent to both x and y. Since there is an edge of weight 2 between vertices x, y in (\widehat{G}, λ) , there exists some positive integer i such that $x, y \in D_i$, and without loss of generality, we may assume that x is contained in y. Let P be a path of length i between x and v, and let z be the unique vertex of $D_{i-1} \cap V(P)$. Then z intersects x and $\bigcup_{u \in V(P)} u$ contains a curve C from x to a point in v not contained in w for any $w \in V(G)$. Since the curve C starts in the interior of y and ends in its exterior, C must intersect y. Therefore, y is adjacent to a vertex of P. However, y is non-adjacent to x in G and cannot be adjacent to any vertex of $D_0 \cup \cdots \cup D_{i-2}$ since $y \in D_i$. Therefore, y must be adjacent to z in G. Hence, the distance between x and y in G is equal to z, as desired.

Let $\mathcal{L}_{d,\alpha}^i$ be the class of weighted graphs that are (i,1)-quasi-isometric to a graph in \mathcal{B}_{α}^d . Note that $\mathcal{L}_{d,\alpha}^1 \subseteq \mathcal{L}_{d,\alpha}^2 \subseteq \cdots$. Let $\mathcal{L}_{d,\alpha} = (\mathcal{L}_{d,\alpha}^1, \mathcal{L}_{d,\alpha}^2, \ldots)$. We show that $\widehat{\mathcal{C}}_{\alpha}^d$ is $\mathcal{L}_{d,\alpha}$ -layerable.

▶ **Lemma 17.** The class of weighted graphs $\widehat{\mathcal{C}}_{\alpha}^d$ is $\mathcal{L}_{d,\alpha}$ -layerable.

Proof. Let $(\widehat{G}, \lambda) \in \widehat{\mathcal{C}}_{\alpha}^d$, let $G \in \mathcal{C}_{\alpha}^d$ be the graph obtained from (\widehat{G}, λ) by removing its edges of weight 2, and let v be the pivot-vertex of (\widehat{G}, λ) . For $x \in V(\widehat{G})$, let $p(x) \coloneqq d_{\widehat{G}}(v, x)$. Then, p is a real projection of (\widehat{G}, λ) . Let S > 0, and let $A \subseteq V(\widehat{G})$ be some maximal (p, S)-bounded set in (\widehat{G}, λ) . Then, there exists some non-negative integer t such that A is the set of vertices in (\widehat{G}, λ) (or equivalently G) whose distance from v is between t and $t + \lceil S \rceil$; indeed, we can let $t \coloneqq \min\{p(x) \mid x \in A\}$.

Let M be the set of maximal vertices of G[A]. Observe that $(\widehat{G}, \lambda)[M] = G[M]$ contains no edge of weight 2 and furthermore that it is a graph in \mathcal{B}^d_{α} . Let $f: A \to M$ be such that for every $u \in A$, f(u) is some maximal vertex containing u. We shall show that f is a $(2\lceil S \rceil + 4, 1)$ -quasi-isometry from $(\widehat{G}, \lambda)[A]$ to G[M], which implies that $(\widehat{G}, \lambda)[A] \in \mathcal{L}^{2\lceil S \rceil + 4}_{d,\alpha}$ and therefore that $\widehat{\mathcal{C}}^d_{\alpha}$ is $\mathcal{L}_{d,\alpha}$ -layerable as we desire.

If there is an edge of weight 1 or 2 between vertices x and y of $(\widehat{G}, \lambda)[A]$, then f(x) and f(y) intersect or coincide, and therefore $\mathsf{dist}_{G[M]}(f(x), f(y)) \leq 1$. It follows that $\mathsf{dist}_{G[M]}(f(x), f(y)) \leq \mathsf{dist}_{(\widehat{G}, \lambda)[A]}(x, y)$ for every pair of vertices $x, y \in A$.

Consider some $m \in M$. Note that $f^{-1}(m)$ is non-empty since f(m) = m, and so f is surjective. We aim to show that each vertex x of $f^{-1}(m)$ has distance at most S+2 from m in $(\widehat{G},\lambda)[A]$. Let $x_0x_1\ldots x_\ell$ be a v-x geodesic in (\widehat{G},λ) (or G), i.e. a path with $x_0=v$, $x_\ell=x$ and $p(x_i)=\operatorname{dist}_{(\widehat{G},\lambda)}(v,x_i)=i$ for each i. Then $\bigcup_{i=0}^\ell x_i$ contains a curve C from x to a point in v not contained in the interior of z for any $z\in V(G)\backslash v$. Since the curve C starts in the interior of $\operatorname{ccl}(m)$ and ends outside the interior of $\operatorname{ccl}(m)$, it follows that m is adjacent in G to some vertex of $\{x_0,\ldots,x_\ell\}$. We further have that m must be adjacent to one of $x_{p(m)-1},x_{p(m)},x_{p(m)+1}$. Note that $t\leq p(m)\leq p(x)=\ell\leq t+\lceil S\rceil$ since $m,x\in A$. If either p(m)>t or m is adjacent to one of $x_{p(m)}$ or $x_{p(m)+1}$, then there is a path in G[A] (and thus in $(\widehat{G},\lambda)[A]$) between m and x of length at most $\lceil S\rceil+1$. So, we may assume now that p(m)=t and that m is non-adjacent to both $x_{p(m)}$ and $x_{p(m)+1}$. It follows that $x_{p(m)}$

is contained in $\operatorname{ccl}(m)$ and that m is adjacent to $x_{p(m)-1}$ in G. Therefore, there is an edge of weight 2 in (\widehat{G}, λ) between m and $x_{p(m)}$. Hence, there is a path of length at most $\lceil S \rceil + 2$ in $(\widehat{G}, \lambda)[A]$ between m and x. Thus, x has distance at most $\lceil S \rceil + 2$ from m in $(\widehat{G}, \lambda)[A]$.

So $f^{-1}(m)$ has radius at most $\lceil S \rceil + 2$ in $(\widehat{G}, \lambda)[A]$ and therefore diameter at most $2\lceil S \rceil + 4$. Thus, as G[M] is a graph, for every $x, y \in A$, we have that $(2\lceil S \rceil + 4)^{-1} \operatorname{dist}_{(\widehat{G}, \lambda)[A]}(x, y) - 1 \le \operatorname{dist}_{G[M]}(f(x), f(y))$. Hence f is a $(2\lceil S \rceil + 4)$ -quasi-isometry between $(\widehat{G}, \lambda)[A]$ and G[M].

We have assembled all the ingredients to prove the main result of this section:

▶ **Theorem 18.** For every positive integer d and every $\alpha \geq 1$, the class \mathcal{C}^d_{α} of intersection graphs of systems of path-connected sets in \mathbb{R}^d , each of which is obtained from a compact convex set of aspect ratio at most α by removing some subset of its interior, has asymptotic dimension at most 2d + 2.

Proof. By Lemma 16, the asymptotic dimension of \mathcal{C}^d_{α} and $\widehat{\mathcal{C}}^d_{\alpha}$ is equal. By Lemma 17, $\widehat{\mathcal{C}}^d_{\alpha}$ is $\mathcal{L}_{d,\alpha}$ -layerable. The graph classes $\mathcal{L}^1_{d,\alpha}, \mathcal{L}^2_{d,\alpha}, \ldots$ all have asymptotic dimension at most 2d+1 by Lemma 15 and Theorem 13. Therefore, by Theorem 14, $\widehat{\mathcal{C}}^d_{\alpha}$ has asymptotic dimension at most 2d+2.

6 Final remarks and open problems

As we have seen, every graph G with at least three vertices has sphere dimension at most |V(G)| - 1 by Observation 7. Can this be improved? Providing a bound with respect to the number of edges is also interesting.

▶ **Problem 19.** What is the maximum sphere dimension of a graph on n vertices?

In light of other known separator theorems for ball intersection graphs [44], it seems likely that the exponent in Theorem 1 is not optimal. We conjecture the following.

▶ Conjecture 20. For any integers $t, d \ge 1$, every n-vertex graph $G \in \mathcal{C}_t^d$ has a balanced separator of size $\mathcal{O}_{t,d}(n^{1-\frac{1}{d+1}})$.

This conjecture is true for d=1 since every *n*-vertex circle graph with a forbidden $K_{t,t}$ subgraph has a separator of size $\mathcal{O}_t(\sqrt{n})$ due to [37] and [24, Theorem 3].

It is also likely possible to improve the asymptotic dimension bound in Theorem 18 for graphs of bounded sphere dimension as follows.

▶ Conjecture 21. For any integer $d \ge 1$, the class of graphs with sphere dimension at most d has asymptotic dimension at most d.

This conjecture would be tight since the hypercubic lattice \mathbb{Z}^d has asymptotic dimension and sphere dimension equal to d. For the latter claim, the sphere dimension is at most d because of the standard sphere packing centred at the integers. The fact that the sphere dimension is at least d follows from a deep result by Benjamini and Schramm [2, 3] stating that \mathbb{Z}^d cannot be quasi-sphere packed in \mathbb{R}^{d-1} , with a little additional work. The case d=2 of the conjecture (furthermore for Assouad–Nagata dimension and in the more general class of string graphs) will be proved in separate work [10]. It is also easy to deduce the d=1 case for circle graphs from known results [8, 26]. Recently Liu and Norin [41] independently, using different methods, proved an improved asymptotic dimension bound of d+1. It might be possible to reduce Conjecture 21 via quasi-isometry to the class of intersection graphs of balls in \mathbb{R}^d (this is the case for d=2 [10]).

▶ Conjecture 22. For any integer $d \ge 2$, the class of graphs with sphere dimension at most d is quasi-isometric to the class of intersection graphs of balls in \mathbb{R}^d .

Recall that an *induced minor* of a graph is obtained by deleting vertices and contracting edges. Let $Forb_{ind}(H)$ denote the class of graphs that do not contain a graph H as an induced minor.

▶ **Problem 23.** Do the graphs in $Forb_{ind}(H)$ have bounded sphere dimension for every finite graph H? If not, is each graph in $Forb_{ind}(H)$ uniformly quasi-isometric to a graph with bounded sphere dimension?

The same questions can be asked for minors instead of induced minors. These two versions of Problem 23 are related via the following problem, which is a special case of [27, Conjecture 1.1] (which has been disproven [11], but special cases remain open):

▶ **Problem 24.** For every finite graph H, each graph in $Forb_{ind}(H)$ is uniformly quasi-isometric to a graph with no H minor.

For $d \geq 3$, it is not possible to replace asymptotic dimension by Assouad–Nagata dimension in Theorem 18, even for the subclass of ball intersection graphs. This was observed by Dvořák and Norin [17]. Assouad–Nagata dimension is closely related to a concept in computer science called sparse partition schemes. Roughly speaking, if a graph class has bounded Assouad–Nagata dimension, and the colourings witnessing this can be computed, then certain universal versions of classical optimisation problems such as TSP, Steiner Tree and Set Cover allow approximations of bounded ratio. These approximate solutions are computed using sparse partition schemes; see, for instance, [4, 32, 6]. As mentioned above, graphs of bounded sphere dimension have unbounded Assouad–Nagata dimension, and so we cannot hope for sparse partition schemes. Still, it would be interesting to obtain bounds on these parameters as a function of the size of the graph. Our proof of Theorem 18 utilises Theorem 14, which has a strengthening preserving boundedness of Assouad–Nagata dimension. Thus, the bottleneck lies in the proof of Theorem 13 in [17].

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